What landed on master? • cartographer

- Internal headers (#976, #979, #982, #983…)
- Time overlapping point clouds (#975, #996)
- Instrument metrics in GlobalTrajectoryBuilder. (#945)
- Use async_grpc (#1013)
- PoseGraph and Trimmer tests (#990, #1002, #1004, #1020)
- Serialize landmark observations. (#1006)
- ...

What landed on master? • cartographer_ros

- Add constraint-dependent trajectory visualization. (#756)
- Ignore empty laser scan message. (#767)
- Launch script to visualize pbstream in rviz (#788)
What landed on master? • point_cloud_viewer
What landed on master / pending PRs? • rfcs

- Committed: Independent weights for local SLAM and odometry (#9)
Current work

- Lifelong
Placeholder for other status reports
Thanks!

Next Open House:  
April 12th, 5pm CET

If you would like to present anything next meeting, please reach out to cschuet@google.com