What landed on master? • cartographer

- Points processor that can generate probability grids (#383).
- Support subdivision of scans in 2D (#408, for ROS: #428).
- More serialization (#334, #395).
- Small refactorings, bug fixes and improvements.
What landed on master? • cartographer_ros

- Bug fixes and refactorings.
Demo • Probability Grid Points Processor

X-Ray (both lasers) • Full size
Current work

- RViz improvements (#416, #422).
- Occupancy Grid Node (#432, #433).
Placeholder for other status reports
Thanks!

Next Open House:
August 17, 5pm CEST (8am PST)

If you would like to present anything next meeting, please reach out to
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