OutbreakFlow: Model-based Bayesian inference of disease outbreak dynamics with invertible neural networks and its application to the COVID-19 pandemics in Germany

Supporting Information

Stefan T. Radev¹, Frederik Graw², Simiao Chen³,⁴, Nico T. Mutters⁵, Vanessa M. Eichel⁶, Till Bärnighausen³,⁷,⁸, Ullrich Köthe⁹*,

1 Institute of Psychology, Heidelberg University, Heidelberg, Germany
2 BioQuant - Center for Quantitative Biology, Heidelberg University, Heidelberg, Germany
3 Heidelberg Institute of Global Health, Heidelberg, Germany
4 Chinese Academy of Medical Sciences and Peking Union Medical College, Beijing, China
5 Institute for Hygiene and Public Health, University Hospital Bonn, Bonn, Germany
6 Center of Infectious Diseases, University Hospital Heidelberg, Heidelberg, Germany
7 Department of Global Health and Population, Harvard University, Harvard, Boston, USA
8 Africa Health Research Institute, Durban, South Africa
9 Computer Vision and Learning Lab, Heidelberg University, Heidelberg, Germany

1) Training Modes for OutbreakFlow (Algorithms S1-S3)

Offline Learning

**Algorithm S1** OutbreakFlow training phase using offline learning

**Require:** $f$ - invertible inference network, $h$ - recurrent summary network, $g$ - convolutional filtering network, $φ$ - neural network parameters, $S$ - total number of simulations, $B$ - number of simulations per batch (batch size).

1: Generate a large reference table $\mathcal{D}^{(S)} := \{θ^{(s)}, x^{(s)}_{1:T}\}_{s=1}^{S}$ by running the simulator $S$ times.

2: repeat

3: Sample a mini-batch of simulations: $\mathcal{D}^{(B)} \sim \mathcal{D}^{(S)}$.

4: Pass each simulated time-series through the filtering network: $\tilde{x}^{(b)}_{1:T} = g(x^{(b)}_{1:T})$.

5: Pass the filtered time-series through the summary network: $y^{(b)} = h(\tilde{x}^{(b)}_{1:T})$.

6: Pass each pair $(θ^{(b)}, y^{(b)})$ through the inference network: $z^{(b)} = f(θ^{(b)}, y^{(b)})$.

7: Compute loss from batch: $L(φ) = -\sum_{b=1}^{B} \log q_{θ^{(b)}}(x^{(b)}_{1:T})$.

8: Update neural network parameters $φ$ via backpropagation.

9: until convergence to $φ^*$

10: **Return** trained networks $g, h, f$ with parameters $φ^*$.
Online Learning

**Algorithm S2** OutbreakFlow training phase using online learning

**Require:** \( f \) - invertible inference network, \( h \) - recurrent summary network, \( g \) - convolutional filtering network, \( \phi \) - neural network parameters, \( B \) - number of simulations per iteration (batch size).

1: repeat
2: Generate a mini-batch \( D^{(B)} := \{\theta^{(b)}, x^{(b)}_{1:T}\}_{b=1}^{B} \) by running the simulator \( B \) times.
3: Pass each simulated time-series through the filtering network: \( \tilde{x}^{(b)}_{1:T} = g(x^{(b)}_{1:T}) \).
4: Pass the filtered time-series through the summary network: \( y^{(b)} = h(\tilde{x}_{1:T}) \).
5: Pass each pair \( (\theta^{(b)}, y^{(b)}) \) through the inference network: \( z^{(b)} = f(\theta^{(b)}, y^{(b)}) \).
6: Compute loss from batch: \( L(\phi) = -\sum_{b=1}^{B} \log q_{\phi}(\theta^{(b)} \mid x^{(b)}_{1:T}) \).
7: Update neural network parameters \( \phi \) via backpropagation.
8: until convergence to \( \phi^* \)
9: Return trained networks \( g, h, f \) with parameters \( \phi^* \).

Round-Based Learning

**Algorithm S3** OutbreakFlow training phase using round-based hybrid learning

**Require:** \( f \) - invertible inference network, \( h \) - recurrent summary network, \( g \) - convolutional filtering network, \( \phi \) - neural network parameters, \( R \) - number of rounds, \( S \) - number of simulations per round, \( B \) - batch size.

1: Initialize reference table \( D^{(R \times S)} := \{\} \).
2: for \( r = 1, ..., R \) do
3: Generate synthetic data \( D^{(S)} := \{\theta^{(s)}, x^{(s)}_{1:T}\}_{s=1}^{S} \) by running the simulator \( S \) times.
4: Aggregate data: \( D^{(R \times S)} := D^{(R \times S)} \cup D^{(S)} \).
5: repeat
6: Sample a mini-batch of simulations: \( D^{(B)} \sim D^{(R \times S)} \).
7: Pass each simulated time-series through the filtering network: \( \tilde{x}^{(b)}_{1:T} = g(x^{(b)}_{1:T}) \).
8: Pass the filtered time-series through the summary network: \( y^{(b)} = h(\tilde{x}_{1:T}) \).
9: Pass each pair \( (\theta^{(b)}, y^{(b)}) \) through the inference network: \( z^{(b)} = f(\theta^{(b)}, y^{(b)}) \).
10: Compute loss from batch: \( L(\phi) = -\sum_{b=1}^{B} \log q_{\phi}(\theta^{(b)} \mid x^{(b)}_{1:T}) \).
11: Update neural network parameters \( \phi \) via backpropagation.
12: until convergence to \( \phi^*_R \)
13: end for
14: Return trained networks \( g, h, f \) with parameters \( \phi^*_R \).
2) Parameter Priors for the Model of the Early Covid-19 Pandemics in Germany (Tables S1-S3)

Disease Model

Table S1. Description of disease model parameters and corresponding prior distributions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Prior Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of initially exposed individuals</td>
<td>$E_0$</td>
<td>$\text{Gamma}(2, 30)$</td>
</tr>
<tr>
<td>Risk of infection from symptomatic patients</td>
<td>$\beta$</td>
<td>$\text{LogNormal}(\log(0.25), 0.3)$</td>
</tr>
<tr>
<td>Rate at which exposed cases become infectious</td>
<td>$\gamma$</td>
<td>$\text{LogNormal}(\log(1/6.5), 0.5)$</td>
</tr>
<tr>
<td>Rate at which symptoms manifest</td>
<td>$\eta$</td>
<td>$\text{LogNormal}(\log(1/3.2), 0.5)$</td>
</tr>
<tr>
<td>Rate at which symptomatic individuals recover</td>
<td>$\mu$</td>
<td>$\text{LogNormal}(\log(1/8), 0.2)$</td>
</tr>
<tr>
<td>Rate at which undiagnosed individuals recover</td>
<td>$\theta$</td>
<td>$\text{Uniform}(1/14, 1/3)$</td>
</tr>
<tr>
<td>Rate at which critical cases die</td>
<td>$d$</td>
<td>$\text{Uniform}(1/14, 1/3)$</td>
</tr>
<tr>
<td>Probability of remaining undetected/undiagnosed</td>
<td>$\alpha$</td>
<td>$\text{Uniform}(0.005, 0.99)$</td>
</tr>
<tr>
<td>Probability of dying from the disease</td>
<td>$\delta$</td>
<td>$\text{Uniform}(0.01, 0.3)$</td>
</tr>
</tbody>
</table>

Intervention Model

Table S2. Description of intervention model parameters controlling the time-varying transmission rate

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Prior Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Onset date of each change to take effect</td>
<td>$t_1$</td>
<td>$\text{Normal}(2020/03/09 = \text{Day 8}, 3)$</td>
</tr>
<tr>
<td></td>
<td>$t_2$</td>
<td>$\text{Normal}(2020/03/16 = \text{Day 15}, 3)$</td>
</tr>
<tr>
<td></td>
<td>$t_3$</td>
<td>$\text{Normal}(2020/03/23 = \text{Day 22}, 3)$</td>
</tr>
<tr>
<td></td>
<td>$t_4$</td>
<td>$\text{Normal}(2020/05/06 = \text{Day 66}, 3)$</td>
</tr>
<tr>
<td>Duration of each change to fully manifest itself</td>
<td>$\Delta t_j$</td>
<td>$\text{LogNormal}(\log(3), 0.3)$</td>
</tr>
<tr>
<td>Transmission rates before / after each change</td>
<td>$\lambda_0$</td>
<td>$\text{LogNormal}(\log(1.2), 0.5)$</td>
</tr>
<tr>
<td></td>
<td>$\lambda_1$</td>
<td>$\text{LogNormal}(\log(0.6), 0.5)$</td>
</tr>
<tr>
<td></td>
<td>$\lambda_2$</td>
<td>$\text{LogNormal}(\log(0.3), 0.5)$</td>
</tr>
<tr>
<td></td>
<td>$\lambda_3$</td>
<td>$\text{LogNormal}(\log(0.1), 0.5)$</td>
</tr>
<tr>
<td></td>
<td>$\lambda_4$</td>
<td>$\text{LogNormal}(\log(0.15), 0.5)$</td>
</tr>
</tbody>
</table>

Observation Model

Table S3. Description of observation model parameters controlling reporting properties

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Prior Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reporting delays (lags)</td>
<td>$L_{C \in {I,R,D}}$</td>
<td>$\text{LogNormal}(\log(8), 0.2)$</td>
</tr>
<tr>
<td>Weekly modulation amplitudes</td>
<td>$A_{C \in {I,R,D}}$</td>
<td>$\text{Beta}(0.7, 0.17)$</td>
</tr>
<tr>
<td>Weekly modulation phases</td>
<td>$\Phi_{C \in {I,R,D}}$</td>
<td>$\text{VonMises}(0.01)$</td>
</tr>
<tr>
<td>Reporting noise scale</td>
<td>$\sigma_{C \in {I,R,D}}$</td>
<td>$\text{Gamma}(1, 5)$</td>
</tr>
</tbody>
</table>
3) Testing and Validation of OutbreakFlow (Table S4, Figures S1-S3)

Parameter Priors

Table S4. Description of model parameters and corresponding prior distributions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Prior Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Initial transmission rate</td>
<td>$\lambda$</td>
<td>LogNormal(log(0.4), 0.5)</td>
</tr>
<tr>
<td>Recovery rate of infected individuals</td>
<td>$\mu$</td>
<td>LogNormal(log(1/8), 0.2)</td>
</tr>
<tr>
<td>Reporting delay (lag)</td>
<td>$L$</td>
<td>LogNormal(log(8), 0.2)</td>
</tr>
<tr>
<td>Number of initially infected individuals</td>
<td>$I_0$</td>
<td>Gamma(2, 20)</td>
</tr>
<tr>
<td>Dispersion of the negative binomial distribution</td>
<td>$\psi$</td>
<td>Exponential(5)</td>
</tr>
</tbody>
</table>

Results with Uninformative Parameters

Fig S1. Posterior predictions on new cases from the first 2 weeks of the Covid-19 pandemics in Germany. We observe accurate reproduction of the real data and well-calibrated uncertainty despite the addition of uninformative parameters.

Fig S2. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by the network trained to estimate the simple SIR-model. The addition of uninformative parameters does not seem to induce systematic biases across the marginal posteriors.
Fig S3. Bivariate and univariate posteriors obtained by applying the simple SIR model (Eq. 16-18) to cases reported in the first 2 weeks of the Covid-19 pandemic in Germany. The addition of uninformative parameters does not lead to results which diverge from or lead to different conclusions from the main analysis (see Fig 3). Dashed black lines on the diagonal indicate posterior means.
4) Periodic SIR Model (Table S5, Figures S4-S5)

In addition to the analyses in the main paper, we explored the behavior of OutbreakFlow on a noisy periodic SIR model with potentially chaotic behavior. Following [1], the model is defined by the following set of ordinary differential equations (ODEs):

\[
\begin{align*}
\frac{dS}{dt} &= -\beta(t) \left( \frac{SI}{N} \right) + \mu N - \mu S \\
\frac{dI}{dt} &= \beta(t) \left( \frac{SI}{N} \right) - (\gamma + \mu) I \\
\frac{dR}{dt} &= \gamma I - \mu R
\end{align*}
\]

(S1)
(S2)
(S3)

The model assumes that at time \( t \), the population is composed of \( S \) susceptible, \( I \) infected, and \( R \) removed (recovered or immune) individuals. Vital dynamics are taken into account by considering a natural mortality rate per capita \( \mu > 0 \) and a number \( \mu N \) of births per time unit, where \( N \) is the total population size. Since we assume that the disease is non-lethal, the size of the population is constant \( N = S + I + R \). We further assume a transmission rate \( \beta(t) \) which is a periodic function of time with a fixed period \( T \). Infected individuals recover at a rate \( \gamma > 0 \).

The transmission rate \( \beta(t) \) varies as a function of time according to:

\[
\beta(t) = \beta_0(1 + \epsilon \cos(2\pi \omega t))
\]

(S4)

Further, we assume the following observation model for the observed new infections \( I_{obs} \):

\[
I_t^{(obs)} \sim \text{Normal}(I_t, \sqrt{I_t} \sigma),
\]

(S5)

Thus, the full parameter vector to be estimated is \( \theta = (\beta_0, \mu, \gamma, \epsilon, \omega, \sigma) \). Prior distributions for the parameters are given in the below table.

**Table S5.** Description of model parameters and corresponding prior distributions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Prior Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Base transmission rate</td>
<td>( \beta_0 )</td>
<td>Uniform(1, 3)</td>
</tr>
<tr>
<td>Natural mortality rate</td>
<td>( \mu )</td>
<td>Uniform(1/14, 1/3)</td>
</tr>
<tr>
<td>Recovery rate</td>
<td>( \gamma )</td>
<td>Uniform(1/13, 1/3)</td>
</tr>
<tr>
<td>Seasonal modulation amplitude</td>
<td>( \epsilon )</td>
<td>Uniform(1/10, 1)</td>
</tr>
<tr>
<td>Seasonal modulation frequency</td>
<td>( \omega )</td>
<td>Uniform(0.9, 10)</td>
</tr>
<tr>
<td>Noise factor of the observation model</td>
<td>( \sigma )</td>
<td>Exponential(5)</td>
</tr>
</tbody>
</table>

In order to calibration, estimation, and predictions, we train the OutbreakFlow networks via online learning for a total of 50000 mini-batch simulations from the model.
Fig S4. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by OutbreakFlow trained on the seasonal SIR model. The results indicate poor calibration, since notable deviations from uniformity are present, revealing systematic parameter recovery and uncertainty quantification deficiencies.
Fig S5. Model-based predictions on 16 simulated time-series from the periodic SIR model. Despite poor calibration, the network is able to encode the periodic structure of the data well and appears to capture the average dynamics.
5) Simulation-Based Calibration of OutbreakFlow for Inference on Entire Germany (Figure S6)

Fig S6. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by the network trained for inference on entire Germany. Uniformly distributed histograms of the rank statistic indicate no systematic biases in the estimation of location and scale of the true marginal posteriors.
6) Ablation Study Results (Figures S7-S12)

6.1) Removing the Convolutional Filtering Network

Fig S7. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by OutbreakFlow without a convolutional filtering network. Uniformly distributed histograms of the rank statistic indicate no systematic biases in the estimation of location and scale of the true marginal posteriors. We observe slightly worse calibration, especially regarding the observation model parameters, when using this reduced architecture.

Fig S8. Posterior predictions and forecasts of new cases based on the same data as in the main text but using an OutbreakFlow architecture without a convolutional filtering network. We observe that this reduced architecture has difficulties recovering the weekly modulation. Cases to the left of the vertical dashed line were used for posterior checking (model training) and cases to the right for posterior forecasts (predictions) on unseen data.
6.2) Removing the Recurrent Summary Network

Fig S9. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by OutbreakFlow without a recurrent summary network. Uniformly distributed histograms of the rank statistic indicate no systematic biases in the estimation of location and scale of the true marginal posteriors. We observe slightly worse calibration, especially regarding the observation model parameters, when using this reduced architecture.

Fig S10. Posterior predictions and forecasts of new cases based on the same data as in the main text but using an OutbreakFlow architecture without a recurrent summary network. We observe that this reduced architecture has difficulties recovering the weekly modulation. Cases to the left of the vertical dashed line were used for posterior checking (model training) and cases to the right for posterior forecasts (predictions) on unseen data.

6.3) Removing the Observation Model

Inference on the observed epidemiological time series yielded only divergent simulations.

6.4) Removing the Intervention Model

Inference on the observed epidemiological time series yielded only divergent simulations.
6.5) Removing the Latent Carrier Compartment

Fig S11. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by OutbreakFlow on a SEIRD model (lacking a latent carrier compartment). Uniformly distributed histograms of the rank statistic indicate no systematic biases in the estimation of location and scale of the true marginal posteriors. We observe slightly worse calibration, especially regarding the observation model parameters, when using this reduced model.
Fig S12. Posterior predictions and forecasts of new cases based on the same data as in the main text but using an OutbreakFlow architecture trained on a reduced SEIRD model (lacking a latent carrier compartment). We observe that this reduced model does not reproduce the data well and largely underestimates the reported cases, especially during the beginning and peak of the pandemic wave. Note: Cases to the left of the vertical dashed line were used for posterior checking (model training) and cases to the right for posterior forecasts (predictions) on unseen data.

7) Simulation-Based Calibration of OutbreakFlow for Inference on the Individual German States (Figure S13)

Fig S13. Simulation-based probabilistic calibration of the marginal approximate posteriors obtained by the networks trained for amortized inference on all German federal states. Uniformly distributed histograms of the rank statistic indicate no systematic biases in the estimation of location and scale of the true marginal posteriors.
8) Predicted New Cases per German Federal State (Figure S14)

Fig S14. Model predictions of new cases Covid-19 deaths for each German federal state. Cases to the left of the vertical dashed line (8 weeks) were used for model fitting and posterior checking and cases to the right (3 weeks) for forecasts on new data. We observe good matches between the model’s median predictions and past and future reported cases for each German federal state.
9) Predicted Cumulative Deaths per German Federal State (Figure S15)

Fig S15. Model predictions of cumulative Covid-19 deaths (derived from predicted new cases) for each German federal state. Cases to the left of the vertical dashed line (8 weeks) were used for model fitting and posterior checking and cases to the right (3 weeks) for forecasts on new data. We observe good matches between the model’s median predictions and past and future reported deaths for each German federal state. However, the number of deaths in the state Mecklenburg-Western Pomerania over time is underestimated (although it lies mostly within the estimated 95%-CI), which is probably due to the very low counts (lowest among all German federal states).
10) Marginal Parameter Posteriors per Federal State (Figures S16-S31)

Baden-Württemberg

Fig S16. Marginal parameter posteriors from data available for the German federal state Baden-Württemberg.
Fig S17. Marginal parameter posteriors from data available for the German federal state Bavaria.
Fig S18. Marginal parameter posteriors from data available for the German federal state Berlin.
Fig S19. Marginal parameter posteriors from data available for the German federal state Brandenburg.
**Bremen**

Fig S20. Marginal parameter posteriors from data available for the German federal state Bremen.
Fig S21. Marginal parameter posteriors from data available for the German federal state Hamburg.
Fig S22. Marginal parameter posteriors from data available for the German federal state Hesse.
Fig S23. Marginal parameter posteriors from data available for the German federal state Lower Saxony.
Mecklenburg-Western Pomerania

Figure S24. Marginal parameter posteriors from data available for the German federal state Mecklenburg-Western Pomerania.
Marginal parameter posteriors from data available for the German federal state North Rhine-Westphalia.

Fig S25.
Rhineland-Palatinate

Fig S26. Marginal parameter posteriors from data available for the German federal state Rhineland-Palatinate.
Fig S27. Marginal parameter posteriors from data available for the German federal state Saarland.
Fig S28. Marginal parameter posteriors from data available for the German federal state Saxony-Anhalt.
Saxony

Fig S29. Marginal parameter posteriors from data available for the German federal state Saxony.
Fig S30. Marginal parameter posteriors from data available for the German federal state Schleswig-Holstein.
Fig S31. Marginal parameter posteriors from data available for the German federal state Thuringia.

References