

Contents

1 Instrument Overview	4
1.1 Physical Specifications	4
1.2 Communicating with the Instrument	8
1.3 Charging the Instrument	9
1.4 Auxiliary Sensors	10
1.5 GPS Functionality (500m Variants Only)	10
1.6 Indicator LED Flash Patterns	11
1.7 Pressure Ratings	11
2 Getting Started	12
2.1 Sensor Cage	12
2.2 X2Change™ Sensors	13
2.2.1 Removing Sensors	14
2.2.2 Installing Sensors	14
2.3 Seals and Plugs	15
2.4 Sailfish Overview	15
2.5 Conducting a Profile	18
2.6 Connecting a GPS Listener	19
3 Instrument Settings	21
3.1 Sensors	21
3.2 Sampling Mode	22
3.3 Included Log Parameters	23
3.4 Instrument Time and Location	24
3.5 Power Management	24
3.6 Manage Files	25
3.7 Firmware Updates	25
3.8 Command Prompt	26
4 Contact AML	27
5 Appendix A - Full command list	28
5.1 Sampling commands	28
5.2 Monitor Configurations and commands	29
5.3 Log File Format/Monitor Output	31
5.4 Pressure Configuration	32
5.5 UV Antifouling	32
5.6 Data Logging	33
5.7 Help	33
5.8 Communication commands	34
5.9 Sensor commands	34
5.10 System commands	34
5.11 GPS commands	35



5.12 Power commands	36
6 Appendix B - Output Formats	37
6.1 Column-Based Format	37
6.2 AMLx Format	37
7 Appendix C - Calculated Parameters	39
8 Appendix E - Storage Recommendations	40
9 Appendix F - USB FAQ	40
10 Appendix G - Regulatory Information	41
11 Appendix H - Warranty Statement	41

1 Instrument Overview

The AML LGR model is a highly configurable family of multiparameter sondes designed for a wide range of data collection applications. This model includes both the AML-3 LGR and the AML-6 LGR, where the '3' and '6' designations refer to the number of sensors that may be simultaneously installed on the instrument's endcap. Additional sensors may be connected externally, allowing up to 4 and 8 sensors respectively in total.

There are three primary models of instruments in the AML-3 and AML-6 family: the AML LGR, a self-powered instrument designed for profiling applications, the AML RTS, an externally powered instrument intended for Real Time Streaming applications, and the AML XC (Xtra Connector), a hybrid instrument with both Logging and Real Time capabilities. While nearly identical in size and form factor, the three models differ in a few key features which specialize them for their respective applications.

Instruments with the LGR designation are self-powered via a rechargeable internal battery and have a mechanical on/off switch adjacent to their shackle. These instruments are designed to internally log sensor measurements and transfer data post-deployment. These instruments are most commonly used for multiparameter profiling such as CTD, SVP, etc.

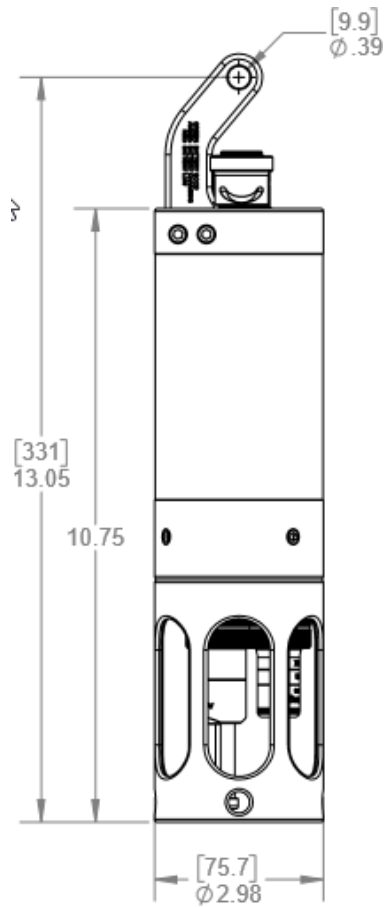
Real Time Streaming instruments, in contrast, are designed to stream data, with no ability to internally record the data. Both power and communication to these instruments is facilitated via a waterproof connector located adjacent to the shackle. These instruments rely on external power for operation and the application of this power turns the instrument on in lieu of a mechanical switch. These instruments are commonly used in moored applications, buoys, underwater observatories, and ROVs.

Instruments with the XC designation combine the strengths from both the LGR and RTS versions. Providing even more flexibility, it can internally record data and has the option of streaming data in real time via a waterproof connector located adjacent to the shackle. These instruments are used when both real time streaming and internal logging may be required.

This manual describes the operation of both the AML-3 and AML-6 Logger (LGR) version.

1.1 Physical Specifications

AML instruments are highly customizable and may be equipped with a wide range of user-specific sensors. The instruments described here are intended to be a representative example of a typical setup and therefore may not be identical to the Reader's unit. The Reader is directed to any unit-specific supplementary documentation provided with their instrument for information on features and functionality not described here.



NOTE: Different cage lengths are available, depending on the sensor payload. Shown above is the shortest cage option.



Figure 1: A typical AML-3 LGR. The instrument shown here is representative only and may differ from the Reader's instrument.

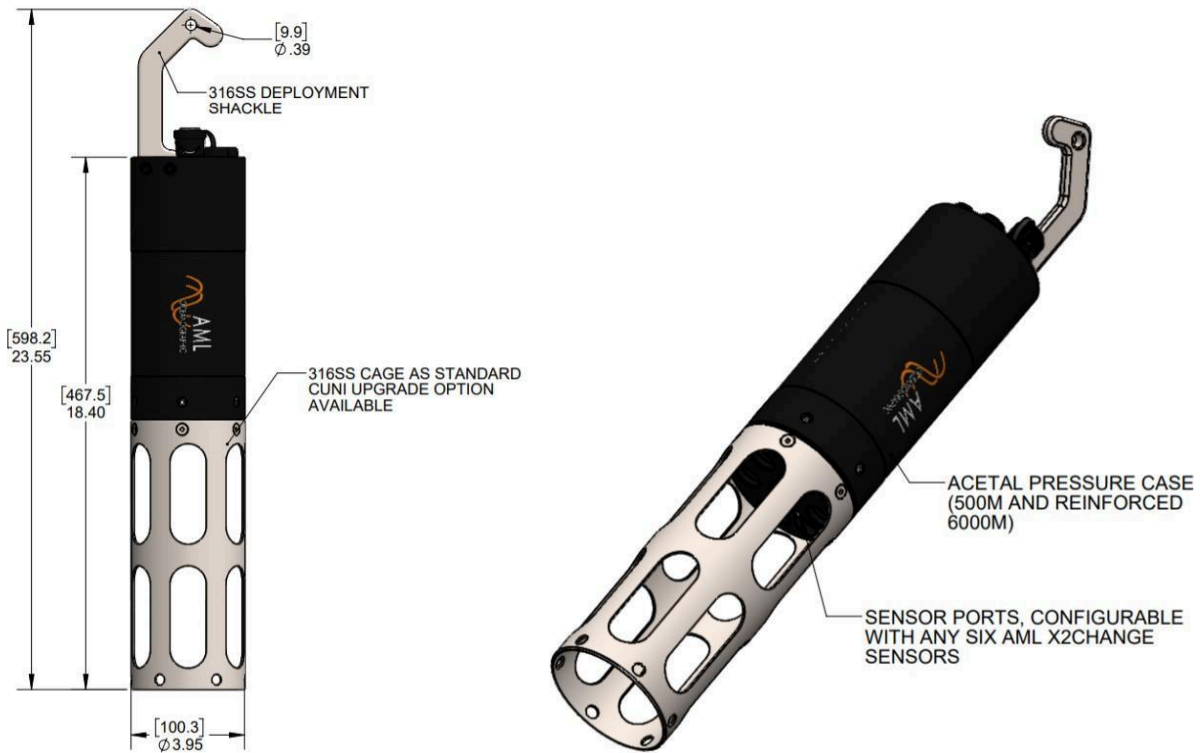
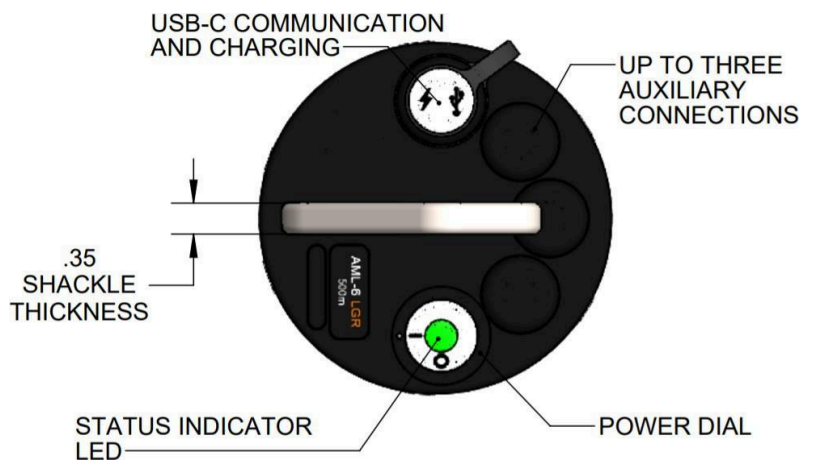


Figure 2: A typical AML-6 LGR. The instrument shown here is representative only and may differ from the Reader's instrument.



By default, both the AML-3 and AML-6 LGR instruments come equipped with a shackle, a USB-C connector, a power switch, and a status indicator LED. The shackle has a hole coincident with the axis of the instrument to facilitate suspension during deployment. It is recommended the instruments be deployed vertically with the shackle end up. The AML-6 LGR shackle is also hook shaped to provide secure handling by a user.

The end of the instrument opposite the shackle houses the sensor payload which is mechanically protected by a cage. **The AML-3 utilizes a thread-on sensor cage, and the AML-6 utilizes a bolted-on sensor cage.** In some configurations the cage may be different



lengths depending on the sensors installed (AML-3 only) or made from a copper alloy to prevent biofouling (AML-6 only). The default cage for both instruments uses stainless steel.

Standard specifications of an AML LGR are described in the table below.

Specifications:

	500m LGR Variant (AML-3 or AML-6)	6000m LGR Variant (AML-3 or AML-6)
Depth rating	500 meters [1640 feet]	6000 meters [19685 feet]
Material	AML-3: Acetal pressure case AML-6: Acetal pressure case	AML-3: Titanium pressure case AML-6: Acetal pressure case with internal metal reinforcement
GPS Capability	Yes	No
Data storage	30 GB	30 GB
Software	Sailfish	Sailfish
Communication	USB-C WiFi	USB-C
Maximum Sample Rate	20 Hz Note: Sampling by pressure or sound velocity increment is also available.	20 Hz Note: Sampling by pressure or sound velocity increment is also available.
Power	<p>AML-3: 4 cell rechargeable internal battery 45Wh capacity (expected battery life ~12 hours)</p> <p>AML-6: 8 cell rechargeable internal battery 95Wh capacity (expected battery life ~24 hours)</p> <p>PC* or wall charging over USB (10W minimum)</p> <p><i>*USB ports on some PCs and laptops may not provide enough power to charge the AML-3 or AML-6. Therefore, it is recommended to use the included USB Wall Charger for charging the instrument.</i></p>	<p>AML-3: 4 cell rechargeable internal battery 45Wh capacity for the AML-3 (expected battery life ~12 hours)</p> <p>AML-6: 8 cell rechargeable internal battery 95Wh capacity (expected battery life ~24 hours)</p> <p>PC* or wall charging over USB (10W minimum)</p> <p><i>*USB ports on some PCs and laptops may not provide enough power to charge the AML-3 or AML-6. Therefore, it is recommended to use the included USB Wall Charger for charging the instrument.</i></p>

Temperature	-20 to +45°C (Operation) -20 to +60°C (Storage)	-20 to +45°C (Operation) -20 to +60°C (Storage)
Dimensions	<p>AML-3:</p> <p>Diameter: 7.6 cm / 3.0 in</p> <p>Length:</p> <p>Short Cage: 33.4 cm / 13.15 in (SVP set up)</p> <p>Medium Cage: 39.8 cm / 15.66 in (CTD set up)</p> <p>Long Cage: 46.4 cm / 18.26 in (UV Protected)</p> <p>Weight*:</p> <p>1.36 kg / 3.00 lb (air) .69 kg / 1.52 lb (water)</p> <p>AML-6:</p> <p>Diameter: 10.0 cm / 3.90 in Length: 60.0 cm / 23.6 in</p> <p>Weight**:</p> <p>4.00 kg / 8.80 lb (air) 2.00 kg / 4.40 lb (water)</p>	<p>AML-3:</p> <p>Diameter: 7.6 cm / 3.0 in</p> <p>Length:</p> <p>Short Cage: 33.4 cm / 13.15 in (SVP set up)</p> <p>Medium Cage: 39.8 cm / 15.66 in (CTD set up)</p> <p>Long Cage: 46.4 cm / 18.26 in (UV Protected)</p> <p>Weight*:</p> <p>2.5 kg / 5.6 lb (air) 1.9 kg / 4.1 lb (water)</p> <p>AML-6:</p> <p>Diameter: 10.0 cm / 3.90 in Length: 60.0 cm / 23.6 in</p> <p>Weight**:</p> <p>5.80 kg / 12.80 lb (air) 3.80 kg / 8.40 lb (water)</p>

* With a medium cage and no sensors, deployed weights will vary

** With no installed sensors, deployment weight will vary.

1.2 Communicating with the Instrument

The preferred method of communication (setup, downloading data, etc.) is through the use of WiFi (500m only, use USB-C for a 6000m rated instrument). By default, the instrument automatically sets up a WiFi hotspot upon power up, allowing WiFi-enabled computers, laptops, and tablets to directly connect.

The 500m versions of AML LGRs come with an accessory USB-WiFi dongle. Use of the dongle is not required (any WiFi adapter will connect to the instrument) but it does provide a convenient method for allowing a compatible PC to host two WiFi connections - the on-board WiFi adapter remains connected with the local network, and the USB adapter connects directly to the instrument. AML's software, Sailfish, allows the user to selectively use available WiFi adapters to connect to the instrument.

In general, users should always use Sailfish to connect to the instrument. However, advanced users (OEM integrators, etc.) may desire connecting to the instrument without Sailfish, in which case a WiFi password will be required. The password is the serial number,



repeated. For example, AML_A30001 has a password of A30001A30001. **Note: You should never be required to enter the password when connecting with Sailfish.**

AML-3 and AML-6 LGR instruments come equipped with a USB-C connector with a waterproof cover. This connector provides power to the instrument when connected to a compatible USB port or wall charger. This connector is also used as a secondary means for data transfer (downloading internally logged data) and may be configured via AML's interface software, Sailfish. **Note: This connector is only waterproof when the protective cover is installed. It is not intended for use when deployed. Do not remove the waterproof cover when the instrument is wet. Applying connector grease to the port can increase resistance to damage from a splash of water when the cover is off.**

Both AML LGR instruments come with a USB-C to USB-A cable for charging and USB communications. If the provided cable is lost, it is feasible to purchase an off the shelf replacement, provided the cable is rated to handle 10W. Generally speaking the shorter the cable the better.

See [Appendix F - USB FAQ](#) for USB-related questions.

1.3 Charging the Instrument

The AML LGR instruments use an internal battery for operation. The battery typically requires a charging top-up when the instrument is first received by the user.

The instrument is charged via its USB-C connector, either through connection with a compatible USB port or via the provided wall charger (recommended). Note that it is common for USB ports to have insufficient power to simultaneously charge and operate the instrument, so it is recommended that the wall charger be used to charge the instrument. **The instrument body may get warm during charging.** This is normal and a result of the instrument's fast-charge capability.

Applying power through the USB-C connector does not turn the instrument on, and the instrument may be charged with the switch in either the 'on' or 'off' position. Charging is fastest with the switch set to 'off' - Charging can typically take up to 8 hrs.

It is recommended to charge the instrument shortly after the LED turns red, indicating a low battery.

When deploying an AML-3 or AML-6 LGR Instrument where the indicator cannot be viewed directly, it is recommended the internal battery thresholds be modified to protect the battery from completely discharging. The command for this can be found in Section 5 under the power commands. AML recommends increasing the battery shutdown voltage to 6.9V in this deployment case.

1.4 Auxiliary Sensors

It is possible for AML instruments to be equipped with additional sensors which are not installed on the instrument sensor endcap. These are referred to as auxiliary sensors and may be either fastened to the side of the instrument body or installed on adjacent moored equipment.

AML-3 LGR instruments can accommodate one auxiliary sensor and AML-6 LGR instruments can accommodate two auxiliary sensors for a maximum sensor load of 4 and 8 sensors, respectively.

In all cases, auxiliary sensors are connected to the instrument via a waterproof connector on the Connector Endcap, providing power and communication (note that Figure 1 and 2 do not show any auxiliary sensors). It is typical for auxiliary sensors mounted on the side of the instrument to be protected by a stainless steel or copper alloy guard.

1.5 GPS Functionality (500m Variants Only)

AML LGR instruments that are 500m rated come equipped with on-board GPS + GLONASS functionality. The instrument will automatically power its GPS module and begin signal acquisition immediately upon bootup. In general, lock times are expected to occur in 3 minutes or less after bootup, though they may take longer in challenging conditions. For best GPS performance, ensure the instrument is located outdoors and with a direct line of sight to the horizon and sky above. It is also recommended that the instrument be powered on in advance of taking a profile to allow sufficient time for signal acquisition.






Note that a GPS lock is not required for instrument functionality; data will be logged regardless of acquisition status.

It is possible to configure Sailfish to assign location coordinates to the instrument as provided by an external GPS broadcast on board a vessel. See the [Connecting a GPS Listener](#) section for more details.

Sailfish enables a feature called Offline Assist to improve GPS lock times. Details can be found in the [GPS Offline Assist](#) section.

1.6 Indicator LED Flash Patterns

The instrument is equipped with a multi-colour indicator LED, located on the Power Switch adjacent to the shackle. The table below describes the pattern and colour indications.

	Steady 	Double flash ³  	Pulsing 	Flashing 
Green	Ready ² Battery good	GPS acquiring ^{1,2} Battery good	-	Logging
Red	Ready ² Battery low	GPS acquiring ^{1,2} Battery low	-	Logging Battery low
Orange/ White/ Blue	-	-	Boot up or boot down sequence.	-
White	Battery full ⁴	-	-	Error state
Orange	-	-	Charging	-

1 - LGR instruments may be deployed without GPS lock. Data will be recorded but location information will not be updated from the previous position.

2 - The instrument may be deployed in any of these states. Data will be logged.

3 - 6000m variants of AML-6 and AML-3 LGR instruments do not have on-board GPS.

Double-flash will not occur.

4 - The instrument will show a solid white LED to signify the battery is full only when the instrument's power switch is in the off position and the charging cable is installed between the instrument and a power source.

1.7 Pressure Ratings

Pressure ratings may differ between installed sensors and the instrument body, and deployments should never exceed the shallower of these ratings. For example, a 500m instrument equipped with a 6000dBar pressure sensor is limited to deployments of 500m depth or less. Similarly, a 6000m instrument equipped with a 500dBar pressure sensor is also limited to deployments of 500m depth or less.

The instrument pressure rating is identified on the top of the instrument, adjacent to the shackle. Typical ratings for AML-3 and AML-6 LGR instruments are 500m and 6000m (note that the AML-3 LGR 500m instrument and both AML-6 LGR ratings use plastic housings, while the AML-3 LGR 6000m instrument uses a titanium housing).

2 Getting Started

This section provides an overview of basic instrument operation and functionality under a factory-default setup. Specifically, this section describes how to connect to the instrument, change settings via interface software, stream sensor measurements, and record and download data.

AML instruments are shipped from the factory with sensors installed and configured. Users are generally not required to remove or install sensors in the course of normal operation. However, there are instances where a user may install or uninstall a sensor such as modifying a sensor payload, returning individual sensors to the factory for calibration, or sending a sensor in for service. AML series instruments and sensors are designed to be user-swappable for maximum flexibility.

2.1 Sensor Cage

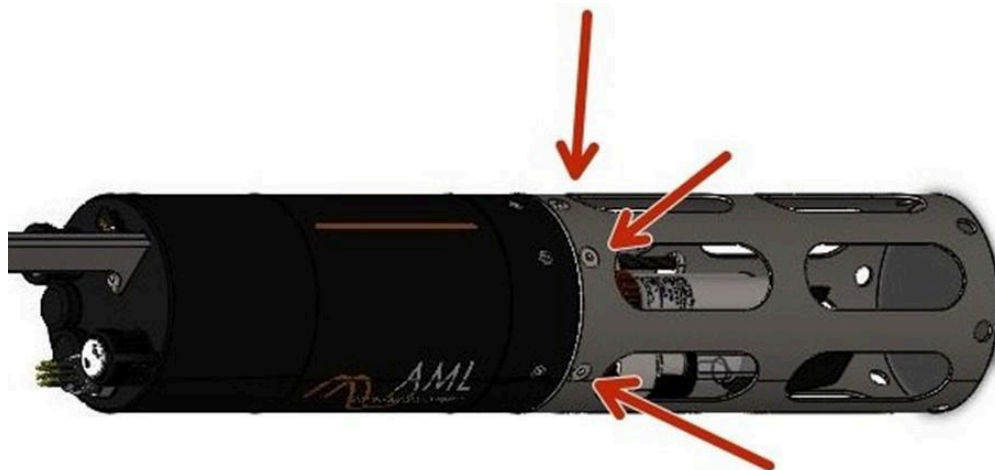
The sensor cage on both AML-3 and AML-6 instruments can be removed to provide better access to the sensors if they need to be swapped.

All AML-3 instruments come with a sensor cage (small, medium or long) that is threaded onto the pressure housing. There are no screws installed which hold the sensor cage in place, therefore it can simply be removed by rotating it off the pressure housing. The image below is a depiction of how to remove the sensor cage from an AML-3.



- ① If you are having trouble removing the AML-3 sensor cage, please place the shackle in a vice grip.
- ② Twist the sensor cage counterclockwise. Be sure to keep your fingers on the outside of the sensor cage so they do not get pinched

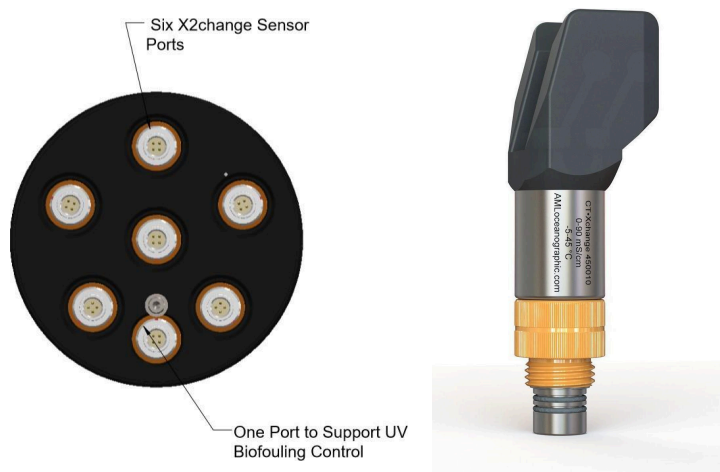
All AML-6 instruments come with either a stainless steel or copper sensor cage which is held in place by 6 screws. To remove the cage, use a 1/8" hex tool to remove the 6 screws holding the cage in place (not the 6 installed on the pressure housing) and slide it off the pressure housing.



Note: It is very important that the screws installed on the pressure housing are not removed. Performing this operation without AML authorization will void the warranty and may damage the instrument.

2.2 X2Change™ Sensors

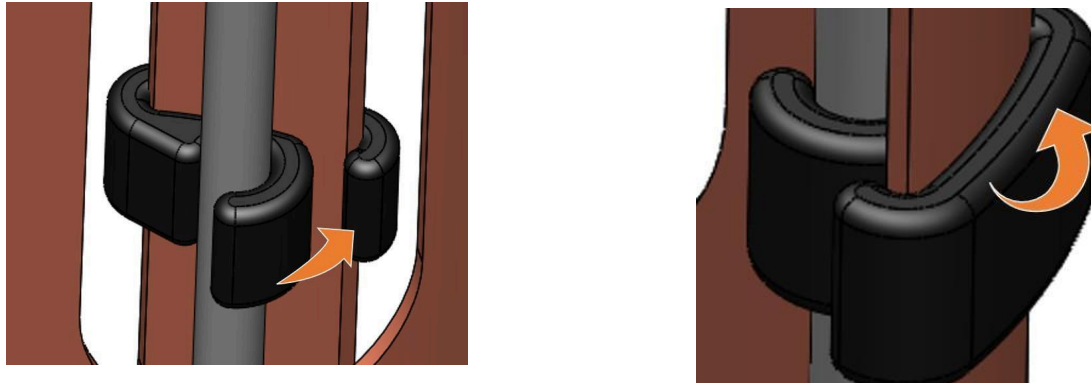
X2Change™ sensors are installed on the AML-3 or AML-6 sensor end cap. There are 3 sensor ports available on the AML-3 and 6 sensor ports available on the AML-6 (and 1 port for an optional UV Antifouling system). Sensors are installed or removed by hand with no special tools required. Most combinations of X2Change™ sensors are permitted ([See notes on installing sensors](#)). The image below is the depiction of an AML-6 sensor end cap with the optional UV Antifouling port.



2.2.1 Removing Sensors

It is important to note that before removing/installing any sensors on any AML instrument, that the instrument and/or external power is turned off

1. If a UV antifouling system is installed, the retaining clip must be removed prior to removing the sensor cage.



2. Configuring the sensors on the end cap is easiest when the sensor cage is removed ([See notes on each instrument's sensor cage](#)).
3. Rotate the orange locking sleeve of the sensor you wish to remove counter-clockwise until you can gently pull the X2Change™ sensor from the sensor port.

2.2.2 Installing Sensors

1. Before installing X2Change™ sensors, ensure that the instrument socket is clean and dry.
2. Check the X2Change™ sensor's o-rings for cleanliness and replace if damaged. Apply o-ring grease to the new o-ring before replacing it.
3. Align the sensor with the sensor port so that the lock and key of the lemo connectors are aligned.
4. Place the sensor into the port.
5. Push the sensor until it drops down into the port enough to allow the orange locking sleeve threads to engage the port threads.
6. Screw down the orange locking sleeve until it stops. The bottom of the sleeve should be within 1 mm of the instrument end cap.

Notes:



- X2Change™ sensors are identified by their orange locking sleeve matching AML-3 and AML-6's orange sensor ports.
- Older AML Xchange™ sensors with blue locking sleeves are not compatible with the AML-3 and AML-6 line of instruments.
- CT X2Change™ should be installed in port 1 on both the AML-3 and AML-6 due to the mechanical fit between the sensor and the cage. All other X2Change™ sensors can be installed in any of the remaining sensor ports.
- A sensor riser (1.5" and 2.5" options available) may be required when installing a CT X2Change™ if other tall X2Change™ sensors are installed nearby.

2.3 Seals and Plugs

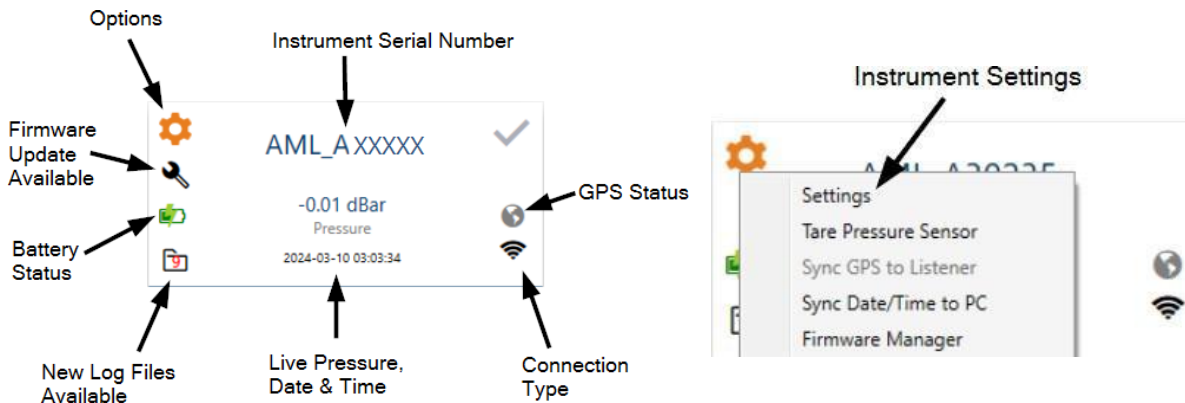
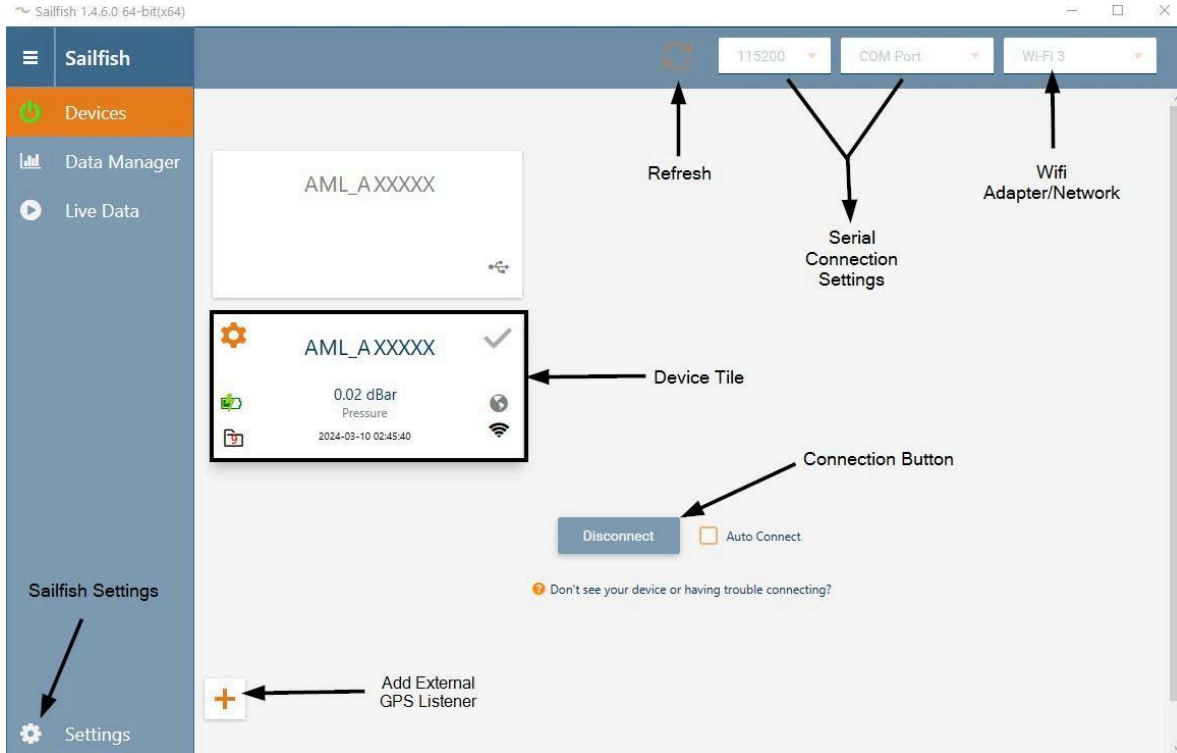
Before deployment, ensure that every empty X2Change™ sensor port is sealed with the X2Change™ Blanking Plug, the USB-C port is capped, and each MCBH is plugged with its dummy plug or cable. Contact AML Support to replace lost plugs or caps.

2.4 Sailfish Overview

The preferred (but not the only) method of communicating with the instrument is via AML's software interface, Sailfish; a user-friendly GUI-based platform which allows users to configure an instrument, observe live sensor measurements (live data streaming), and download logged data. Sailfish may be downloaded free of charge from the AML Oceanographic website (<https://amloceanographic.com/sailfish-software>).

Sailfish provides the easiest means of adjusting the instrument's configuration and other settings. Advanced commands exist, and can be applied via a terminal within Sailfish if necessary. Refer to section *Configuring an Instrument* later in this document for more details.

The 3 figures below label the user interface features which might be used when initially connecting your instrument to the software and the terminology used within this manual.



The steps below provide the general procedure for connecting your instrument to Sailfish.

1. Download the Sailfish installation package from the AML website and follow the on-screen installation instructions. Sailfish is compatible with Windows 7, 8, 10 and 11.
 - a. The installation package will be contained within a .zip folder, extract the contents and run the application within, named **setup**.
 - b. Be sure to enable both private and public network access if prompted during installation.

2. Turn the instrument on using the power switch. When the switch is set to the 'on' position the instrument will commence its bootup sequence, indicated by an alternating colour pattern on the status indicator LED. Typical boot duration is about 10 seconds.
 - a. After the boot sequence is complete the LED could be one of several different colours/patterns depending on the instrument status. Please refer to the [LED Indicator Flash Patterns](#) section for full details. Most commonly though, the LED will be green.
3. Start Sailfish and wait for the software to load. Your PC may ask for permission to run the software.
4. If you open Sailfish before connecting your instrument, you will need to click on the 'Refresh' button for your instrument to appear.
5. Connect the instrument to the PC via WiFi (preferred) or the included USB-C cable. If using the USB-C connector, the user's PC may produce the default USB-device connection chime when recognition and setup is successful.
 - a. Note that if using the USB-C connection, the instrument may commence charging its internal battery. The instrument is equipped with fast-charge capabilities so it may become warm during this time.
 - b. If the battery is very low, the instrument may require more power than a PC USB port can provide. If this is the case, the usb port may disable until the PC is restarted. Charge your instrument using the supplied wall charger for several hours before connecting the USB to your PC once more.
 - c. 6000m AML-3 LGR instruments do not have WiFi; connection must be done via USB-C.
6. A tile corresponding to available instrument connections will appear in the *Devices* tab of Sailfish. A small icon in the corner of the tiles denotes the corresponding connection method. Either WiFi, USB-C, or Serial may be selected.
 - a. Note: If connection difficulties are encountered, restart the PC. This solves the majority of connection issues.
7. Select the appropriate tile and click 'Connect'.
8. Click the gear icon on the instrument tile to open the *Instrument Settings* page.
 - a. Note: A common action at this step is to zero the pressure sensor if required. This is achieved by clicking the Gear Icon and selecting Tare Pressure Sensor.
9. The user is encouraged to explore the *Instrument Settings* page to familiarize themselves with typical settings.

10. Optional: a common step for first time users is to commence real-time measurement (data) streaming from the instrument. This is achieved through the *Live Data* tab in Sailfish.

To disconnect the instrument, click the 'Disconnect' button in the *Devices* tab.

2.5 Conducting a Profile

The typical workflow for conducting a profile is as follows:

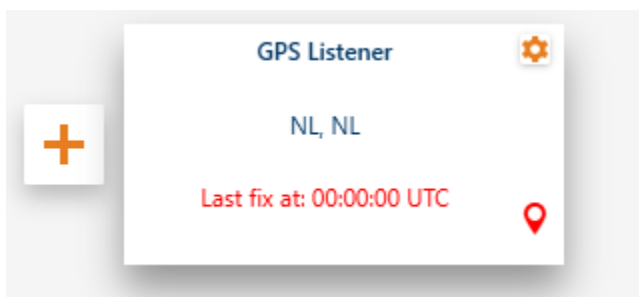
1. Turn the instrument on and connect it to Sailfish using either WiFi (preferred) or USB-C (refer [Getting Started](#)) and confirm the instrument's battery status and configuration. Be sure to zero the pressure sensor if required.
2. The instrument's indicator LED will flash if it is attempting to acquire a GPS signal. If GPS is locked, the instrument's LED will turn solid. Refer to the LED Flash Patterns in Section 1.5 for more details.
 - a. Note that an instrument may be deployed without a GPS lock. Data will still be logged, but the location data will be absent.
 - b. In the absence of a GPS lock, an instrument may be manually provided with GPS coordinates in the *Instrument Settings* page.
3. If settings are correct, then ensure the instrument is ready for immersion by confirming that the USB-C connector cover is in place. **Do not deploy the instrument without the USB-C cover threaded completely onto the bulkhead.**
4. The instrument may be deployed at any time. If connected via WiFi, there is no need to select the *Disconnect* button in Sailfish.
5. Lower the instrument into the water until its shackle sits just below the water line and its indicator LED is visible. In most applications, the instrument is suspended by its shackle from a downrigger, crab puller, rope, or other mechanical device.
6. By default, the instrument will create a new log file and begin to record (log) data automatically upon water detection.
 - a. Water detection is achieved by monitoring the measurements of an installed Sound Velocity or Conductivity sensor. This behaviour is configurable through advanced commands.
7. When in water and recording data, the instrument's indicator LED will flash steadily, confirming operation.
8. Hold the instrument submerged just below the surface of the water for 60 - 90 seconds to allow the instrument to thermalize. The instrument may then be lowered to the desired depth.

9. If the instrument was connected via WiFi then its connection to Sailfish will be lost (by default, the instrument will turn its WiFi off when in water). Sailfish will recognize this action and sit idle, awaiting for the instrument to return to the surface.
10. When the desired depth is achieved, retrieve the instrument and pull it completely out of the water. The instrument will close its log file when it detects that it is out of water.
11. When out of water the instrument will turn its WiFi back on. Sailfish can automatically detect the return of the instrument and connect.
 - a. Note: If the instrument's WiFi connection was manually disconnected from Sailfish prior to deployment (by pressing *Disconnect*), then the instrument will need to be manually re-connected to Sailfish by the user.
 - b. If re-connecting via USB-C, dry the instrument prior to removing the USB-C waterproof cover.**
12. Upon (re)-connection, Sailfish will recognize new log files available for download. Automatic downloads can be enabled in Sailfish, but this is not the default setting.
 - a. Note: It may take up to a minute of being connected, for the new files to appear.
13. New log files may be viewed, plotted, and exported in various formats using the *Data Manager* tab in Sailfish.

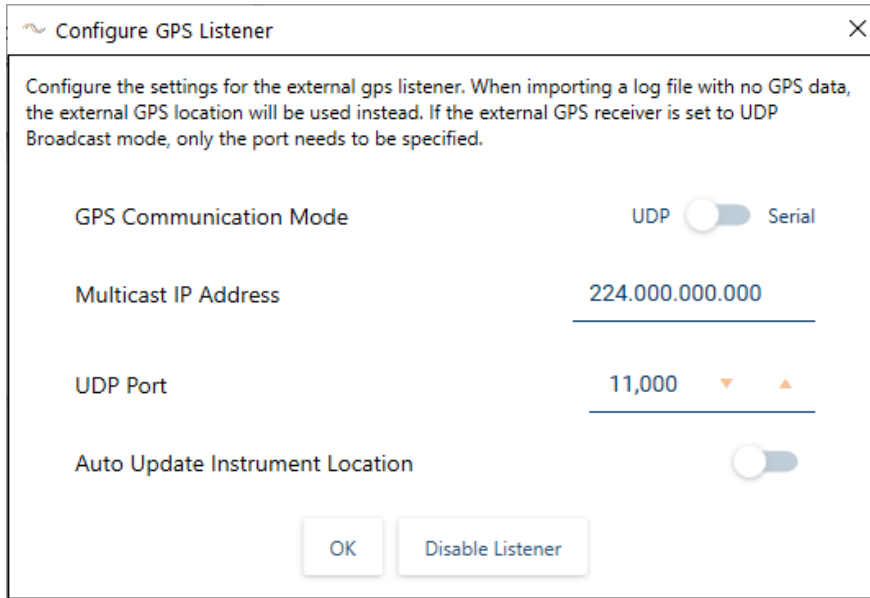
2.6 Connecting a GPS Listener

Sailfish has the ability to connect to an external GPS listener so that GPS location data may be sent to an instrument. To set up an external listener, follow these steps:

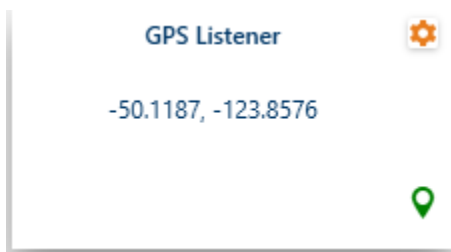
1. Navigate to the *Devices* page and click on the 'Add Listener' button. Select 'GPS Listener'.



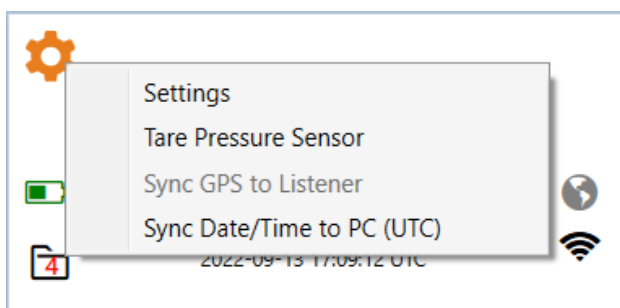
2. To configure the GPS listener settings, click the 'Gear Icon' on the listener tile.
3. Configure the settings according to your external GPS listener device. Both serial and UDP connections are supported. Sailfish will remember your GPS listener settings and automatically connect next time you add the listener.



4. If the listener has been configured correctly, position data will be displayed in the tile and the location icon will turn green.



5. It is now possible to sync the external listener location to the instrument by clicking the 'Instrument Settings' icon on the *Device Tile* and selecting 'Sync GPS to Listener'

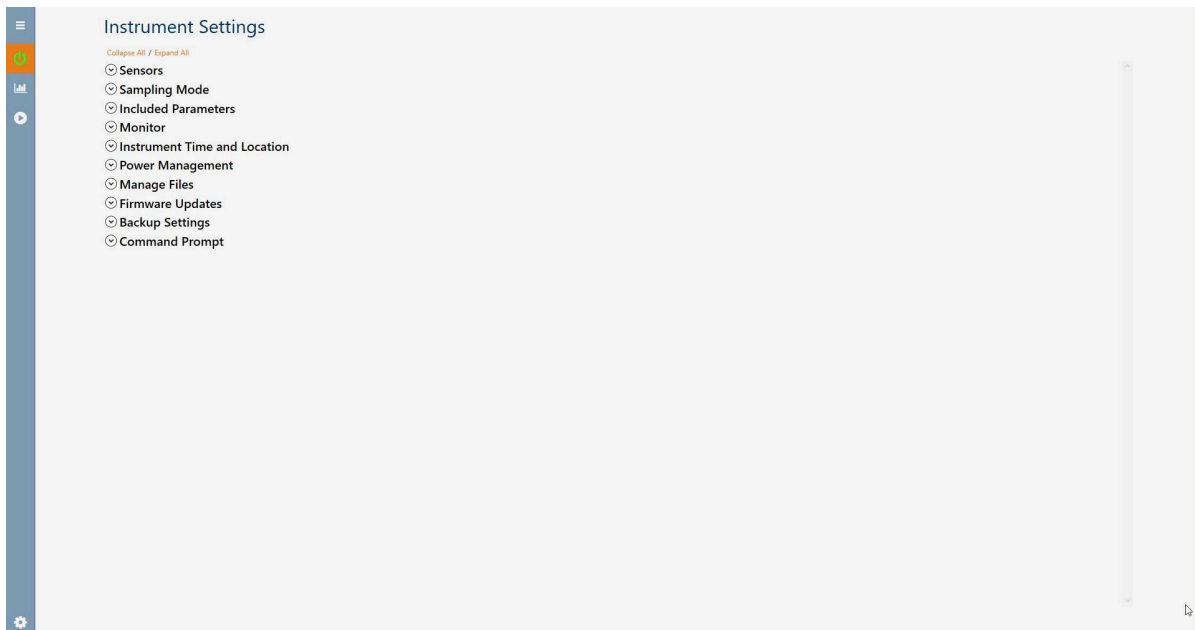


6. If your instrument's location mode was previously set to 'GPS', you will be prompted to set it to 'Manual'. Doing this will tell the instrument to ignore its on-board GPS module. This synced position information will be stored and used in newly created log files until the instrument's location is either synced again or the Location Mode is set back to 'GPS'. This can be done on the *Instrument Settings* page.

7. If connection to the GPS listener is lost, you can still sync to the last known location until you disable the GPS listener or close Sailfish.
8. To automatically sync your instrument to the GPS listener every time you reconnect to Sailfish, enable the 'Auto Update Instrument Location" setting.

3 Instrument Settings

To configure your instrument with Sailfish, reference the [Getting Started with Sailfish](#) section. Settings most commonly configured via Sailfish are detailed below.



3.1 Sensors

The *Sensors* section of the instrument settings will show relevant information pertaining to the sensors currently installed on your instrument. On the right side of this section there is the option to download the latest calibration certificates for each sensor as well as zero any installed pressure sensors.

Instrument Settings

[Collapse All](#) / [Expand All](#)

⊖ **Sensors**

These settings are sensor specific. Only settings for installed sensors are shown.

Port 2

Model: P.X2 Firmware Version: 1.05.0 [Calibration Certificate](#)

Parameter: Pressure Serial Number: 307483 [Tare Sensor](#)

Calibration Date: 11/15/2022

Port 3

Model: SV.X2 Firmware Version: 2.02.0 [Calibration Certificate](#)

Parameter: SV Serial Number: 211359

Calibration Date: 1/13/2023

- ⊖ Sampling Mode
- ⊖ Included Parameters
- ⊖ Monitor
- ⊖ Instrument Time and Location
- ⊖ Power Management
- ⊖ Manage Files
- ⊖ Firmware Updates
- ⊖ Backup Settings
- ⊖ Command Prompt

3.2 Sampling Mode

Instrument Settings

[Collapse All](#) / [Expand All](#)

⊖ **Sensors**

⊖ **Sampling Mode**

These settings control how frequently measurements are logged by the instrument. If Burst Mode is enabled, settings must be configured such that the burst duration is less than or equal to the burst interval.

Sample Trigger: Time ▾

Sample Unit: /second ▾

Sample Rate: 2 ▾ ▲

Burst Mode Enabled: Instrument will log 2 times /second

- ⊖ Included Parameters
- ⊖ Monitor
- ⊖ Instrument Time and Location
- ⊖ Power Management
- ⊖ Manage Files
- ⊖ Firmware Updates
- ⊖ Backup Settings
- ⊖ Command Prompt

Sample Trigger: Sets the variable that determines when a sample is taken. Options are time, pressure increment, sound velocity increment, and continuous (20Hz) sample rate.

- **Pressure Increment:** Available when pressure increment is set as the sample trigger. Sets the pressure increment (in dBar) when a sample should be taken.
- **Sound Increment:** Available when sound velocity is selected as the sample trigger. Sets the sound velocity increment (in m/s) when a sample should be taken.
- **Continuous(20Hz):** While the conditions for water detection are met, the instrument will log data at a continuous 20Hz.

Sample Unit: Referring to units of time, option is available when time is selected as the sample trigger. Options are: /second, /minute, /hour, seconds, minutes, hours.

Sample Rate: This is the quantitative rate with reference to the selected *Sample Unit*, option is available when time is selected as the sample trigger.

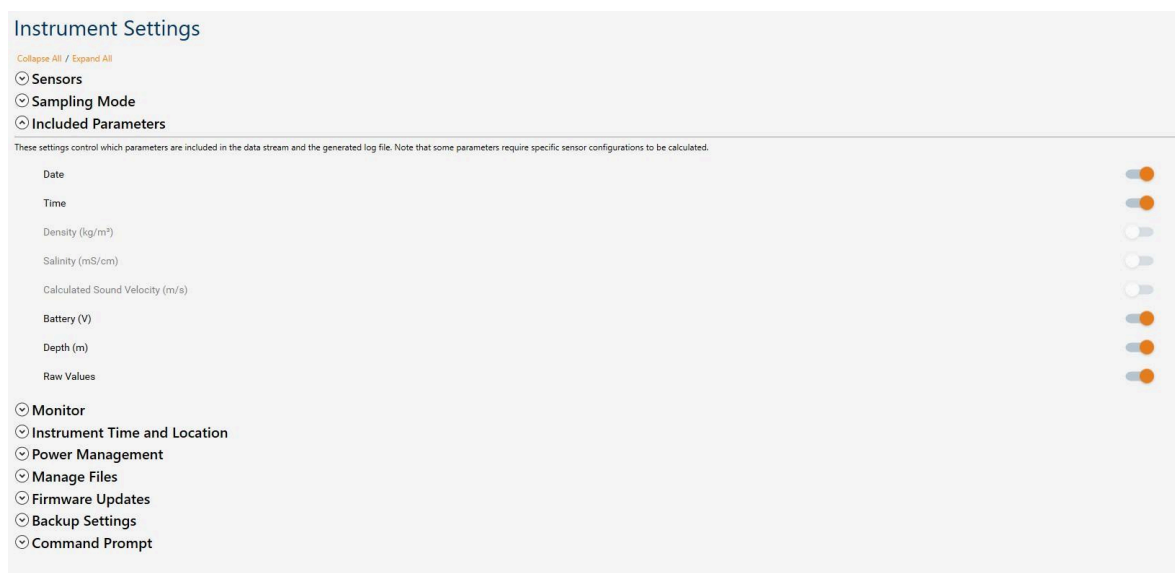
- For example: Selecting a sample rate of 10 with the sample unit set to seconds would result in one sample taken every 10 seconds. Changing the sample unit to /second would result in 10 samples taken, per second.

Burst Mode: This configures the instrument to take a cluster of samples at a set interval. Burst mode will override the sample trigger setting and is most commonly used in combination with *sleep mode*(please see section 5.1 for more information). The following options appear when burst mode is enabled.

- Burst Samples: Number of samples taken in a single burst.
- Burst Interval: Time between bursts, in seconds.
- Burst Monitor Output: The user has the option to log every sample taken in a burst, or only log the average of the samples taken in a burst. Options are: Samples, Average.

3.3 Included Log Parameters

These settings control which parameters are included in the data stream and the generated log file. Note that some parameters require specific sensors to be installed, to be calculated. Options include date, time, density, salinity, calculated sound velocity, battery, depth, and raw values. Please refer to [7 Appendix C](#) for full details on calculated parameter requirements.



Instrument Settings

Collapse All / Expand All

- ⊖ Sensors
- ⊖ Sampling Mode
- ⊖ **Included Parameters**

These settings control which parameters are included in the data stream and the generated log file. Note that some parameters require specific sensor configurations to be calculated.

Date	<input checked="" type="checkbox"/>
Time	<input checked="" type="checkbox"/>
Density (kg/m ³)	<input type="checkbox"/>
Salinity (mS/cm)	<input type="checkbox"/>
Calculated Sound Velocity (m/s)	<input type="checkbox"/>
Battery (V)	<input checked="" type="checkbox"/>
Depth (m)	<input checked="" type="checkbox"/>
Raw Values	<input checked="" type="checkbox"/>

- ⊖ Monitor
- ⊖ Instrument Time and Location
- ⊖ Power Management
- ⊖ Manage Files
- ⊖ Firmware Updates
- ⊖ Backup Settings
- ⊖ Command Prompt

3.4 Instrument Time and Location



Date and time source: Select which clock to synchronize the instrument to. Options are the connected computer's clock, or GPS.

Location Mode: Select the GPS source to synchronize the instrument to. Options are Instrument (internal GPS), manual (external GPS), and none. Please refer to section [2.3 Connecting a GPS Listener](#) for full details on external GPS source setup.

Offline Assist: This feature enables Sailfish to transfer GPS satellite data files over to the instrument to improve GPS lock times. If enabled, Sailfish will download the latest GPS satellite position data once per day (requires internet connection) and transfer the Offline Assist data to the instrument upon connecting. The instrument will utilize the transferred satellite data during its next boot sequence to reduce GPS lock time.

Sailfish will download satellite data forecasted for the next 20 days, however data forecasted beyond approximately 5 days tends to be less accurate. **For optimal performance, it is recommended that Sailfish be provided an internet connection daily to ensure up to date GPS information.**

This setting is enabled by default but can be turned on/off in the Sailfish Settings page



3.5 Power Management

These settings control directly related power management features of the instrument.



In-Water WiFi Sleep: Specify if the WiFi chip should be disabled while underwater or not. Default is on.

In-Water WiFi Sleep Timeout(secs): The amount of time, in seconds, before the WiFi chip will be disabled once the instrument detects that it is underwater. Default is set to 60 seconds.

Power Timeout: Specify if the instrument should turn itself off if left idle. Default is on.

Power Timeout (minutes): The amount of minutes left idle before the instrument turns itself off. Default is set to 20 minutes.

Sleep Mode: This enables the instrument to temporarily go to sleep between samples. Minimum value is 20 seconds to account for the time it takes for the instrument to power up and power off. Note that this is not necessarily the most power efficient value. Most commonly used in long term deployments where battery conservation is crucial. It is recommended to consult technical support before utilizing this setting as it can significantly alter instrument operation. The following option appears when sleep mode is enabled.

- **Sleep Mode Timeout:** The time, in seconds, after the last sample is taken(when burst mode is enabled) or after a single sample is taken(when burst mode is disabled), that the instrument waits before going back to sleep.

3.6 Manage Files

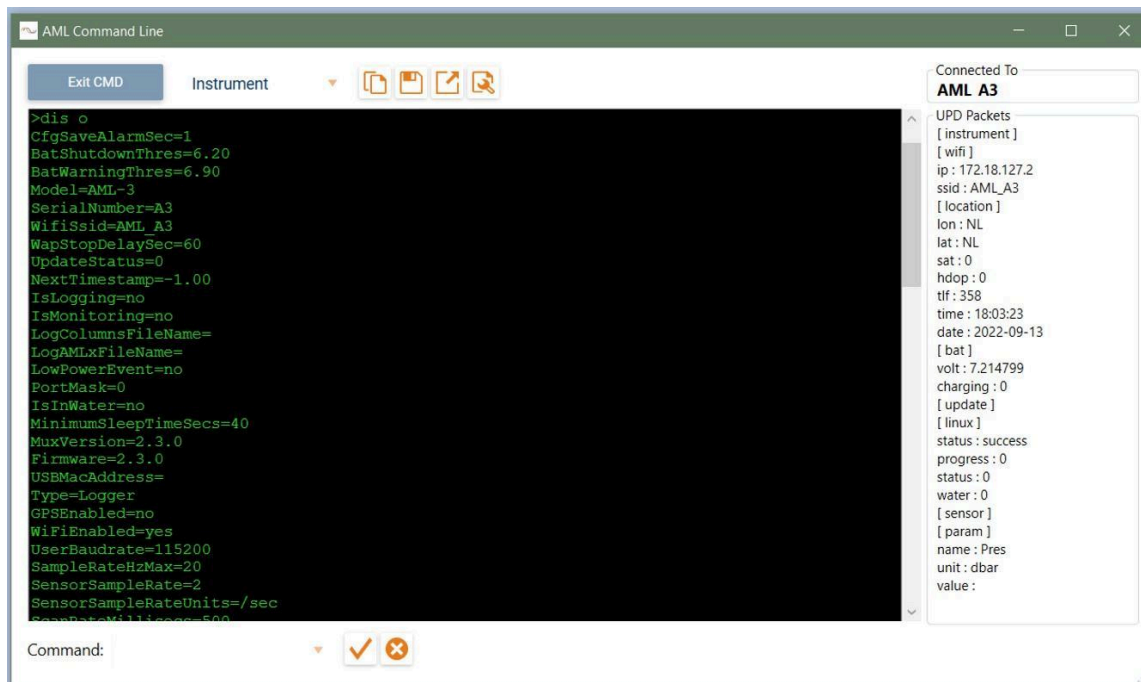
View storage capacity and download or delete files stored on the device.

3.7 Firmware Updates

View current OS and controller firmware versions, check for and install updates.

3.8 Command Prompt

A command window for sending other commands to the instrument or viewing current advanced configurations. See [Appendix A](#) for details on commands.





4 Contact AML

Service

To request an RMA or technical support

Email:

service@AMLoceanographic.com

Phone: 1-250-656-0771

Phone: 1-800-663-8721 (NA)

<http://www.AMLoceanographic.com>

Sales

For all general sales inquiries

Email: sales@AMLoceanographic.com

Phone: 1-250-656-0771

Phone : 1-800-663-8721 (NA)

<http://www.AMLoceanographic.com>

5 Appendix A - Full command list

All of the commonly utilized settings are accessible via GUI using Sailfish. However, Sailfish does not provide GUI access to the entire command set; advanced functionality beyond common settings exists. This advanced functionality is described here.

These commands are applied to the instrument via command line. This is achieved by using the *Advanced Commands* section of the bottom of the *Instrument Settings* page in Sailfish, or using the shortcut key, *ctrl+alt+x* while connected to an instrument and in the *Devices* page.

5.1 Sampling commands

Command	Description
<i>set sample <rate> [/second /minute /hour seconds minutes hours max]</i>	Set the rate at which the instrument logs and monitors data from the sensors. Maximum sample rate is 20 Hz.
<i>set scan mode [burst single]</i>	Switch between single and burst mode. When the instrument is in burst mode it will sample in bursts at a set interval. Note that the burst duration must be less than or equal to the burst interval.
<i>set burst interval <interval></i>	Set the burst interval in seconds. Minimum: 5 Maximum: 14400
<i>set burst samples <samples></i>	Set the number of samples taken per burst. Samples will be taken at the set sample rate. Minimum: 2 Maximum: 1200
<i>set burst monitor [samples average]</i>	Set whether the monitor output will display all the burst samples or an average of the samples. Note: averaging applies only to monitor data. Log files will record individual samples.
<i>display burst</i>	Display the current burst mode settings.
<i>set trigger [time sound pressure]</i>	Set the sampling trigger to sample by time, sound velocity increment or pressure increment. Sampling by sound or pressure increment is not supported in burst mode.
<i>set sound inc <value></i>	Set sound velocity increment.

<i>set pressure inc <value></i>	Set pressure increment.
<i>set [conduct sound pressure] threshold <value></i>	<p>Set the threshold for water detection to begin automatic logging. Valid detection parameters are “conduct”, “sound”, and “pressure”. By default pressure is set to 99999.99 and it is not recommended to detect water by pressure unless there are no sound velocity or conductivity sensors installed.</p> <p>Note: This is a secure command.</p>

5.2 Monitor Configurations and commands

Command	Description
<i>monitor</i>	Start streaming data on the user terminal. Hit <i><enter></i> to exit monitor, hit <i><enter></i> three times to exit monitor when in robust mode.
<i>mmonitor</i>	Start streaming data in AMLx format.
<i>scan</i>	Print a single line of the latest sensor data.
<i>mscan</i>	Print a single line of the latest sensor data in AMLx format.
<i>set monitor robust [y n]</i>	<p>Enable/disable robust monitor mode. When enabled, monitoring is halted via 3 carriage returns.</p> <p>When disabled, a single carriage return will halt monitoring.</p>
<i>set monitor auto <seconds></i>	<p>Monitoring will begin automatically after an interval of inactivity. Setting to “0” disables auto monitor.</p> <p>Min value: 5</p> <p>This command applies only to monitoring via serial connection</p>
<i>set monitor startup [y n]</i>	<p>Enable/disable monitoring on startup. When enabled the instrument will start monitoring when powered on.</p> <p>This command applies only to monitoring via serial connection</p>

<p><i>set monitor log [y n]</i></p>	<p>Enable/disable monitor log mode. When enabled, the instrument will log data when monitoring. Stopping monitor will halt logging.</p> <p>Note: If LOG MODE is set to AUTO the instrument will commence logging when in water regardless of monitor status.</p>
<p><i>set monitor delimiter [comma tab space colon]</i></p>	<p>Set the delimiter of the monitor output.</p>
<p><i>set monitor checksum [y n]</i></p>	<p>Enable/disable a 8 bit XOR checksum in the monitor output. The checksum is appended to each scan preceded by a “*”.</p> <p>Ex. >mon 1450.132,14.543*2B 1451.122,15.133*29</p>
<p><i>set monitor format [columns amlx]</i></p>	<p>Set the monitor output format. See Appendix B for a description of the columns and AMLx formats.</p> <p>Note that checksum does not appear in log files.</p>
<p><i>set monitor sync [seconds]</i></p>	<p>Synchronizes the start of monitoring to the nearest sync interval in seconds. When set to 0 the feature is disabled.</p> <p>If enabled and the conditions for monitoring are met (auto/start/command), the first sample will start when the sync interval, referenced to the time, is aligned.</p> <p><i>Ex. Set Monitor Sync 600</i></p> <p><i>When the instrument is monitoring, it will remain idle until the next 10 min mark. At this point the monitoring and data flow will begin.</i></p>
<p><i>display monitor</i></p>	<p>Print the current monitor settings.</p>

5.3 Log File Format/Monitor Output

Command	Description
<p><i>set scan <parameter></i></p>	<p>Add a parameter to be included in the log file and monitor output.</p> <p>Optional Parameters: date time bat (Battery) vbat (Battery Voltage) ibat (Battery Current) vext (External Voltage) iext (External Current) chargestate (Charger Board Status) sn (Serial Number) dep (Calculated Depth) sal (Calculated Salinity) den (Calculated Density) sound (Calculated Sound Velocity) raw (Raw Values)</p> <p>Note: Calculated parameters will output -99.9999 if outside of the valid range of the calculation formula.</p>
<p><i>set scan <parameter></i></p>	<p>Remove a parameter from being included in the log file and monitor output.</p> <p>Optional Parameters: nodate notime nobat (Battery) novbat (Battery Voltage) noibat (Battery Current) novext (External Voltage) noiext (External Current) nochargestate (Charger Board Status) nosn (Serial Number) nodep (Calculated Depth) nosal (Calculated Salinity) noden (Calculated Density) nosound (Calculated Sound Velocity) noraw (Raw Values)</p>
<p><i>set derive <parameter> [y n]</i></p>	<p>Enable/disable a parameter to be calculated if the required sensors are installed.</p>

	<p>Derived Parameters: depth (from pressure) salc (salinity from conductivity) salsv (salinity from sound velocity) density (requires salinity) sv (sound velocity, requires salinity)</p> <p>Note: a parameter will only be output if it is ALSO included in monitor scans. Refer 'SET SCAN' command, above.</p>
--	--

5.4 Pressure Configuration

Command	Description
<code>set pressure autozero [on off now]</code>	Sets the instrument to zero any installed pressure sensor, on startup. <i>On</i> enables this feature, <i>Off</i> disables this feature, and <i>Now</i> zeros any installed pressure sensor at that moment.
<code>set pressure fixed [value on off]</code>	Set a fixed pressure value for derived parameter calculations. Will be used if set to on and no pressure sensor is available. Previous set value is stored even when set to off.

5.5 UV Antifouling

Note that these commands apply only in the instance of a UV system installed on the instrument.

Command	Description
<code>display uv</code>	Print the current UV settings.
<code>set uv time <ontime> <offtime></code>	Set the duty cycle of the UV lantern in seconds. Note: Setting UV time to 0 0 will disable light emission.
<code>set uv [enable disable]</code>	Enables or disables the <i>uv time</i> settings

5.6 Data Logging

Command	Description
<i>display status</i>	Print the current logging status, including in-water status, number of samples recorded, log duration, and sample rate.
<i>set logmode [auto manual]</i>	By default logmode will be set to “auto” and will automatically start logging when the water immersion is detected.
<i>logon</i>	Start logging when log mode is set to manual.
<i>logoff</i>	Stop logging when log mode is set to manual.
<i>set filetype [columns amlx all]</i>	Set the file type that data will be logged to. The columns format has file extension “.aml” while the amlx format has extension “.amlx”. If ALL is selected, two files will be created, one in each format. See Appendix B for more details on these two formats.
<i>directory</i>	List all files present in the log directory.
<i>delete <filename>/all</i> <i>delete <filename>/all yes</i>	Deletes a log file that matches the filename. If ‘all’ is used instead of a file name, all files will be deleted. If the ‘yes’ is not included in the command, a confirmation is required. If ‘yes’ is included, the file(s) will be deleted without confirmation.
<i>dump <filename></i>	Sends the contents of the specified file out the interface port.

5.7 Help

Command	Description
<i>display options</i>	Displays a full list of all configurable settings and their current values.
<i>help</i>	Displays a menu of all commands.

5.8 Communication commands

Command	Description
<i>set baud <baud rate></i>	<p>Set the serial baud rate for the instrument. All standard baud rates between 9600 and 115200 are accepted. Default is 115200.</p> <p>Note: This command takes immediate effect. Users must change the BAUD rate of their terminal program.</p>

5.9 Sensor commands

Command	Description
<i>display sensors</i>	Print information about all connected sensors.
<i>rawtalk <port></i>	<p>Start a rawtalk session with a connected sensor. Send <i><1s pause>+++<1s pause></i> to exit the rawtalk session.</p>

5.10 System commands

Command	Description
<i>set fulltime <yyyy-mm-dd> <hh:mm:ss></i>	Set the system date and time.
<i>set wapstop <delay in seconds></i>	<p>Set the in-water stop timeout for the WiFi access point in seconds. When the instrument is in water, it will disable the WiFi access point to save power. This setting configures the delay between the in-water detection and disabling WiFi.</p> <p>Setting the delay to 0 disables this feature.</p>
<i>display memory</i>	Print the SD card's total and used memory in bytes.
<i>display version</i>	Print the version header, including the model name, firmware version, serial number, and total space of the installed SD card.
<i>display volt</i>	Print the current battery voltage.

<i>secure on</i>	Enables the user to send “secure” commands. Secure mode is not persistent through multiple telnet sessions or a power cycle.
------------------	--

5.11 GPS commands

Command	Description
<i>gps</i>	Print location and other GNSS information in the following format: <date> <time> <latitude> <longitude> <#satellites> <hdop>
<i>fullsync</i>	Synchronize the instrument’s date and time to GNSS date and time.
<i>set location <mode></i>	Set the instrument’s location mode. Options are <i>gps</i> , <i>man</i> , or <i>non</i> . <i>gps</i> uses GPS to determine the location <i>man</i> makes the location user configurable <i>non</i> disables the location If <i>man</i> is enabled, <i>set latitude</i> and <i>set longitude</i> can be used to set the instrument’s location.
<i>set latitude <latitude></i>	Set the instrument’s latitude location. This command always changes the instrument’s manual latitude setting, even if not in manual mode. The instrument only uses this setting to determine its location if in manual location mode.
<i>set longitude <longitude></i>	Set the instrument’s longitude location. This command always changes the instrument’s manual longitude setting, even if not in manual mode. The instrument only uses this setting to determine its location if in manual location mode.
<i>set gnss mgadbd [y n]</i>	Enable/disable GPS database dump to enable GPS warm start. If enabled, the GPS module will store almanac data that will improve lock times after a recent fix has been lost. Enabling this feature generally improves GPS lock times.
<i>set gnss offline [y n]</i>	Enable/disable GPS offline assist. Requires connecting to Sailfish with an active internet connection at least once every 5 days. Offline data will help improve lock times on power up.

5.12 Power commands

Command	Description
<i>poweroff</i>	Turn the instrument off indefinitely, until the power dial switch is toggled or external power cycled.
<i>hibernate <minutes></i>	Turn the instrument off for a set amount of minutes.
<i>set wakeonpower [y/n]</i>	Once enabled, the instrument will stay on until a Power Off command is issued or poweroff timeout has occurred. Note: This is a secure command.
<i>set powerofftimeout <minutes></i>	Set the instrument's idle timeout in minutes. If there is no user interaction and the instrument is idling, i.e. not streaming data or logging, the instrument will power down after the set timeout. Setting the timeout to 0 disables this feature.
<i>set batwarning <voltage></i>	Set the threshold for the low battery warning to be triggered. If triggered the indicator led will turn red to notify users to charge the instrument. Note: This is a secure command.
<i>set batshutdn <voltage></i>	Set the threshold for the low battery shutdown to be triggered. If the instrument's battery voltage drops below this threshold the instrument will shut down. It is not recommended to set this lower than 6.2 V. Note: This is a secure command.
<i>set batvnoboot <voltage></i>	On power up if the battery voltage is less than the batvnoboot value, the instrument will not boot up. Note: This is a secure command.
<i>set batinoboot <voltage></i>	On power up if the battery current in mA is larger than the batinoboot value, the instrument will not boot up. Note: This is a secure command.

6 Appendix B - Output Formats

AML-3 and AML-6 series instruments support two monitoring formats: a column-based format whereby all transmitted data is organized into vertical columns, and a proprietary self-describing format referred to as AMLx.

The commands to adjust monitor formats are described in [5.2 Monitor commands](#).

6.1 Column-Based Format

The factory default of both the AML-3 and AML-6 instruments is column-based formatting, typically using a comma delimiter (the delimiter is configurable). This format is preferred for applications where human readability of the raw data is required as it is easy to quickly parse and interpret the scrolling columns of measurements.

The disadvantage of this format is that the user must have knowledge of the meta-data to correctly interpret the readings. The relevant meta-data is obtained by issue the following command:

```
>DIS SENSORS
```

```
[MeasurementMetadata]
```

```
Columns=Date,Time,Cond,TempCT,Pressure,SV,Depth
```

```
Units=yyyy-mm-dd, hh:mm:ss.ss, mS/cm, C, dbar, m/s, m
```

```
>MONITOR
```

```
>2020-05-27,18:59:26.03,5.122,24.044,10.09,1459.111,10.07
```

```
...
```

It is assumed the sensor meta-data is uniformly applicable to every line. that the number of columns, order of columns, and units of each measurement never change. This assumption makes the format extremely inflexible. **Users are strongly discouraged from creating drivers that rely on this output format.**

6.2 AMLx Format

The AMLx format is a proprietary self-describing string that does not rely on assumed static meta-data for interpretation. Each sentence contains sufficient information to contextualize the measurement data provided.

The general format of AMLx is:

```
msg<MsgNumber>{mux[meta=time,<UnixEpochTime>,s][data=uv,<status>],port<PortNumber>[data=<ParameterName>,<Value>,<ParameterUnits>][rawi=<RawParameterName>,<Raw
```

Value>,<RawUnits>}}

Sample output in this format is shown below.

>MONITOR

```
>msg138{mux[meta=time,1590605500.55,s],port1[data=Cond,0.000000,mS/cm][rawi=ADC,563,none][data=TempCT,23.881313,C][rawi=ADC,428710,none],port2[data=Pressure,0.071390,dbar][rawi=ADC,844470,2sComp],port3[data=SV,0.000000,m/s][rawf=NSV,0.000000,samples],derive[data=Depth,0.070998,m]}
```

In this format every measurement has, at minimum, an explicit unit, parameter, and port association. A driver written to interpret this format is able to understand output from every X2Change generation instrument regardless of specific sensor or derived parameter configuration. **Users are strongly encouraged to use drivers that rely on this output format.**

Parameter name	Description
SV	Sound velocity
TempSVT	Temperature from an SVT.X2 sensor
Cond	Conductivity
TempCT	Temperature from a CT.X2 sensor.
Pressure	Pressure
Turbidity	Turbidity
Dissolved Oxygen	Dissolved Oxygen
DOM	CDOM/FDOM
Chloro-blue	Chlorophyll, blue excitation
Chloro-red	Chlorophyll, red excitation
pH	pH
Fluorescein	Fluorescein dye
Oil-crude	Crude oil
Oil-fine	Fine oil
Brighteners	Optical brighteners
Phycocyanin	Phycocyanin (freshwater cyanobacteria)
Phycoerythrin	Phycoerythrin (marine cyanobacteria)
PTSA	PTSA

Rhodamine	Rhodamine
Tryptophan	Tryptophan

7 Appendix C - Calculated Parameters

The AML-3 and AML-6 instruments have the ability to calculate certain parameters depending on your sensor configuration. Below is a table outlining the parameters that can be calculated.

Parameter	Required Sensors	Equation	Range
Salinity	C, T, P	Practical Salinity Scale 1978	0 - 90 PSU ¹
Salinity (from SV)	SV, T, P	AML	0 - 90 PSU
Density	C,T, P	TEOS10	0 - 2000 kg/m ³
Density (from SV)	SV,T, P	TEOS10	0 - 2000 kg/m ³
Sound Velocity*	C,T, P	Chen & Millero	0 - 3000 m/s
Depth	P	UNESCO	-20 - 12000 m

C - conductivity, T- temperature, SV - sound velocity, P- pressure

1 - Instrument will report 0-90 PSU, however PSS-78 equation is valid only from 2-50 PSU.

*Calculated salinity must be enabled for the calculated Sound Velocity to operate correctly

8 Appendix E - Storage Recommendations

AML recommends the following practices for storing your instrument:

- Thoroughly rinse the instrument off with clean fresh water
- Dry off the instrument using a soft rag and allow to air-dry the rest completely
- Store in a cool dry environment, ideally inside an AML supplied shipping/storage case
- Charge the battery to above 80%, recharge the battery to above 80% at least once every 4 months. This is to preserve the health of the Lithium Ion battery.

Note that if leaving your instrument in storage for long periods of time(> 1 year), your sensors may require recalibration.



9 Appendix F - USB FAQ

Question	Answer
Can I charge my instrument using my computer's USB port?	Yes, but note that some USB ports on computers cannot deliver the power that is required by the instrument for charging (10 Watts). We recommend using the included AC-DC Wall Adapter for charging your instrument.
I cannot communicate to the instrument via USB, what should I be checking?	<ol style="list-style-type: none"> 1. Check if your computer's USB port is USB 3.1 or later. Some USB ports will tend to shut down due to the output power limit. 2. Use a powered USB hub that supports USB 3.1 connectivity. Contact AML for approved USB hubs that are tested with our instruments.
Can I use a different USB-C cable for charging/communicating to the instrument?	AML highly recommends using the factory-supplied USB cable. In cases where you have to use a different one, you may do so but AML cannot guarantee that it meets the required specification in order to work seamlessly with our instrument.

10 Appendix G - Regulatory Information

This product is compliant within the requirements of CE standards.

The WiFi adaptor used in this instrument is a certified radio module under the following regulatory bodies:

FCC Part 15.247 Intentional Radiator Certification		FCCID: Z64-WL18SBMOD
Industry Canada RSS-210		IC ID: 4511-WL18SBMOD
Japan Certificates		201-135370

11 Appendix H - Warranty Statement

AML Warranty Policy: New Product (Instrumentation)

AML warrants the instrument and sensor for a period of TWO YEARS (24 months) from the date of delivery. AML will repair or replace, at its option and at no charge, components which prove to be defective. The warranty applies only to the original purchaser of the instruments and only to instruments and sensors manufactured by AML Oceanographic. The warranty of third party sensors will apply as per the specific vendor's warranty policy. The warranty does not apply if the instrument has been damaged, by accident or misuse, and is void if repairs or modifications are made by other than authorized personnel.

This warranty is the only warranty for new products given by AML. No warranties implied by law, including but not limited to the implied warranties of merchantability and fitness for a particular purpose shall apply. In no event will AML be liable for any direct, indirect, consequential or incidental damages resulting from any defects or failure of performance of any instrument supplied by AML.