# ATV12H075M2

variable speed drive, Altivar 12, 0.75kW, 1hp, 200 to 240V, 1 phase, with heat sink



Main	
Range of product	Altivar 12
Product or component type	Variable speed drive
Product specific application	Simple machine
Mounting mode	Cabinet mount
Communication port protocol	Modbus
Supply frequency	50/60 Hz +/- 5 %
[Us] rated supply voltage	200240 V - 1510 %
Nominal output current	4.2 A
Motor power hp	1 hp
Motor power kW	0.75 kW
Motor power hp	1 hp
EMC filter	Integrated
IP degree of protection	IP20

#### Complementary

Complementary		
Discrete input number	4	
Discrete output number	2	
Analogue input number	1	
Analogue output number	1	
Relay output number	1	
Physical interface	2-wire RS 485	
Connector type	1 RJ45	
Continuous output current	4.2 A at 4 kHz	
Method of access	Server Modbus serial	
Speed drive output frequency	0.5400 Hz	
Speed range	120	
Sampling duration	20 Ms, tolerance +/- 1 ms for logic input 10 ms for analogue input	
Linearity error	+/- 0.3 % of maximum value for analogue input	
Frequency resolution	Analog input: converter A/D, 10 bits Display unit: 0.1 Hz	
Time constant	20 ms +/- 1 ms for reference change	
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s	
Transmission frame	RTU	
Number of addresses	1247	
Data format	8 bits, configurable odd, even or no parity	
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/Write multiple registers (23) 4/4 words Read device identification (43)	
Type of polarization	No impedance	
4 quadrant operation possible	False	

Asynchronous motor control profile	Quadratic voltage/frequency ratio Voltage/Frequency ratio (V/f) Sensorless flux vector control
Maximum output frequency	4 kHz
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor
Acceleration and deceleration ramps	Linear from 0 to 999.9 s U S
Motor slip compensation	Preset in factory Adjustable
Switching frequency	216 kHz adjustable 416 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	False
Line current	10.2 A at 100 V (heavy duty) 8.5 A at 120 V (heavy duty)
Maximum input current	8.5 A
Maximum output voltage	240 V
Apparent power	2.0 kVA at 240 V (heavy duty)
Maximum transient current	6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty)
Network frequency	5060 Hz
Relative symmetric network frequency tolerance	5 %
Prospective line Isc	1 kA
Base load current at high overload	4.2 A
Power dissipation in W	Natural: 44.0 W
With safety function Safely Limited Speed (SLS)	False
With safety function Safe brake management (SBC/SBT)	False
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	False
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	False
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t
Tightening torque	0.8 N.m
Insulation	Electrical between power and control
Quantity per set	Set of 1
Width	72 mm
Height	143 mm
Depth	131.2 mm
Net weight	0.8 kg

#### Environment

Environment	
Operating altitude	> 10002000 m with current derating 1 % per 100 m <= 1000 m without derating
Operating position	Vertical +/- 10 degree
Product certifications	NOM[RETURN]CSA[RETURN]C- Tick[RETURN]UL[RETURN]GOST[RETURN]RCM[RETURN]KC
Marking	CE
Standards	UL 508C UL 618000-5-1 IEC 61800-5-1 IEC 61800-3
Assembly style	With heat sink
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Surge immunity test level 3 conforming to IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz
Overvoltage category	Class III
Regulation loop	Adjustable PID regulator
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to IEC 61800-3 216 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to IEC 61800-3 212 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to IEC 61800-3 2, 4 and 16 kHz shielded motor cable <10 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to IEC 61800-3 412 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to IEC 61800-3 412 kHz shielded motor cable <50 m
Vibration resistance	1 gn (f = 13200 Hz) conforming to IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) - drive unmounted on symmetrical DIN rail - conforming to IEC 60068-2-6
Shock resistance	15 gn conforming to IEC 60068-2-27 for 11 ms
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
Noise level	0 dB
Pollution degree	2
Ambient air transport temperature	-2570 °C
Ambient air temperature for operation	-1040 °C without derating 4060 °C with current derating 2.2 % per °C
Ambient air temperature for storage	-2570 °C
Packing Units	
Unit Type of Package 1	PCE

Unit Type of Package 1	PCE	
Number of Units in Package 1	1	
Package 1 Height	11.700 cm	
Package 1 Width	19.000 cm	
Package 1 Length	19.500 cm	
Package 1 Weight	1.118 kg	
Unit Type of Package 2	P06	

Number of Units in Package 2	45	
Package 2 Height	75.000 cm	
Package 2 Width	60.000 cm	
Package 2 Length	80.000 cm	
Package 2 Weight	63.085 kg	

# Offer Sustainability

REACh Regulation	REACh Declaration	
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)	
Mercury free	Yes	
China RoHS Regulation	China RoHS Declaration	
RoHS exemption information		
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	

# Contractual warranty

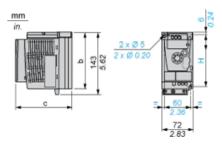
1.1	
Warranty	18 months
varianty	To monate

# Product data sheet Dimensions Drawings

# ATV12H075M2

# **Dimensions**

## Drive without EMC Conformity Kit



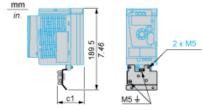
#### Dimensions in mm

b	С	Н
130	131.2	120

#### Dimensions in in.

b	С	н
5.12	5.16	4.72

# Drive with EMC Conformity Kit



#### Dimensions in mm

c1	
63	

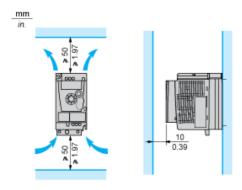
#### Dimensions in in.

с1	
2.48	

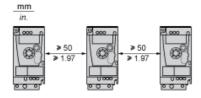
# ATV12H075M2

## Mounting Recommendations

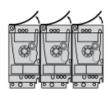
## Clearance for Vertical Mounting



# Mounting Type A

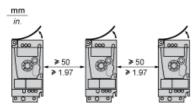


## Mounting Type B



Remove the protective cover from the top of the drive.

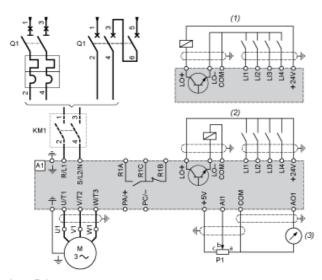
## Mounting Type C



Remove the protective cover from the top of the drive.

# ATV12H075M2

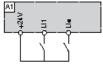
#### Single-Phase Power Supply Wiring Diagram



- A1 Drive
- KM1 Contactor (only if a control circuit is needed)
- P1 2.2 k $\Omega$  reference potentiometer. This can be replaced by a 10 k $\Omega$  potentiometer (maximum).
- Q1 Circuit breaker
- (1) Negative logic (Sink)
- (2) Positive logic (Source) (factory set configuration)
- (3) 0...10 V or 0...20 mA

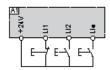
#### **Recommended Schemes**

## 2-Wire Control for Logic I/O with Internal Power Supply



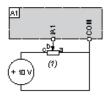
LI1 : Forward LI• : Reverse A1 : Drive

#### 3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive

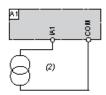
#### Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2  $k\Omega$ ...10  $k\Omega$  reference potentiometer

À1: Drive

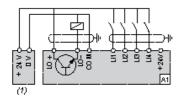
# Analog Input Configured for Current with Internal Power Supply



0-20 mA 4-20 mA supply

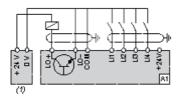
À1: Drive

## Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdo A1 : Drive 24 vdc supply

# Connected as Negative Logic (Sink) with External 24 vdc supply



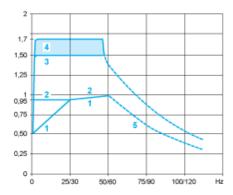
(1) 24 vdc supply

A1: Drive

# Product data sheet Performance Curves

# ATV12H075M2

## **Torque Curves**



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.