

Characterization of the planetary boundary layer during SAMUM-2 by means of lidar measurements

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ABSTRACT

Measurements with two Raman-depolarization lidars of the Meteorological Institute of the Ludwig-Maximilians-Universität, München, Germany, performed during SAMUM-2, were used to characterize the planetary boundary layer (PBL) over Praia, Cape Verde. A novel approach was used to determine the volume fraction of dust ν_d in the PBL. This approach primarily relies on accurate measurements of the linear depolarization ratio. Comparisons with independent in situ measurements showed the reliability of this approach. Based on our retrievals, two different phases could be distinguished within the measurement period of almost one month. The first (22–31 January 2008) was characterized by high aerosol optical depth (AOD) in the PBL and large $\nu_d > 95\%$. During the second phase, the AOD in the PBL was considerably lower and ν_d less than $\sim 40\%$. These findings were in very good agreement with ground based in situ measurements, when ambient volume fractions are considered that were calculated from the actual measurements of the dry volume fraction. Only in cases when dust was not the dominating aerosol component (second phase), effects due to hygroscopic growth became important.

1. Introduction

The planetary boundary layer (PBL) is the lowermost part of the troposphere, directly influenced by the Earth's surface. Its height varies strongly in time and space and can extend from a few hundred meters to a few kilometres (Stull, 1988). Aerosols found in the PBL typically show a large variability, e.g. with respect to the type, and the concentration of the aerosols. To improve our knowledge of the structure and extension of the boundary layer, numerous research activities have been pushed by modern remote sensing techniques (Schwiesow, 1984). Already in 1977 Kunkel et al. showed the potential of lidar systems for boundary layer studies, as they can determine the vertical distribution of aerosols and distinguish between different aerosol layers. Further studies, e.g. on convection in the PBL (Melfi et al., 1985), PBL-height (Strawbridge and Snyder, 2004, Wiegner et al., 2006), humidity fluxes (Kiemle

et al., 1997) and wind in the PBL (Hooper and Eloranta, 1986) followed. Matthias and Bösenberg (2002) used regular lidar data to establish an aerosol climatology of the PBL over Hamburg, and Murayama et al. (1999) analysed the effects of dust and sea-salt in the PBL by means of lidar depolarization measurements.

In this work we present lidar measurements of the Meteorological Institute (MIM), of the Ludwig-Maximilians-Universität (LMU), Munich, Germany, of aerosol optical properties in the PBL taken during the second field campaign of the Saharan Mineral Dust Experiment (SAMUM). The measurement site was located at the airport of Praia (14.92°N, 23.49°W, 75 m above sea level), the capital of the Cape Verde Islands in the Atlantic Ocean 500 km off the coast of Africa. The distance of the site to the eastern coast of the island was about 1000 m and about 4000 m to the southern coast of the island. It was free of buildings, vegetation or orographical barriers. Measurements were performed in January and February 2008. During this time of the year the Cape Verde Islands are mainly influenced by an easterly flow, advecting occasionally dust-loaded air-masses from the African continent and marine aerosols from the Atlantic Ocean.

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The lidar derived optical properties discussed in this paper include the aerosol optical depth (AOD), the lidar ratio (S_p), and the particle linear depolarization ratio (δ_p) at wavelengths $\lambda = 355$ and 532 nm, with the only exception that S_p at 532 nm was not available during January. Furthermore, based on the lidar measurements we determine the volume-concentrations of Saharan dust and sea-salt particles in the PBL, that means, sort of a mixing ratio of dust and sea-salt was derived. The characterization of the PBL during this campaign is important as it provides a link between column-integrated measurements (Toledano et al., 2011), ground based measurements (e.g. Schladitz et al., 2011a,b, Kandler et al., 2011a,b) and airborne in situ measurements (e.g. Weinzierl et al., 2011; Lieke et al., 2011) in lofted layers.

The organization of the paper is as follows. In Section 2, the measurement situation and the instrumentation are briefly described, in Section 3 we outline our methodology to derive optical properties and the volume fraction of dust. The results are discussed in detail in Section 4. A short summary concludes the paper.

2. Measurements and Instrumentation

To improve our knowledge about the optical, microphysical and chemical properties of Saharan dust, two field campaigns were conducted in the framework of SAMUM. The first one (SAMUM-1 – Tellus Special Issue, Volume 61, 2009) in May and June 2006 was carried out in Ouarzazate and Tinfou, Morocco, to characterize Saharan dust close to its source region. Measurements of the second campaign (SAMUM-2) were performed in 2008 at Cape Verde Islands for two reasons: first, to determine possible changes of Saharan dust within the first few days of its transport towards the Atlantic Ocean, and second to analyse Saharan dust mixed with other types of aerosols, e.g. sea salt and biomass burning aerosol. An overview of the activities during SAMUM-2 is given by Ansmann et al. (2011). The general weather conditions are described by Knippertz et al. (2011).

The Meteorological Institute MIM participated in SAMUM-2 with its two Raman- and depolarization lidar systems POLIS (Groß et al., 2008) and MULIS (Freudenthaler et al., 2009), and additionally with the sun- and sky-photometer SSARA (Toledano et al., 2009). POLIS (portable lidar system) is a small, modular, two channel lidar system. It is operating either in the Raman-mode, taking measurements of the elastic lidar return at 355 nm and of the inelastic N_2 -Raman shifted return at 387 nm or in the linear depolarization mode, measuring the co- and cross-polarized signals (with respect to the laser polarization plane) at 355 nm. The full overlap is at about 100 m. MULIS (multiwavelength lidar system) is a Raman- and linear depolarization lidar with elastic backscatter channels at 355 , 532 and 1064 nm, and inelastic N_2 -Raman channels at 387 and 607 nm. The linear depolarization ratio at 532 nm is derived from the

Table 1. System parameters of the depolarization channels of the lidar systems.

Lasers	MULIS Continuum, Surelite II	POLIS Big Sky, Brilliant Ultra
Wavelengths (nm)	1064, 532, 355	355
Puls energy (mJ)	175 + 50 + 175	7
Repetition rate (Hz)	10	20
Laser divergence (mrad)	0.6	0.69
Telescope	Cassegrain	Dall-Kirkham
Telescope diameter (m)	0.3	175
Focal length (m)	1.2	0.96
Field of view (mrad)	1 to 3.5	2.5
Detected wavelengths (nm)	1064, 532 _{par} , 355, 607, 387, 532 _{perp}	355, 387 or 355 _{par} , 355 _{perp}
Range resolution (m)	7.5	7.5

co- and cross-polarized signals. MULIS' ability to scan allowed us to better observe the lowermost parts of the atmosphere. Together with the inherent low overlap of POLIS, measurements from about 100 m above ground level (note that henceforward all altitudes are given above ground level) up to the free troposphere are possible and make the combination of MULIS and POLIS an outstanding tool for observations of the PBL. The range-resolution of the raw data of both lidars is 7.5 m, and the temporal average of the raw data is 10 s. Technical details of the lidar systems are listed in Table 1.

The sun- and sky-photometer SSARA provides measurements of direct spectral radiances at twelve wavelengths between 340 and 1550 nm, and scattered radiances from the almucantar geometry. Measurements are available for the whole SAMUM-2 campaign. However, high cloudiness often prevents the evaluation of the data. Radiosondes launched twice a day by the Leibniz Institute of Tropospheric Research (IfT) provided temperature- and pressure-profiles, which are required for the calibration of the lidar signals.

Measurements of both lidar systems were performed from 14 January to 9 February 2008, whenever possible simultaneously to allow the determination of the linear depolarization ratio at two wavelengths. The typical measurement times for the lidar systems were three hours before noon (morning session) and three hours after sunset (night session). During the morning sessions POLIS operated in the depolarization mode, whereas the night sessions were performed in the Raman-mode. Furthermore, additional depolarization measurements were often performed two hours before the night sessions. We would like to point out, that the lidar ratios S_p measured during the night sessions were used as input parameter for the retrieval of extinction coefficient profiles during daytime if we had sufficient

information on the temporal stability of the atmosphere. For this purpose, POLIS occasionally was operated continuously for a whole day documenting the temporal development of the aerosol distribution.

3. Methodology

Independent profiles of the particle extinction coefficient α_p and particle backscatter coefficient β_p are retrieved from lidar signal analysis according to the Raman-method (e.g. Ansmann et al., 1992). Consequently, the extinction-to-backscatter ratio (lidar ratio) S_p can be derived. As the signal-to-noise ratio of the Raman measurements is quite low due to high solar background during day, measurements of the Raman signals at 387 and 607 nm are reasonable at nighttime only. Another consequence of the low backscatter intensities is that the signals must be averaged over typically one to two hours. Note that averaging must take care of the atmosphere's temporal stability within this time slot. The resulting lidar ratios S_p are used as input for the well-established analytical algorithm (Fernald, 1984) to retrieve α_p from the elastic signals of day time measurements. As these signals have a much better signal-to-noise ratio, a better vertical resolution of the α_p - and β_p -profiles is provided. To investigate the temporal stability of the atmosphere between the day- and nighttime measurements (a prerequisite for the S_p extrapolation) we compared profiles of the retrieved extinction coefficient (Groß et al., 2011b), of the depolarization ratio, and the lidar ratio. The AOD of the PBL is derived from the integration of α_p -profiles assuming constant extinction below the height of full overlap.

Depolarization is described either as the volume linear depolarization ratio δ_v or the particle linear depolarization ratio δ_p . The former is achieved from the co- (P_p) and cross-polarized (P_s) returns according to $\delta_v = C \times P_p/P_s$ with C as the calibration factor that describes the different sensitivities of the involved lidar channels. The high co-polarized signal is detected in the reflected branch of the polarizing beam-splitter cube to reduce cross-talk. Polarizing filters behind the polarizing beam-splitter additionally suppress cross-talk. The calibration factor C is determined with the highly accurate $\pm 45^\circ$ -calibration method described by Freudenthaler et al. (2009), either with a half-wave-plate (MULIS) or by manually rotating the channels with respect to the laser polarization (POLIS). A mechanical limit stop assures the high accuracy of the last method. The particle linear depolarization ratio δ_p is derived according to Biele et al. (2000), it depends mainly on δ_v and β_p , i.e. an inversion of the lidar signals is required before δ_p can be assessed.

The values discussed in this paper are layer integrated mean values. Although δ_p and S_p are intensive parameters of the aerosols, low signal intensities lead to large uncertainties. To reduce these statistical uncertainties the layer mean values are weighted with the backscatter coefficient β_p (see eqs 1 and 2). The error bars show the mean systematic error calculated

according to Freudenthaler et al. (2009) for δ_p and Groß et al. (2011a) for S_p .

$$\overline{S_p} = \int_{r_1}^{r_2} \frac{\beta_p(r) \cdot S_p(r)}{\int_{r_1}^{r_2} \beta_p(r) dr} dr = \frac{\int_{r_1}^{r_2} \alpha_p(r) dr}{\int_{r_1}^{r_2} \beta_p(r) dr}. \quad (1)$$

$$\overline{\delta_p} = \int_{r_1}^{r_2} \frac{\beta_p(r) \cdot \delta_p(r)}{\int_{r_1}^{r_2} \beta_p(r) dr} dr. \quad (2)$$

We also determine the volume fraction v_d of dust in the PBL. For this purpose we use the ratio of the volume concentration of dust v_d and all particles v_p with volume concentration v_i defined as volume of the particles of type "i" per volume of air, and assume only two aerosol components: dust (subscript d) and marine aerosols (subscript m).

$$v_d = \frac{v_d}{v_d + v_m}. \quad (3)$$

The volume concentration v_i can be derived according to

$$v_i = \eta_i \cdot \alpha_i = \eta_i \cdot S_{p,i} \cdot \beta_i. \quad (4)$$

with η_i being the conversion factor from extinction to volume concentration. This factor can be determined if the microphysics of the aerosols are known, in particular the size distribution, the refractive index and the particle shape. We use conversion factors published by Hess et al. (1998) in the OPAC-database. Their conversion factor for dust of $c_d = 0.905 \times 10^{-6}$ m is based on the assumption of spherical particles. Gasteiger et al. (2011) have shown that in case of non-spherical dust particles this overestimates the true value, consequently we estimate $c_d = 0.7 \times 10^{-6}$ m for our evaluations. For the marine component, we use $c_m = 0.615 \times 10^{-6}$ m according to OPAC (maritime aerosols, 70% relative humidity). The lidar ratios of dust ($S_p = 58$ sr ± 7 sr at 355 nm and $S_p = 62$ sr ± 5 sr at 532 nm) and marine aerosols ($S_p = 18$ sr ± 4 sr at 355 nm and $S_p = 18$ sr ± 2 sr at 532 nm) are taken from Groß et al. (2011b). The backscatter coefficient profiles β_i of the two components are derived following the procedure described by Tesche et al. (2009). They found that if an aerosol ensemble consists of two components, their backscatter coefficients can be separated, provided that the linear depolarization ratios of the components are known. Adapted for our purposes, we can write for the backscatter coefficient of the dust β_d

$$\beta_d = \beta_p \frac{(\delta_p - \delta_m)(1 + \delta_d)}{(\delta_d - \delta_m)(1 + \delta_p)}. \quad (5)$$

The backscatter coefficient of the marine aerosols can easily be calculated from $\beta_m = \beta_p - \beta_d$.

The linear depolarization ratios are set to $\delta_d = 0.25$ at 355 nm and $\delta_d = 0.30$ at 532 nm for dust and $\delta_m = 0.02$ for marine aerosols at both wavelengths according to our findings from SAMUM-2 (Groß et al., 2011). With β_p and δ_p known from our lidar measurements, we can determine β_d according to eq.

(5). Inserting this into eq. (4) we finally derive the volume fraction of dust v_d according to eq. (3). The relative uncertainties of the volume fractions are estimated to be 20–30%. They mainly result from uncertainties of the lidar measurements and retrieval, and from uncertainties of the size distribution of the particles.

For comparison we also discuss volume fractions of mineral dust and marine aerosols as derived from ground-based in situ measurements performed during SAMUM-2. In Schladitz (2011a, b) the derivation of a ‘dry’ dust volume fraction v_d^{dry} is described. Based on this parameter, an ‘ambient’ volume fraction v_d^{amb} is derived from numerical models using measured particle number size distribution, hygroscopic mixing state information, and hygroscopic growth factors. In Schladitz (2011a) the particle number size distribution is described by two fine modes, representing the fine portion of the marine aerosol, and two coarse modes including an external mixture of sea salt and Saharan mineral dust. Using the method described in Schladitz (2011b), the hygroscopic growth factors and hence the ambient particle number size distribution at the actual relative humidity is determined. The size resolved hygroscopic mixing state information shown in fig. 11 in Schladitz (2011a) is used to separate the hydrophobic mineral dust fraction from the ambient particle number size distribution. Subsequently, from the respective volume concentrations of the marine and the dust aerosols, ambient volume fractions of dust and marine aerosol are calculated. The temporal resolution of the retrieved data is three hours, thus somewhat lower than the remote sensing data; on the other hand they are continuously available. The relative uncertainty of the volume fractions is roughly estimated from the calculated volume concentrations to be 20%. As a conclusion, v_d^{amb} is representative for the mixing state under the actual atmospheric conditions and thus, directly comparable to the volume fractions retrieved from remote sensing techniques. The dry volume fraction v_d^{dry} might differ from v_d^{amb} in case of hygroscopic particles and high relative humidity.

4. Properties of the Boundary Layer

Profiles of the relative humidity derived from the radiosonde data sets (not shown) and profiles of the optical properties from lidar measurements (Groß et al., 2011b; Tesche et al., 2011) were used to determine the height z_{PBL} of the upper boundary of the PBL. It is identified by a sharp decrease of the relative humidity and a change of the extensive and intensive optical properties. As a result, we found that z_{PBL} ranges between 0.3 and 0.8 km during SAMUM-2 (Fig. 1). The relative humidity within the PBL is higher than 60%, except for 6 February with a relative humidity of about 50%. Thus in all cases, sea-salt particles advected to Cape Verde from the Atlantic Ocean would still remain liquid at this relative humidity range. So we do not assume crystalline sea-salt particles in our characterization.

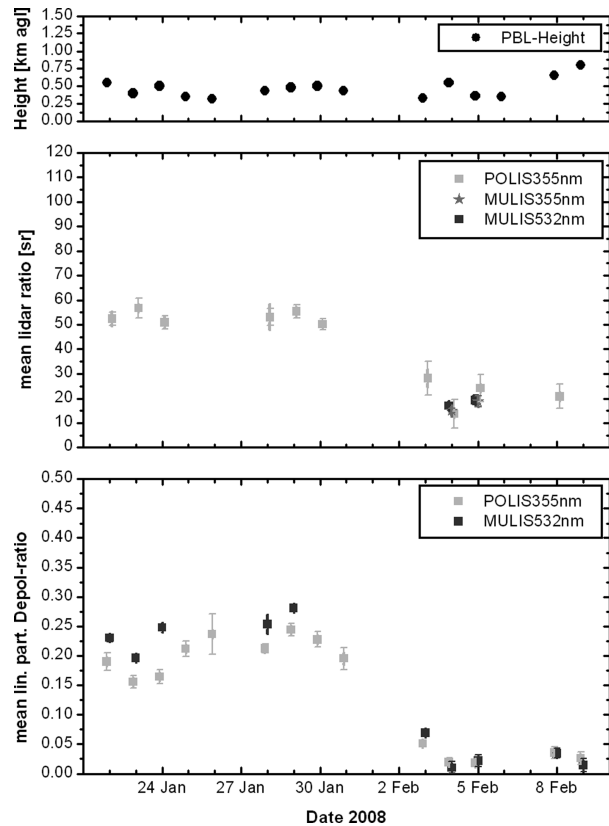


Fig. 1. PBL height (upper panel), and backscatter-weighted mean values of lidar ratio (middle panel) and of particle linear depolarization ratio (lower panel) in the PBL, measured with the lidar systems MULIS and POLIS. The thick lines show the standard deviation of the mean, the error bars indicate the mean systematic uncertainties.

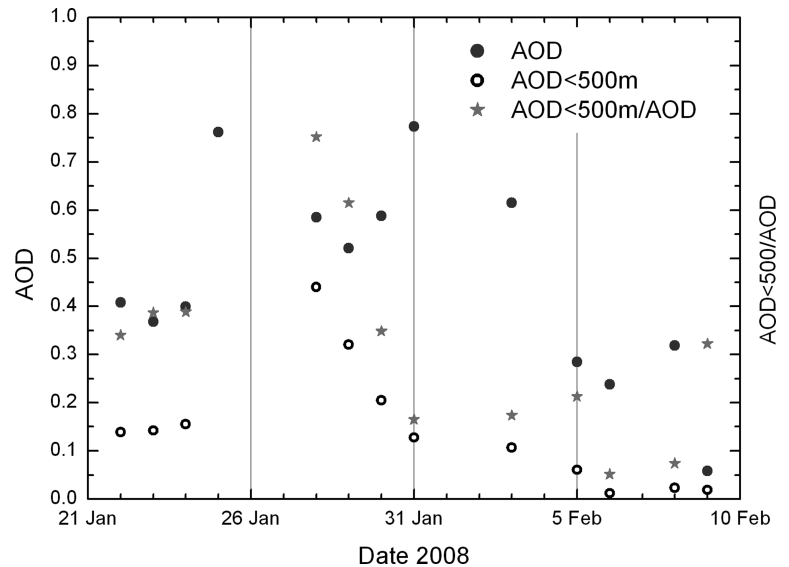
4.1. Overview

As already briefly mentioned, the campaign can be divided into two phases if the characteristics of the PBL are considered. The best criterion to identify differences is the consideration of the intensive aerosol properties S_p and δ_p as shown in Fig. 1. Here, we can clearly distinguish two periods: from 22 to 31 January 2008 the lidar ratio (only available at 355 nm) ranges between $50 < S_p < 55$ sr, and the δ_p values are wavelength dependent with $0.16 < \delta_p < 0.24$ at 355 nm and $0.19 < \delta_p < 0.28$ at 532 nm. The lidar ratios S_p are almost as high as found for pure Saharan dust, i.e. 58 sr at 355 nm, during SAMUM-2 (Groß et al., 2011). In addition, δ_p shows high, wavelength dependent mean values similar to those of pure dust (Freudenthaler et al., 2009, Groß et al., 2011) of $\delta_p = 0.25$ at 355 nm and $\delta_p = 0.30$ at 532 nm. This is a clear indication of Saharan dust as dominating type in the PBL. In the second phase, from 3 to 9 February, S_p in the PBL is significantly lower than during the first period, with wavelength independent values of $14 < S_p < 27$ sr only, indicating a dominance of spherical particles, probably wet sea-salt particles. This assumption is confirmed by the analyses of

Table 2. Summary of the mean lidar ratios S_p , particle linear particle depolarization ratios δ_p , and dominant aerosol type of the two identified time periods at 355 nm from POLIS measurements and at 532 nm from MULIS measurements.

Date	S_p mean (sr)		S_p range (sr)		δ_p mean		δ_p range		Dominant type
	355 nm	532 nm	355 nm	532 nm	355 nm	532 nm	355 nm	532 nm	
22.01.–31.01.	54	–	50–59	–	0.20	0.24	0.16–0.24	0.19–0.28	Saharan dust
3.01.–9.01.	21	18	14–27	17–19	0.03	0.03	0.02–0.05	0.01–0.07	Sea-salt

Fig. 2. Daytime mean aerosol optical depth at 340 nm (AOD – dark grey dots) derived from SSARA sun-photometer measurements, AOD at 355 nm below 0.5 km height (AOD < 500 m – dark grey circles) calculated from POLIS lidar measurements, and relative contribution of the AOD below 0.5 km height to the total AOD (light grey stars).



δ_p , where we find low values of $0.02 < \delta_p < 0.05$ at 355 nm and $0.01 < \delta_p < 0.07$ at 532 nm. An overview of the most relevant intensive aerosol properties of the PBL for the two time periods is given in Table 2. It includes the mean values of S_p and δ_p , as well as their maximum and minimum values.

The discrimination of the two episodes is not so clear considering only the total optical depth. Figure 2 shows daily averages of the AOD (τ) derived from the SSARA sun-photometer measurements at 340 nm, and the AOD in the lowermost 500 m (τ_{500}) calculated from POLIS lidar measurements at 355 nm. The latter quantity is a simplification as it applies a constant height range, but it was chosen to have the same representative and comparable parameter of the PBL for the whole campaign. Furthermore, the ratio of both quantities $\varepsilon = \tau_{500}/\tau$ is given to describe the relative contribution of the PBL to the total AOD at 355 nm. For this purpose, we calculated the total AOD at 355 nm from SSARA measurements at 340 nm using the Angström exponent between 340/500 nm. Missing values are either due to high cloudiness or the absence of daytime lidar measurements. Figure 1 shows a large variability of the vertical integrated properties—of the absolute as well as of the relative quantities. During the first phase of the measurements the AOD of the PBL varies between $\tau_{500} = 0.13$ on 31 January and $\tau_{500} = 0.44$ on 28 January, and the relative contribution ε ranges between 17% and 76%. During the second phase of the SAMUM-2 campaign (3–9 February)

the relative contribution of the lowermost 500 m ranges between 5% and 32%. The values of τ_{500} between 0.02 on 9 February and 0.1 on 3 February are considerably lower than during the first period.

Note that the time periods identified on the basis of the lidar measurements conform with the general weather situation as described in Knippertz et al. (2011) where they found higher wind velocities during the second phase, and therefore good conditions for sea-salt aerosol production

4.2. Case studies

In this section, we want to focus not only on the optical properties of the aerosols in the PBL but also on the quantitative assessment of the volume fraction of dust in the PBL. For this purpose we discuss in depth representative time slices from three days, two of them from the first phase.

22 January 2008

The first period we selected for a detailed analysis is 22 January 2008, 16–17 UTC. Analyses of POLIS measurements show an AOD in the lowermost 500 m of $\tau_{500} = 0.14$. This is about 34% of the total AOD at 355 nm. The PBL height determined from profiles of the relative humidity and lidar derived optical

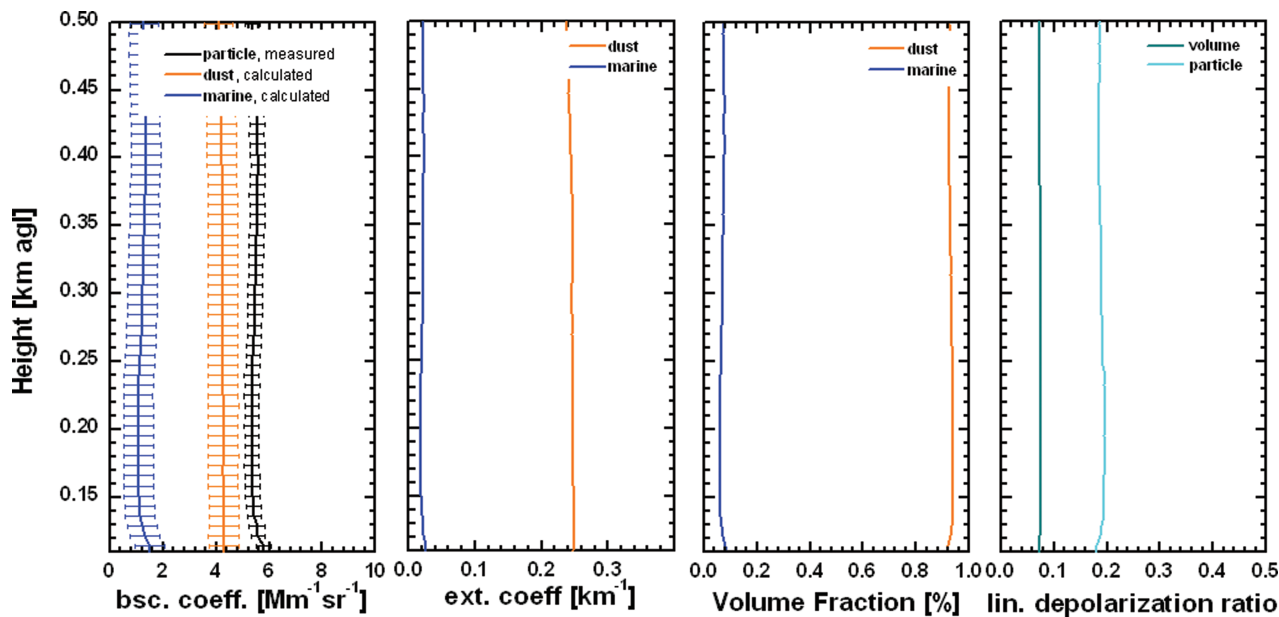


Fig. 3. Dust (orange line), marine (blue line) and total backscatter coefficient, dust and marine extinction coefficient, both at 355 nm, volume fraction of dust and marine aerosols, and measured volume and particle linear depolarization ratio (from left to right) on 22 January 2008 between 16:00 and 17:00 UTC.

properties is $z_{PBL} = 550$ m. The relative humidity in the PBL is about 60%. The mean lidar ratio of this layer is $S_p = 52 \text{ sr} \pm 3 \text{ sr}$ (note that the \pm range denotes the mean systematic uncertainty) at 355 nm and thus similar to lidar ratios of dust.

An overview of the height dependent (measured) parameters that are relevant for the assessment of the volume fraction of dust v_d as well as the retrieved profiles of v_d and v_m are shown in Fig. 3. The rightmost panel shows the profile of δ_p (355 nm), the parameter that is essential according to eq. (5) to derive the backscatter coefficient profiles β_d of dust and β_m of marine aerosols (first panel). With respect to the backscatter coefficient, dust is contributing with roughly 80% to the total. The volume linear polarization ratio δ_v is included as it is required for the calculation of δ_p (rightmost panel). The PBL during the considered time period is well mixed, consequently the polarization ratios are almost height independent throughout the PBL with a mean linear particle depolarization ratio δ_p of 0.19 ± 0.02 at 355 nm and 0.23 ± 0.01 at 532 nm. This points to a high amount of non-spherical dust particles. As described in the previous section the extinction coefficients α_d and α_m (second panel) are calculated applying adequate lidar ratios. The extinction due to dust was $\alpha_d = 0.25 \text{ km}^{-1}$, compared to only 0.02 km^{-1} of marine aerosols. Finally, the volume fractions of dust and marine aerosols are derived (see third panel). They exhibit a very high dominance of dust in the PBL with $v_d = 93\%$.

These results were compared to the volume fractions derived from the ground-based in situ measurements of a 3-h sample between 12 UTC and 15 UTC, and from the single particle analysis (Kandler et al., 2011a). Under dry conditions the in situ

measurements give volume fractions of dust of $v_d^{dry} = 92\%$ and consequently $v_m^{dry} = 8\%$ for the marine component. Calculation of the ambient volume fraction results in $v_d^{amb} = 83\%$. The difference can be attributed to hygroscopic growth of the marine particles. The single particle analysis results in a volume fraction of Saharan dust of $v_d = 89\%$ (dry conditions). As a conclusion, the findings from the in situ analyses and from the remote sensing approach are in good agreement.

30 January 2008

On 30 January 2008 the AOD of the PBL is $\tau_{500} = 0.2$, corresponding to about 35% of the total AOD. The PBL layer height is $z_{PBL} = 500$ m and the relative humidity in the PBL ranges between 60% and 70%. The mean S_p and δ_p values at 355 nm are $50 \text{ sr} \pm 2 \text{ sr}$ and 0.22 ± 0.01 , respectively, again indicating a high amount of non-spherical dust particles. Analogue to Fig. 3, POLIS measurements of the particle backscatter coefficient, and of the volume and particle depolarization ratios, that are required for the retrieval of the volume fractions, are shown in Fig. 4. They are based on two-hour averages from 18 to 20 UTC. The retrieved profiles of the dust and marine aerosols (β_d and β_m , α_d and α_m) as well as the calculated volume fractions v_d and v_m are also plotted in Fig. 4. It can be seen that the dominance of dust was even higher than on 22 January: the dust contributes more than 90% to the particle backscatter coefficient (leftmost panel). The dust related extinction coefficient is $\alpha_d \sim 0.40 \text{ km}^{-1}$, whereas the marine aerosol related extinction coefficient is virtually negligible with $0.01 < \alpha_m < 0.02 \text{ km}^{-1}$. Accordingly, the

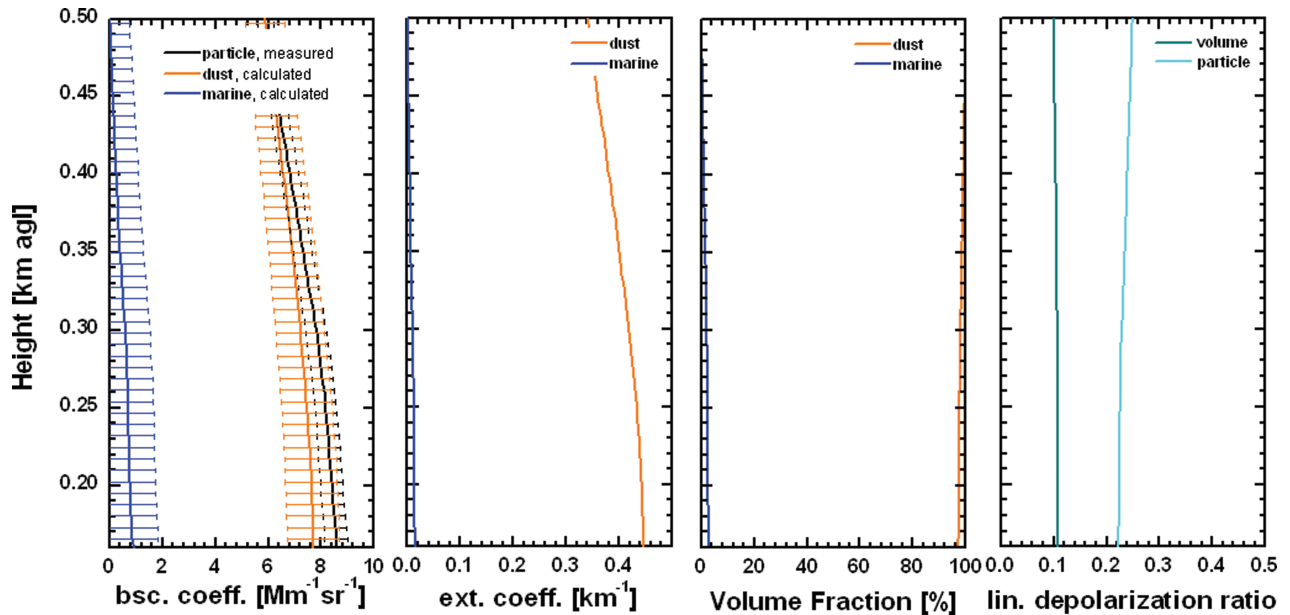


Fig. 4. Same as Fig. 3 but for 30 January 2008, 18:00–20:00 UTC.

dust contribution to the total volume of the PBL v_d is 98%, the marine aerosols' contribution is only 2%.

This result is in perfect agreement with the outcome of the single particle analysis, that results in $v_d = 98\%$ for the volume fraction of dust. Comparison with the in situ measurements, sampled between 18 UTC and 21 UTC, reveals v_d^{dry} and v_d^{amb} to be 99% for the Saharan dust contribution.

3 February 2008

From the second phase, we selected 3 February for a detailed analysis and considered the two-hour interval from 17:30 to 19:30 UTC. The PBL height is $z_{PBL} = 300$ m. The AOD of the PBL, τ_{500} , with $\tau_{500} = 0.10$ is considerably lower than on the days discussed before. The contribution to the total AOD is about 20%. As already briefly mentioned the intensive values of the aerosols in the PBL show differences to the days discussed above. The mean values of S_p are wavelength independent with $S_p = 28 \text{ sr} \pm 7 \text{ sr}$. Mean δ_p -values are $\delta_p = 0.05 \pm 0.01$ at 355 nm and $\delta_p = 0.07 \pm 0.01$ at 532 nm, respectively. These values indicate a high contribution of spherical particles. As before, the profiles of the measured backscatter coefficient, the volume and particle linear depolarization ratios, the calculated backscatter and extinction coefficients of dust and marine aerosols, and the resulting volume fractions are shown in the four panels of Fig. 5. As already expected from inspection of the δ_p -profiles, the retrieval of the dust and marine volume fractions in the PBL reveals completely different results than the previous cases: with $v_d = 42\%$ and $v_m = 58\%$ both components are almost equally contributing.

Comparing these values to the results from the in situ sampling from 18 to 21 UTC, we see very good agreement with the ambient volume fraction of dust ($v_d^{amb} = 39\%$), but significant differences when the dry volume fraction, which is much higher with $v_d^{dry} = 66\%$, is considered. This effect may be explained with the hygroscopicity of marine aerosols (e.g. Tang et al., 1997). From Wise et al. (2005) we estimate an increase of 60% of the volume equivalent radius of marine aerosols due to hygroscopic growth for the meteorological conditions of Praia during SAMUM-2, i.e. relative humidity in the range of 60–70% and transport of marine particles from the sea, where higher humidity is likely. In contrast, the Saharan dust particles are not hygroscopic. The consequences with respect to v_d are illustrated in Fig. 6, where v_d under dry and ambient conditions is plotted. If the volume fraction of Saharan dust v_d in the PBL is large, the difference between v_d^{amb} and v_d^{dry} is small, because virtually all particles are hydrophobic. With decreasing v_d^{dry} , which is equivalent to an increasing amount of hygroscopic (marine) particles, the ambient volume fraction of dust v_d^{amb} decreases even stronger.

To elaborate the implications of hygroscopic growth on aerosol mixtures consisting of hydrophobic and hygroscopic components – in our case dust and marine aerosols – and to compare the available methodologies, we show the different time series of our analyses over the whole measurement period in Fig. 7. Shown are the dry and ambient volume fractions of dust derived from the ground based in situ measurements – data that are available almost continuously, the retrievals from the single particle analysis, and the volume fractions calculated from our lidar measurements. Note that the lidar retrievals include 12

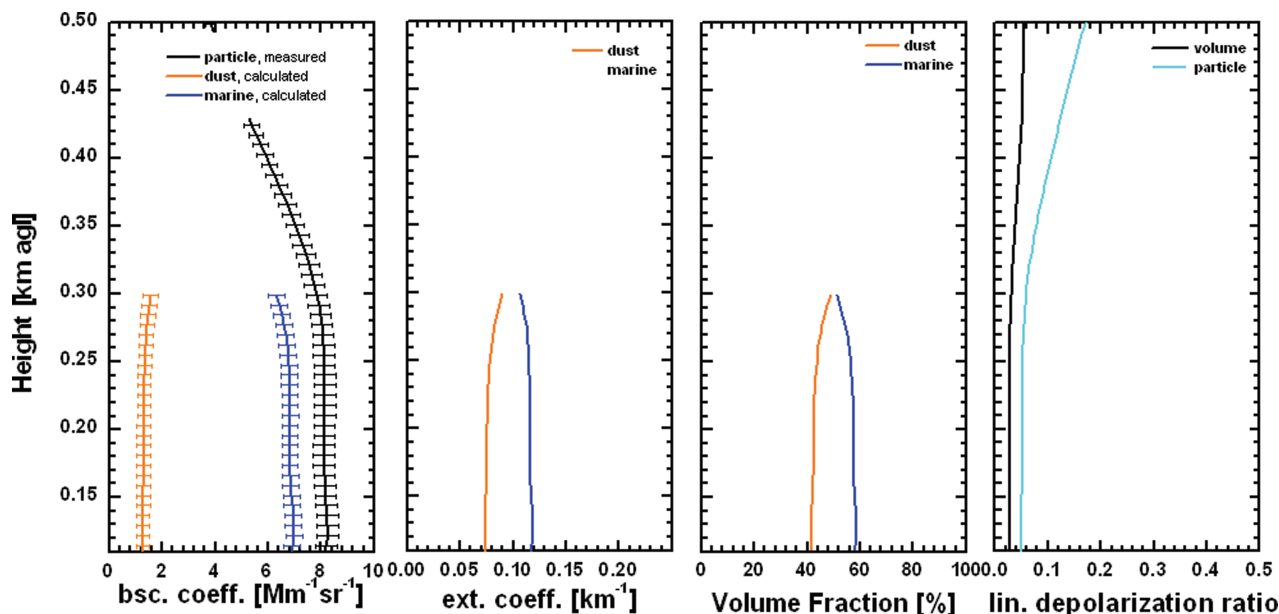


Fig. 5. Same as Fig. 3 but for 3 February 2008, 17:30–19:30 UTC.

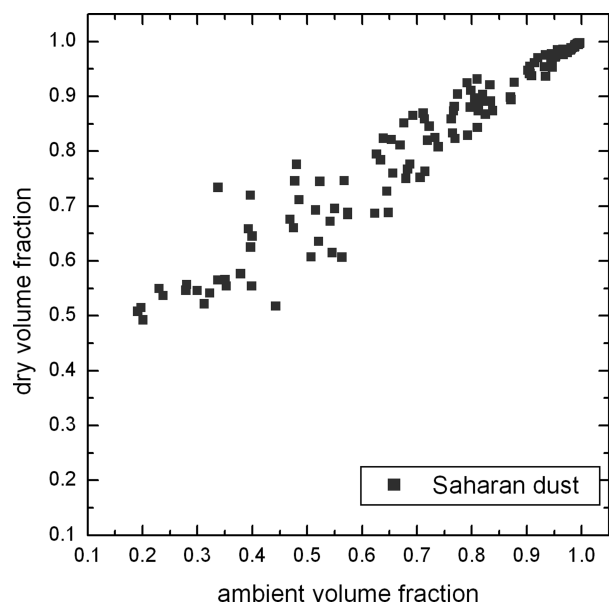


Fig. 6. Dry volume fraction of Saharan dust versus ambient volume fraction derived from in situ measurements at Praia, Cape Verde from 20 January to 9 February 2008. Each point describes a three hour sample.

cases at 355 nm and 6 cases at 532 nm in total, thus more than the 3 case studies discussed earlier.

Three features are of special relevance. First, it is clearly visible, that at the beginning of February the aerosol regime changed from a dust-dominated mixture to a mixture with significant contribution of marine aerosols. This change was already found from the intensive aerosol properties from the lidar

measurements (Fig. 2). However, the temporal coverage of the in situ measurements is better so that the time of the change can be assessed more accurately. Second, it is obvious that the dry volume fraction is always equal or greater than the ambient volume fraction (derived from the in situ measurements). This is a consequence of the underlying physical concept that under conditions of high relative humidity a certain number of the non-dust aerosols grow. The reduction of the volume fraction of dust during the second part of the experiment is much more pronounced than during the first part. This fact is consistent with the higher amount of marine aerosols. The third feature is the very good general agreement of the different retrievals. In this context it is noteworthy that the agreement of the retrieval based on the lidar measurements with the ambient volume fraction is much better than with the dry volume fraction, as expected from the physical processes. For the same reason v_d from the single particle analysis agrees better with the dry volume fraction from the in situ data.

Slight differences between v_d from the lidar retrieval and the ambient volume fraction (in situ) are only observed when the contribution of dust was low, i.e. $v_d^{amb} < 30\%$ (5, 6 and 9 February). On these days in situ measurements reveal a larger dust volume fraction than the lidar measurements. A possible reason for this discrepancy is the relative large error of the retrievals when v_d is low. Another reason is that the lowermost hundred meters cannot be observed by the lidars in spite of the low overlap of POLIS and the fact that MULIS measurements under low elevation angles were considered in the evaluation. Under conditions with a high marine component in the PBL this very shallow height range might become relevant: as the wind speed is high (Knippertz et al., 2011), the production of

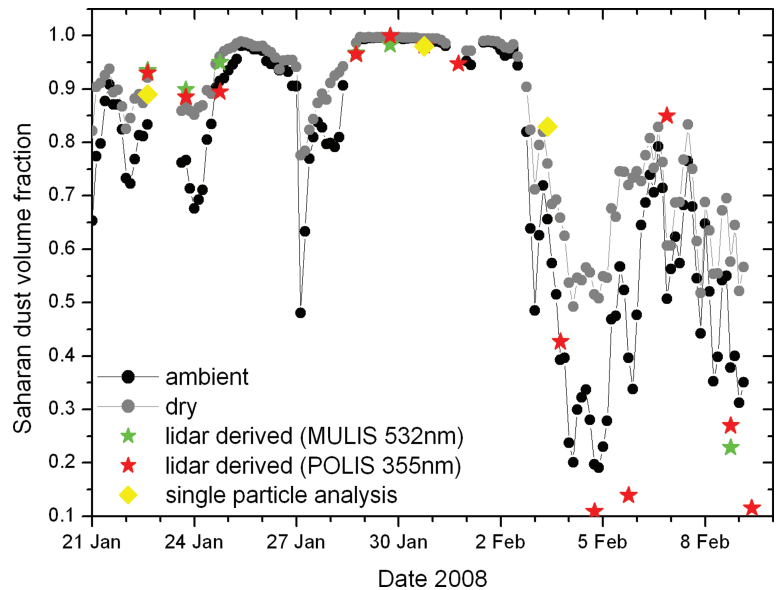


Fig. 7. Volume fraction of Saharan dust in the PBL over Praia, Cape Verde, from 21 January–9 February 2008. The black dots show the in situ measurements under ambient relative humidity, the grey dots in situ measurements of the dry volume fraction. The single particle analysis, as well as the lidar derived volume fractions are indicated by yellow rectangles, and green and red stars, respectively.

dust with large particles (radius larger than $10 \mu\text{m}$) from local sources might be enhanced and accumulate in this layer (Kandler et al., 2011b). As a consequence, a vertical gradient of aerosol properties builds up, leading to differences between the ground based aerosol samples and the atmospheric volume that is sensed by the lidar. This effect is in particular relevant on days with a low background concentration of Saharan dust as during the last days of the campaign.

5. Summary and conclusion

This paper focuses on the investigation of aerosols in the PBL over Cape Verde conducted in the framework of SAMUM-2 from 21 January till 9 February 2008. On the one hand we determined intensive optical properties from lidar measurements that are known to be suited to characterize aerosol particles: the lidar ratio S_p and the linear depolarization ratio δ_p . On the other hand, we present a novel approach to derive the volume fractions of dust v_d and marine aerosols v_m based on lidar measurements. This approach is based on high quality measurements of δ_p . The results were compared to independent in situ measurements.

On the basis of the lidar derived optical characterization the field campaign could be divided into two phases with respect to the presence of dust in the PBL. Colocated sun-photometer data support this classification, though it was partly masked by the inherent vertical integration. During the first phase, the PBL was dominated by hydrophobic Saharan dust particles. Calculations of the volume fraction of dust agree very well with in situ measurements of the volume fraction at ambient relative humidity. The agreement with the dry volume fraction was also good as the majority of the particles are hydrophobic. During the second phase, the dry and ambient volume fraction of the in situ measurements differ, as during this episode the abun-

dance of hygroscopic marine aerosols was significant. We found (not unexpectedly) that this effect gets larger with an increasing fraction of marine aerosols. So the assessment of v_d , its interpretation, and the comparison between different measurement techniques (in situ versus remote sensing) must take into account the ambient relative humidity and the hygroscopicity of the particles.

It should be mentioned that the assessment of v_d^{amb} involves several evaluation steps and assumptions, thus we estimate the relative errors to be in the range of 20–30%, both for the lidar retrieval as well as for the in situ measurements. The methodology in general is based on the assumption of an aerosol mixture of two components, one of which being hydrophobic and one hygroscopic. The lidar retrieval relies on the prescribed linear depolarization ratios of the two pure components, which is not a critical issue in our case, as these numbers are known with high accuracy from our previous measurements. Furthermore, the methodology requires lidar systems that are capable to measure as close to the ground as possible – an overlap of 500 m or even more is certainly not acceptable for the characterization of the PBL. Our lidar systems fulfil this requirement, as the overlap is not more than 100 m. The assessment of v_d^{amb} by means of in situ measurements is among others influenced by the accuracy of the assumed hygroscopic growth factors and information on the hygroscopic mixing state.

In this paper we have demonstrated, that from lidar measurements the volume fraction of dust in the PBL can be derived. As the lidar systems of the Meteorological Institute of the LMU provide lidar depolarization ratios at two wavelengths, $\lambda = 355$ and 532 nm, the investigation of the potential of an extension of the methodology is envisaged in a next step. This extension might either increase the accuracy of the derived volume fractions in case of a two-component aerosol mixture (e.g. dust and

marine aerosols), or makes it possible to adapt the approach for more component mixtures. The extension of our retrieval of volume fractions to a retrieval of mass fractions is expected to be easily feasible, as only the mass density of the aerosols has to be known. The knowledge of mass fractions can be quite important with respect to air quality and flight safety.

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