Binary Classification Using Fast Gaussian Filtering Algorithm

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Abstract

Speed up binary classification on 2D/3D using the Gaussian kernel faster than C-SVMs if # of data is 150,000+.

Training (pre-computation): $O(n^3) \rightarrow O(4^d n \log^{2d} n)$ Prediction: $O(n) \rightarrow O(4^d \log^{2d} n)$



Existing Work

C-SVM is a good binary classifier, but

- learning takes $O(n^3)$ time,
- prediction takes O(n) time.

We cannot use C-SVMs if # of data gets large.

Solution

- **Training:** $O(n^3) \rightarrow We \text{ don't learn.}$ But it takes $O(4^d n \log^{2d} n)$ for pre-computation.
- Treat every datum equally.
 - For future works,
 - we want to pretend learning of C-SVM, though.

Prediction: $O(n) \rightarrow O(4^d \log^{2d} n)$ Speed it up using our fast Gaussian filtering algorithm.

Outline

- Fast Gaussian filtering algorithm (FGFA)
 A fundamental algorithm of this study
- 2. Binary classification using FGFA
 - Extension of the previous work for binary classification
- 3. Evaluations
- 4. Conclusions

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Benefit of FGFA

The fast Gaussian filtering algorithm computes one Gaussian-filtered pixel in constant time to the area size $n (\propto \sigma^2)$.



The naïve method requires O(n) time.

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Key Ideas of FGFA

- The Gaussian function can be approximated with a spline.
- Splines become discrete if they are differentiated some times.
- Convolution of an image and a spline would be computed fast since convolution of an image and a discrete function is easy.

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Gaussian Function

The Gaussian filter is computed by convolutions with the 2D Gaussian function.



where a parameter σ is variance.

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Approximation



Approximation of 2D

$$\tilde{\psi}(x,y) = \tilde{\psi}(x)\tilde{\psi}(y)$$



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1. Fast Gaussian Filtering Algorithm

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Properties of the Function

- It is a 2nd order spline.
 - Piecewise polynomial function
- It has only 2% approximation error $-(\int |\tilde{\psi}(x) \psi(x)| dx) / (\int |\psi(x)| dx)$
- It has only 4 control points
- It has unequal intervals of control points while general approximation functions often have equal intervals.
 - It is sufficiently optimized as a spline.

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Benefit of Splines

Differentiating splines, they get constant.



The Gaussian-like function can also become discrete!

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Speed Up of Convolution

Convolution can be reduced by differentiating splines until they become discrete.



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Transformation

Transform convolution into summation

$$\begin{aligned} (\tilde{\psi} * I)(x) &= \sum_{\Delta x \in \mathbb{Z}} \tilde{\psi}(\Delta x) I(x - \Delta x) \\ &= \sum_{\Delta x \in \mathbb{Z}} \left(\sum_{i=0}^{m} a_i (\Delta x - b_i)_+^n \right) I(x - \Delta x) \\ &= \left(\sum_{i=0}^{m} a_i J(x - b_i) \right), \ J(x) = \left(\sum_{\Delta x \in \mathbb{Z}} \Delta x_+^n I(x - \Delta x) \right) \end{aligned}$$

$$O(m) \text{ linear combination Pre-computed}$$

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2D Convolution

The 2D Gaussian function is decomposed:

$$\exp\left(-\frac{x^2+y^2}{2\sigma^2}\right) = \exp\left(-\frac{x^2}{2\sigma^2}\right)\exp\left(-\frac{y^2}{2\sigma^2}\right)$$

The approximation can be defined as:

$$(\tilde{\psi} * I)(x, y) = \sum_{i=1}^{m} a_i \sum_{j=1}^{m} a_j J(x - b_i, y - b_j)$$

where $J(x,y) = \sum_{(\Delta x,\Delta y) \in \mathbb{Z}^2_+} \Delta x^n \Delta y^n I(x - \Delta x, y - \Delta y)$

 $O(m^2)$ linear combination \checkmark

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Overview of FGFA

Using J(x,y), which is an integrated image of an input image, we can compute every pixel apart in constant time to the area size.



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Naïve FGFA

If we regard 2D/3D spaces as images, we can determine the class of any point in constant time using the naïve FGFA.



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Problem

Data of images (especially 3D images) exhaust memory resources.

If the size of each coordinate is 1000, # of blocks gets 10⁹. This is often lager than # of training data.



Goal

Extend FGFA to apply to sparse images.

However, FGFA computes this expression:

$$(\tilde{\psi} * I)(x, y) = \sum_{i=1}^{m} a_i \sum_{j=1}^{m} a_j J(x - b_i, y - b_j)$$

 $J(x,y) = \sum_{(\Delta x,\Delta y) \in \mathbb{Z}_+^2} \Delta x^n \Delta y^n I(x - \Delta x, y - \Delta y)$

Badly, J(x,y) cannot be pre-computed because of memory space.

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What Is J(x)?

J(x) is an integrated array of an input I(x).



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What Is J(x,y)?

J(x,y) is an extend version of J(x) for 2D.

If such I(x,y) is given, J(x,y) gets...

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What Is J(x,y)?



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Solution

The proposed method builds a data structure that can answer J(x,y) fast using range trees.

Task:

Answer J(x,y) fast, but you cannot have the size of combinations of coordinate values.

$$J(x,y) = \sum_{(\Delta x,\Delta y) \in \mathbb{Z}^2_+} \Delta x^n \Delta y^n I(x - \Delta x, y - \Delta y)$$

Many combinations Sparse

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Range Tree

A *d*-dimensional range tree can compute the total sum in a box \mathbf{x}_1 - \mathbf{x}_2 in $O(\log^d n)$ time with $O(n\log^d n)$ space.



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Deformation of J(x)

Range tree can give
$$\sum_{i=a,\dots,b} f(x)I(x)$$
,

but J is $\sum_{i=0,\dots,a} (a-x)^n I(x)$, which contains *a*.

It can be deformed into:

$$\sum_{i=0,\cdots,a} (a-x)^2 I(x) = \sum_{\substack{i=0,\cdots,a \\ i=0,\cdots,a}} x^2 I(x)$$
$$-2a \sum_{\substack{i=0,\cdots,a \\ i=0,\cdots,a}} x I(x)$$
$$+a^2 \sum_{\substack{i=0,\cdots,a \\ i=0,\cdots,a}} I(x)$$

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Deformation of J(x)

Example (1D case):

If you want to calculate $J(3/4) \left(\frac{3}{4} - x\right)_{+}^{2}$,

you can calculate it using three K:

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Deformation of J(x,y)

Range tree can give:

$$K_{i,j}(x,y) = \sum_{(\Delta x, \Delta y) \in \{(0,0), \cdots, (x,y)\}} \Delta x^i \Delta y^j I(\Delta x, \Delta y).$$

Using this, J can be computed with:

$$J(x,y) = \begin{pmatrix} y^2 \\ -2y \\ 1 \end{pmatrix}^{\mathrm{T}} \begin{pmatrix} K_{0,0}(x,y) & K_{1,0}(x,y) & K_{2,0}(x,y) \\ K_{0,1}(x,y) & K_{1,1}(x,y) & K_{2,1}(x,y) \\ K_{0,2}(x,y) & K_{1,2}(x,y) & K_{2,2}(x,y) \end{pmatrix} \begin{pmatrix} x^2 \\ -2x \\ 1 \end{pmatrix}$$

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Binary Classifier

The proposed binary classifier can decide the class of any point in $O(4^d \log^{2d} n)$ time, and the pre-computation is $O(4^d n \log^{2d} n)$ time.



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December 1, ALSIP 2012 **3. Evaluations**

Relations to C-SVM

Objective function of C-SVM: max: $\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j y_i y_j \exp\left(-\frac{|x_i - x_j|^2}{\sigma^2}\right),$ s.t.: $0 \le \alpha_i \le C \ (i = 1, \cdots, n), \ \sum \alpha_i y_i = 0,$ i=1Proposed method: $\max: \quad \sum \alpha_i,$ s.t.: $0 < \alpha_i \leq C \ (i = 1, \dots, n).$

– The solution is $\alpha_i = C$.

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Experiments for Accuracy

Accuracy of binary classification:

	Proposed	C-SVM					
	Method	C = 0.1	C = 1	C = 10	$C = 10^{6}$		
$\sigma = 0.1$	93%	58%	68%	69%	69%		
$\sigma = 0.3$	93%	83%	94%	93%	93%		
$\sigma = 1$	93%	93%	95%	93%	92%		
$\sigma = 3$	86%	90%	94%	95%	89%		
$\sigma = 10$	84%	85%	90%	93%	92%		

Figure Accuracy for Iris Flower Data Set

It is not so worse than C-SVM.

Experiments for Time

CPU time of training and prediction:

# of training data		1,000	10,000	100,000	1,000,000
Proposed	Prediction	2.43 ms	2.48 ms	$2.55 \mathrm{ms}$	2.96 ms
method	(Precomputation)	(0.13 s)	(1.48 s)	(17.8 s)	(203 s)
LIBSVM	Prediction	0.02 ms	$0.22 \mathrm{\ ms}$	$2.29 \mathrm{\ ms}$	23.6 ms
	(Training)	(0.05 s)	(4.47 s)	(442 s)	(1000 + s)

Figure Time of Training and Prediction for 2D Data

The proposed method is faster when # of training data is over 150,000.

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Conclusions

We proposed a new binary classifier.

- It is not so worse than C-SVM, and it can also speed up prediction of C-SVM.
- Pre-computation is O(4^dnlog^{2d}n) time, and prediction is O(4^dlog^{2d}n) time.

The proposed method consists of

- Fast Gaussian filtering algorithm,
- Range trees.