

Utility of silicone filtering for diffusive model CO₂ sensors in field experiments

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ABSTRACT

Installing a diffusive model CO₂ sensor in the soil is a direct and useful method to observe the time variation of gas CO₂ concentration in soil. Furthermore, it requires no bulky measurement system. A hydrophobic silicone filter prevents water infiltration. Therefore, a sensor whose detection element is covered with a silicone filter can be durable in the field even when experiencing inundation (e.g. farmland with snow melting, wetland with varying water level). The utility of a diffusive model of CO₂ sensor covered with silicone filter was examined in laboratory and field experiments. Applying the silicone filter delays the response to change in ambient CO₂ concentration, which results from lower gas permeability than those of other conventionally used filters made of materials, such as polytetrafluoroethylene. Theoretically, apart from the precision of the sensor itself, diurnal variation of soil gas CO₂ concentration is calculable from obtained series of data with a silicone-covered sensor with negligible error. The error is estimated at approximately 1% of the diurnal amplitude in most cases of a 10-min logging interval. Drastic changes that occur, such as those of a rainfall event, cause a larger gap separating calculated and real values. However, the proportion of this gap to the extent of the drastic increase was extremely small (0.43% for a 10-min logging interval). For accurate estimation, a smoothly varied data series must be prepared as input data. Using a moving average or applying a fitting curve can be useful when using a sensor or data logger with low resolution. Estimating the gas permeability coefficient is crucial for calculation. The gas permeability coefficient can be estimated through laboratory experiments. This study revealed the possibility of evaluating the time variation of soil gas CO₂ concentration by installing a diffusive model of silicone-covered sensor in an inundated field.

Keywords: calculating backward, gas permeability, hydrophobic material, inundation, soil gas CO₂

1. Introduction

Installing a diffusion model CO₂ sensor in the soil is one method to measure the gas CO₂ concentration in the soil (e.g. Hirano et al., 2003; Tang et al., 2003; Chen et al., 2005; Liang et al., 2010; Pingintha et al., 2010). One important benefit of this method is that it can directly measure the time variation with high resolution. Moreover, it does not disturb the soil pores because of its artificial air flow once it is installed. Different from occasional manual observation, this measurement can be implemented irrespective of weather conditions. However, this method is usually inapplicable to a flooded field (e.g. farmland with snow melt, wetland with varying water levels).

Nevertheless, some studies have sampled soil gas from hydrophobic silicone tubes installed in the soil, and subsequently measured CO₂ concentrations of the sampled gas in

a laboratory (e.g. Holter, 1990; Syväsalö et al., 2004; Yanai et al., 2011). Using such a method, sampling can be done in waterlogged or temporary saturated fields, and spatial averages can be found using a certain length tube. DeSutter et al. (2006) reported another important feature: silicone is cheaper than other hydrophobic materials. Yanai and Tokida (2009) reported that the silicone tube permeability is higher than that of other hydrophobic materials, although the gas permeability of silicone is lower than that of widely used polytetrafluoroethylene (PTFE), which cannot be used under waterlogged conditions. However, this occasional measurement cannot evaluate time variation in high resolution.

Some studies have used silicone (or other hydrophobic material) tubes or tubes covered with silicone in the soil to analyse CO₂ concentrations by circulating or flushing the air in the tube to the equipped analyser. This method can be operated automatically. However, this measurement system is bulky and needs several additional materials (e.g. gas cylinder, pump) (e.g. Flechard et al., 2007; Panikov et al., 2007).

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Other reports have described studies that have used diffusive-type CO₂ sensors covered with hydrophobic (e.g. silicone, Teflon) membrane (Jassal et al. 2004; Deppe et al. 2010), but the reports do not describe the inherent permeating time lag. To evaluate the time variation accurately, this lag must be considered.

This study examined the practical application of a silicon-covered sensor in field experiments, especially how accurately the variation of soil gas CO₂ concentration can be estimated from the series of data obtained with a silicone-covered sensor.

2. Measurements

Two 98 × 64 × 35 mm ($W \times D \times H$) BEC-CO2SA sensor boxes (Baron Electric Co. Inc., Tokyo, Japan) were used. An infrared gas sensor module for CO₂ sensing (CO₂ Engine K30; SenseAir, Delsbo, Sweden) is installed in this CO₂ sensor box. This module uses a non-dispersive infrared absorption (NDIR) method for CO₂ sensing. Electricity consumption is 0.48 W with a 12-V current. The sensing volume is $8.0 \times 10^{-5} \text{ m}^3$. The measurement range is 0–5000 ppm with 1–5 V output and accuracy of $\pm 30 \text{ ppmv} \pm 5\%$ of measured values. The response time to 63% of a signal is 20 s. The output depends only slightly on the ambient temperature. Initially, a 4-cm diameter air vent was sealed with a cellulose filter using a rubber O-ring from the inside. The vent is protected from the outside by an aluminium mesh. The thickness and gas permeability coefficient for CO₂ (Q , $\text{mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$) of the cellulose filter, for which data are provided from the manufacturer, are $1.60 \times 10^{-4} \text{ m}$ and 1.03×10^{-3} , respectively (Q_{cel} , $\text{mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$). These values reflect that the cellulose filter prevents gas permeation only slightly. A silicone filter prevents gas permeation only slightly. A silicone filter was installed on one of the two sensors instead of a cellulose filter. The silicone filter thickness is $5.0 \times 10^{-4} \text{ m}$. The information of Q of the silicone filter (Q_{sil} , $\text{mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$) is not available from the manufacturer.

For laboratory experiments, two CO₂ sensor boxes with cellulose and silicone filter were placed in a 1950 ml plastic container (Fig. 1). Cables for the signal and power supply from the sensor boxes exited through the drilled hole of the plastic container. Reference gases were injected through the urethane tube (4-mm inner diameter) to the plastic container. The air exits through the urethane tube attached at the other side. The gas was closed using a stopcock attached to the tubes. N₂ and air-balanced CO₂ standard (1930 ppmv) gases were injected by turns. Gaps were sealed with epoxy resin adhesive to prevent gas leaks. The sensor output was recorded every 10 s using a voltage recorder (VR-71; T&D, Nagano, Japan). Its resolution was 5 mV or more. To remove periodical electric noise every minute,

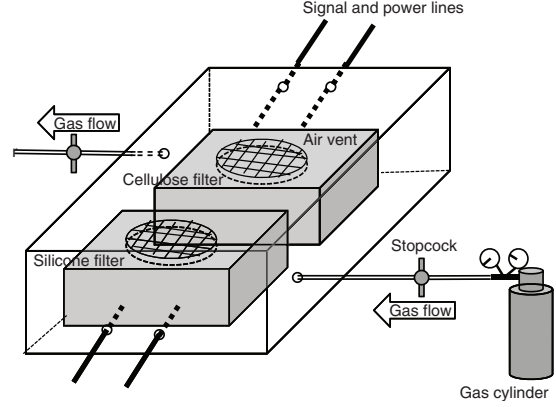


Fig. 1. Schematic of laboratory experiment.

a moving average of six data was used. Ambient air temperature was recorded every minute using a thermo-recorder (TR-72S; T&D, Nagano, Japan). The temperature was assumed to vary linearly among recorded data.

As for field experiments, the two sensor boxes were installed with cellulose and silicone filter at 10 cm depth of bare soil. The sensors were placed with the air vent side downward. The sensor output was recorded every 10 min by averaging the 10 outputs at every minute using a data logger (CR1000; Campbell Scientific Inc., Logan, UT, USA) with a resolution of 1333 μV . Soil temperature at 10 cm depth was measured using a copper–constantan thermocouple. Precipitation was measured using a tipping-bucket rain gauge (Model 52202; R. M. Young Co., Traverse City, MI, USA). These were recorded every 10 min. Soil temperature was recorded by averaging the 60 outputs every 10 s. Data from 2–3 October 2011 and 5–6 October 2011 were used.

3. Calculation

I assumed that no driving force causes significant advective flow through the membrane, and that gas permeation velocity v (mol s^{-1}) is expressed as the following widely used equation (e.g. Brandrup and Immergut, 1989):

$$v = A \frac{Q}{\delta} \Delta p \quad (1)$$

where A (m^2) is the polymeric membrane filter area, δ (m) is the membrane thickness, and Δp (kPa) is the difference of membrane partial pressure (inside vs. outside). In this study, CO₂ concentration was assumed to be uniform inside the sensor. At time t (s), assuming atmospheric pressure in the sensor $P_{(t)}$ (kPa) is equivalent to that in the soil, $v_{(t)}$ is expressed as

$$v_{(t)} = A \frac{Q}{\delta} P_{(t)} \frac{C_{\text{soil}(t)} - C_{\text{room}(t)}}{10^6} \quad (2)$$

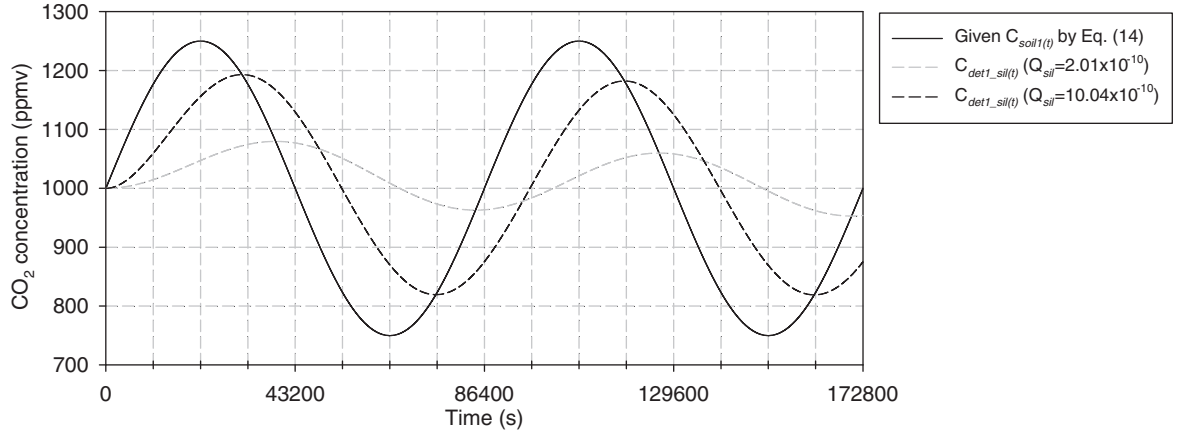
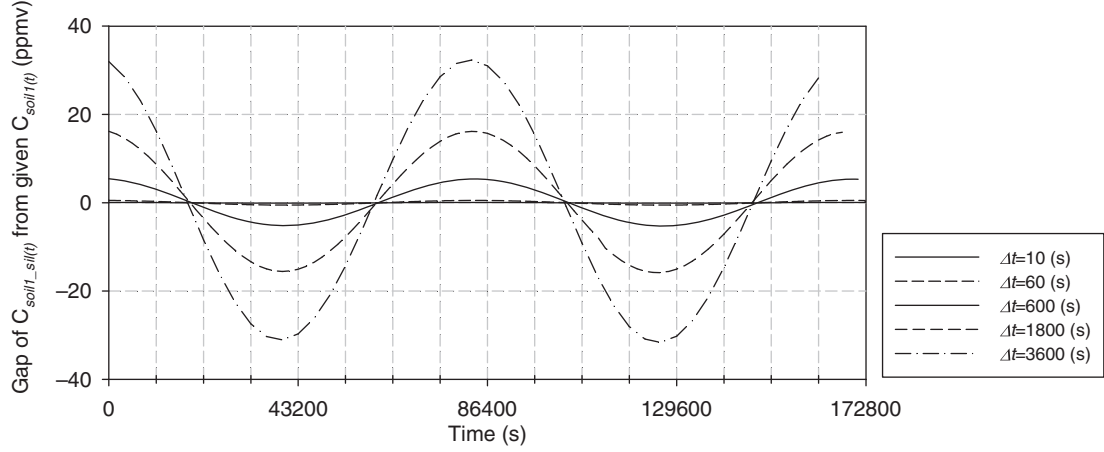
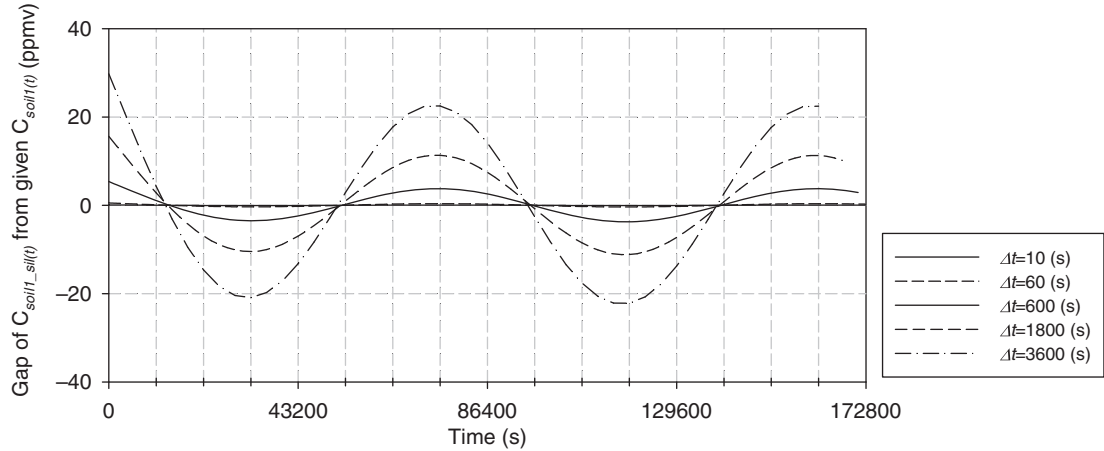
(a) Variation of given $C_{soil(t)}$ and $C_{det1_sil(t)}$ (b) Gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$ using $Q_{sil}=2.01 \times 10^{-10}$ (c) Gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$ using $Q_{sil}=10.04 \times 10^{-10}$ 

Fig. 2. (a) Time variations of given $C_{soil(t)}$ (black solid line) by eq. (14) and $C_{det_sil(t)}$ with $Q_{sil} = 2.01 \times 10^{-10}$ and 10.04×10^{-10} mol m⁻² s⁻¹ kPa⁻¹ (grey dashed line and black dashed line, respectively); (b) Time variation of the gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$, using $Q_{sil} = 2.01 \times 10^{-10}$ mol m⁻² s⁻¹ kPa⁻¹ and eq. (13). A negative value means that $C_{soil_sil(t)}$ is smaller than the given $C_{soil(t)}$. Five lines for five logging intervals (10 s, 1 min, 10 min, 30 min and 60 min) are shown; and (c) Time variation of the gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$, using $Q_{sil} = 10.04 \times 10^{-10}$ mol m⁻² s⁻¹ kPa⁻¹ and eq. (13). Lines are depicted as (b).

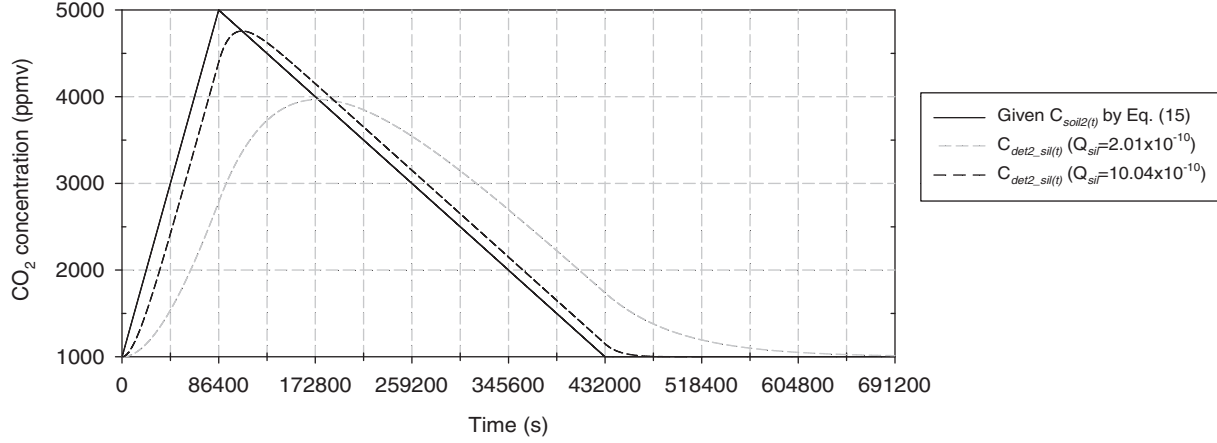
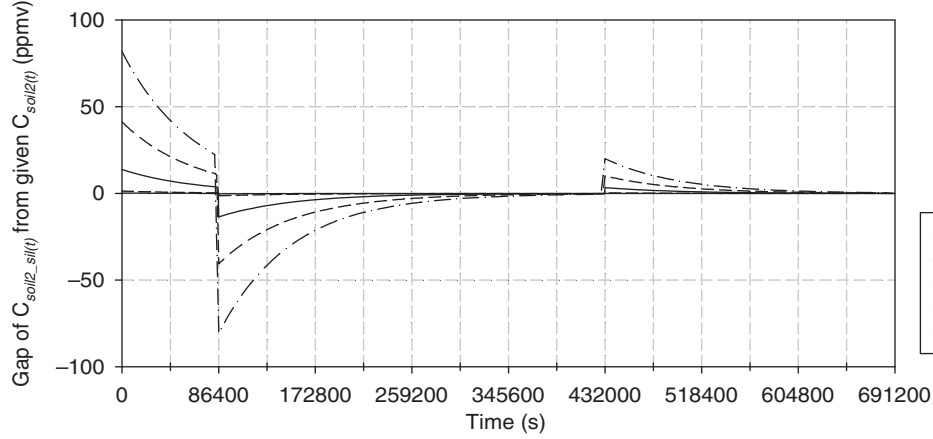
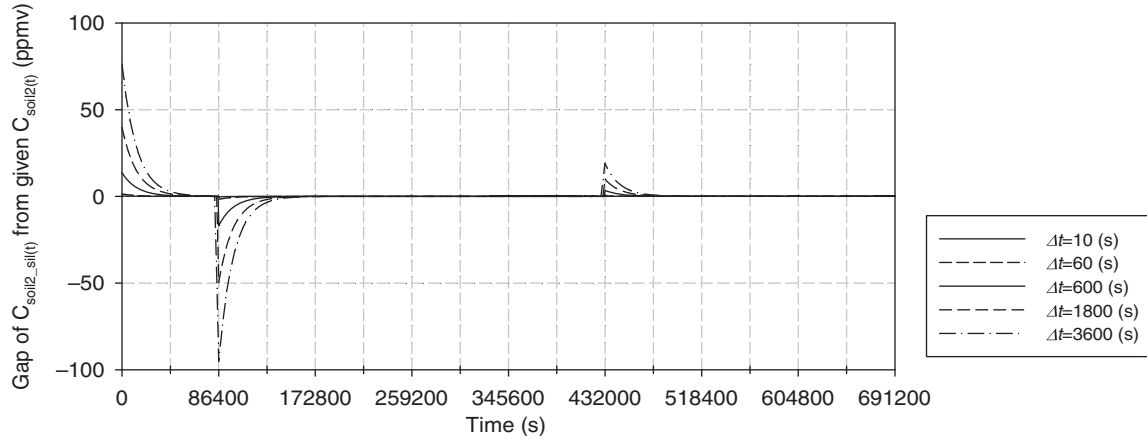
(a) Variation of given $C_{soil2(t)}$ and $C_{det2_sil(t)}$ (b) Gap of $C_{soil2_sil(t)}$ from given $C_{soil2(t)}$, using $Q_{sil}=2.01 \times 10^{-10}$ (c) Gap of $C_{soil2_sil(t)}$ from given $C_{soil2(t)}$, using $Q_{sil}=10.04 \times 10^{-10}$ 

Fig. 3. (a) Time variations of given $C_{soil(t)}$ (black solid line) by eq. (15) and $C_{det_sil(t)}$ with $Q_{sil} = 2.01 \times 10^{-10}$ and 10.04×10^{-10} mol m m⁻² s⁻¹ kPa⁻¹ (grey dashed line and black dashed line, respectively); (b) Time variation of the gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$, using $Q_{sil} = 2.01 \times 10^{-10}$ mol m m⁻² s⁻¹ kPa⁻¹ and eq. (13); (c) Time variation of the gap of $C_{soil_sil(t)}$ from given $C_{soil(t)}$, using $Q_{sil} = 10.04 \times 10^{-10}$ mol m m⁻² s⁻¹ kPa⁻¹ and eq. (13). Lines are depicted as Fig. 2.

where $C_{\text{soil}(t)}$ (ppmv) and $C_{\text{room}(t)}$ (ppmv) denote the CO₂ concentrations in the soil and the sensing room, respectively. At this time, assuming that CO₂ gas is always distributed uniformly in the sensing room, the number of moles of total gases $N_{\text{total}(t)}$ (mol) in the sensing room of the sensor is expressed as follows:

$$N_{\text{total}(t)} = \frac{P_{(t)} V}{RT_{(t)}} \quad (3)$$

where R represents the gas constant 8.31×10^{-3} (kPa m³ mol⁻¹ K⁻¹), $T_{(t)}$ (K) represents temperature, and V (m³) represents the sensing volume inside the sensor. Therefore, the rate of increase in the CO₂ concentration in the sensing room $C'_{\text{room}(t)}$ (ppmv s⁻¹) is expressed by the following equation:

$$\begin{aligned} C'_{\text{room}(t)} &= \frac{v_{(t)}}{N_{\text{total}(t)}} \times 10^6 \\ &= \frac{v_{(t)} RT_{(t)} / P_{(t)}}{V} \times 10^6 \\ &= \frac{AQRT_{(t)}}{\delta V} \{C_{\text{soil}(t)} - C_{\text{room}(t)}\} \end{aligned} \quad (4)$$

$C'_{\text{room}(t)}$ can be assumed to be constant during the micro time period (from t to $t + \Delta t$). Probable errors depending on the scale of Δt are shown in Sections 4.1 and 4.2. In this case, the increase in CO₂ concentration in the sensing room from at t to at $t + \Delta t$ can be expressed as $C'_{\text{room}(t)} \Delta t$. Therefore, at time Δt (s) after time t , the CO₂ concentration in the sensing room is as follows:

$$\begin{aligned} C_{\text{room}(t+\Delta t)} &= C_{\text{room}(t)} + \frac{AQRT_{(t)}}{\delta V} \{C_{\text{soil}(t)} - C_{\text{room}(t)}\} \Delta t \\ &= \frac{AQRT_{(t)}}{\delta V} \Delta t C_{\text{soil}(t)} + \left\{1 - \frac{AQRT_{(t)}}{\delta V} \Delta t\right\} C_{\text{room}(t)} \end{aligned} \quad (5)$$

Transforming this equation, $C_{\text{soil}(t)}$ is the value shown below.

$$\begin{aligned} C_{\text{soil}(t)} &= \frac{\delta V}{AQRT_{(t)}} \frac{1}{\Delta t} \{C_{\text{room}(t+\Delta t)} - C_{\text{room}(t)}\} + C_{\text{room}(t)} \\ &= \frac{\delta V}{AQRT_{(t)}} \frac{1}{\Delta t} C_{\text{room}(t+\Delta t)} + \left\{1 - \frac{\delta V}{AQRT_{(t)}} \frac{1}{\Delta t}\right\} C_{\text{room}(t)} \end{aligned} \quad (6)$$

To express the response character of the detector, which finally outputs the signal of CO₂ concentration, there are some conceivable response functions (e.g. Robert, 1993). I applied the simple time response function in the first-order system because of the limited technical information of the sensor. After the CO₂ concentration in the room is replaced with C_{room} at $t=0$ from the state

that the sensor stably outputs the constant CO₂ concentration in the room ($C_{\text{det}(0)}$), $C_{\text{det}(t)}$ would be expressed as follows:

$$C_{\text{det}(t)} = C_{\text{det}(0)} + \{C_{\text{room}} - C_{\text{det}(0)}\} \{1 - \exp(-at)\} \quad (7)$$

where $C_{\text{det}(t)}$ is the detected CO₂ concentration (ppmv), C_{room} is a constant, and a is a coefficient. The CO₂ sensor specifications imply the following equation:

$$0.63 = 1 - \exp(-20a) \quad (8)$$

At this time,

$$a = -\frac{\ln 0.37}{20} \approx 0.0497 \quad (9)$$

The rate of increase in the detected CO₂ concentration $C'_{\text{det}(t)}$ (ppmv s⁻¹) is calculated from the time derivative of both sides in eq. (7). Furthermore, constant C_{room} is replaced with $C_{\text{room}(t)}$ because $C_{\text{room}(t)}$ is assumed to be constant during the micro time period Δt for each calculation step.

$$C'_{\text{det}(t)} = a \{C_{\text{room}(t)} - C_{\text{det}(t)}\} \quad (10)$$

Transforming this equation, $C_{\text{room}(t)}$ is expressed as shown as follows:

$$\begin{aligned} C_{\text{room}(t)} &= \frac{1}{a} C'_{\text{det}(t)} + C_{\text{det}(t)} \\ &= \frac{1}{a} \frac{C_{\text{det}(t+\Delta t)} - C_{\text{det}(t)}}{(t+\Delta t) - t} + C_{\text{det}(t)} \\ &= \frac{1}{a\Delta t} C_{\text{det}(t+\Delta t)} + \left\{1 - \frac{1}{a\Delta t}\right\} C_{\text{det}(t)} \\ &\Leftrightarrow C_{\text{det}(t+\Delta t)} = a\Delta t C_{\text{room}(t)} + (1 - a\Delta t) C_{\text{det}(t)} \end{aligned} \quad (11)$$

When a cellulose filter is used, $C_{\text{soil}} = C_{\text{room}}$ can be assumed. This is because the cellulose filter prevents gas permeation only slightly as described in Section 2. Therefore,

$$C_{\text{soil}(t)} = \frac{1}{a\Delta t} C_{\text{det}(t+\Delta t)} + \left\{1 - \frac{1}{a\Delta t}\right\} C_{\text{det}(t)}. \quad (12)$$

Combining eqs. (6) and (11), $C_{\text{soil}(t)}$ is expressed as follows:

$$\begin{aligned}
 C_{\text{soil}(t)} &= \frac{\delta V}{AQRT_{(t)}\Delta t} \left[\frac{1}{a\Delta t} C_{\text{det}(t+2\Delta t)} + \left\{ 1 - \frac{1}{a\Delta t} \right\} C_{\text{det}(t+\Delta t)} \right] \\
 &+ \left\{ 1 - \frac{\delta V}{AQRT_{(t)}\Delta t} \right\} \left[\frac{1}{a\Delta t} C_{\text{det}(t+\Delta t)} + \left\{ 1 - \frac{1}{a\Delta t} \right\} C_{\text{det}(t)} \right] \\
 &= \frac{\delta V}{AQRT_{(t)}\Delta t} \left\{ \frac{1}{a\Delta t} C_{\text{det}(t+2\Delta t)} + \frac{a\Delta t - 1}{a\Delta t} C_{\text{det}(t+\Delta t)} \right\} \\
 &+ \frac{AQRT_{(t)}\Delta t - \delta V}{AQRT_{(t)}\Delta t} \left\{ \frac{1}{a\Delta t} C_{\text{det}(t+\Delta t)} + \frac{a\Delta t - 1}{a\Delta t} C_{\text{det}(t)} \right\} \\
 &= \frac{1}{aAQRT_{(t)}(\Delta t)^2} \left[\begin{aligned} &\delta VC_{\text{det}(t+2\Delta t)} \\ &+ \left\{ \delta V(a\Delta t - 1) + AQRT_{(t)}\Delta t - \delta V \right\} C_{\text{det}(t+\Delta t)} \\ &+ (AQRT_{(t)}\Delta t - \delta V)(a\Delta t - 1)C_{\text{det}(t)} \end{aligned} \right] \\
 &= \frac{1}{aAQRT_{(t)}(\Delta t)^2} \left[\begin{aligned} &\delta VC_{\text{det}(t+2\Delta t)} \\ &+ \left\{ \delta V(a\Delta t - 2) + AQRT_{(t)}\Delta t \right\} C_{\text{det}(t+\Delta t)} \\ &+ (AQRT_{(t)}\Delta t - \delta V)(a\Delta t - 1)C_{\text{det}(t)} \end{aligned} \right] \quad (13)
 \end{aligned}$$

The precision with which $C_{\text{soil}(t)}$ was estimated was deduced theoretically with eq. (13) from recorded data of $C_{\text{det}(t)}$, depending on the length of the logging interval (i.e. Δt). According to a report by Lebovits (1966), Q_{sil} was 2.01×10^{-10} – $10.04 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$. These minimum and maximum values were used in this study for theoretical calculations.

Hereinafter, the outputs of the cellulose-covered and silicone-covered sensor are denoted as $C_{\text{det}_\text{cel}(t)}$ and $C_{\text{det}_\text{sil}(t)}$, respectively. $C_{\text{soil}(t)}$ is calculated from $C_{\text{det}_\text{cel}(t)}$ or $C_{\text{det}_\text{sil}(t)}$ using eq. (13). These calculated $C_{\text{soil}(t)}$ are represented as $C_{\text{soil}_\text{cel}(t)}$ and $C_{\text{soil}_\text{sil}(t)}$, respectively.

4. Results

4.1. Theoretical uncertainty of the calculated $C_{\text{soil}(t)}$ in diurnal variation

The diurnal variation of soil CO_2 concentration was assumed depending on the soil temperature, as expressed by the following equations:

$$\begin{aligned}
 C_{\text{soil}1(t)} &= 1000 + 250 \sin \left(2\pi \times \frac{t}{86400} \right) \\
 C_{\text{room}1(0)} &= 1000 \\
 C_{\text{det}1(0)} &= 1000 \\
 T_{1(t)} &= 20 + 2.5 \sin \left(2\pi \times \frac{t}{86400} \right) \quad (14)
 \end{aligned}$$

In these equations, $C_{\text{room}1(0)}$ and $C_{\text{det}1(0)}$ denote the initial recorded $C_{\text{room}1(t)}$ and $C_{\text{det}1(t)}$, respectively. Subscript '1' is used in this exercise (e.g. $C_{\text{soil}1(t)}$, $C_{\text{room}1(t)}$, $C_{\text{det}1(t)}$ and $T_{1(t)}$). $C_{\text{det}_\text{sil}(t)}$ was calculated as follows. First, this author set $C_{\text{room}(0)} = C_{\text{soil}(0)}$ and $C_{\text{det}(0)} = C_{\text{soil}(0)}$ and then set $\Delta t = 1$ (s) and calculated $C_{\text{room}(t)}$ and $C_{\text{det}(t)}$ step-by-step every second.

Second, this author calculated $C_{\text{room}(t+\Delta t)}$ using the data $C_{\text{soil}(t)}$ and $C_{\text{room}(t)}$ with eq. (5). Finally, this author calculated $C_{\text{det}(t+2\Delta t)}$ using the data $C_{\text{room}(t+\Delta t)}$ and $C_{\text{det}(t+\Delta t)}$ with eq. (11), replacing t with $t+\Delta t$. In this exercise, $\Delta t = 1$ is assumed to be a sufficiently short interval for calculation because a negligible gap (less than $1.1 \times 10^{-7}\%$) exists between calculated $C_{\text{det}1(t)}$ with $\Delta t = 1$ and that with $\Delta t = 0.2$ (data not shown), and this result implies that calculated $C_{\text{det}1(t)}$ with infinitesimal Δt has insignificant difference with calculated $C_{\text{det}1(t)}$ with $\Delta t = 1$. Such diurnal variation described by $C_{\text{soil}1(t)}$, was described in earlier studies (e.g. Tang et al., 2003; Chen et al., 2005; Panikov et al., 2007; DeSutter et al., 2008). For this study, 10 s, 1 min, 10 min, 30 min and 1 hr were set as logging intervals.

The variation of given $C_{\text{soil}1(t)}$ by eq. (14) and $C_{\text{det}1_\text{sil}(t)}$ is presented in Fig. 2a. The second positive peak of $C_{\text{det}_\text{sil}(t)}$ lags that of $C_{\text{soil}1(t)}$ 10 392–18 297 s (about 3–5 h). The value depends on Q_{sil} . The gap separating $C_{\text{soil}1(t)}$ and $C_{\text{det}1_\text{sil}(t)}$ is 172.5–250.7 ppmv at most, whereas the gap separating $C_{\text{soil}1(t)}$ and $C_{\text{det}1_\text{cel}(t)}$ is 0.367 ppmv at most. Figure 2b and c shows the gap of $C_{\text{soil}_\text{sil}(t)}$ at each logging interval from $C_{\text{soil}1(t)}$. A negative value signifies that $C_{\text{soil}_\text{sil}(t)}$ is less than $C_{\text{soil}1(t)}$. Apart from the gap at the beginning, the gap is 5.4 ppmv, which is equivalent to 1.08% of the amplitude of $C_{\text{soil}1(t)}$, at $\Delta t = 600$.

4.2. Theoretical uncertainty of the calculated $C_{\text{soil}(t)}$ during a rainfall event

The sudden increase and decrease in soil CO_2 concentration caused by rainfall events are assumed to be expressed as the following equations:

$$\begin{aligned}
 C_{\text{soil}2(t)} &= 1000 + 4000 \times \frac{t}{86400} \quad (0 \leq t < 86400) \\
 C_{\text{soil}2(t)} &= 6000 - 1000 \times \frac{t}{86400} \quad (86400 \leq t < 432000) \\
 C_{\text{soil}2(t)} &= 1000 \quad (432000 \leq t) \\
 C_{\text{room}2(t)} &= 1000 \\
 C_{\text{det}2(t)} &= 1000 \\
 T_{2(t)} &= 20 \quad (15)
 \end{aligned}$$

In these equations, $C_{\text{room}2(0)}$ and $C_{\text{det}2(0)}$ denote the initial recorded $C_{\text{room}2(t)}$ and $C_{\text{det}2(t)}$, respectively. Subscript '2' is used in this exercise as in Section 4.1. $C_{\text{det}2(t)}$ was calculated as in Section 4.1. In this exercise, I also assumed that $\Delta t = 1$ is a sufficiently short interval for calculating $C_{\text{det}2(t)}$. The gap separating calculated $C_{\text{det}2(t)}$ with $\Delta t = 1$ and that with $\Delta t = 0.2$ is also negligible ($5.8 \times 10^{-4}\%$, data not shown).

Such variation was shown in earlier studies as well (e.g. Chen et al., 2005; DeSutter et al., 2008). Five logging

intervals were set as examining diurnal variation. The variation of given $C_{\text{soil}2(t)}$ by eq. (15) and $C_{\text{det}2_sil(t)}$ is depicted in Fig. 3a. The positive peak of $C_{\text{det}2_sil(t)}$ delays from those of $C_{\text{soil}2(t)}$ 20 952–89 175 s (about 6–25 h). The gap of $C_{\text{det}2_sil(t)}$ from $C_{\text{soil}2(t)}$ ranges from –2213 to 738 ppmv with $Q_{\text{sil}} = 2.01 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$, and from –602 to 151 ppmv with $Q_{\text{sil}} = 10.04 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$, whereas the gap separating $C_{\text{soil}2(t)}$ and $C_{\text{det}2_cel(t)}$ is 0.93 ppmv at most. Figure 3b and c shows the gap of $C_{\text{soil}2_sil(t)}$ at each logging interval from $C_{\text{soil}2(t)}$. The gap is 17.1 ppmv at most at $\Delta t = 600$, which is equivalent to a 0.43% increase from initial $C_{\text{soil}2(t)}$ (1000 ppmv) to the peak (5000 ppmv). The gap becomes large when the change in increasing (or decreasing) rate of $C_{\text{soil}2(t)}$ becomes large, especially around the positive peak.

4.3. Laboratory experiment

The variations of $C_{\text{det_cel}(t)}$ and $C_{\text{det_sil}(t)}$ are presented for comparison in Fig. 4a. Every time after introducing

reference gas, $C_{\text{det_cel}(t)}$ and $C_{\text{det_sil}(t)}$ had approached the CO₂ concentration outside the plastic container (approximately 400 ppmv), which is expected to be true because gas penetrates through epoxy resin adhesive or urethane tube to some degree. As might be assumed, $C_{\text{det_sil}(t)}$ lagged $C_{\text{det_cel}(t)}$. Hereinafter, $C_{\text{soil_cel}(t)}$ and $C_{\text{soil_sil}(t)}$ represent the calculated CO₂ concentrations in the plastic container. $C_{\text{det}(t)}$ depends only on the responsivity of the sensor, as expressed in eq. (12). Therefore, $C_{\text{det_cel}(t)}$ was assumed to be calculable from $C_{\text{soil_cel}(t)}$ without significant error.

Q_{sil} was calculated as follows. First, $C_{\text{soil_cel}(t)}$ was calculated with obtained $C_{\text{det_cel}(t)}$ and eq. (13). Furthermore, treating Q_{sil} as an unknown variable, I assumed that $C_{\text{soil_sil}(t)}$, which was calculated from obtained $C_{\text{det_sil}(t)}$ and eq. (13), overlaps $C_{\text{soil_cel}(t)}$. Finally, I obtained the answer $Q_{\text{sil}} = 11.5 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$ using the least squares method. $C_{\text{soil_sil}(t)}$ varied fluctuating with width of about 900 ppmv (grey line in Fig. 4b). If $C_{\text{soil_sil}(t)}$ was calculated from the series of 60-data (10 min) moving averages of $C_{\text{det_sil}(t)}$, then the fluctuation was settled.

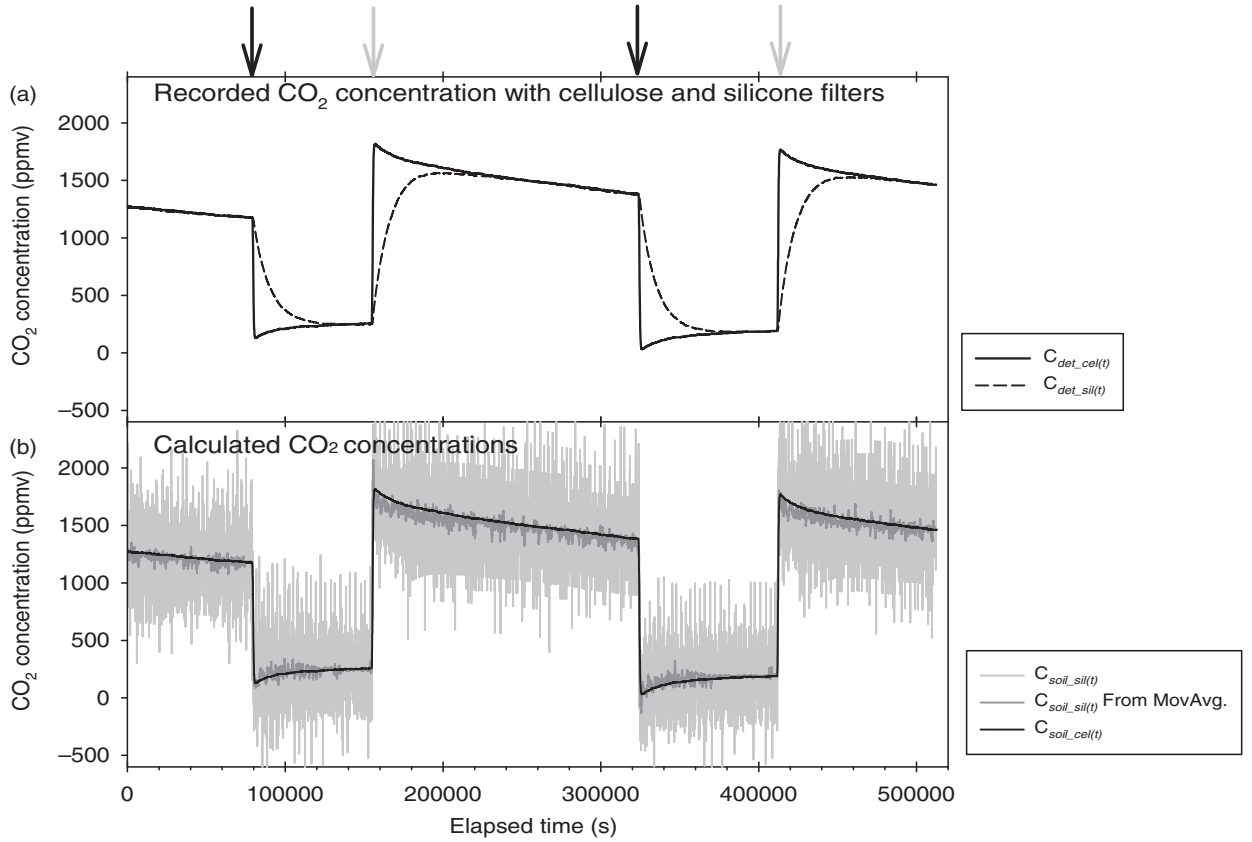


Fig. 4. (a) Time variation of $C_{\text{det_cel}(t)}$ (solid line) and $C_{\text{det_sil}(t)}$ (dashed line) responding to CO₂ concentration in the container. Black and grey arrows respectively indicate the time to infuse the N₂ and air-balanced CO₂ standard (1930 ppmv) gases; and (b) time variation of $C_{\text{soil_sil}(t)}$ (grey line), $C_{\text{soil_sil}(t)}$ calculated from 60-data (10 min) moving averages of $C_{\text{det_sil}(t)}$ (dark grey line) and $C_{\text{soil_cel}(t)}$ (black line). These variations are calculated with $Q_{\text{sil}} = 11.5 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$. Black solid lines do not denote the moving average of the grey solid line. $C_{\text{soil_sil}(t)}$ and $C_{\text{soil_cel}(t)}$ are calculated with eq. (13).

4.4. Field experiment

Figures 5 and 6 present results of field experiments. Observed diurnal variation and increment of CO_2 concentration because rainfall is indicated, respectively, in Fig. 5 and 6. Both in Fig. 5 and 6, the belated and gentle increase (and decrease) of $C_{\text{det_sil}(t)}$ were observed compared to $C_{\text{det_cel}(t)}$. Using the calculated $Q_{\text{sil}} (= 11.5 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1})$ in Section 4.3, the variation of $C_{\text{soil_sil}(t)}$ was synchronised with that of $C_{\text{soil_cel}(t)}$. The rate of change in $C_{\text{soil_sil}(t)}$ was similar to that in $C_{\text{soil_cel}(t)}$, but some gap existed between their absolute values. $C_{\text{soil_sil}(t)}$ had some fluctuation, but it was settled by calculation from the series of six-data (60 min) moving averages of $C_{\text{det_sil}(t)}$.

5. Discussions

5.1. Theoretical uncertainty

Strictly speaking, $\Delta t = 600$ might not be applicable to the equations which lead to $C_{\text{soil}(t)}$ under the assumption that Δt is micro time. However, in the case of $\Delta t = 600$, theoretical calculation indicated that diurnal variation of soil CO_2 gas

concentration can be evaluated with a silicone-covered CO_2 sensor without marked error. Regarding a sudden increase (or decrease) in CO_2 gas concentration mainly caused by rainfall event, a silicone-covered CO_2 sensor evaluates soil gas CO_2 concentration with a larger gap than in the case of diurnal variation. However, the proportion of this gap to the extent of increase was small. The degree of these errors depends on the pattern and scale of the variation, but the reliable variations of CO_2 soil gas concentration were revealed by the obtained data.

5.2. Practical application

In field experiments, a gap separating $C_{\text{soil_cel}(t)}$ and $C_{\text{soil_sil}(t)}$ remained, which might indicate the spatial variation of soil CO_2 gas concentration: an unavoidable shortcoming of one-point measurement. In addition to responsiveness, it is necessary to tackle this issue.

In both laboratory and field experiments, the variations of $C_{\text{soil_sil}(t)}$ were similar to those of $C_{\text{soil_cel}(t)}$. The exact gas permeability coefficient, as inferred from laboratory experiments, is indispensable to evaluate the exact variation of soil gas CO_2 concentration. Figures 2 and 3 show that

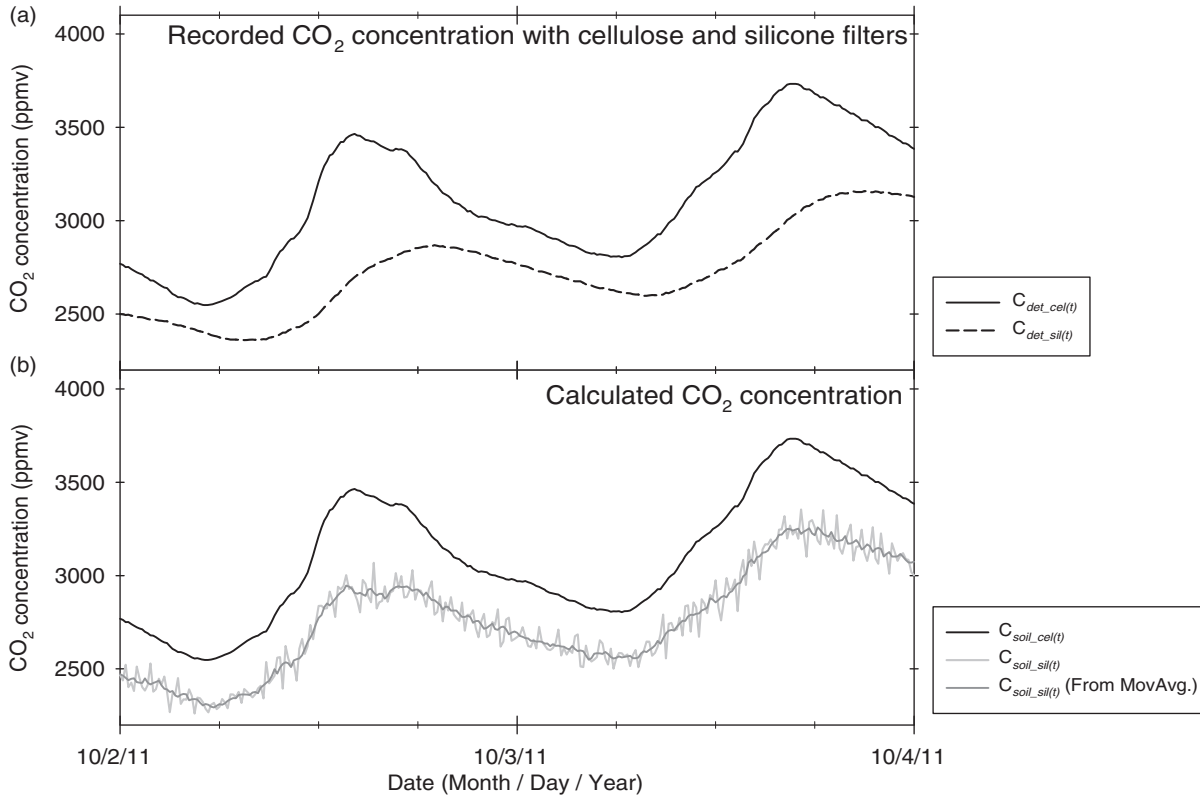


Fig. 5. Observed diurnal variations of CO_2 concentration in the field experiment. (a) $C_{\text{det_cel}(t)}$ (solid line) and $C_{\text{det_sil}(t)}$ (dashed line); (b) $C_{\text{soil_cel}(t)}$ (black line), $C_{\text{soil_sil}(t)}$ (grey line) and $C_{\text{soil_sil}(t)}$ calculated from six-data (60 min) moving averages of $C_{\text{det_sil}(t)}$ (dark grey line). These variations are calculated with $Q_{\text{sil}} = 11.5 \times 10^{-10} \text{ mol m m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$. Black solid lines do not show the moving average of the grey solid line.

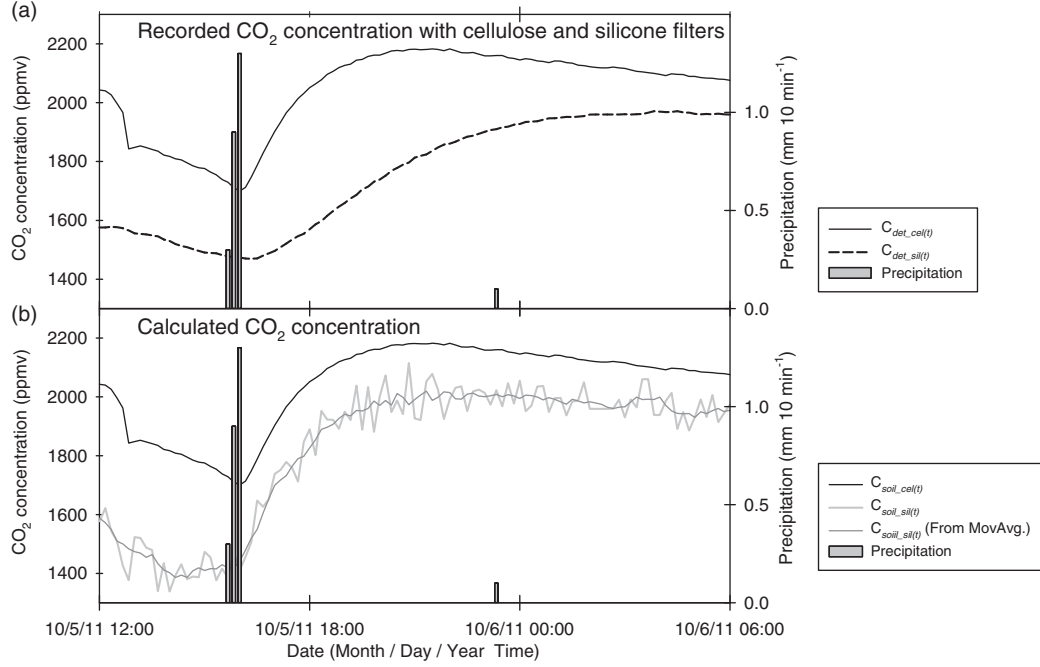


Fig. 6. Observed time variations of CO₂ concentration after rainfall in the field experiment. (a) $C_{det_cel(t)}$ (solid line) and $C_{det_sil(t)}$ (dashed line); and (b) $C_{soil_cel(t)}$ (black line), $C_{soil_sil(t)}$ (grey line) and $C_{soil_sil(t)}$ calculated from 6-data (60 min) moving averages of $C_{det_sil(t)}$ (dark grey line). These variations are calculated with $Q_{sil} = 11.5 \times 10^{-10} \text{ mol m}^{-2} \text{ s}^{-1} \text{ kPa}^{-1}$. Black solid lines do not show the moving average of the grey solid line.

the sensor responsivity depends strongly on Q_{sil} . My calculated Q_{sil} is slightly larger than the reference value reported by Lebovits (1966), but my calculated value can be regarded as a plausible value.

The fluctuations of $C_{soil_sil(t)}$ in the laboratory experiment were greater than those in the field experiment. This high level of fluctuation probably occurs because the degree of fluctuation of $C_{det_sil(t)}$ in the laboratory experiment was greater than that in the field experiment. Nevertheless, none of the variations of $C_{det_sil(t)}$ appear to fluctuate in the indicated time scale. This is related to the difference of resolutions between the data loggers. The CR1000 data logger resolution ($1333 \mu\text{V} = 1.67 \text{ ppmv}$) in the field experiment was better than that of VR-71 ($5 \text{ mV} = 6.25 \text{ ppmv}$) in the laboratory experiment. The notched variation of $C_{soil_sil(t)}$ reflects irregular variation attributable to low resolution of the data logger or sensor. Especially, low resolution of the data logger influenced the fluctuation of $C_{soil_sil(t)}$ in this study. The fluctuation of $C_{soil_sil(t)}$ can be alleviated using a moving average of the recorded data. Application of an approximation curve can also be useful.

6. Conclusions

The following conclusions were inferred from theoretical calculations, and from laboratory and field experiments. The observed variation in the CO₂ concentration by

silicone-installed sensor in soil is lagged and dampened compared with the real variation. However, the time variation of CO₂ concentration in soil was evaluated from the data series obtained using the silicone sensor. For accurate estimation overall, accurate estimation of the gas permeability of silicone is indispensable. A smoothly varying data series should be prepared, which means that a sensor and recording device with high accuracy and resolution must be used. Applying a fitting curve and using a moving average to smooth the obtained data are expected to be useful when using sensors and devices with lower precision. Although the introduced equations and assumptions include some uncertainty, they are available for evaluating the variation of gas CO₂ concentration in soil with recorded data every 10 min. The study results demonstrate that silicone-covered diffusive model CO₂ sensors are applicable to estimate the time variation of CO₂ concentrations in soil.

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