LINEAR ALGEBRA AND VECTOR ANALYSIS

MATH 22B

Unit 20: Constraints

INTRODUCTION

20.1. There is rarely a "free lunch". If we want to maximize a quantity, we often have to work with constraints. Obstacles might prevent us to change the parameters arbitrarily. The gradient can still be used as a guiding principle. While we can not achieve ∇f to be zero, we can look for points where the gradient is perpendicular to the constraint. This gives us an optimal point under the confinement. If you hike on a path in the mountains, you often reach a local maximum without being on top of the mountain. What happens at such points x is that $\nabla f(x)$ is perpendicular to the curve meaning that $\nabla f(x)$ is parallel to $\nabla g(x)$.

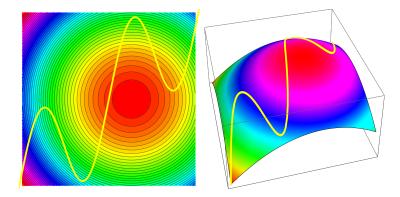


FIGURE 1. The situation, where a function f(x, y) is optimized along a curve g(x, y) = c is a frame-work which can be tackled with Lagrange. The condition of being maximal means that the gradient of f is perpendicular to the curve. This means that the gradients of f and g are parallel. $\nabla f = \lambda \nabla g$.

20.2. The method of Lagrange is much more general. We can work with arbitrary many constraints and still use the same principle. The gradient of $f : \mathbb{R}^n \to \mathbb{R}$ is then perpendicular to the constraint surface which means that is a linear combination of the gradients of all the *m* constraints: these are *n* equations $\nabla f = \sum_{j=1}^{m} \lambda_j \nabla g_j$ because the vectors have *n* components. Together with the *m* equations $g_j = c_j$ we have n + m equations for n + n variables $x_1, \ldots, x_n, \lambda_1, \ldots, \lambda_m$.

Lecture

20.3. If we want to maximize a function $f : \mathbb{R}^m \to \mathbb{R}$ on the constraint $S = \{x \in \mathbb{R}^m \mid g(x) = c\}$, then both the gradients of f and g matter. We call two vectors v, w **parallel** if $v = \lambda w$ or $w = \lambda v$ for some real λ . The zero vector is parallel to everything. Here is a variant of Fermat:

Theorem: If x_0 is a maximum of f under the constraint g = c, then $\nabla f(x_0)$ and $\nabla g(x_0)$ are parallel.

20.4. Proof by contradiction: assume $\nabla f(x_0)$ and $\nabla g(x_0)$ are not parallel and x_0 is a local maximum. Let T be the tangent plane to $S = \{g = c\}$ at x_0 . Because $\nabla f(x_0)$ is not perpendicular to T we can project it onto T to get a non-zero vector v in T which is not perpendicular to ∇f . Actually the angle between ∇f and v is acute so that $\cos(\alpha) > 0$. Take a curve r(t) in S with $r(0) = x_0$ and r'(0) = v. We have $d/dtf(r(0)) = \nabla f(r(0)) \cdot r'(0) = |\nabla f(x_0)| |v| \cos(\alpha) > 0$. By linear approximation, we know that f(r(t)) > f(r(0)) for small enough t > 0. This is a contradiction to the fact that f was maximal at $x_0 = r(0)$ on S.

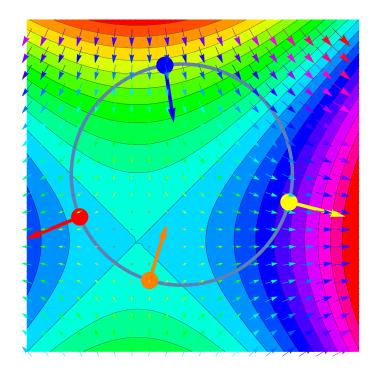


FIGURE 2. A Lagrange problem

20.5. This immediately implies: (distinguish $\nabla g \neq 0$ and $\nabla g = 0$)

Theorem: For a maximum of f on $S = \{g = c\}$ either the Lagrange equations $\nabla f(x_0) = \lambda \nabla g(x_0), g = c$ hold, or then $\nabla g(x_0) = 0, g = c$.

20.6. For functions f(x, y), g(x, y) of two variables, this means we have to solve a system with three equations and three unknowns:

$$\begin{array}{rcl} f_x(x_0, y_0) &=& \lambda g_x(x_0, y_0) \\ f_y(x_0, y_0) &=& \lambda g_y(x_0, y_0) \\ g(x, y) &=& c \end{array}$$

20.7. To find a maximum, solve the Lagrange equations and add a list of critical points of g on the constraint. Then pick a point where f is maximal among all points. We don't bother with a second derivative test. But here is a possible statement:

$$\frac{d^2}{dt^2} D_{tv} D_{tv} f(x_0)|_{t=0} < 0$$

for all v perpendicular to $\nabla g(x_0)$, then x_0 is a local maximum.

20.8. Of course, the case of maxima and minima are analog. If f has a maximum on g = c, then -f has a minimum at g = c. We can have a maximum of f under a smooth constraint $S = \{g = c\}$ without that the Lagrange equations are satisfied. An example is f(x, y) = x and $g(x, y) = x^3 - y^2$ shown in Figure (3).

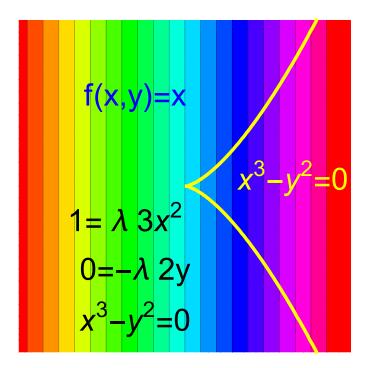


FIGURE 3. An example of a function, where the Lagrange equations do not give the minimum, here (0, 0). It is a case, where $\nabla g = 0$.

20.9. The method of Lagrange can maximize functions f under several constraints. Lets show this in the case of a function f(x, y, z) of three variables and two constraints g(x, y, z) = c and h(x, y, z) = d. The analogue of the Fermat principle is that at a maximum of f, the gradient of f is in the plane spanned by ∇g and ∇h . This leads to the **Lagrange equations** for 5 unknowns x, y, z, λ, μ . Linear Algebra and Vector Analysis

$$\begin{array}{rcl} f_x(x_0, y_0, z_0) &=& \lambda g_x(x_0, y_0, z_0) + \mu h_x(x_0, y_0, z_0) \\ f_y(x_0, y_0, z_0) &=& \lambda g_y(x_0, y_0, z_0) + \mu h_y(x_0, y_0, z_0) \\ f_z(x_0, y_0, z_0) &=& \lambda g_z(x_0, y_0, z_0) + \mu h_z(x_0, y_0, z_0) \\ g(x, y, z) &=& c \\ h(x, y, z) &=& d \end{array}$$

20.10. For example, if $f(x, y, z) = x^2 + y^2 + z^2$ and $g(x, y, z) = x^2 + y^2 = 1$, h(x, y, z) = x + y + z = 4, then we find points on the ellipse g = 1, h = 4 with minimal or maximal distance to 0.

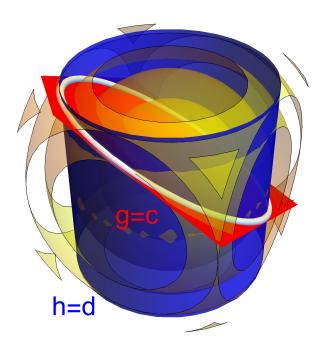


FIGURE 4. We see a situation where we try to maximize a function f under two constraints. In this case the intersection g = c, h = d is an ellipse.

EXAMPLES

20.11. Problem: Minimize $f(x, y) = x^2 + 2y^2$ under the constraint $g(x, y) = x + y^2 = 1$. Solution: The Lagrange equations are $2x = \lambda$, $4y = \lambda 2y$. If y = 0 then x = 1. If $y \neq 0$ we can divide the second equation by y and get $2x = \lambda$, $4 = \lambda 2$ again showing x = 1. The point x = 1, y = 0 is the only solution.

20.12. Problem: Which cylindrical soda can of height h and radius r has minimal surface A for fixed volume V? Solution: We have $V(r,h) = h\pi r^2 = 1$ and $A(r,h) = 2\pi rh + 2\pi r^2$. With $x = h\pi, y = r$, you need to optimize $f(x, y) = 2xy + 2\pi y^2$ under the constrained $g(x, y) = xy^2 = 1$. We will do that in class.

20.13. Problem: If $0 \le p_k \le 1$ is the probability that a dice shows k, then we have $g(p) = p_1 + p_2 + \cdots + p_6 = 1$. This vector p is called a **probability distribution**. The **Shannon entropy** of p is defined as

$$S(p) = -\sum_{i=1}^{6} p_i \log(p_i) = -p_1 \log(p_1) - p_2 \log(p_2) - \dots - p_6 \log(p_6) .$$

Find the distribution p which maximizes entropy S. Solution: $\nabla f = (-1 - \log(p_1), \ldots, -1 - \log(p_n)), \nabla g = (1, \ldots, 1)$. The Lagrange equations are $-1 - \log(p_i) = \lambda, p_1 + \cdots + p_6 = 1$, from which we get $p_i = e^{-(\lambda+1)}$. The last equation $1 = \sum_i \exp(-(\lambda + 1)) = 6 \exp(-(\lambda + 1))$ fixes $\lambda = -\log(1/6) - 1$ so that $p_1 = p_2 = \cdots = p_6 = 1/6$. It is the fair dice that has maximal entropy. Maximal entropy means least information content.

20.14. Assume that the probability that a physical or chemical system is in a state k is p_k and that the energy of the state k is E_k . Nature minimizes the **free energy**

$$F(p_1,\ldots,p_n) = -\sum_i [p_i \log(p_i) - E_i p_i]$$

if the energies E_i are fixed. The probability distribution p_i satisfying $\sum_i p_i = 1$ minimizing the free energy is called a **Gibbs distribution**. Find this distribution in general if E_i are given. **Solution:** $\nabla f = (-1 - \log(p_1) - E_1, \ldots, -1 - \log(p_n) - E_n),$ $\nabla g = (1, \ldots, 1)$. The Lagrange equation are $\log(p_i) = -1 - \lambda - E_i$, or $p_i = \exp(-E_i)C$, where $C = \exp(-1 - \lambda)$. The constraint $p_1 + \cdots + p_n = 1$ gives $C(\sum_i \exp(-E_i)) = 1$ so that $C = 1/(\sum_i e^{-E_i})$. The **Gibbs solution** is $p_k = \exp(-E_k)/\sum_i \exp(-E_i)$.

20.15. If f is a quadratic function on \mathbb{R}^m and g is linear that is $f(x) = Bx \cdot x/2$ with $B \in M(m,m)$ and if the constraint g(x) = Ax = c is linear $A \in M(1,m)$, then $\nabla f(x) = Bx$ and $\nabla g(x) = A^T$. Lets call $b = A^T \in M(m,1) \sim \mathbb{R}^m$. The Lagrange equations are then $Bx = \lambda b$, Ax = c. We see in general that for quadratic f and linear g, we end up with a **linear system of equations**.

20.16. Related to the previous remark is the following observation. It is often possible to reduce the Lagrange problem to a problem without constraint. This is a point of view often taken in economics. Let us look at it in dimension 2, where we extremize f(x, y) under the constraint g(x, y) = 0. Define $F(x, y, \lambda) = f(x, y) - \lambda g(x, y)$. The Lagrange equations for f, g are now equivalent to $\nabla F(x, y, \lambda) = 0$ in three dimensions.

¹This example is from Rufus Bowen, Lecture Notes in Math, 470, 1978

Homework

Problem 20.1: Find the cylindrical basket which is open on the top has has the largest volume for fixed area π . If x is the radius and y is the height, we have to maximize $f(x, y) = \pi x^2 y$ under the constraint $g(x, y) = 2\pi xy + \pi x^2 = \pi$. Use the method of Lagrange multipliers.

Problem 20.2: Given a $n \times n$ symmetric matrix B, we look at the function $f(x) = x \cdot Bx$. and look at extrema of f under the constraint that $g(x) = x \cdot x = 1$. This leads to an equation

$$Bx = \lambda x$$

A solution x is called an **eigenvector**. The Lagrange constant λ is an **eigenvalue**. Find the solutions to $Bx = \lambda x$, |x| = 1 if B is a 2×2 matrix, where $f(x, y) = ax^2 + (b + c)xy + dy^2$ and $g(x, y) = x^2 + y^2$. Then solve the problem with a = 4, b = 1, c = 1, d = 4.

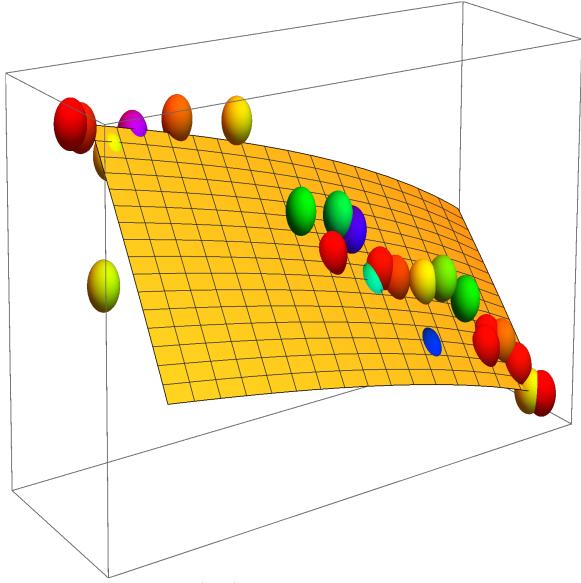
Problem 20.3: Which pyramid of height *h* over a square $[-a, a] \times [-a, a]$ with surface area is $4a\sqrt{h^2 + a^2} + 4a^2 = 4$ has maximal volume $V(h, a) = 4ha^2/3$? By using new variables (x, y) and multiplying *V* with a constant, we get to the equivalent problem to maximize $f(x, y) = yx^2$ over the constraint $g(x, y) = x\sqrt{y^2 + x^2} + x^2 = 1$. Use the later variables.

Problem 20.4: Motivated by the Disney movie "Tangled", we want to build a hot air balloon with a cuboid mesh of dimension x, y, z which together with the top and bottom fortifications uses wires of total length g(x, y, z) = 6x + 6y + 4z = 32. Find the balloon with maximal volume f(x, y, z) = xyz.

Problem 20.5: A solid bullet made of a half sphere and a cylinder has the volume $V = 2\pi r^3/3 + \pi r^2 h$ and surface area $A = 2\pi r^2 + 2\pi r h + \pi r^2$. Doctor Manhattan designs a bullet with fixed volume and minimal area. With $g = 3V/\pi = 1$ and $f = A/\pi$ he therefore minimizes $f(h,r) = 3r^2 + 2rh$ under the constraint $g(h,r) = 2r^3 + 3r^2h = 1$. Use the Lagrange method to find a local minimum of f under the constraint g = 1.

20.17. The mathematician and economist **Charles W. Cobb** at Amherst college and the economist and politician **Paul H. Douglas** who was also teaching at Amherst, found in 1928 empirically a formula $F(K, L) = L^{\alpha}K^{\beta}$ which fits the **total production** F of an economic system as a function of the **capital investment** K and the **labor** L. The two authors used logarithms variables and assumed linearity to find α, β . Below are the data normalized so that the date for year 1899 has the value 100.

| Y ear | K | L | P |
|-------|-----|-----|-----|
| 1899 | 100 | 100 | 100 |
| 1900 | 107 | 105 | 101 |
| 1901 | 114 | 110 | 112 |
| 1902 | 122 | 118 | 122 |
| 1903 | 131 | 123 | 124 |
| 1904 | 138 | 116 | 122 |
| 1905 | 149 | 125 | 143 |
| 1906 | 163 | 133 | 152 |
| 1907 | 176 | 138 | 151 |
| 1908 | 185 | 121 | 126 |
| 1909 | 198 | 140 | 155 |
| 1910 | 208 | 144 | 159 |
| 1911 | 216 | 145 | 153 |
| 1912 | 226 | 152 | 177 |
| 1913 | 236 | 154 | 184 |
| 1914 | 244 | 149 | 169 |
| 1915 | 266 | 154 | 189 |
| 1916 | 298 | 182 | 225 |
| 1917 | 335 | 196 | 227 |
| 1918 | 366 | 200 | 223 |
| 1919 | 387 | 193 | 218 |
| 1920 | 407 | 193 | 231 |
| 1921 | 417 | 147 | 179 |
| 1922 | 431 | 161 | 240 |



The graph of $F(L, K) = L^{3/4} K^{1/4}$ fits pretty well that data set. You can see in the data that there is an out-layer.

20.18. Assume that the labor and capital investment are bound by the additional constraint $G(L, K) = L^{3/4} + K^{1/4} = 50$. (This function G is unrelated to the function F(L, K) as we are in a Lagrange problem.) Where is the production P maximal under this constraint? Plot the two functions F(L, K) and G(L, K).

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