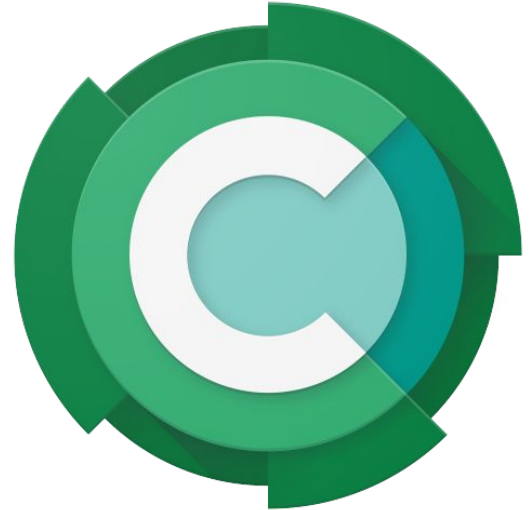


Cartographer Open House 0x11

March 29, 2018



What landed on master? • cartographer

- Internal headers (#976, #979, #982, #983...)
- Time overlapping point clouds (#975, #996)
- Instrument metrics in GlobalTrajectoryBuilder. (#945)
- Use `async_grpc` (#1013)
- PoseGraph and Trimmer tests (#990, #1002, #1004, #1020)
- Serialize landmark observations. (#1006)
- ...

What landed on master? • `cartographer_ros`

- Add constraint-dependent trajectory visualization. (#756)
- Ignore empty laser scan message. (#767)
- Launch script to visualize pbstream in rviz (#788)

What landed on master? • `point_cloud_viewer`

-

What landed on master / pending PRs? • `rfcs`

- Committed: Independent weights for local SLAM and odometry (#9)

Current work

- Lifelong

Placeholder for other status reports

Thanks!

Next Open House:
April 12th, 5pm CET

If you would like to present anything next meeting, please reach out to
cschuet@google.com