

Payload 3 Daily Flight Report



Date: 2025-08-13

Flight Campaign ID: P3C1

Airport, FBO ID, City: Boulder Municipal Airport (KBDU) - Boulder, CO

Aircraft: N821AR

Domain: 10 (Central Plains)

Sites Flown: RMNP (Rocky Mountain National Park)

Days left in Domain: 14

Report Author: Matt

Lidar Operators: Matt Flight Hours: 02:28

Spectrometer Operators: Mitch Hours until maintenance: 83.32

Pilots: Jeff, Troy GPS Instruments: AOP_KBDU, AOP_NIWO

Adt'l Flight Crew: Alyssa

Summary

The crew got an early start and arrived on station at the Rocky Mountain National Park for the 35-degree solar window. 15 lines were collected in yellow conditions primarily due to low lying smoke and haze.

Concerns

None.

Comments

None.

Daily Coverage

Estimated Cloud Cover Key

Green: Yellow: Red: 0-10% 11-50% >50%

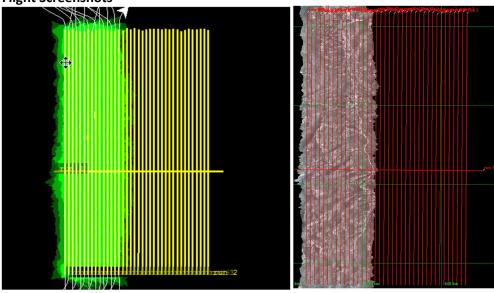
Solar Angle Less Than 40 degrees: (*)

D10|RMNP

Line #	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39
Lidar	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
Spectrometer	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
Camera	✓	✓	√	✓	✓	✓	✓	✓	√	√	✓	√	√	√	√
Cloud Cover															

Total number of lines flown: 15

Flight Screenshots



Lidar NIS

Cumulative Domain Coverage

D10 | ARIK (Arikaree River)

		1,			· ,														
3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
23	24	25	26	27	28	29	30	31	32	33	34	35							

Flown: 0% (0/33) Green: 0% (0/33) Yellow: 0% (0/33) Red: 0% (0/33)

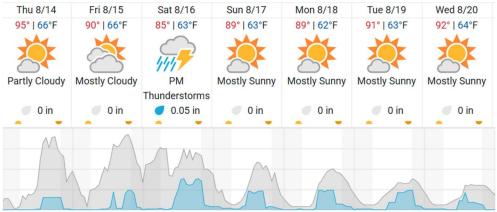
D10 RMNP (Rocky Mountain National Park)

2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38*	39*	40	,

Flown: 38% (15/39) Green: 0% (0/39) Yellow: 38% (15/39) Red: 0% (0/39)

Weather Forecast

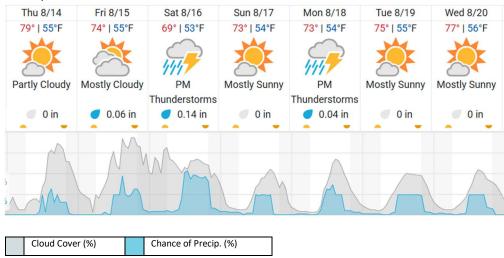
Boulder, CO



^{*} Flown within 35deg solar angle

^{*} Flown within 35deg solar angle

Allanspark, CO



source: wunderground.com

Flight Collection Plan for 14 August 2025

Flyority 1

Collection Area: Rocky Mountain National Park (RMNP)

Flight Plan Name: D10_RMNP_R2_P1_v5_Q780 On-Station Time 40 degree: 1550 UTC / 0950 L

Crew: Mitch (Lidar), Matt (NIS), Alyssa (Ground/Lidar Observing)