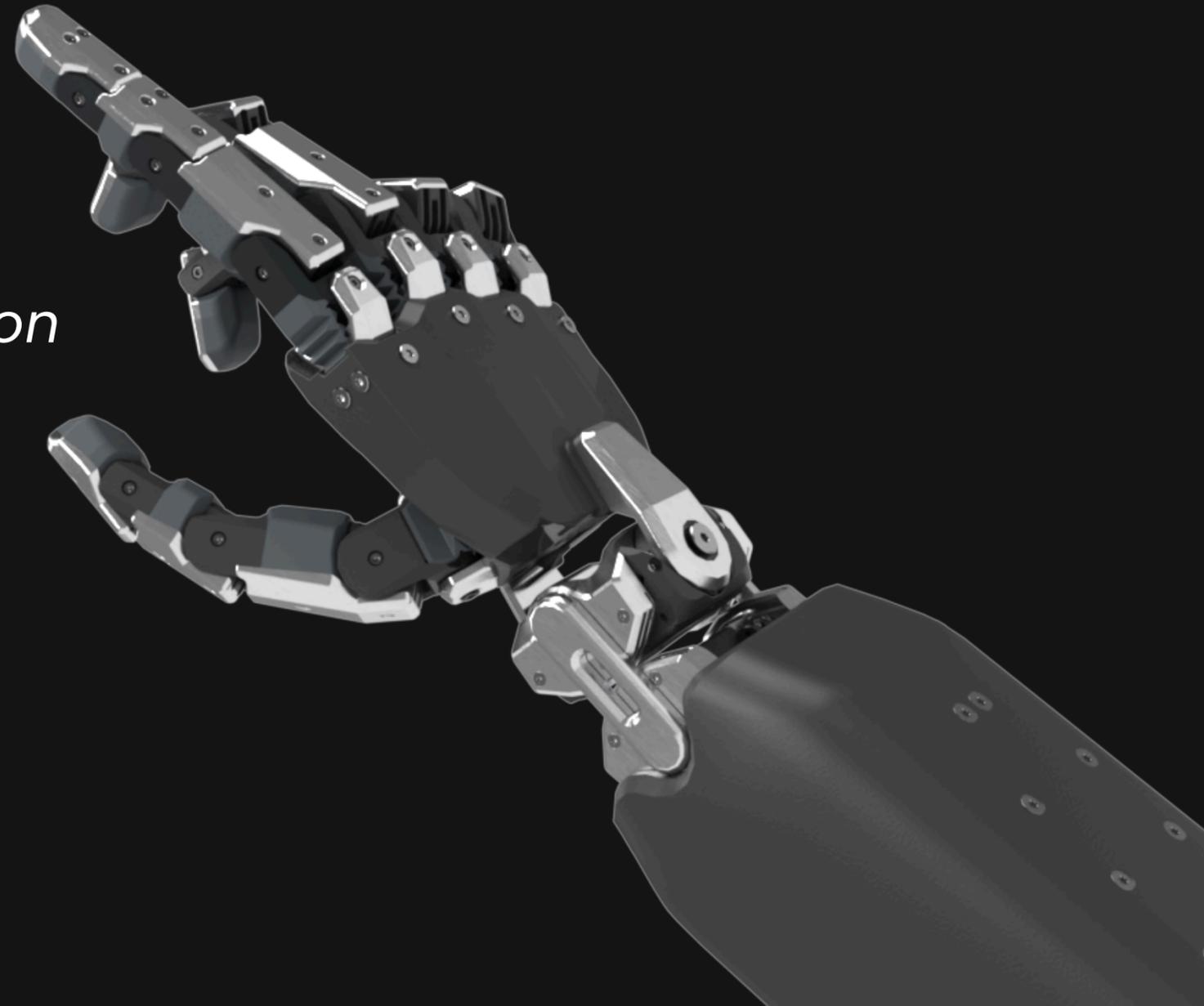


SARCOMERE
DYNAMICS

ARTUS Dex

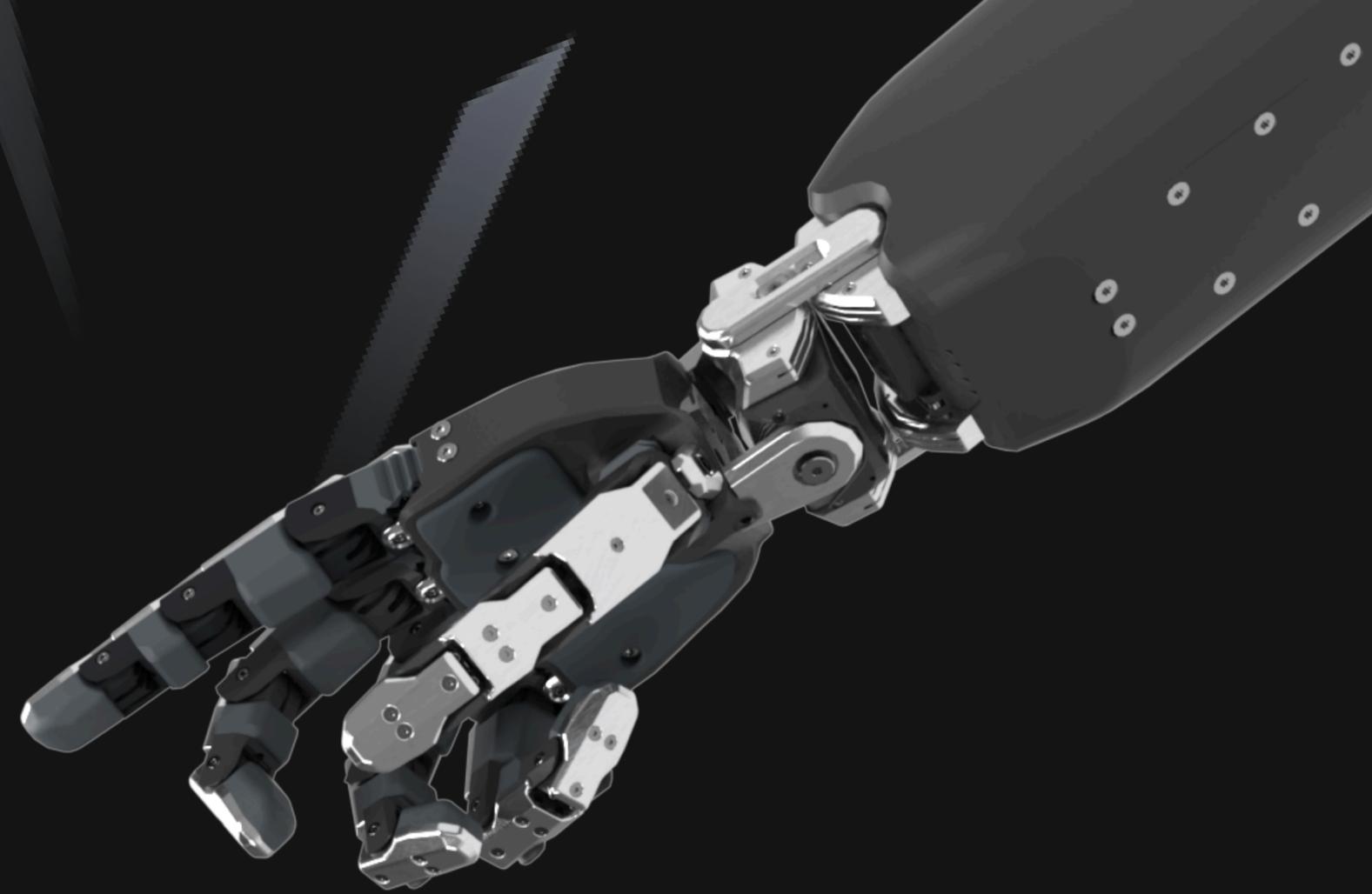
bringing near-human capability to automation



ARTUS Dex

Enabling embodied AI to interact naturally with a world designed by humans, for humans.

This ultimate, general purpose end-of-arm tool is engineered to replicate the capabilities of the human hand—empowering humanoid robots to perform intricate manipulation and non-routine tasks in unstructured environments.



ARTUS Dex Specifications

DEGREES OF FREEDOM	22	<ul style="list-style-type: none">• 4 underactuated DoF for the distal phalange of the fingers• 2 DoF for the wrist
MAX PAYLOAD	10kg	<ul style="list-style-type: none">• Payload for objects being manipulated.• Higher payloads are possible for pick and place (up to 20kg)
WEIGHT	2.3kg	
VOLTAGE & POWER	24V, 150W	<ul style="list-style-type: none">• Peak Power draw will be 500W (all actuators drawing max power simultaneously)
FINGER CYCLING SPEED	1.5Hz	<ul style="list-style-type: none">• This frequency describes how many times a finger joint can go from fully open, to fully closed, back to fully open
FORCE AT FINGERTIP	3.5kg	<ul style="list-style-type: none">• Force at tip of fingertip during continuous operation• Intermittent forces up to 8kg are possible (double human capability)
WRIST PAYLOAD	5kg	<ul style="list-style-type: none">• This describes continuous payload in the wrists reachable workspace• Intermittent payload up to 10kg

COMMUNICATION PROTOCOLS

- CAN, USB-C, Wifi , RS485, SPI,
- Ethernet and EtherCAT in development

MOUNTING INTERFACE

- ISO 9409-1-50-4-M6
- Customizable

CONNECTOR INTERFACE

Nano M8 4-pin connector: High Power
Nano M8 8-pin connector: Communication and Low Power

ARTUS Dex Features

FEATURES

- Lightweight
- Passive Cooling
- Quasi direct drive brushless actuators for fingers and wrist
- Robust design with Series Elastic actuators
- Replaceable Silicone grip pads
- Human form factor hand and forearm
- Water and dust resistant
- Cobot capabilities enable interaction with humans

SENSORS

- Absolute position sensors in finger joints
- Supports force sensors in fingertips (tactile arrays, shear force sensor, etc.)
- 6-axis IMU in palm and forearm
- Tension sensors provide joint torque information

ARTUS Dex Hand ROM

THUMB JOINTS			FINGER JOINTS		
	Degrees			Degrees	
	Min	Max		Min	Max
DISTAL PHALANGE	0	90	DISTAL PHALANGE	0	90
MIDDLE PHALANGE	0	90	MIDDLE PHALANGE	0	90
PROXIMAL PHALANGE	10	90	PROXIMAL PHALANGE	-2.5	90
KNUCKLE	-45	45	KNUCKLE	-17	17

ARTUS Dex Wrist ROM

WRIST JOINTS

Degrees

Min

Max

WRIST PITCH

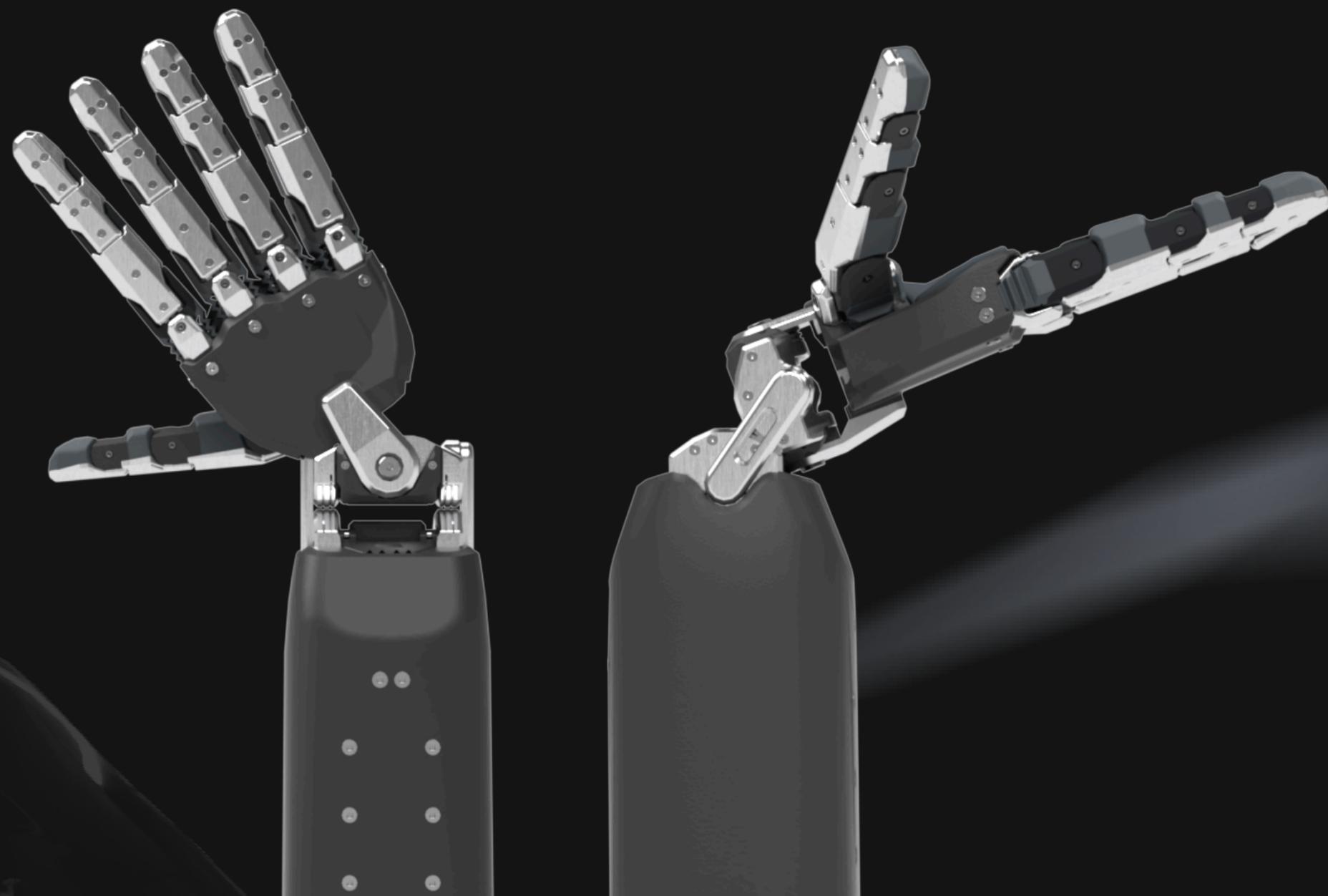
-70

70

WRIST YAW

-35

35



**The future is here, and it is
automated.**

Web: sarcomeredynamics.com

Sales: info@sarcomeredynamics.com

