

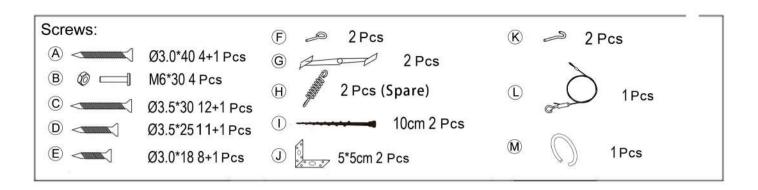
User Manual

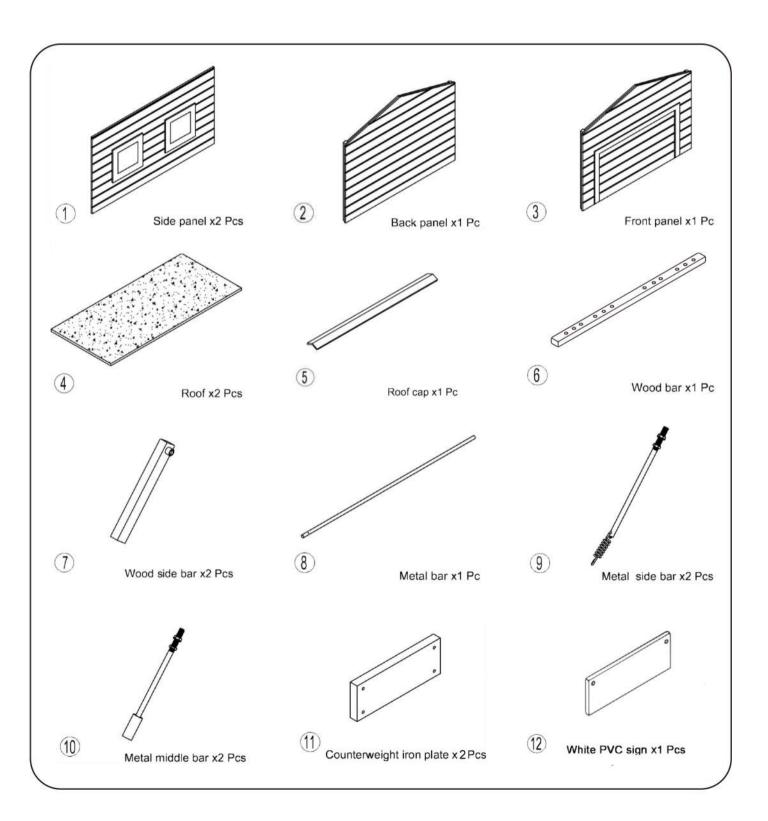


My Robot Home Compact





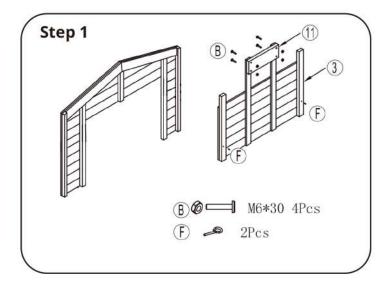


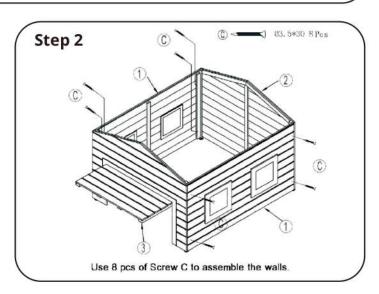


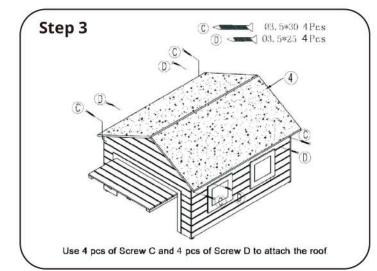


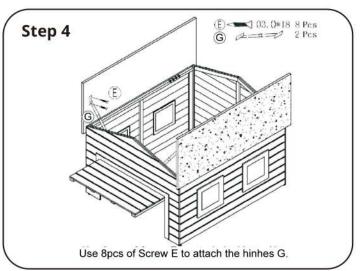
BEFORE STARTING THE INSTALLATION:

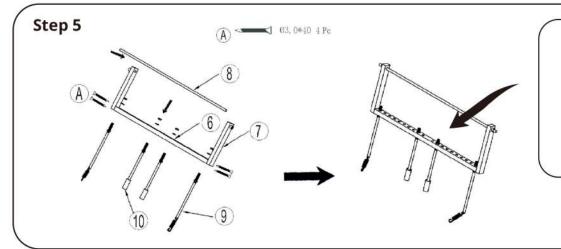
- 1.For the best result, Auto-mow recommends placing the garage on concrete, brick, or similar flat and hard surface.
- 2.If installed on grass, Auto-Mow recommends that you put small bricks below on all 4 corners, to support the garage, and to make sure the garage will not sink into the ground.









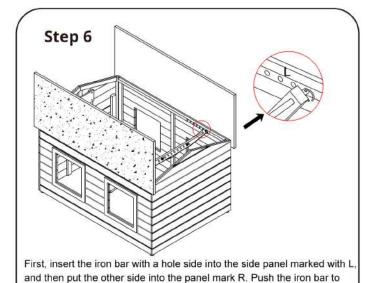


Remark:

Remember to tighten the nut on the metal post on both sides of the wooden panel.

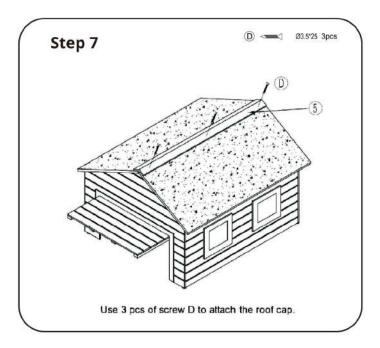
The metal posts must be completely fixed so that they cannot move individually.

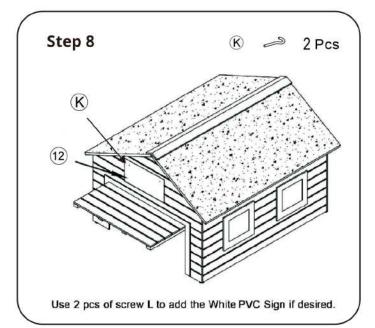


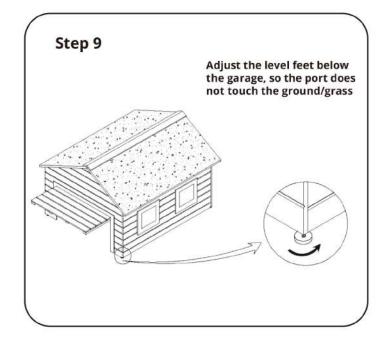


the bottom to R side until the hole of the iron bar is exposed, and insert

the pin M into the hole to fix it.



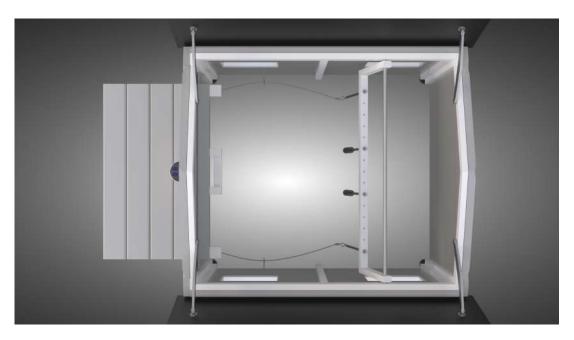




Remark:

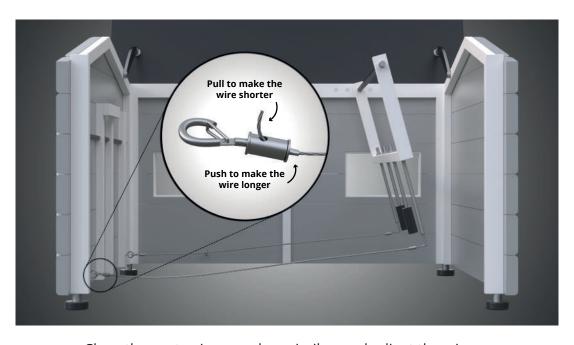
We also have the Angle Bracket with long spikes. (Part J & Part H)
If you want to fix the house to the ground,
please use screw D to connect the Angle.
Bracket (H) to the house.
Make sure the long spikes (J) are fixed in the ground.

Step 1 - Adjust the mechanism to the docking station



Place the robot inside the Garage and adjust the 2 poles to fit the docking station and the robotic lawn mower.

Step 2 - Fit the string to adjust the tention of the automatic door.



Close the port using a rock or similar, and adjust the wires to fit the position between the door, robot and docking station.

TROUBLESHOOTING:

- 1.If the door cannot open or close completely: Inspect the feet leveler beneath the garage.
- 2.If the door cannot close fully: Return to step 3 and fine-tune the mechanism's angle towards the door to provide a more extended push on the rods for complete closure.
- 3.If the door doesn't fully open: Return to step 3 and adjust the mechanism's angle towards the docking station.
- 4.If the door still struggles to open or lock: Go back to step 2 and readjust the mechanism at the top of the side panels for a optimal position.