

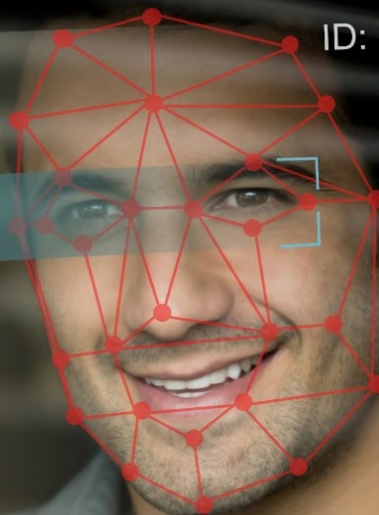


DRIVER 1 PRESENT

ID: DRIVER 1



ATTENTIVE



MEASURING NEAR-INFRARED LIGHT SOURCES FOR DRIVER MONITORING SYSTEMS (DMS)

Matt Scholz, Radiant Vision Systems

Radiant Vision Systems | A Konica Minolta Company

IN-VEHICLE SENSING SYSTEMS



Automotive Interior Monitoring Systems (IMS)



Driver Monitoring Systems (DMS)

- Presence detection
- Eye/gaze/eyelid tracking
- Head position
- Facial recognition for ID
- Facial expression for mood
- Steering hand presence
- Steering/pedal use
- Biometrics (heart rate)

Image Source:
[Continental.com](https://www.continental.com)

Occupant Monitoring Systems (OMS)

- Presence detection
- Body position/posture
- Facial recognition for ID
- Door open/closed
- Seatbelt fastened/unfastened
- Biometrics (heart rate, respiration, temperature)

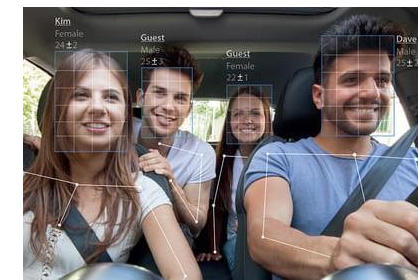


Image Source:
[Cipia.com](https://www.cipia.com)

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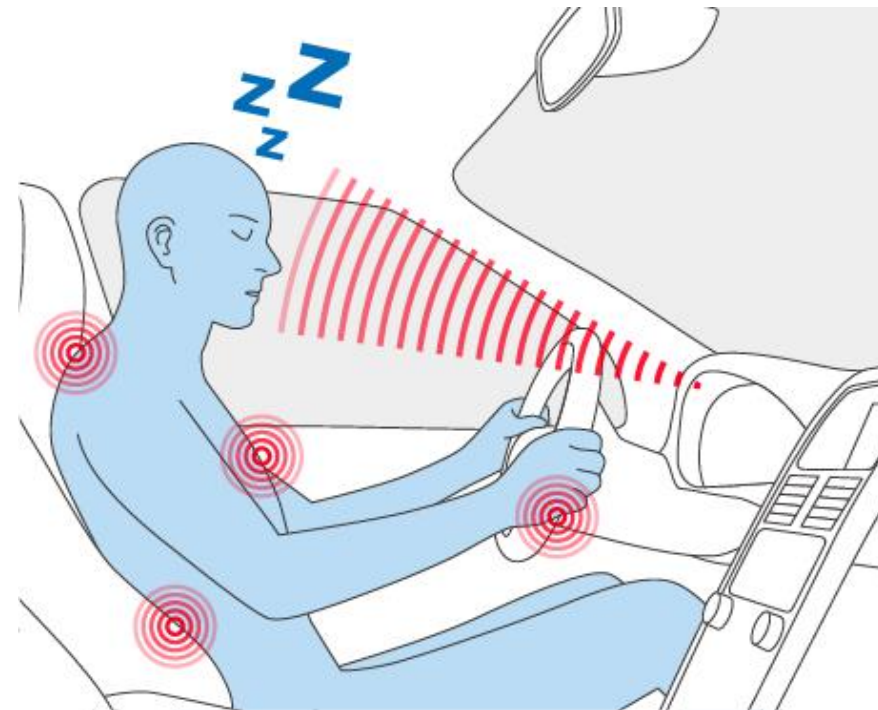
REGULATIONS: EUROPEAN UNION



- **MANDATE: NEW VEHICLES AS OF 2022**
- System: DMS
- Safety systems mandated by EU GSR:
 - Driver drowsiness and attention warning
 - Advanced driver distraction warning
 - Emergency braking systems
 - Intelligent speed assistance
 - Emergency lane-keeping systems
- 21,337 fewer EU car-related deaths projected through 2037 with these systems

Read More:

- <https://eur-lex.europa.eu/eli/reg/2019/2144/oj>



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REGULATIONS: UNITED STATES



- *COMING SOON...*
- System: DMS
- SAFE ("Stay Aware for Everyone") Act of 2020
- Research initiated to determine final ruling to install DMS to eliminate:
 - Driver distraction
 - Driver disengagement
 - Automation complacency
 - Misuse of ADAS

Read More:

- <https://www.congress.gov/bill/116th-congress/senate-bill/4123/text>



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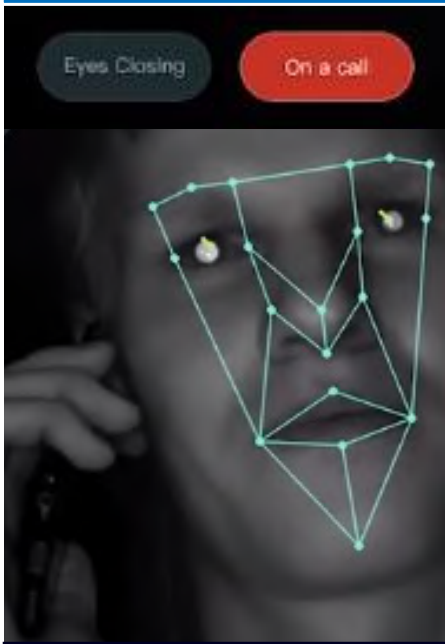
4

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IN-VEHICLE SENSING TECHNOLOGY

VISION

Eyes Closing On a call



NXP

RADAR

Someone is Here!



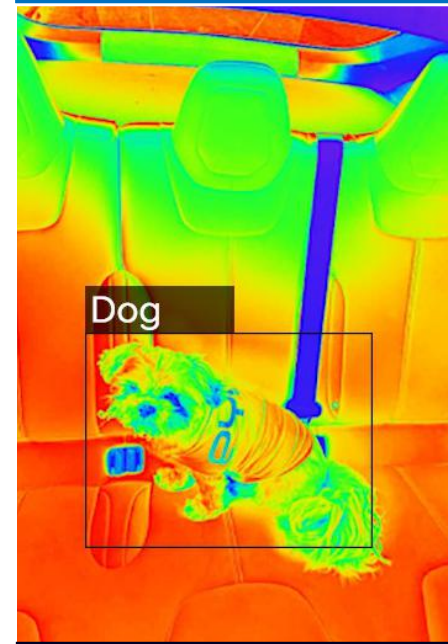
Vital

12 BPM

72 BPM

bitsensing

THERMAL (IR)



Dog

eyeris

EKG/ECG

HeartKey



B Secur
Connecting Your Heart

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IN-VEHICLE SENSING TRENDS



OEM	Technology	Type	Primary Sensing Method	In-Vehicle Functions
Audi	AI:ME (concept)	DMS/Driver Assistance System	Near-infrared	<ul style="list-style-type: none"> • Eye/gaze tracking
BMW	i Interaction EASE (concept); Extended Traffic Jam Assistant System	DMS/Driver Assistance System	Near-infrared (EASE); Vision Camera (EJAS)	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position • Responsive AR-HUD (EASE)
GM	Cadillac Super Cruise System	DMS/Driver Assistance System	Near-infrared, Steering sensors	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position • Steering hand presence
Hyundai	Driver State Warning (DSW); Rear Occupant Alert	DMS; OMS	Near-infrared (DMS); Radar, Ultrasound (OMS)	<ul style="list-style-type: none"> • Eye/gaze tracking • Facial recognition • Personalization • Child/occupant presence
Ford	Co-Pilot360	DMS/Driver Assistance System	Near-infrared	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position
Mazda	i-ACTIVSENSE	DMS/Driver Assistance System	Near-infrared	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position
Mercedes-Benz	2021 S-Class	Driver Assistance System	Near-infrared	<ul style="list-style-type: none"> • Eye/gaze tracking
Nissan	ProPILOT	DMS/Driver Assistance System	Near-infrared, Steering sensors	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position
Subaru	DriverFocus (EyeSight Driver Assist)	DMS/Driver Assistance System	Near-infrared	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position • Facial recognition
Tesla	TBD	OMS	Radar	<ul style="list-style-type: none"> • Child/occupant presence
Toyota	Lexus Safety System (LSS)/ Safety Sense	Driver Assistance System	Radar, Camera	<ul style="list-style-type: none"> • Eye/gaze tracking • Head motion/position

Multiple Sources. See "A Comprehensive Survey of Driving Monitoring and Assistance Systems" by Muhammad Qasim Khan and Sukhan Lee, as well as OEM announcements.

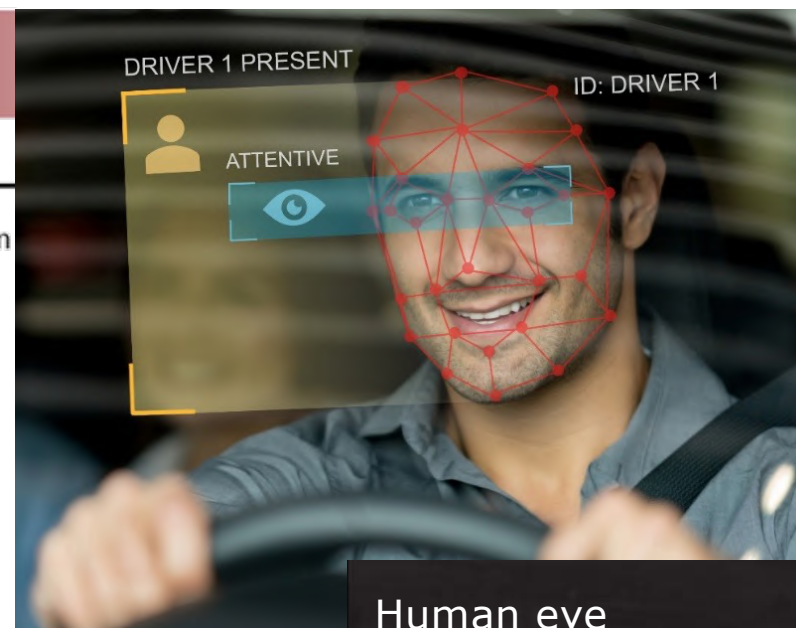
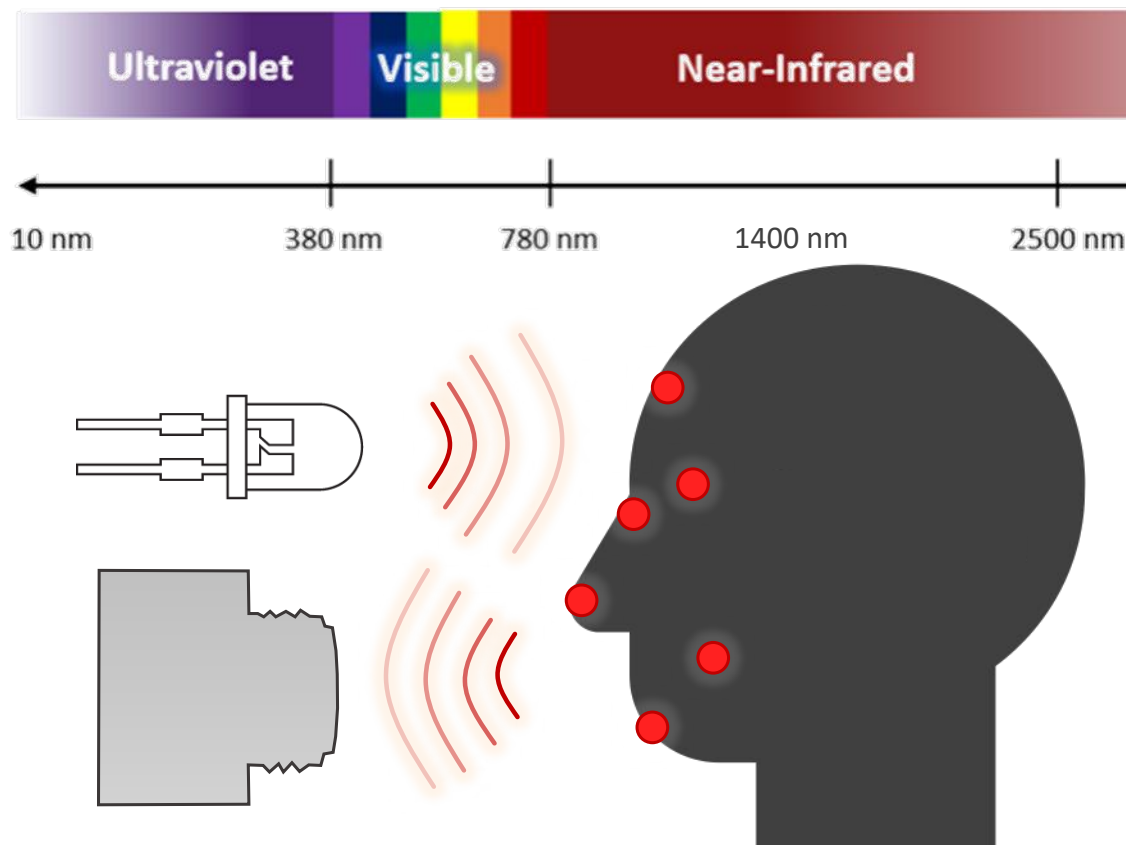
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NEAR-INFRARED LIGHT/CAMERA SYSTEMS



Human eye

Vision Camera

NIR Camera

Image [Source](#)

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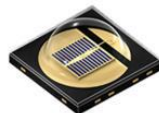
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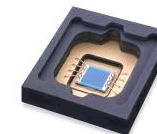
NEAR-IR LIGHT SOURCES

Features and Applications of LEDs and Lasers

NIR LIGHT SOURCE COMPARISON



Example LED. Source: [Osram](#)



Example VCSEL. Source: [Finisar](#)



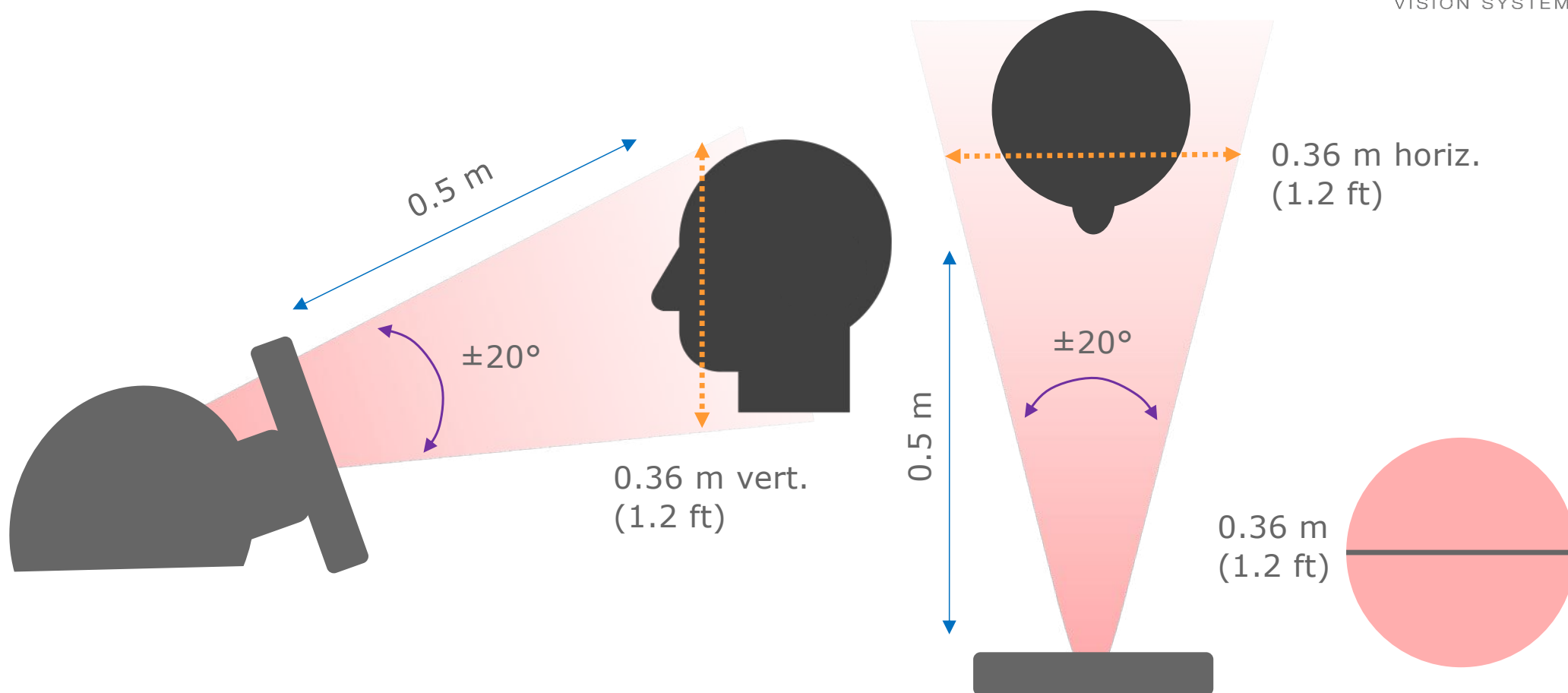
	LED	VCSEL
Spot Size	100 μm	35 μm
Beam Angle	$\leq 120^\circ$	$\leq 20^\circ$ (no diffraction)
Beam Quality	Lambertian; Low coherence	Low-divergence; High coherence
Range	Shorter	Longer
Response (Rise/Fall Time)	$\sim 10 \text{ ns}$ (Source: Lumileds)	$< 1 \text{ ns}$ (Source: Lumileds)
Operating Temperature	-40 to $\sim 125^\circ\text{C}$	-20 to $\sim 85^\circ\text{C}$
Stability vs. Temperature	$\sim 0.25 \text{ nm}/^\circ\text{C}$ (Source: Lumileds)	$\sim 0.07 \text{ nm}/^\circ\text{C}$ (Source: Lumileds)
Eye Safety	"Intrinsically Safe"	Requirements per class
Cost	Lower	Higher
Application	Illumination; Stereo Vision; TOF	Patterns (Structured Light); TOF

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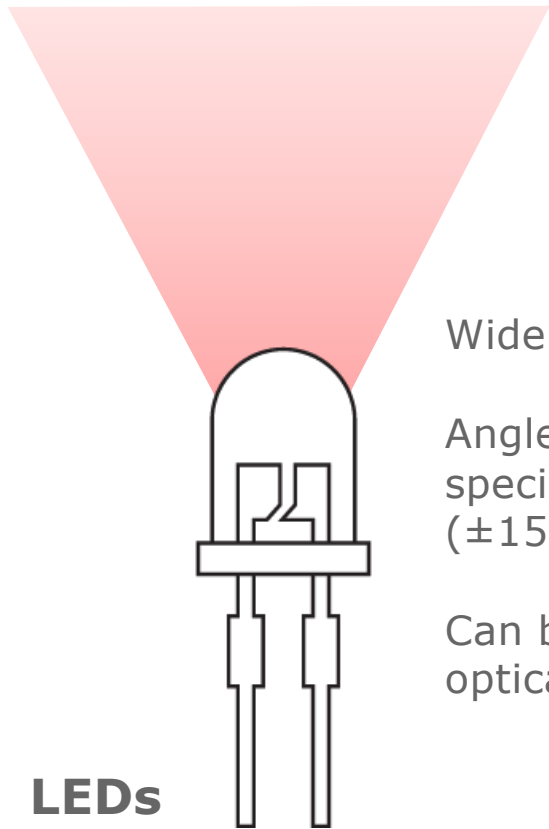
9

BEAM ANGLE



SEE THE DIFFERENCE

BEAM ANGLE

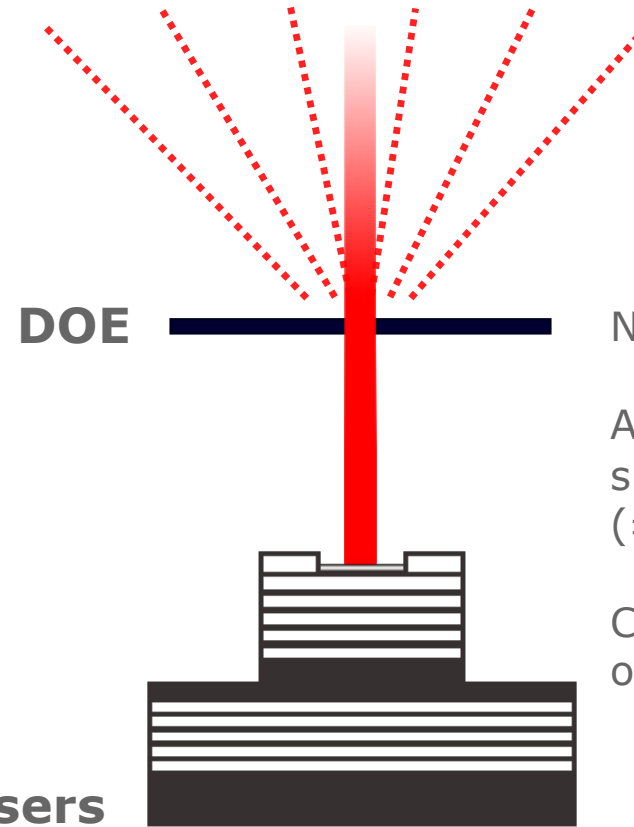


Wider beam angle

Angle defined in source specifications
($\pm 15^\circ$, $\pm 25^\circ$, etc.)

Can be narrowed using optical elements

LEDs



DOE

Narrower beam angle

Angle defined in source specifications
($\pm 6^\circ$, $\pm 15^\circ$, etc.)

Can be diffracted using optical elements

Lasers

SEE THE DIFFERENCE

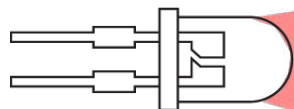
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11

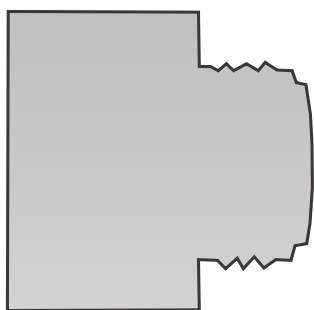
APPLICATIONS: 2D SENSING (LED)

Illumination

NIR LED with given
distribution angle



IR light beam



Camera with IR sensor

Reflected IR light



Target object

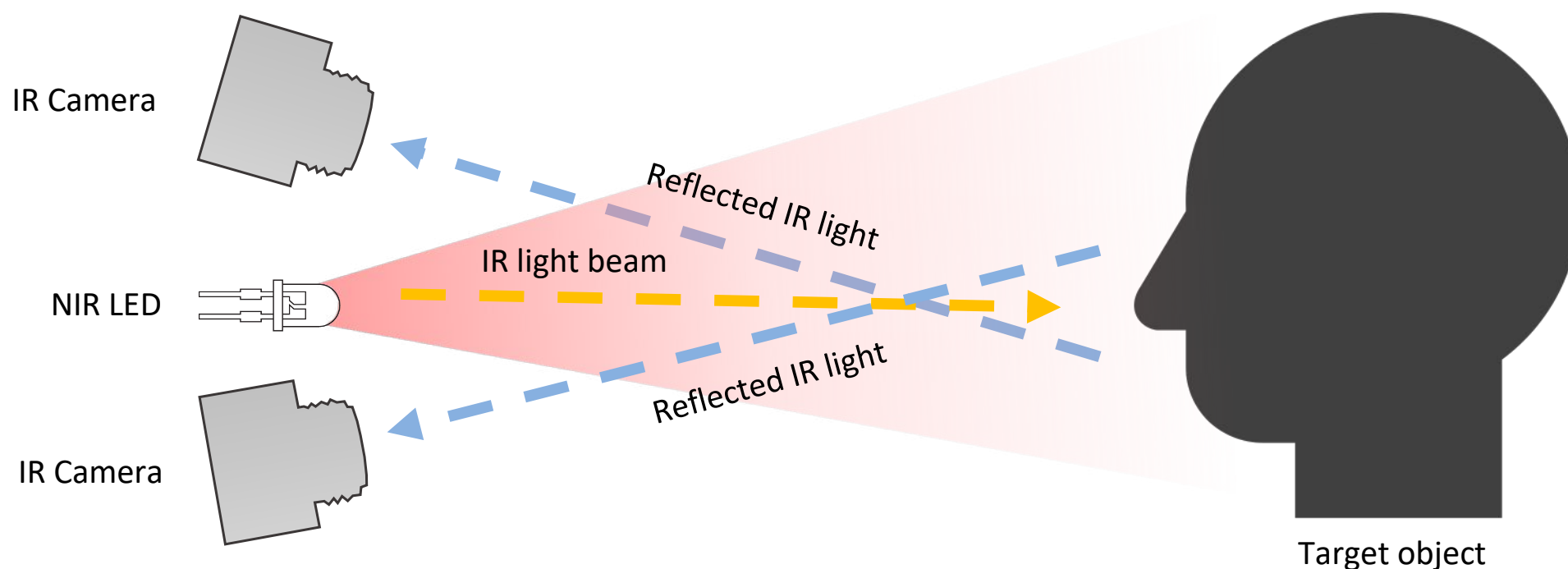
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APPLICATIONS: 3D SENSING (LED/LASER)

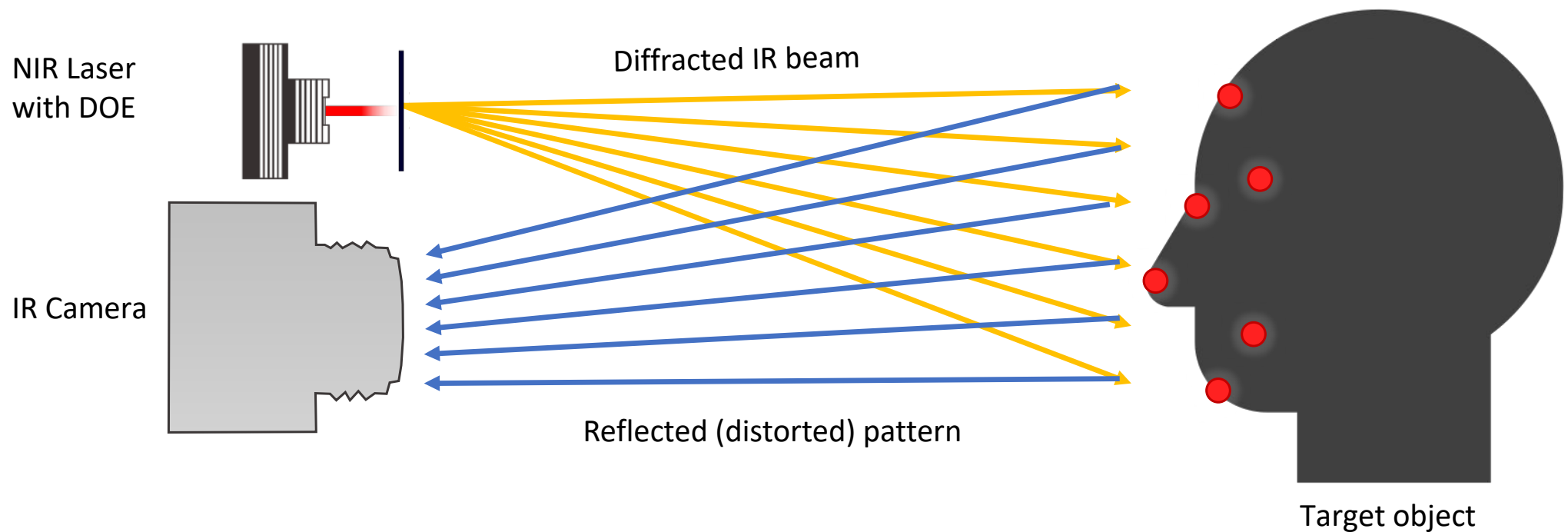
Stereo Vision



SEE THE DIFFERENCE

APPLICATIONS: 3D SENSING (LASER)

Structured Light Patterns



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DRIVER 2 PRESENT

ID: DRIVER 2



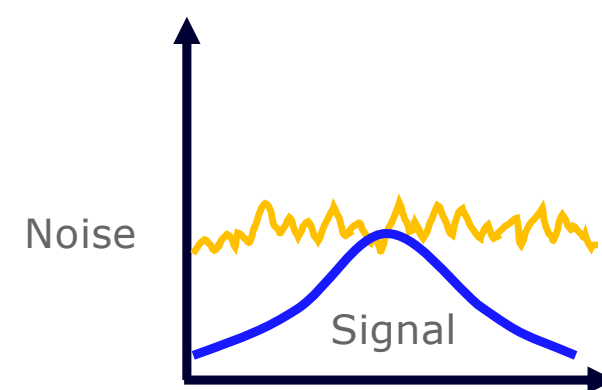
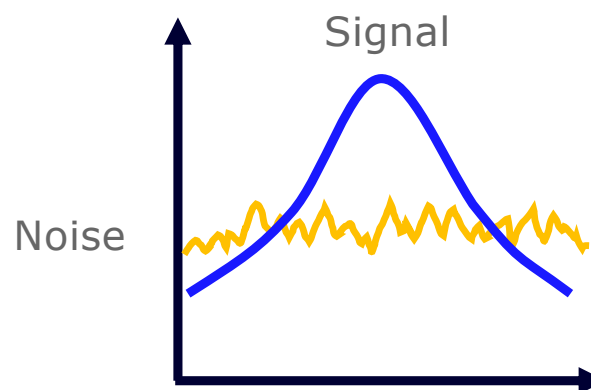
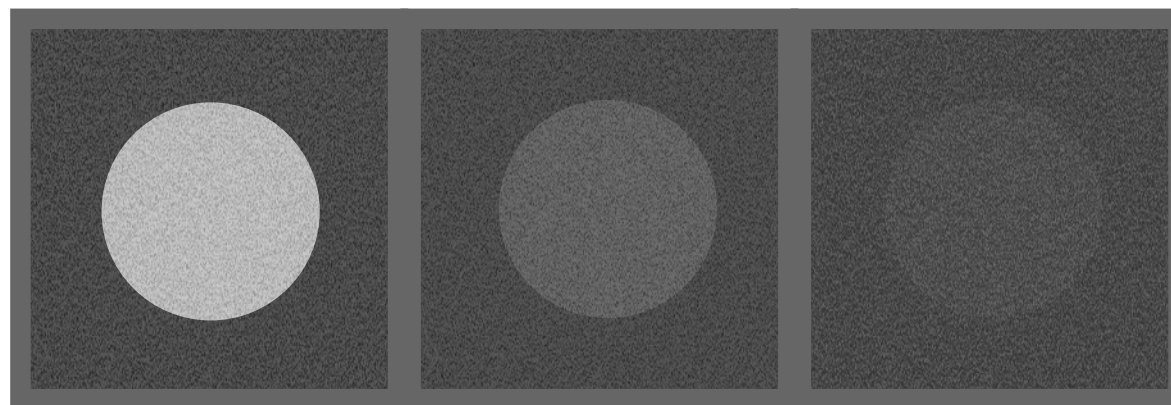
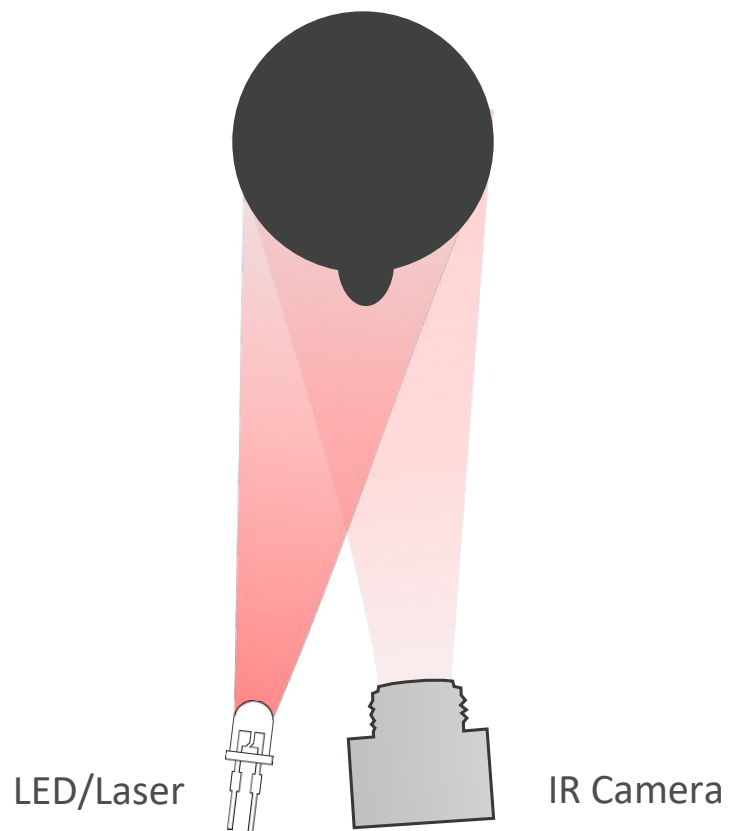
ATTENTIVE



PERFORMANCE CONSIDERATIONS

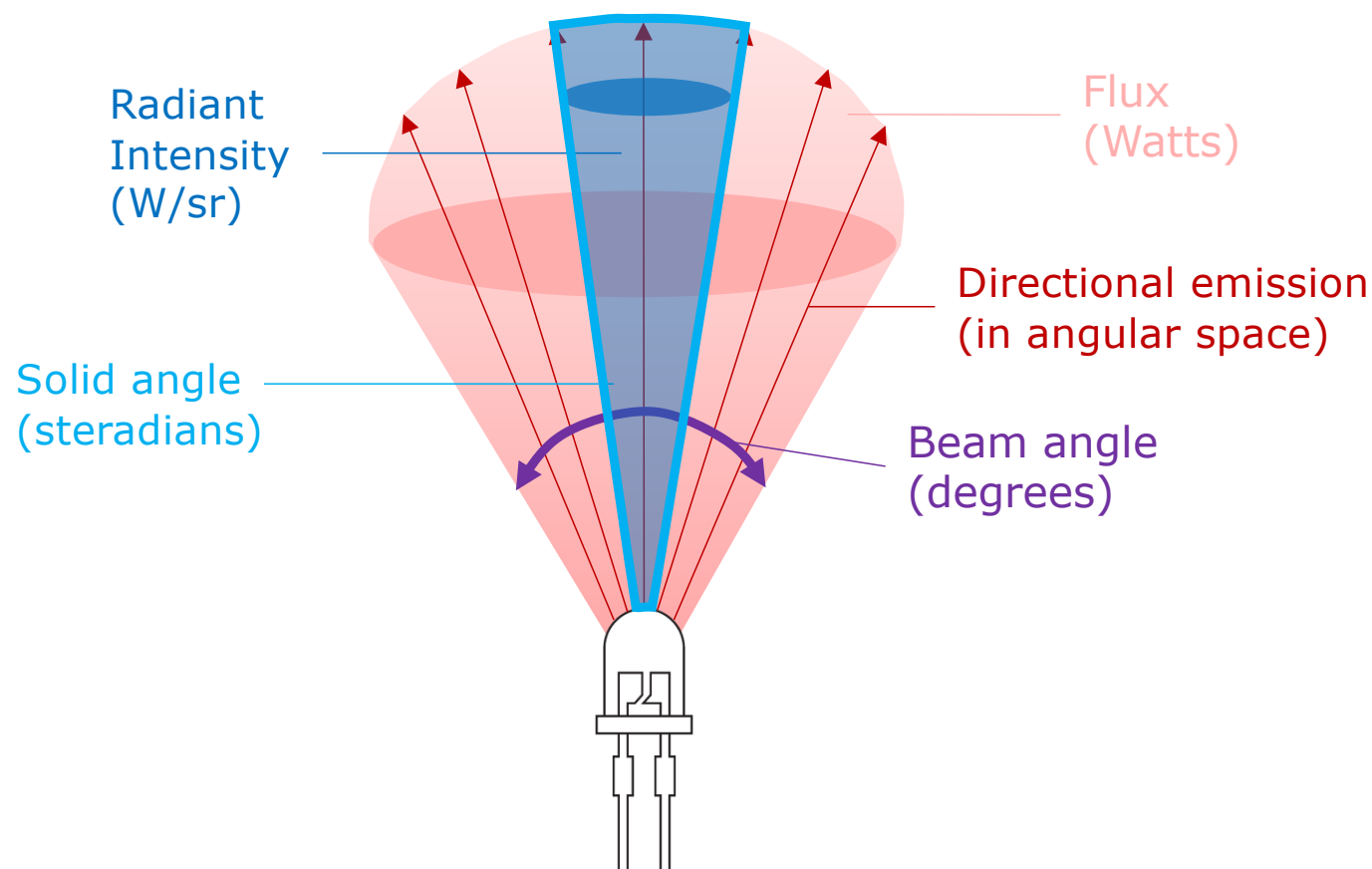
Qualities of NIR Sources for Sensing

SUFFICIENT INTENSITY

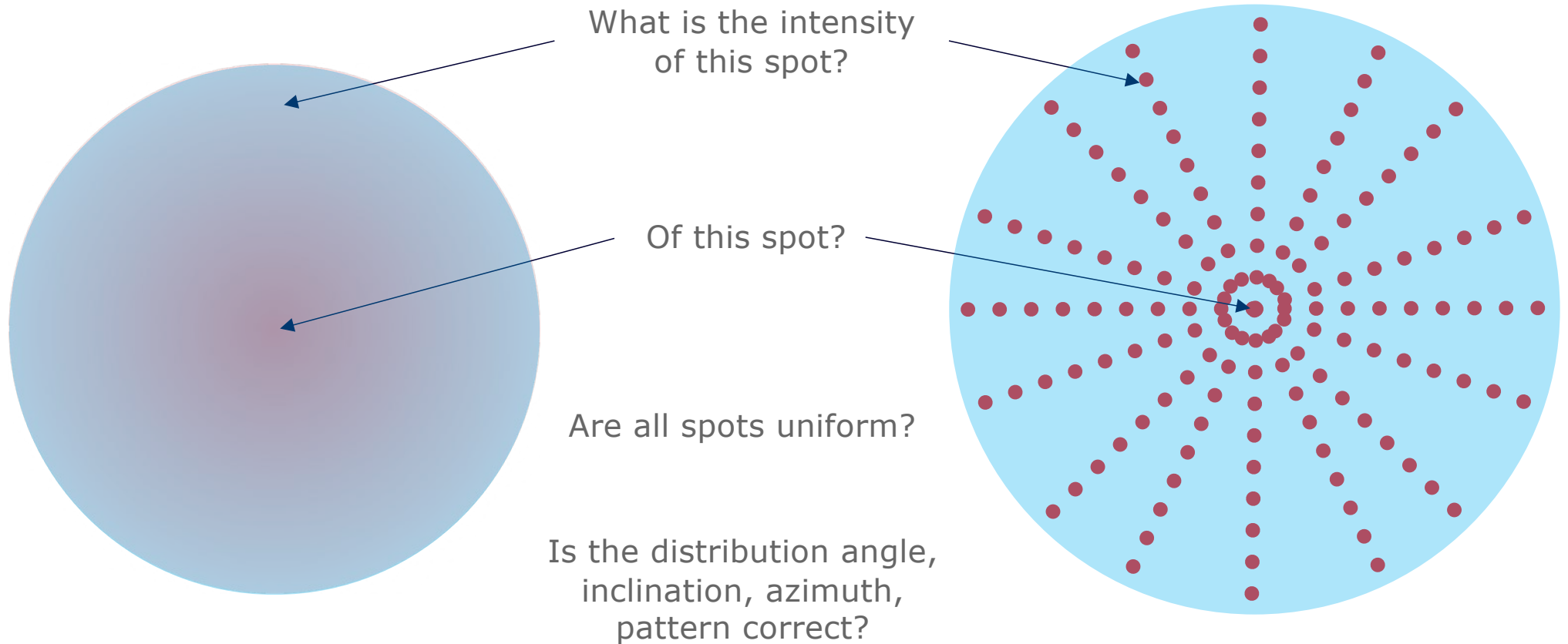


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POWER OVER ANGLE



DISTRIBUTION INTEGRITY



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MEASURING NEAR-IR LIGHT SOURCES

Solutions to Ensure Sensing Performance



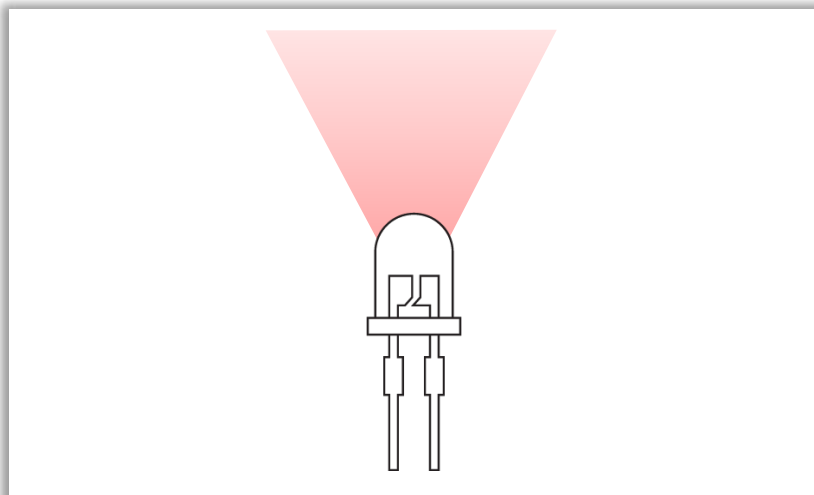
254.1 (mW/sr)

Inclination = 11.28(°), Azimuth = 20.94(°)

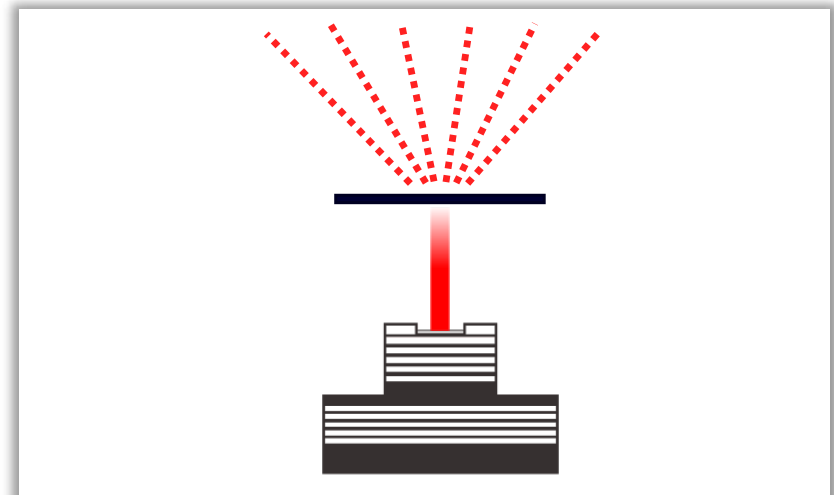
Col=1758, Row=1440

MEASUREMENT CONSIDERATIONS

We need measurement solutions that address multiple geometries—including pattern, direction, and angle.



**Broad Angular
Distributions**



**Structured Light
Patterns**

SEE THE *DIFFERENCE*

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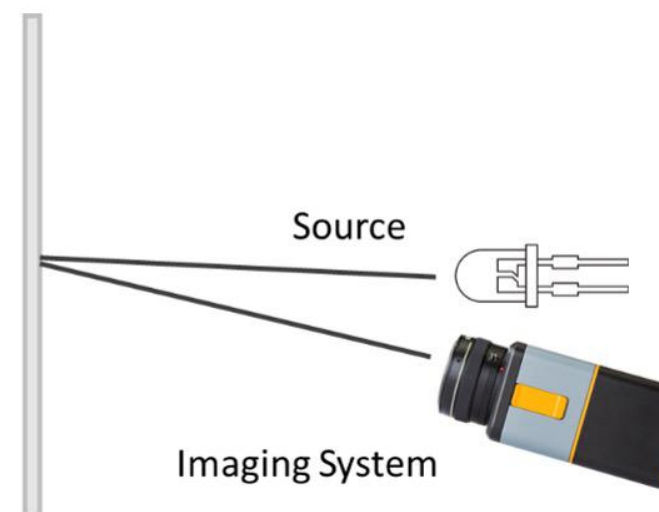
20

INDIRECT REFLECTANCE MEASUREMENT

Beam/Pattern on a Wall

- Cast light on a wall/screen and measure with imaging system
- Measure irradiance of LED beam
- Measure structured light emissions and verify dot position against a target pattern or coordinates
 - *Pass/fail on pattern match*

Projection Screen



DIRECT ANGULAR MEASUREMENT



- **Goniometer**
 - Rotate source relative to a photodetector or camera to capture intensity data at each angle
 - More images, higher resolution
 - *Full resolution at each degree*
 - Output IES, EULUMDAT, ray set files



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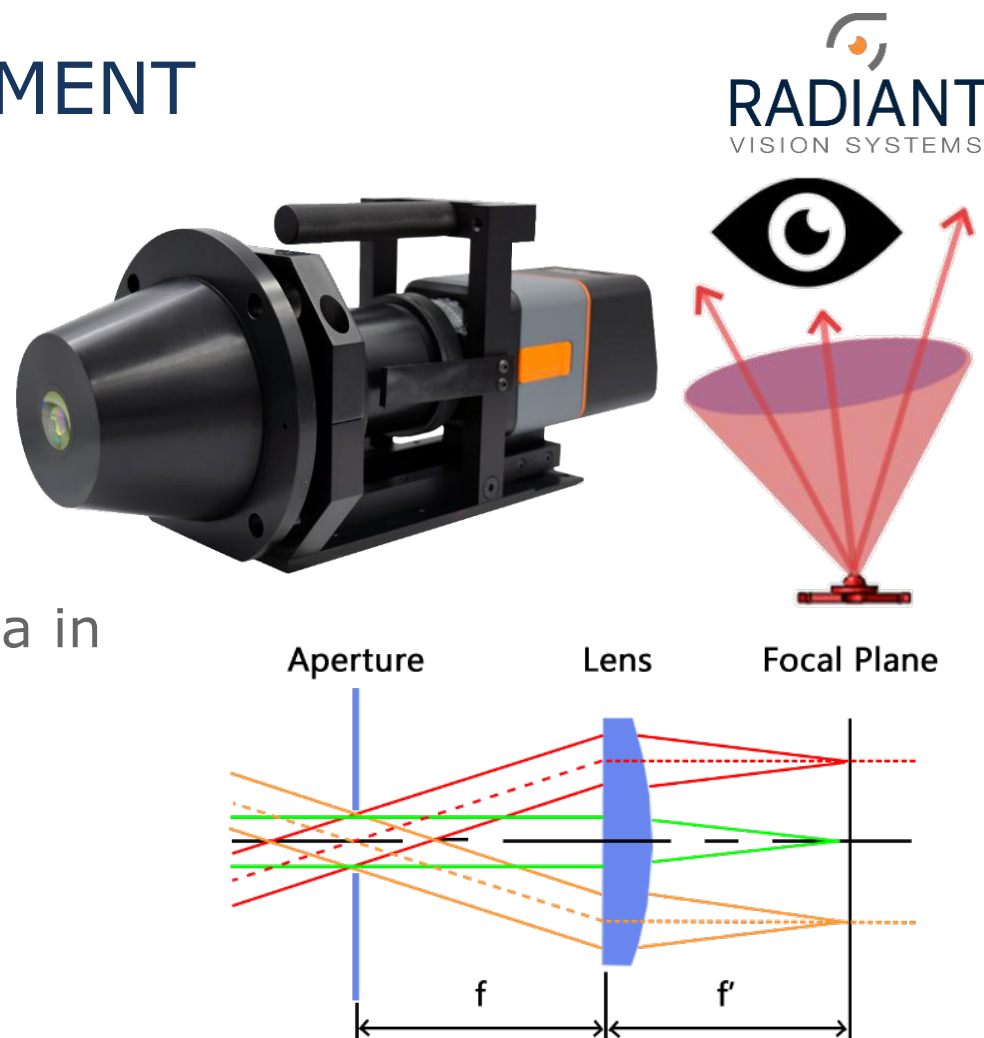
22

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DIRECT ANGULAR MEASUREMENT

Fourier Optic Lens

- Lens and radiometric imager
 - *850/940 nm light sources*
 - *Angular FOV to ± 70 degrees*
- Instantly measure full cone of data in a single image
- No rotation of photodetector or source to capture distribution
- Angular resolution to $\sim 0.05^\circ$ per sensor pixel



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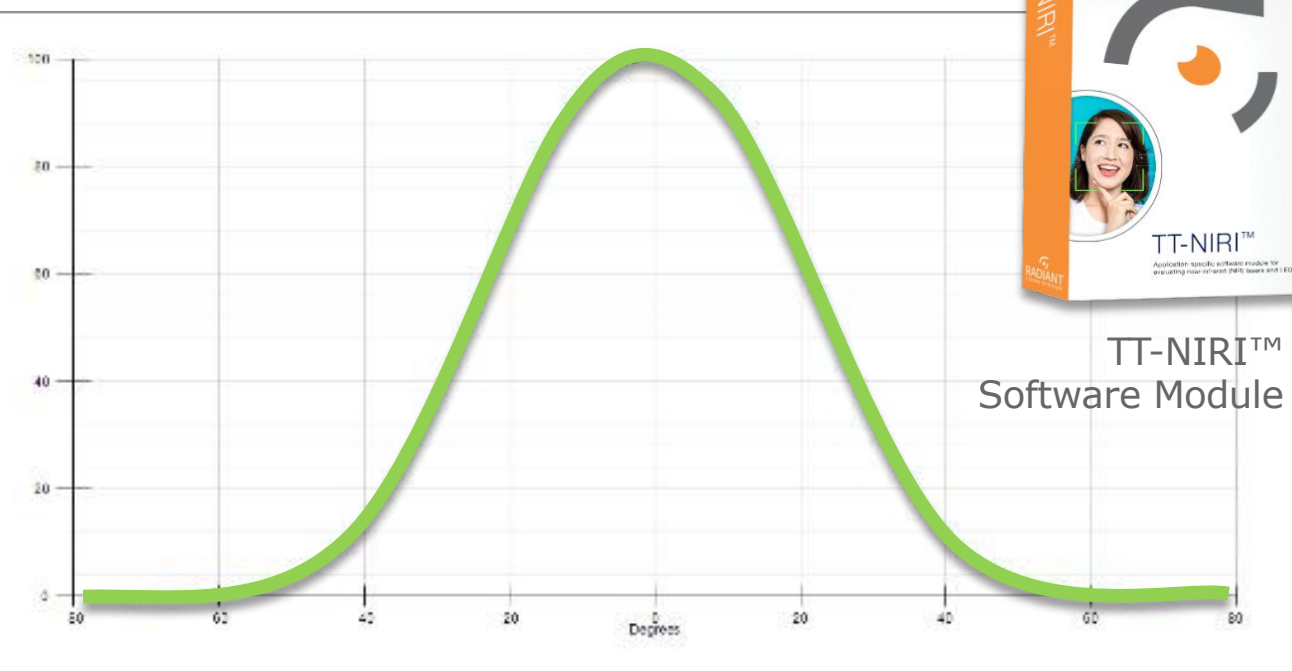
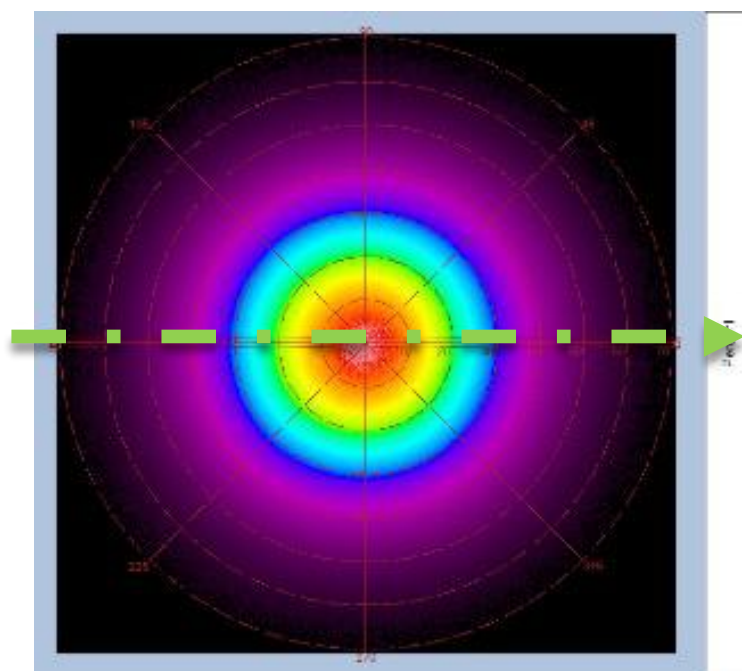
The background of the slide is a dark blue to black gradient, overlaid with a complex network of glowing blue lines and nodes. The nodes are small, semi-transparent blue spheres, and the lines are thin, glowing blue lines that connect the nodes in a web-like pattern, creating a sense of connectivity and data flow.

NIR MEASUREMENT SOFTWARE

Automated Light Source Analysis & Data Output

DIRECT ANGULAR MEASUREMENT

Radar plot showing **radiant intensity as function of angle** of an NIR LED light source.



TT-NIRI™
Software Module

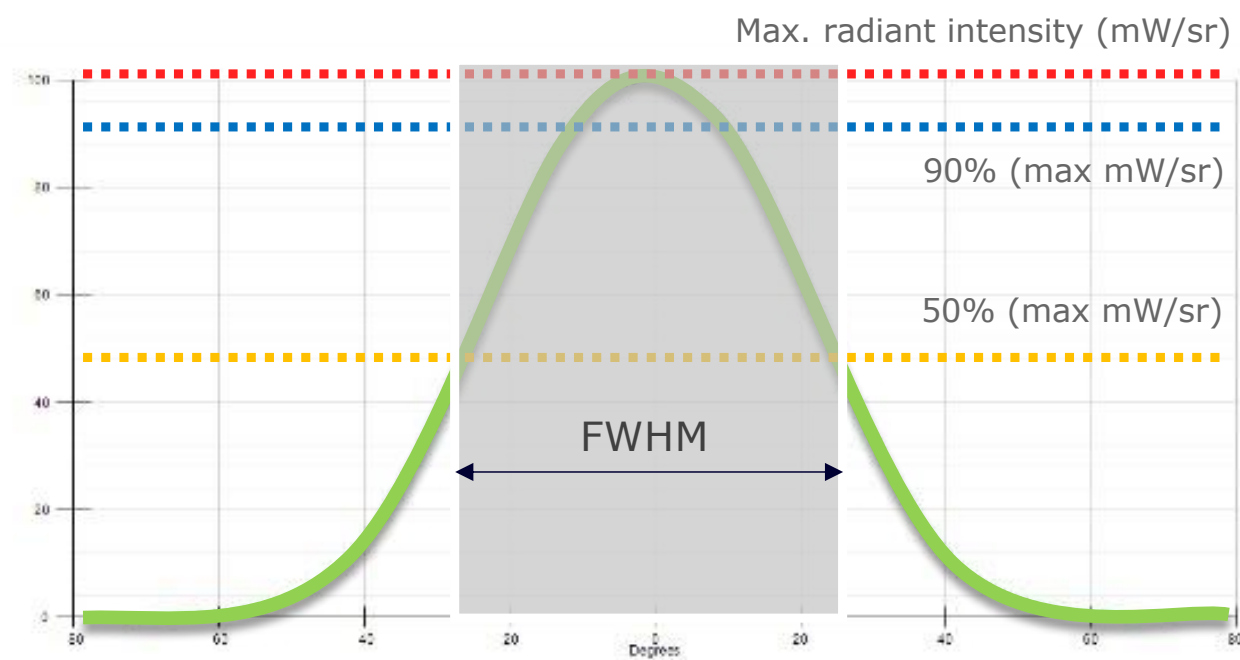
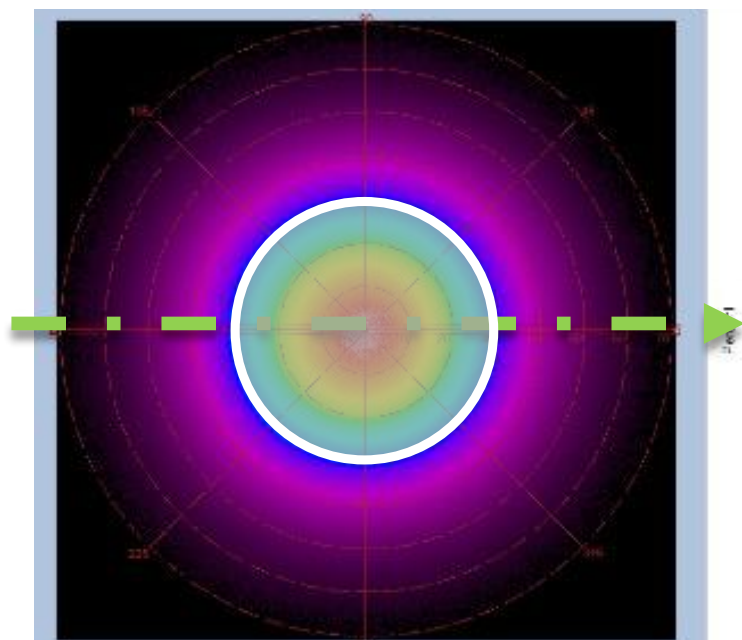
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DIRECT ANGULAR MEASUREMENT

Full-width half-max (FWHM) of the angular cross-section defines the primary area for intensity measurement.



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Run Sequence



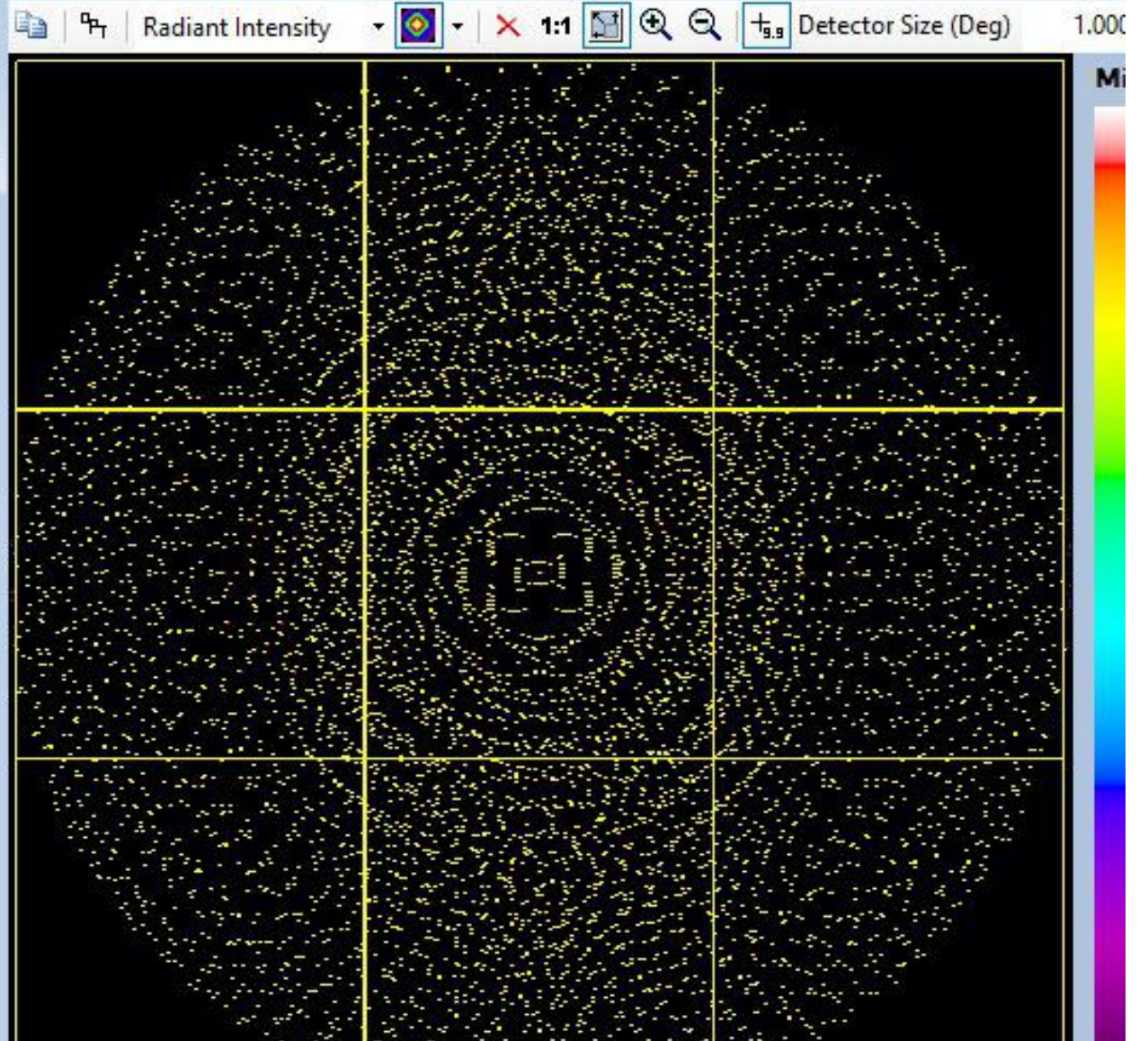
Save Sequence | Save Sequence As

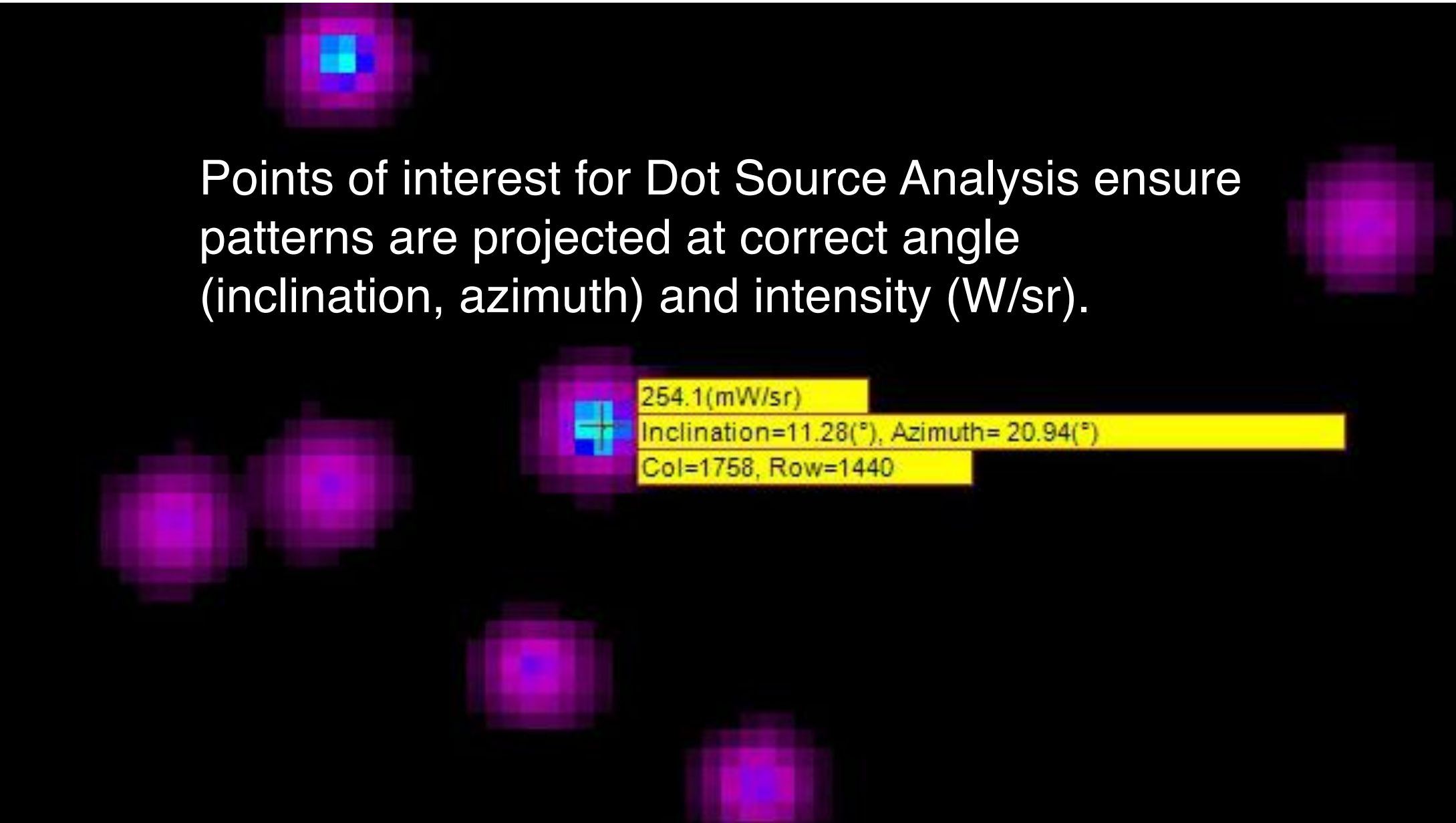
+ Add Step | Copy Step | ↓ ↑ X Delete Step

	Select	Measurement Setup	Analysis	Edit
1	<input checked="" type="checkbox"/>	NIR Conoscope	Dot Source Analysis	Edit
2	<input checked="" type="checkbox"/>	NIR Conoscope	Dot Source Analysis	Edit
3	<input type="checkbox"/>	NIR Conoscope	Total Flux	Edit
4	<input checked="" type="checkbox"/>	NIR Conoscope	POI Total Power	Edit
5	<input checked="" type="checkbox"/>	NIR Conoscope	MaxPower	Edit
6	<input type="checkbox"/>	NIR Conoscope	Pixel Solid Angle	Edit
7	<input type="checkbox"/>	NIR Conoscope	Flood Source Analysis	Edit

DOT SOURCE ANALYSIS

1) NIR Lens Dot Source Analysis (Stitched Regions)





Points of interest for Dot Source Analysis ensure patterns are projected at correct angle (inclination, azimuth) and intensity (W/sr).

254.1(mW/sr)

Inclination=11.28(°), Azimuth= 20.94(°)

Col=1758, Row=1440

CHOOSING A MEASUREMENT SOLUTION



Ideal for:	LED	Laser	Wide Beam	Structured Light	Angular Output	Radiant Intensity (Direct Output)	Irradiance/ Reflectance (Indirect Output)	R&D/ Lab	Production Testing
Beam/Pattern on a Wall	X	X	X	X			X	X	
Goniometer	X		X		X	X		X	
Fourier Optic Lens	X	X	X	X	X	X		X	X



Radiometric Imaging System (ProMetric® Imaging Radiometer)



Goniometric System (SIG-400)



Fourier Optic Lens System (NIR Intensity Lens)

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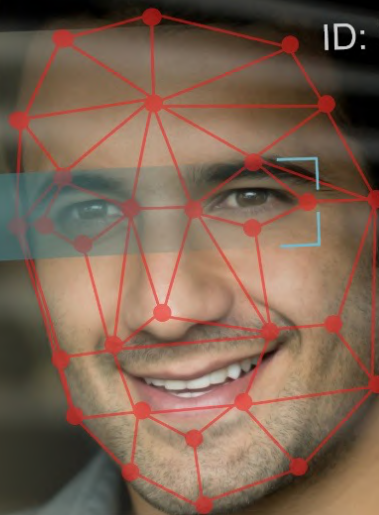


DRIVER 1 PRESENT

ID: DRIVER 1



ATTENTIVE



THANK YOU!

Questions? Contact Matt.Scholz@RadiantVS.com
RadiantVisionSystems.com

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