

SUPPORTING INFORMATION S1

1. Derivation of Modified Lyapunov Equation: Equation (6)

$$\text{vec}(\mathbf{J}\Gamma + \Gamma\mathbf{J}^T = -2\mathbf{D})$$

$$\text{vec}(\mathbf{J}\Gamma + \Gamma\mathbf{J}^T) = \text{vec}(-2\mathbf{D})$$

$$\text{vec}(\mathbf{J}\Gamma) + \text{vec}(\Gamma\mathbf{J}^T) = -2\mathbf{d}$$

with \mathbf{d} being vectorized form of \mathbf{D} .

Rule 1: $\text{vec}(\mathbf{ABC}) = (\mathbf{C}^T \otimes \mathbf{A}) \text{vec}(\mathbf{B})$

Rule 2: Multiplication with identity matrix will not affect the equality.

Applying those rules;

$$\text{vec}(\mathbf{I}\mathbf{J}\Gamma) = (\Gamma^T \otimes \mathbf{I}) \text{vec}(\mathbf{J})$$

$$\text{vec}(\Gamma\mathbf{J}^T\mathbf{I}) = (\mathbf{I} \otimes \Gamma) \text{vec}(\mathbf{J}^T)$$

$$(\Gamma^T \otimes \mathbf{I}) \text{vec}(\mathbf{J}) + (\mathbf{I} \otimes \Gamma) \text{vec}(\mathbf{J}^T) = -2\mathbf{d}$$

Rule 3: $\text{vec}(\mathbf{J}) = \mathbf{P} \text{vec}(\mathbf{J}^T)$ with \mathbf{P} being a permutation matrix

$$(\Gamma^T \otimes \mathbf{I}) \text{vec}(\mathbf{J}) + (\mathbf{I} \otimes \Gamma) \mathbf{P} \text{vec}(\mathbf{J}) = -2\mathbf{d}$$

Hence,

$$\mathbf{A} = (\Gamma^T \otimes \mathbf{I}) + (\mathbf{I} \otimes \Gamma) \mathbf{P} = (\Gamma \otimes \mathbf{I}) + (\mathbf{I} \otimes \Gamma) \mathbf{P} \quad (\text{since } \Gamma \text{ is symmetric, its transpose is the same})$$

For a 2 x 2 system, given that covariance matrix, Γ , is of the form $\begin{bmatrix} a & b \\ b & d \end{bmatrix}$, eqn.(5) with

Jacobian matrix in vectorized form looks as follows;

$$\begin{bmatrix} a & b & 0 & 0 \\ b & d & 0 & 0 \\ 0 & 0 & a & b \\ 0 & 0 & b & d \end{bmatrix} \begin{bmatrix} j_{11} \\ j_{12} \\ j_{21} \\ j_{22} \end{bmatrix} + \begin{bmatrix} a & b & 0 & 0 \\ 0 & 0 & a & b \\ b & d & 0 & 0 \\ 0 & 0 & b & d \end{bmatrix} \begin{bmatrix} j_{11} \\ j_{12} \\ j_{21} \\ j_{22} \end{bmatrix} = -2 \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

The addition of two coefficient matrices appearing in the equation above gives **A** matrix of eqn. (6).

2. The Algorithm of the Developed Method to Infer the Network based on Lyapunov Equation

Input: covariance matrix, fluctuation matrix

Output: Jacobian vector (j)

Algorithm:

1. Fix the length of the individuals of Genetic Algorithm (GA), to be represented as bit-string.
2. Convert the input covariance matrix to GGM (Graphical Gaussian Model) correlation matrix
3. Check GGM-type correlations with >0.60 and < 0.001

IF >0.60

Make the corresponding symmetric entries in binary individuals 1

ELSEIF < 0.001

Make the corresponding symmetric entries in binary individuals 0.

4. Determine the number of entries of the individuals that was not assigned a value. This will be the input parameter to GA as the length of individuals.
5. Enter parameters for GA:
Population Size (150), Number of Generations (800), Mutation Rate (1/IndividualLength), Elite Count (3), Individual Length, Other Parameters: default
6. Do GA to assign binary values to the rest of entries in the original individual vectors
7. For each generated individual,
 - a. Apply least square solution to $Aj=d$ by fixing the entries of j which corresponds to zeros of the individual vector to zero.
 - b. Calculate the values of each of the two terms of the fitness equation (Eqn.7) for the individual.

- c. Replace the first term by $(n^2-n) \times 0.9$ if it is greater than this value.
 - d. Replace the second term by $(10 - [10 + \log_{10}(\|A_j + 2d\|)]/50)$ if the residual norm of the individual is smaller than 1×10^{-10} .
 - e. Calculate the fitness of the individual.
8. Repeat 6. and 7. for the entered Number of Generations.
 9. Select best individual in the last population, and record the corresponding j .
 10. Compare it with the true Jacobian vector, calculate TPR, FPR.