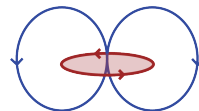
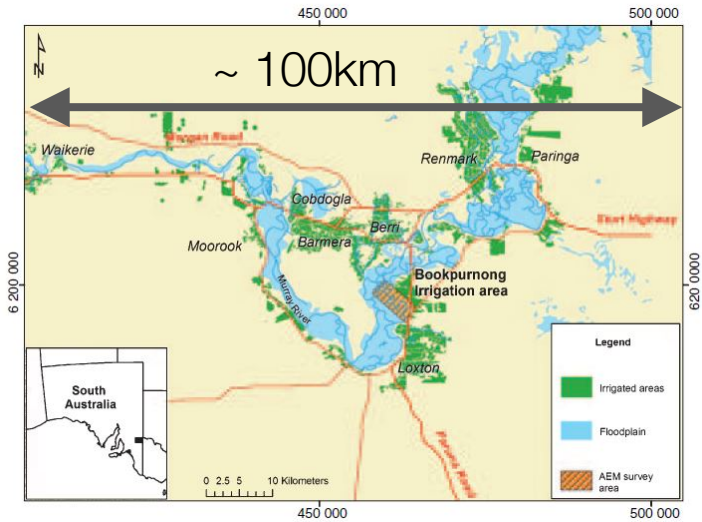


# EM: Inductive Sources

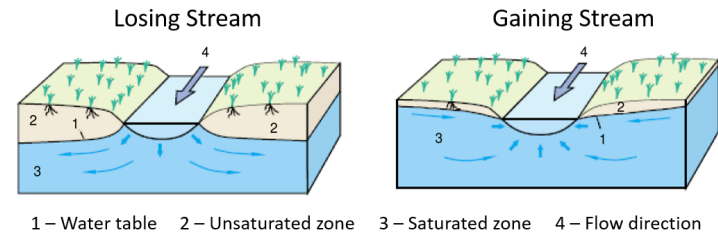


# Motivation

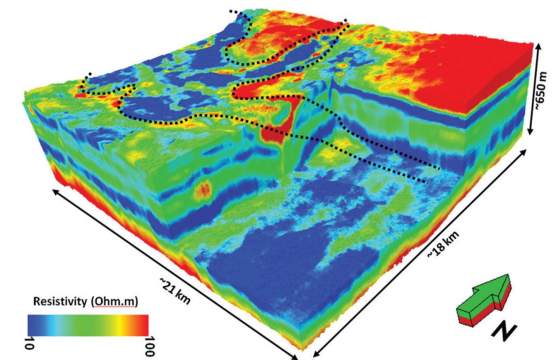
Large areas to be covered



Groundwater



High resolution near surface



Rugged terrain



Minerals



# Outline

## Setup

- Basic experiment
- Transmitters, Receivers

## Frequency Domain EM

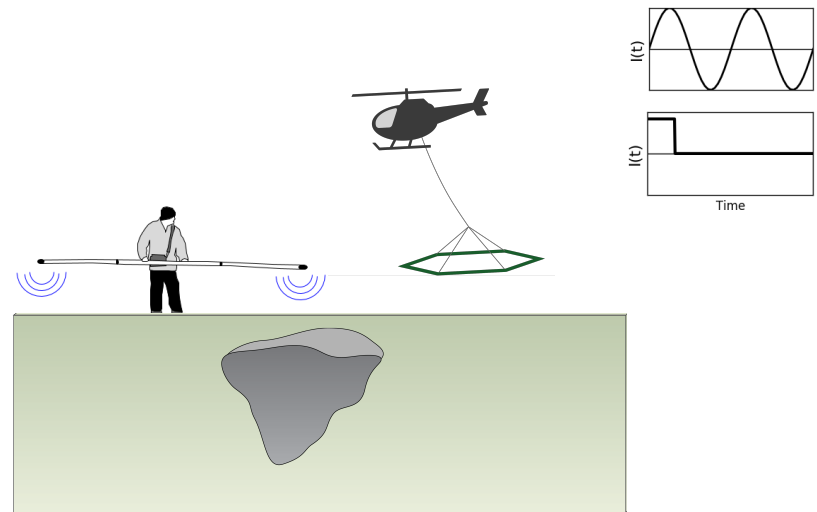
- Vertical Magnetic Dipole
- Effects of Frequency
- Case History – Groundwater

## Time Domain EM

- Vertical Magnetic Dipole
- Propagation with Time
- Case History – Near surface geology

# Important questions

- What is the target?
  - at the surface? At depth?. 1D, 2D, 3D?
- Transmitter
  - Location: surface? in the air?
  - Waveform: frequency or time?
  - “Size” and orientation?
- Exciting the target
  - Conductivity of the target and host
  - Geometry of the target (Coupling)
- Receiver and data
  - What fields to measure?
  - What instrument?
- Where to collect data? How many? How accurate?
- What is depth of investigation?
- What is the “footprint” of the transmitter”
  - These are questions of SURVEY DESIGN



# Basic Experiment

- **Transmitter:**

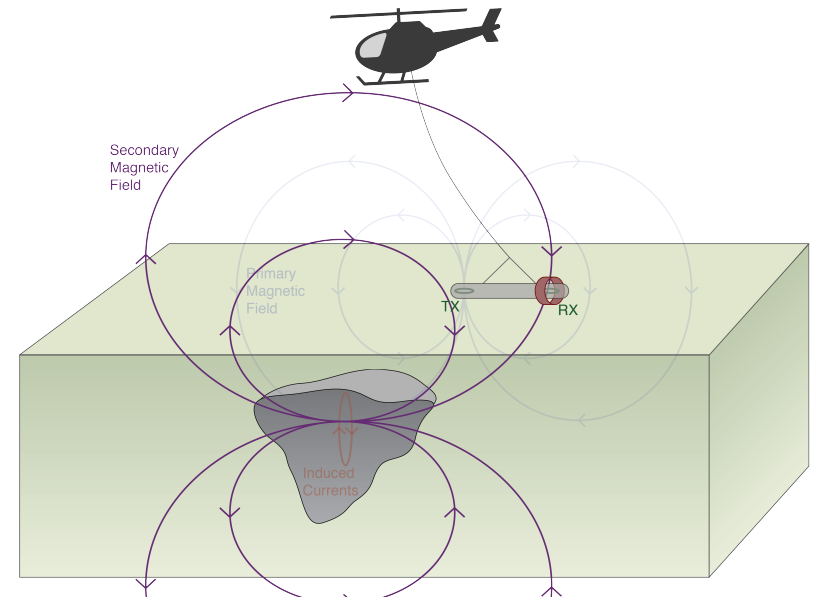
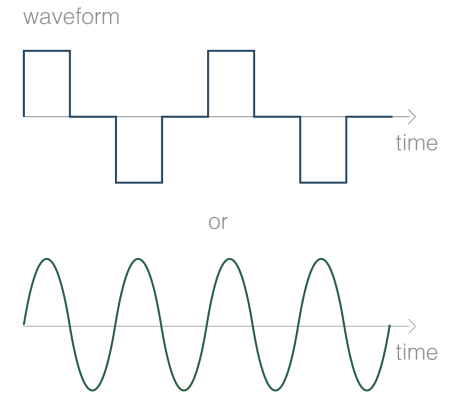
- Produces a primary magnetic field

- **Exciting the target:**

- Time varying magnetic fields generate electric fields everywhere
- Producing currents in conductors

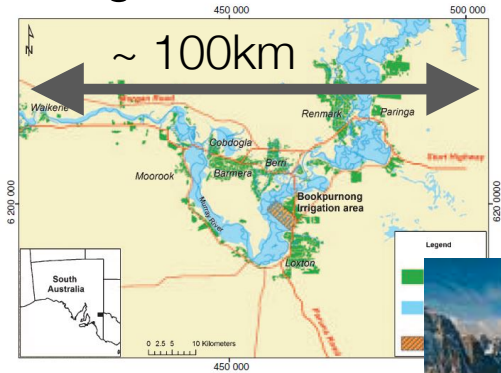
- **Receiver:**

- Induced currents produce secondary magnetic fields



# Transmitter

Large areas



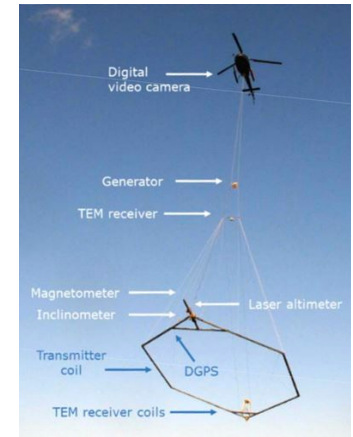
Rugged terrain



Airborne Survey

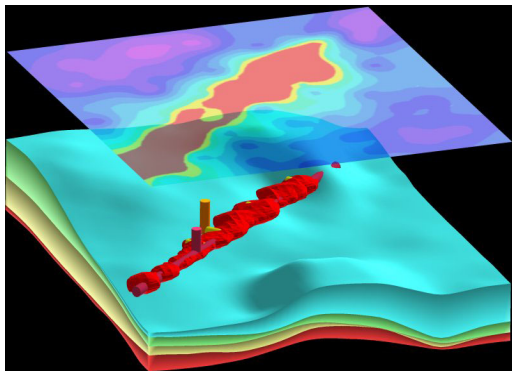


Resolve

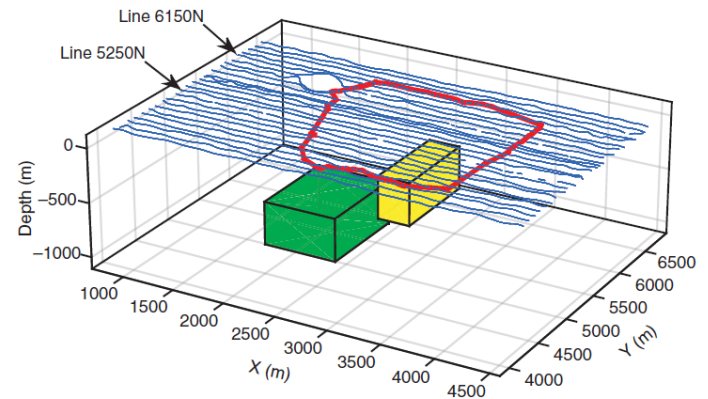


SkyTEM

Deep Targets

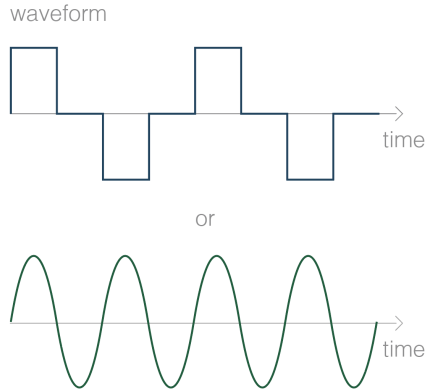


Large Loop



# Transmitter

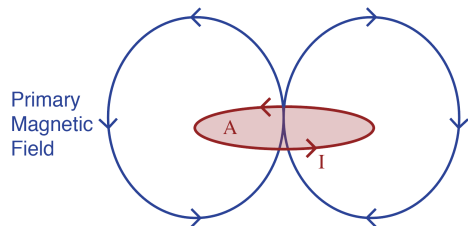
- Frequency or Time?



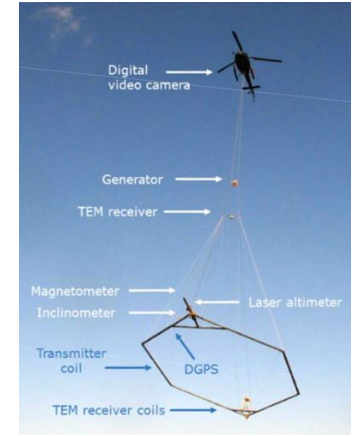
- Key factor is moment

$$m = I \text{ (current)} A \text{ (area)} N \text{ (# of turns)}$$

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left( \frac{3\mathbf{r}(\mathbf{m} \cdot \mathbf{r})}{|\mathbf{r}|^5} - \frac{\mathbf{m}}{|\mathbf{r}|^3} \right)$$



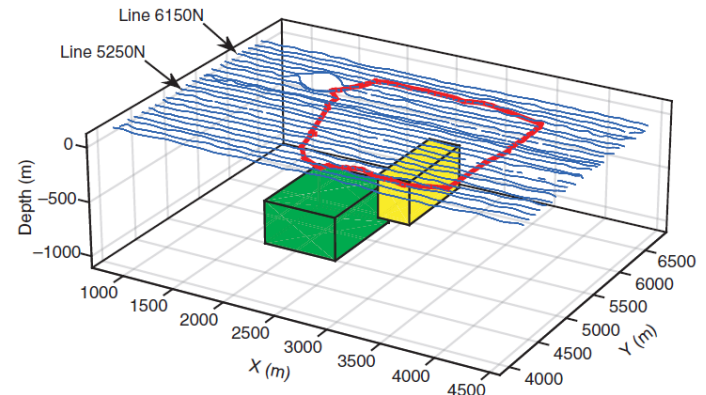
## Airborne Survey



Resolve

SkyTEM

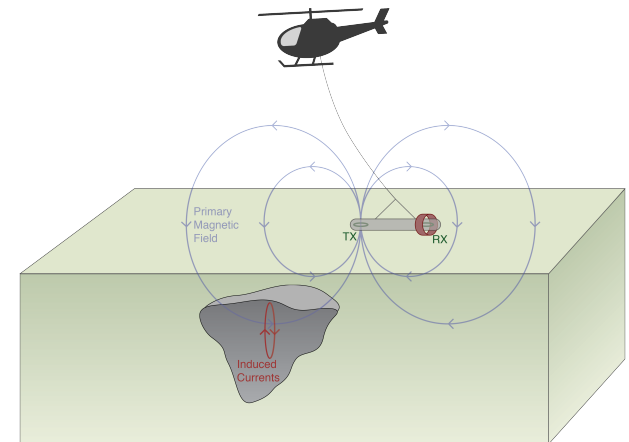
## Large Loop



# Exciting the target

- Primary field from a loop
- Fields fall off
  - $1/r^3$  geometric decay
  - Attenuation
- Want to be as close as possible to target
  - Ground based systems
  - Helicopter
  - Fixed wing aircraft
- Always concerned about coupling

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left( \frac{3\mathbf{r}(\mathbf{m} \cdot \mathbf{r})}{|\mathbf{r}|^5} - \frac{\mathbf{m}}{|\mathbf{r}|^3} \right)$$



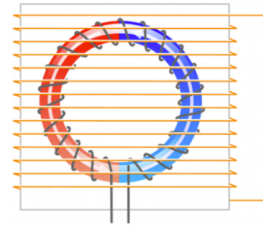


# Receiver and Data

## Magnetometer

- Measures:
  - Magnetic field
  - 3 components
- eg. 3-component fluxgate

$\mathbf{b}(t)$

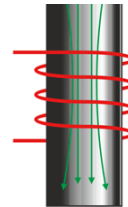


Fluxgate

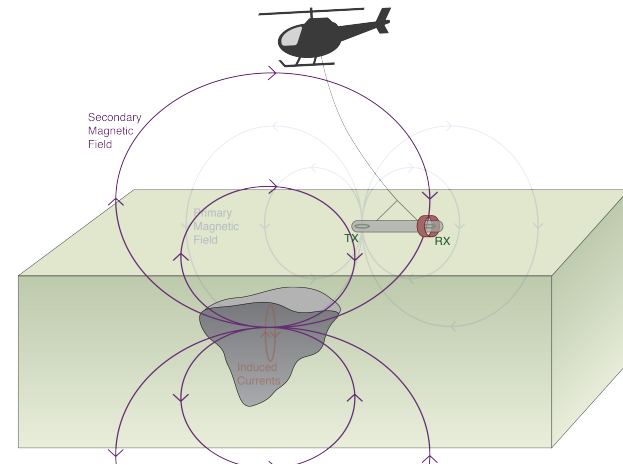
## Coil

- Measures:
  - Voltage
  - Single component that depends on coil orientation
    - Coupling matters
- eg. airborne frequency domain.
  - ratio of  $H_s/H_p$  is the same as  $V_s/V_p$

$$\frac{\partial b}{\partial t}$$

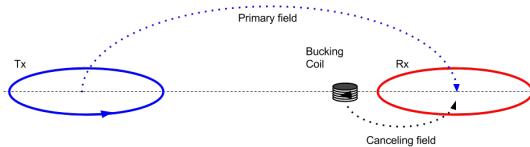


Coil

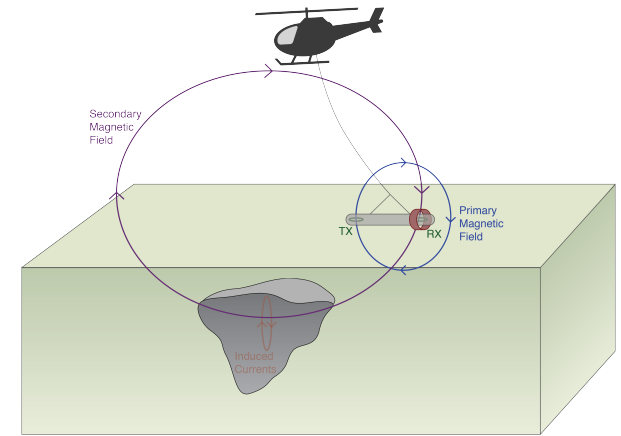


# Receiver: Frequency Domain

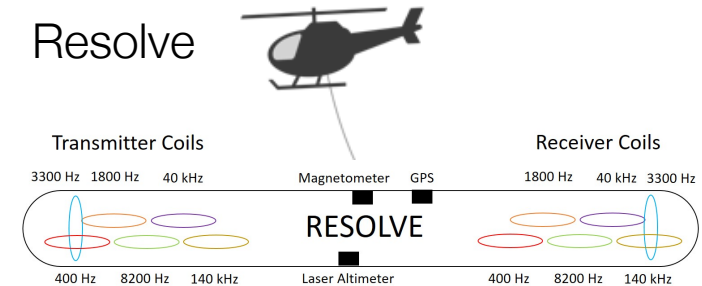
- Primary field
  - always “on”
  - large compared to secondary fields
- Primary removal
  - Compute and subtract
  - Bucking coil



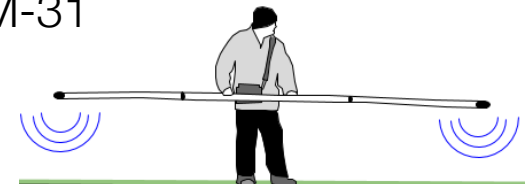
- Main requirement:
  - Know positions of Tx and Rx
  - Keep them in one unit



Resolve

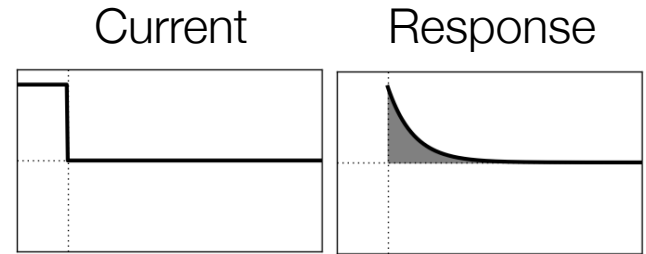


EM-31

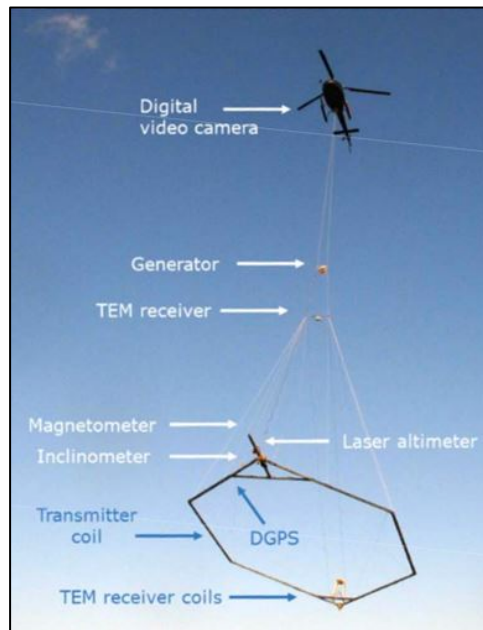


# Receiver: Time Domain

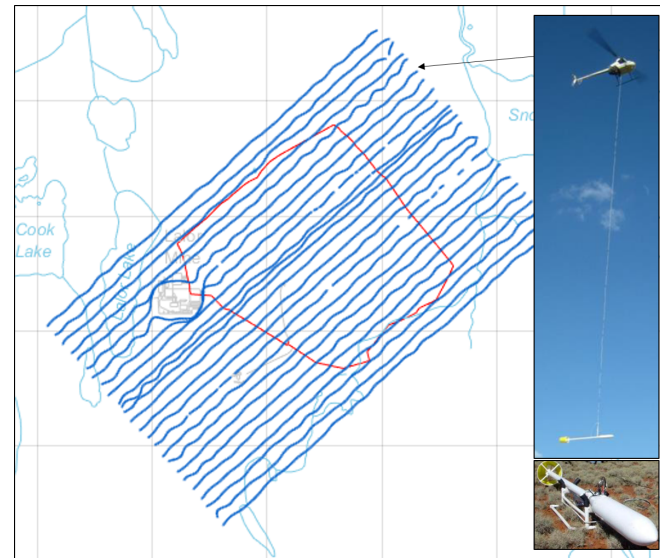
- Primary field has off-time
- Measure secondary fields
- Receivers can be mounted on transmitter loop or above it



SkyTEM

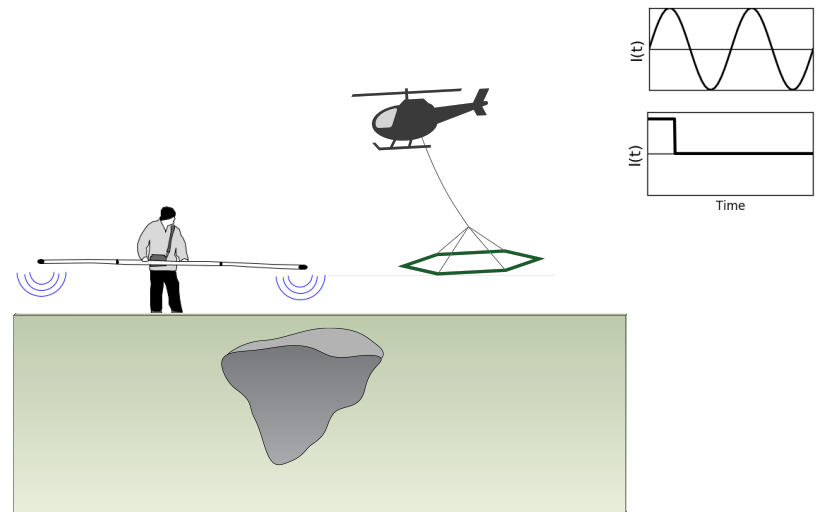


HeliSAM



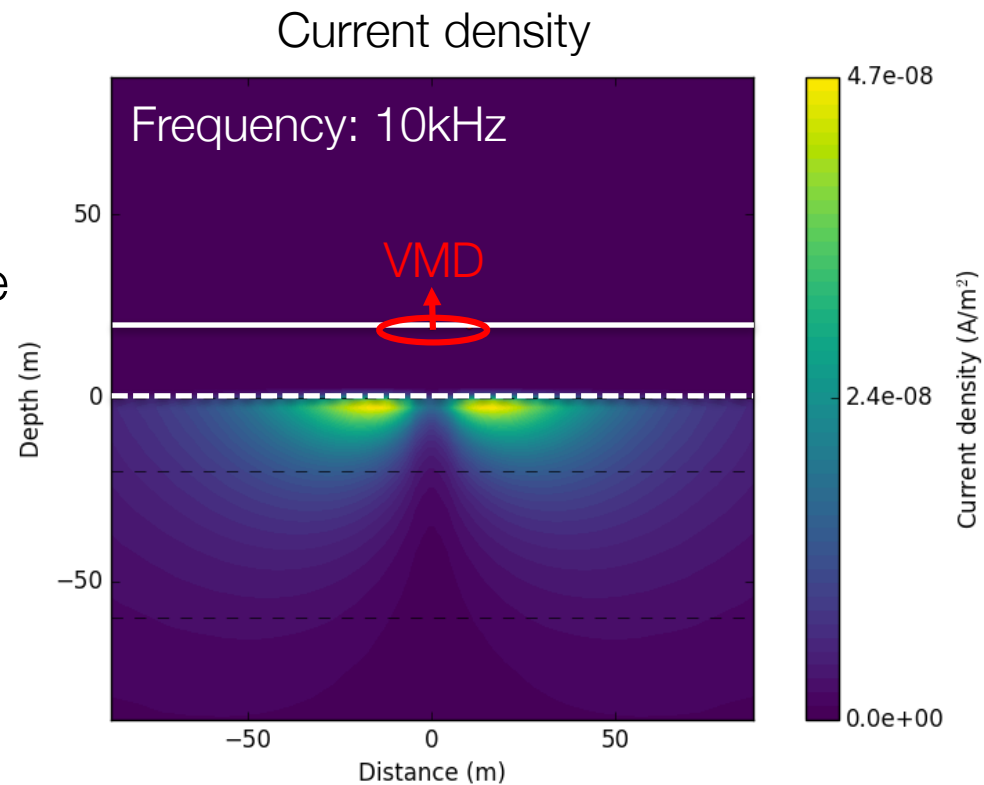
# Important questions

- What is the target?
  - at the surface? At depth?. 1D, 2D, 3D?
- Transmitter
  - Location: surface? in the air?
  - Waveform: frequency or time?
  - “Size” and orientation?
- Exciting the target
  - Conductivity of the target and host
  - Geometry of the target (Coupling)
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  - These are questions of SURVEY DESIGN

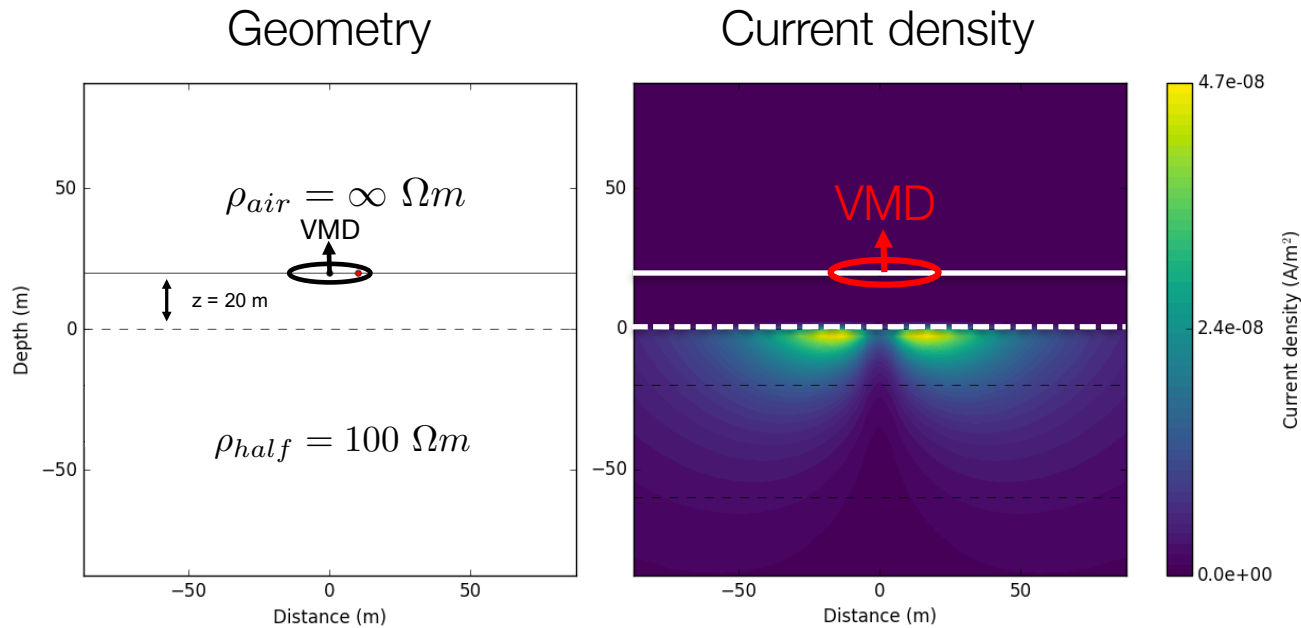


# Footprint of Airborne EM system

- What volume of earth is “seen” by the airborne system?
  - Where are the currents?
- Currents depend on
  - Transmitter
  - Waveform: frequency or time
  - Background conductivity
- Simple case: loop source over homogeneous earth

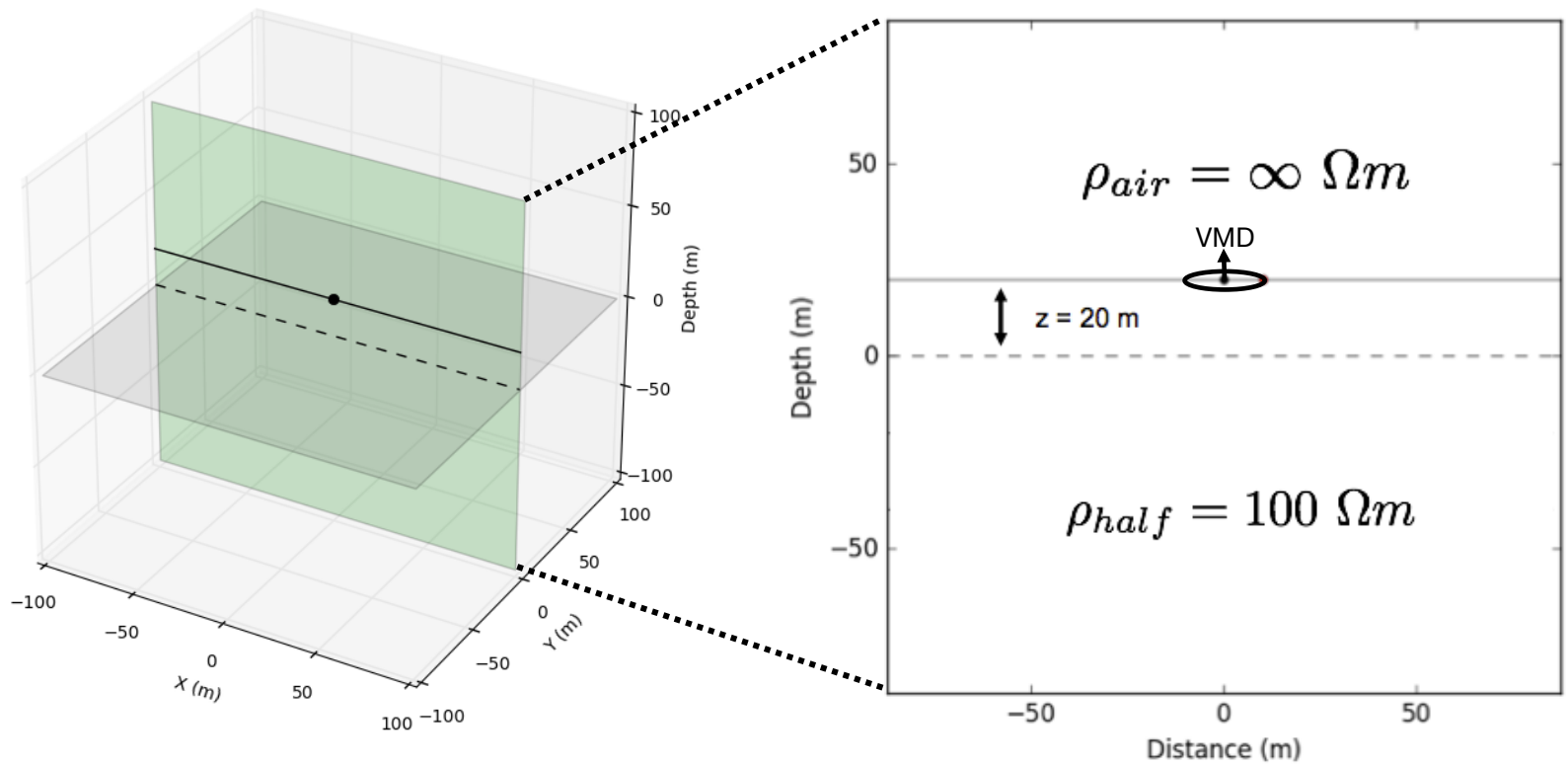


# Vertical Magnetic Dipole (VMD)



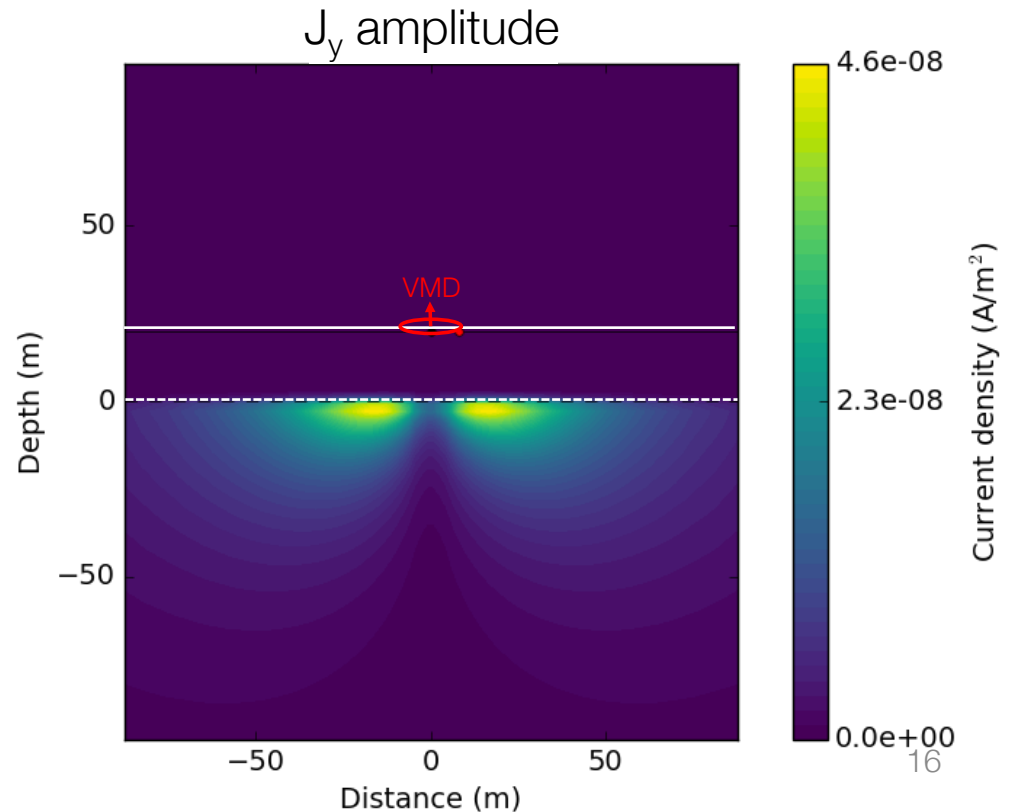
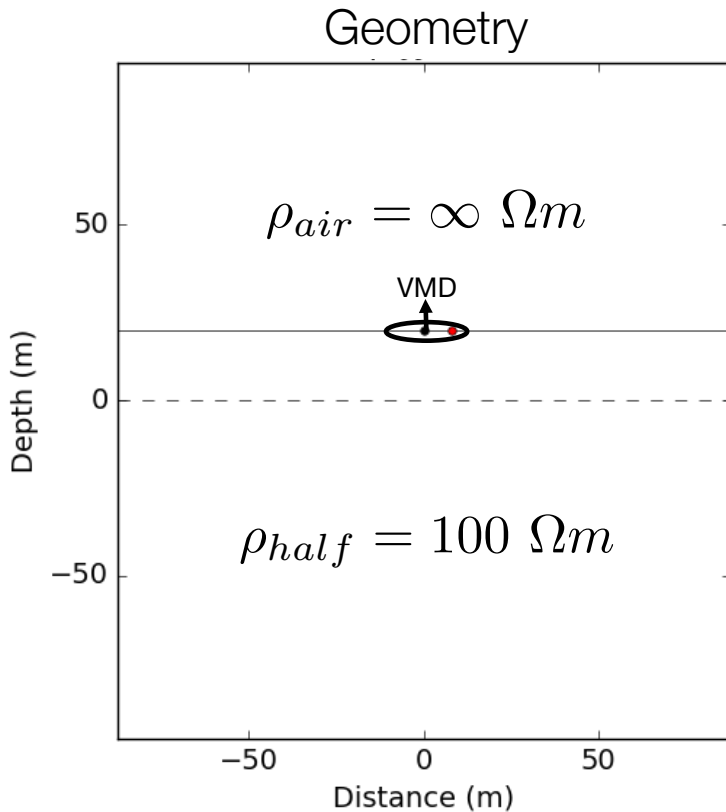
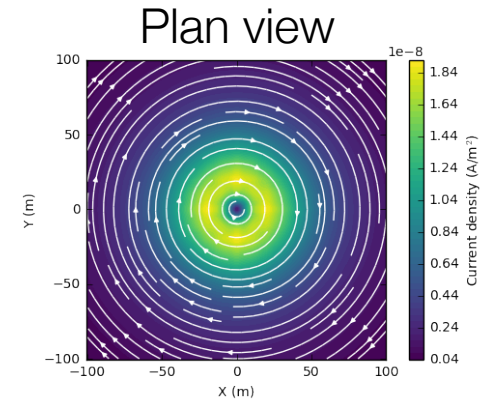
- Some questions
  - Where, and how strong, are the currents?
  - How do they change with transmitter frequency?
  - How do they depend upon the conductivity?
  - What do the resulting magnetic fields look like?

# Vertical Magnetic Dipole over a halfspace (FDEM)



# Current Density

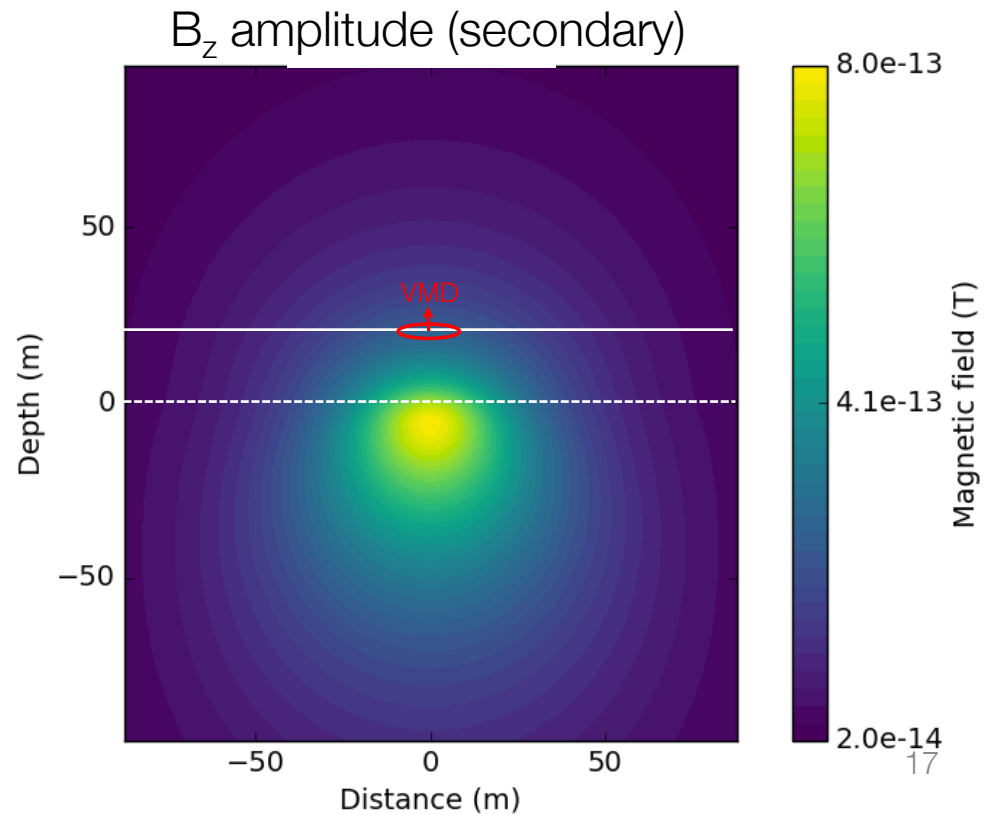
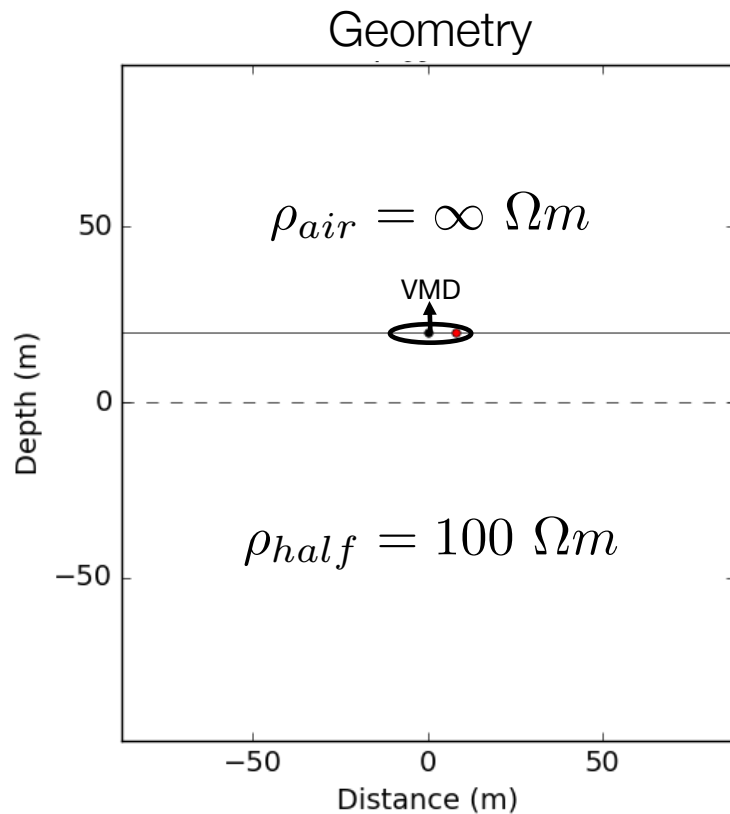
- Frequency = 10 kHz
- Currents in the earth flow in planes parallel to the Tx





# Secondary Magnetic Flux Density

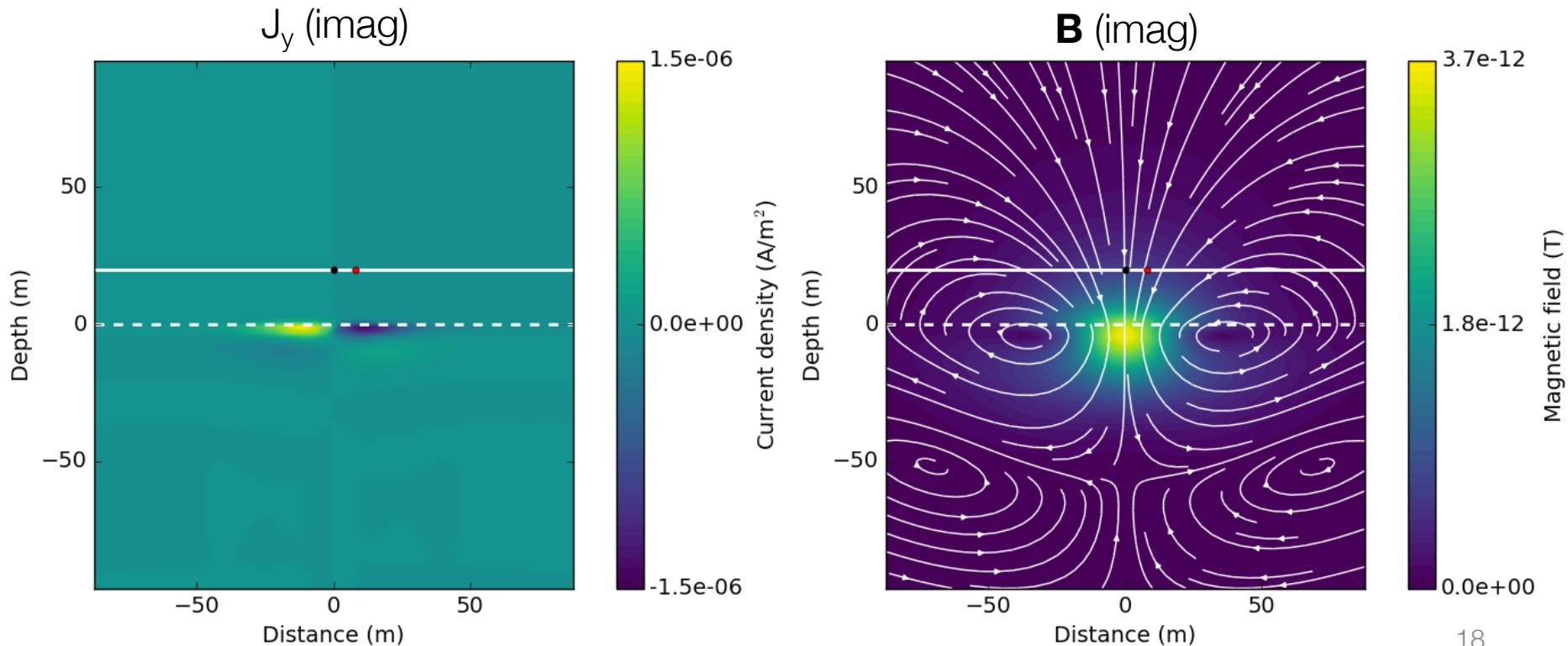
- Frequency = 10 kHz



# Effects of Frequency

- Frequency at 100 kHz
- Skin depth = 16 m
- Currents are concentrated at surface

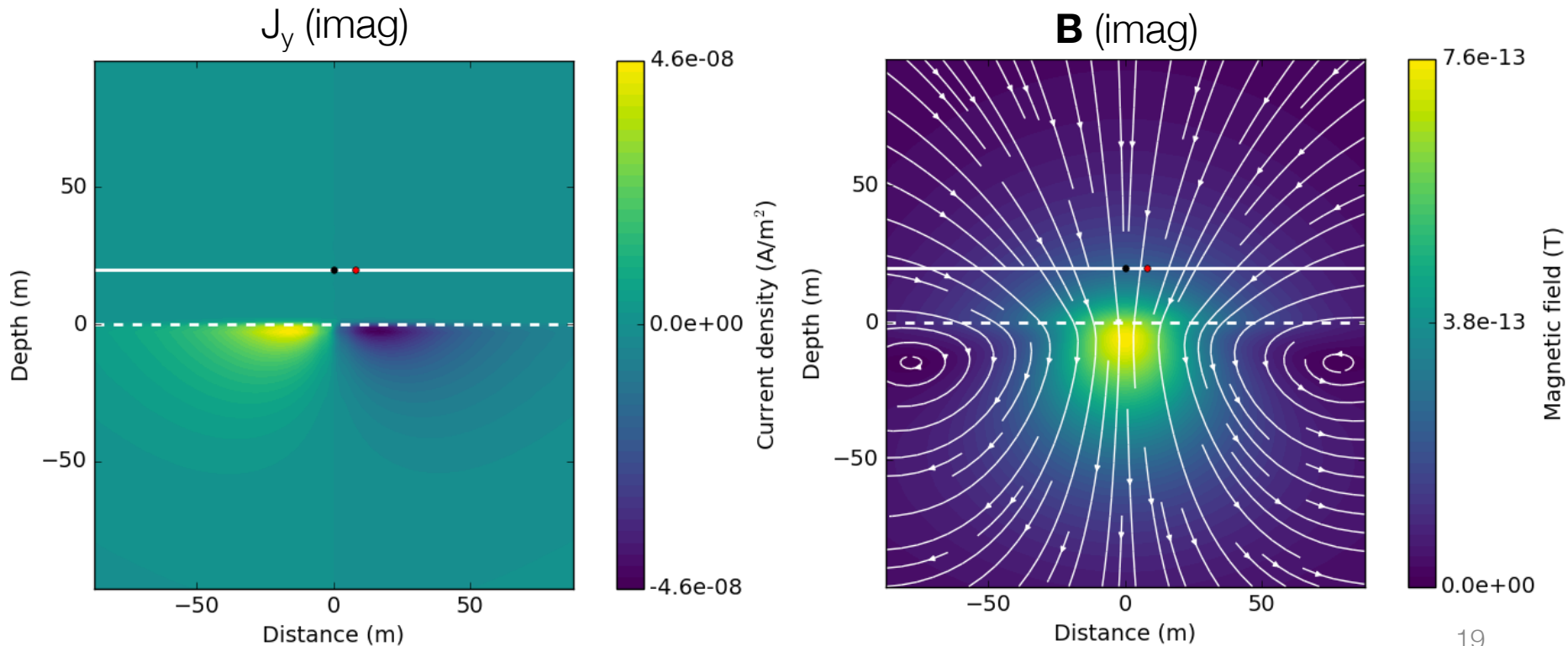
$$\delta = 503 \sqrt{\frac{\rho}{f}}$$



# Effects of Frequency

- Frequency at 10 kHz
- Skin depth = 50 m
- Currents diffusing downward and outward

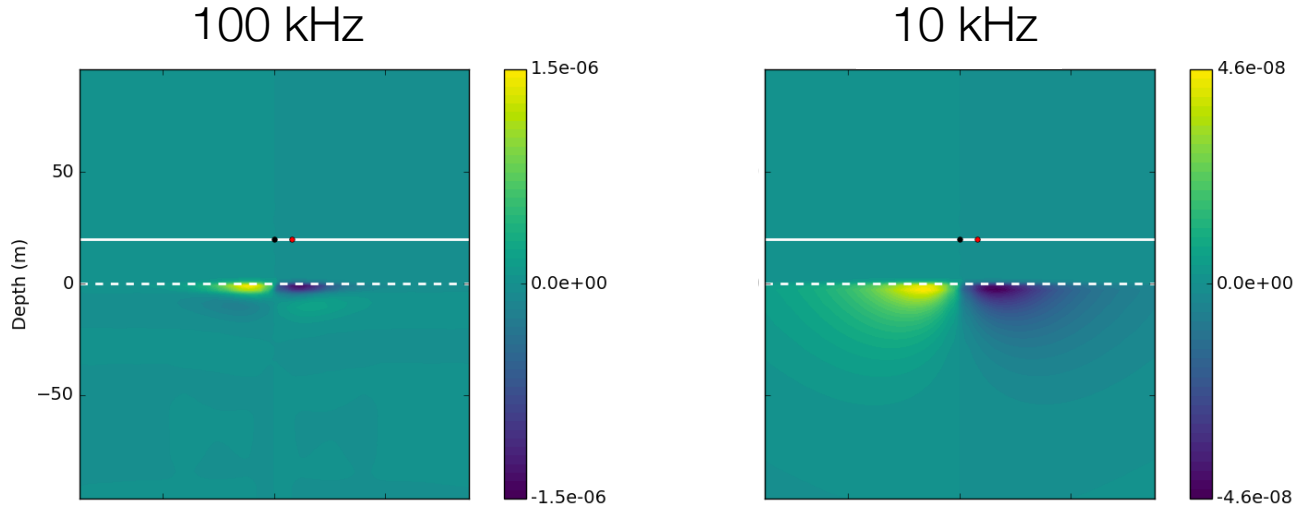
$$\delta = 503 \sqrt{\frac{\rho}{f}}$$



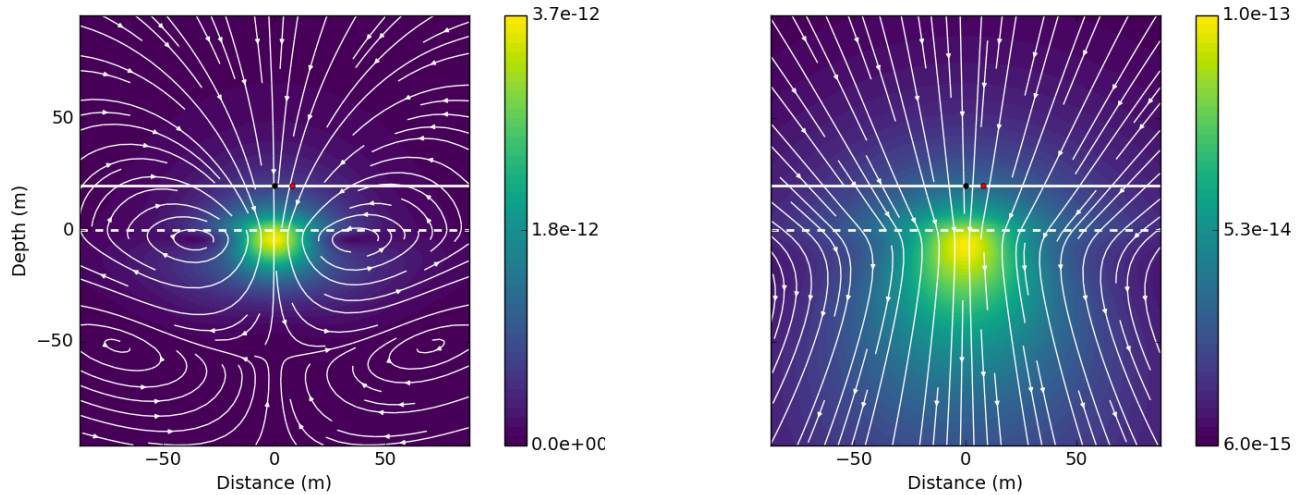
# Summary: Effects of Frequency

$$\delta = 503 \sqrt{\frac{\rho}{f}}$$

$J_y$  imag.

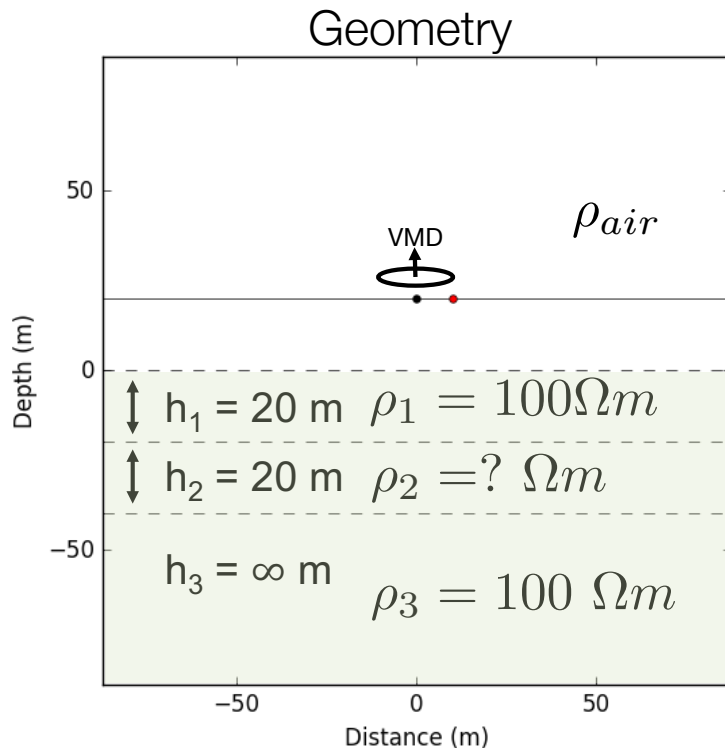


$\mathbf{B}$  imag.



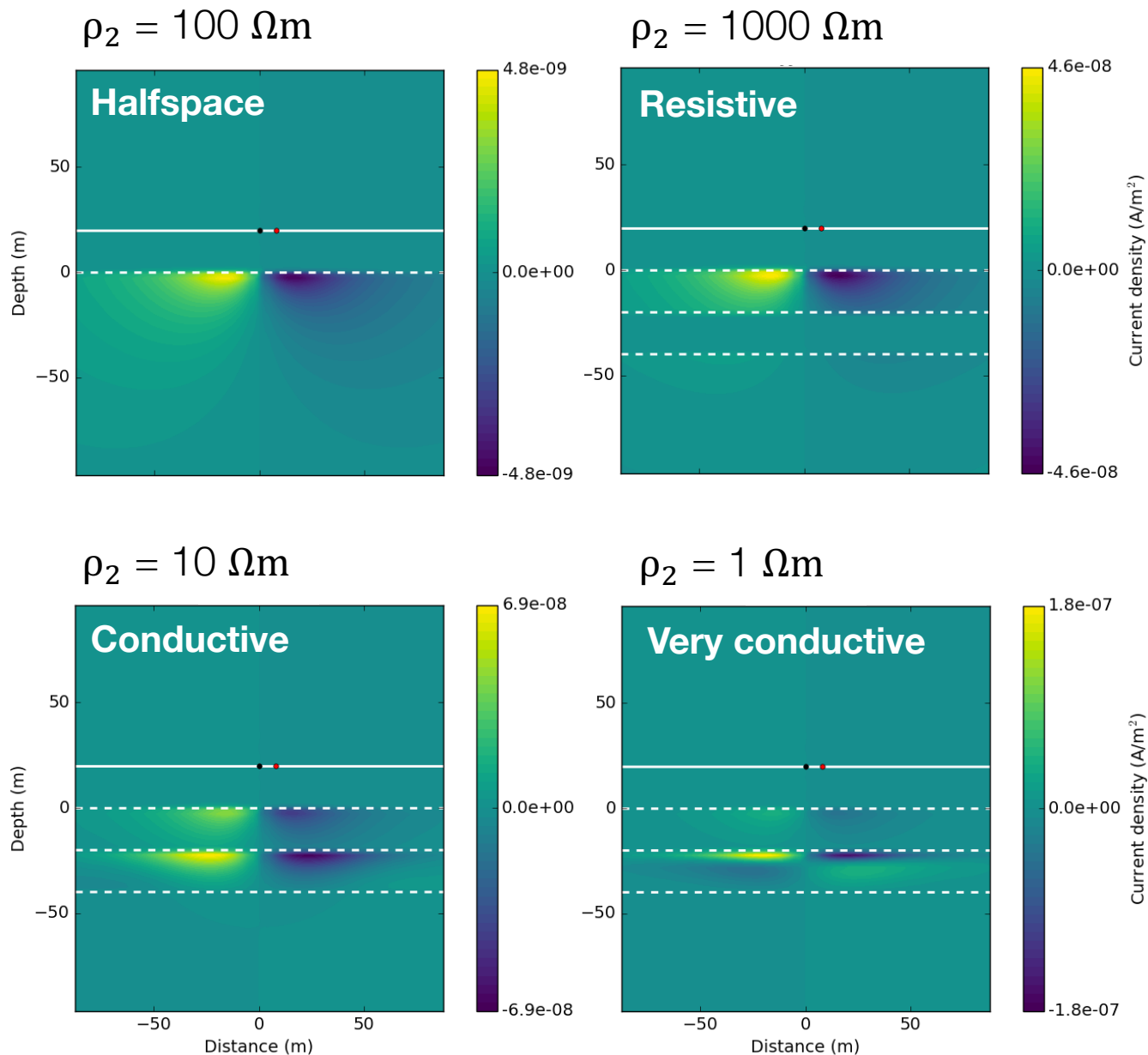
# Layered earth

- 3 layers + air,
- $\rho_2$  varies

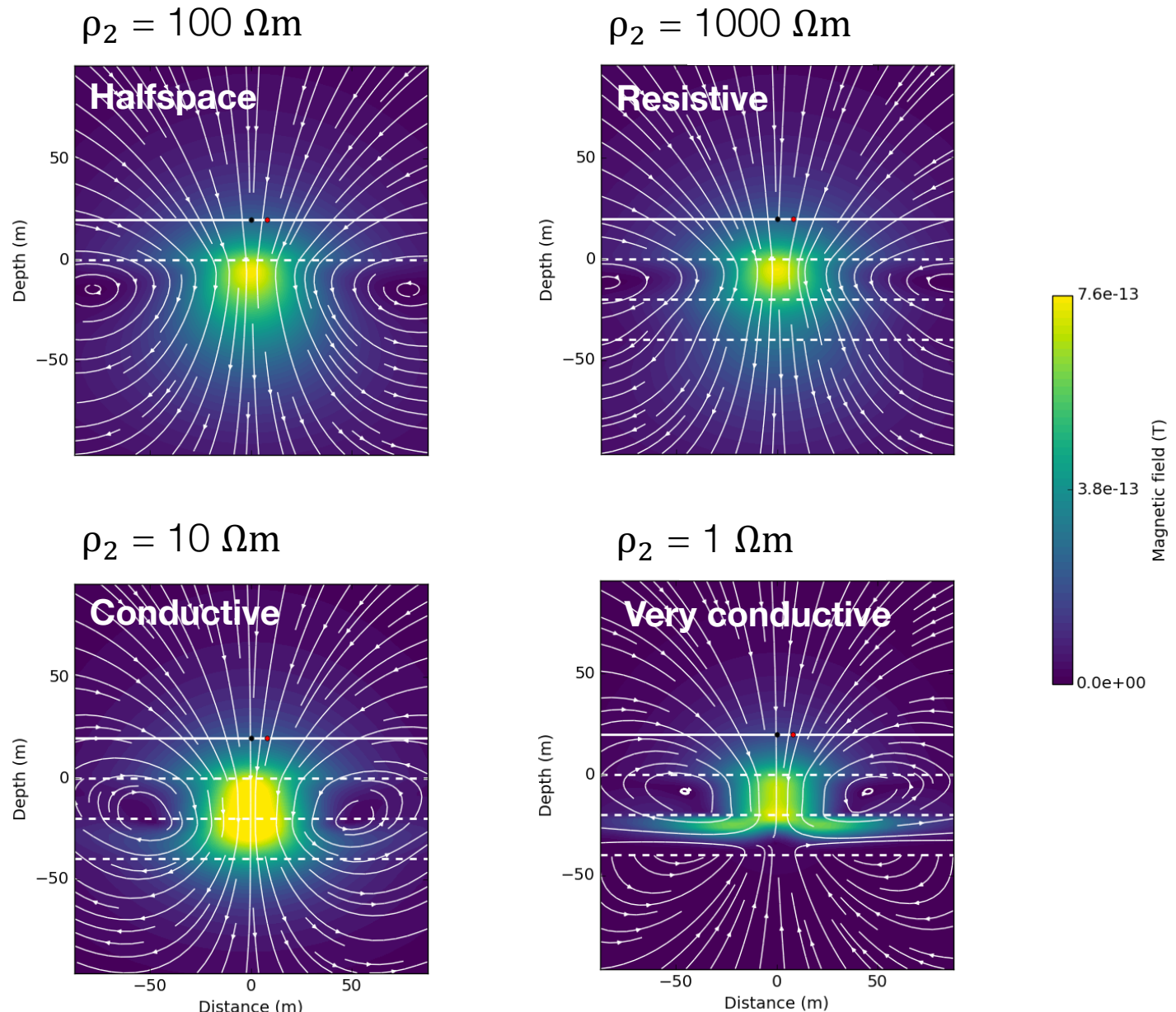


- Four different cases:
  - Halfspace
    - $\rho_2 = 100 \Omega m$
  - Resistive
    - $\rho_2 = 1000 \Omega m$
  - Conductive
    - $\rho_2 = 10 \Omega m$
  - Very conductive
    - $\rho_2 = 1 \Omega m$
- Fields
  - $J_y$  imag
  - Secondary **B** imag

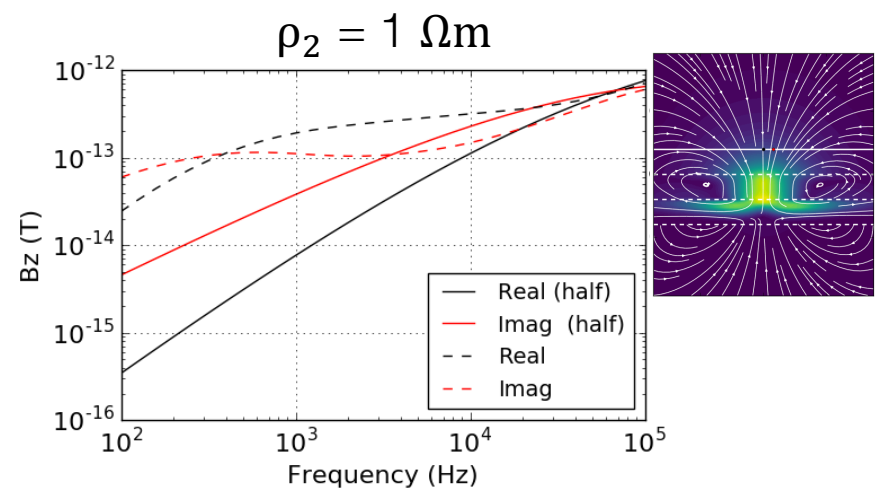
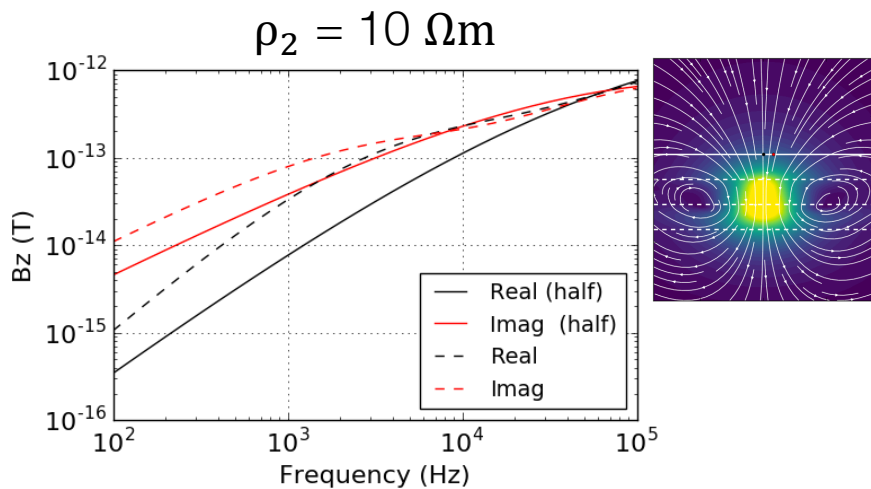
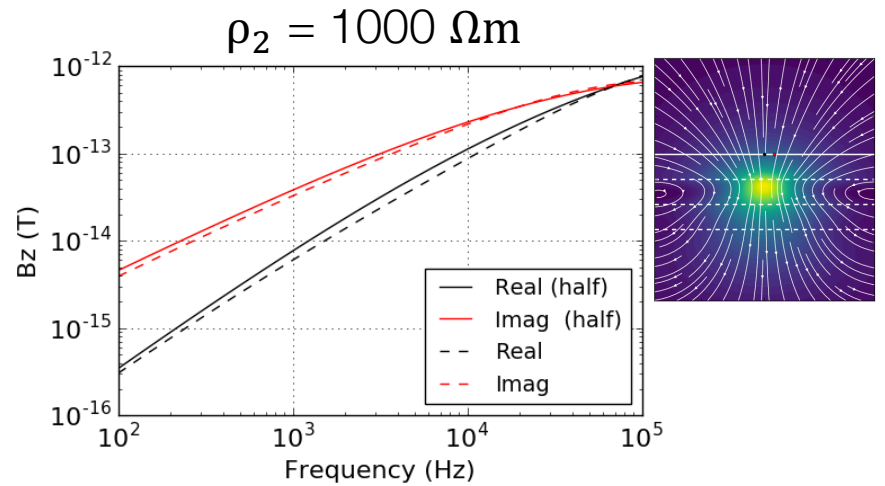
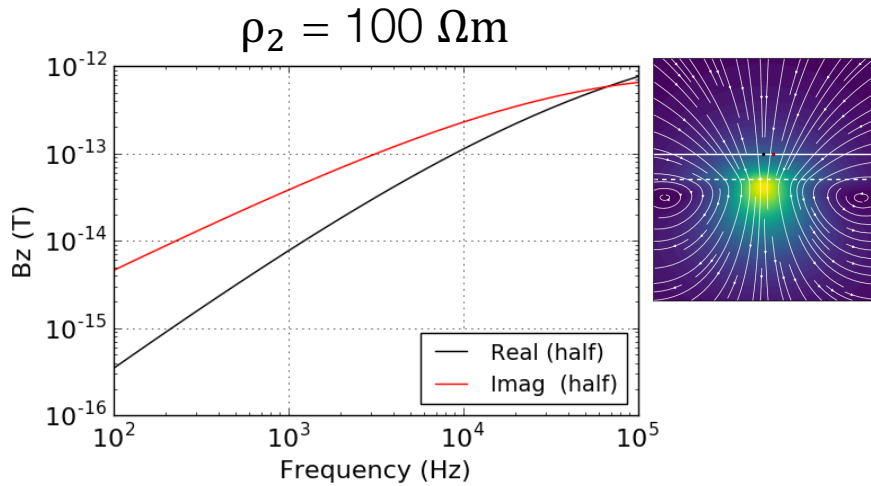
# Current density ( $J_y$ imag)



# Magnetic flux density (**B** imag)

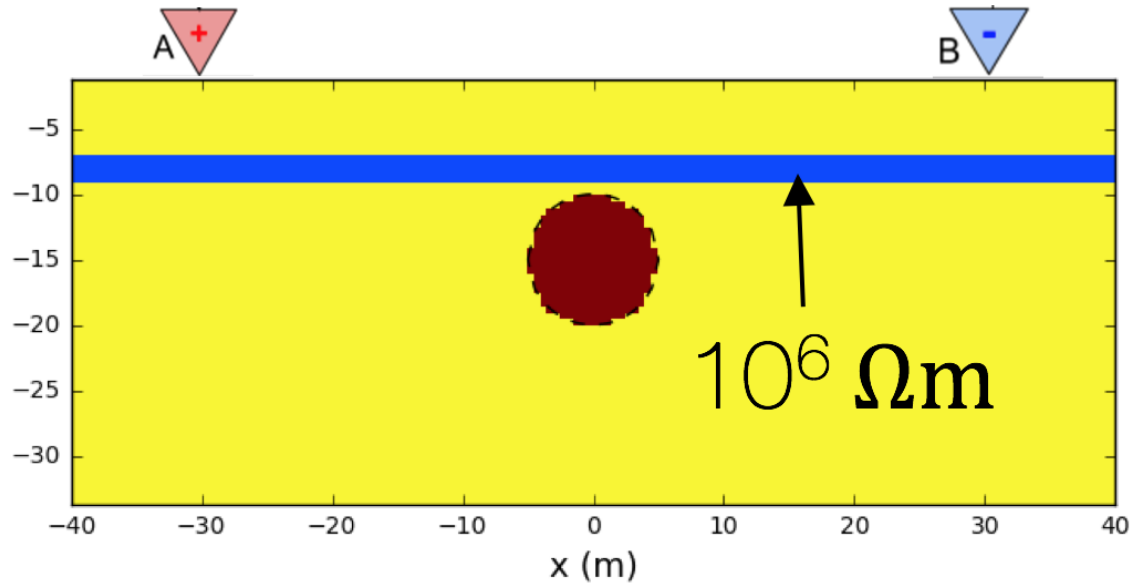


# $B_z$ sounding curves



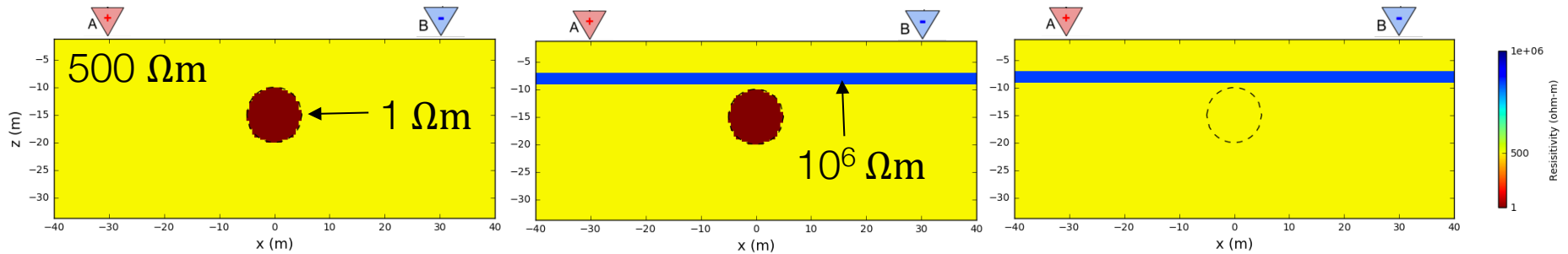


# Back to the “shielding” problem

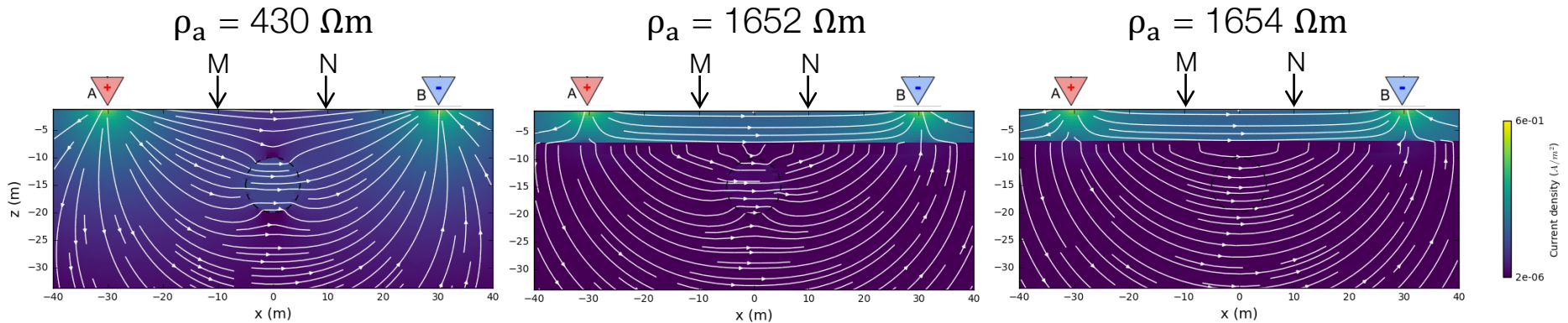


# Shielding: DC with resistive layer

Resistivity models (thin **resistive** layer)

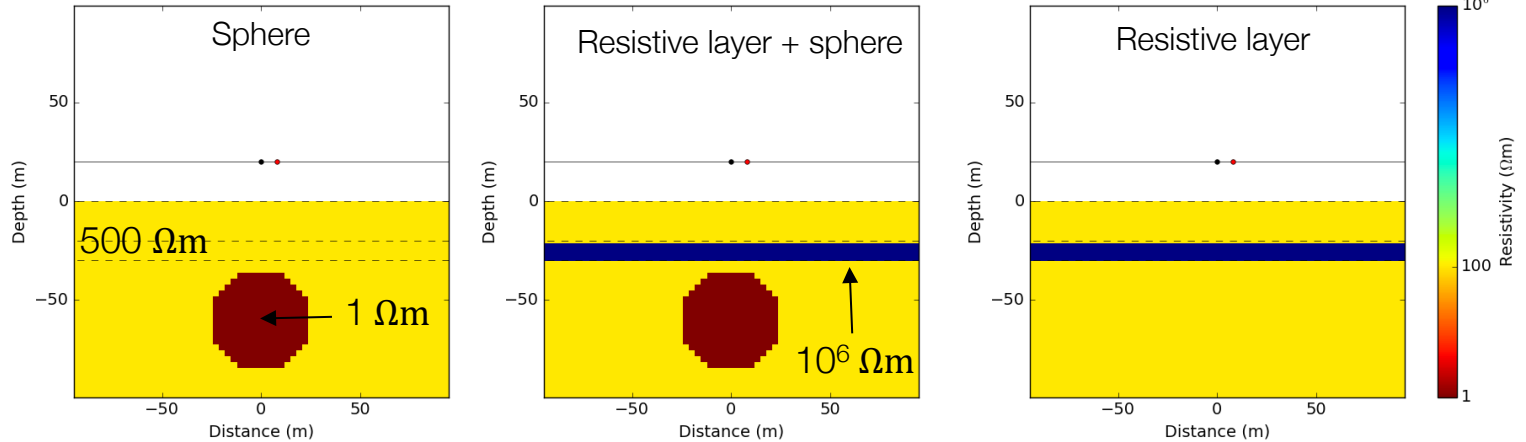


Currents and measured data at MN

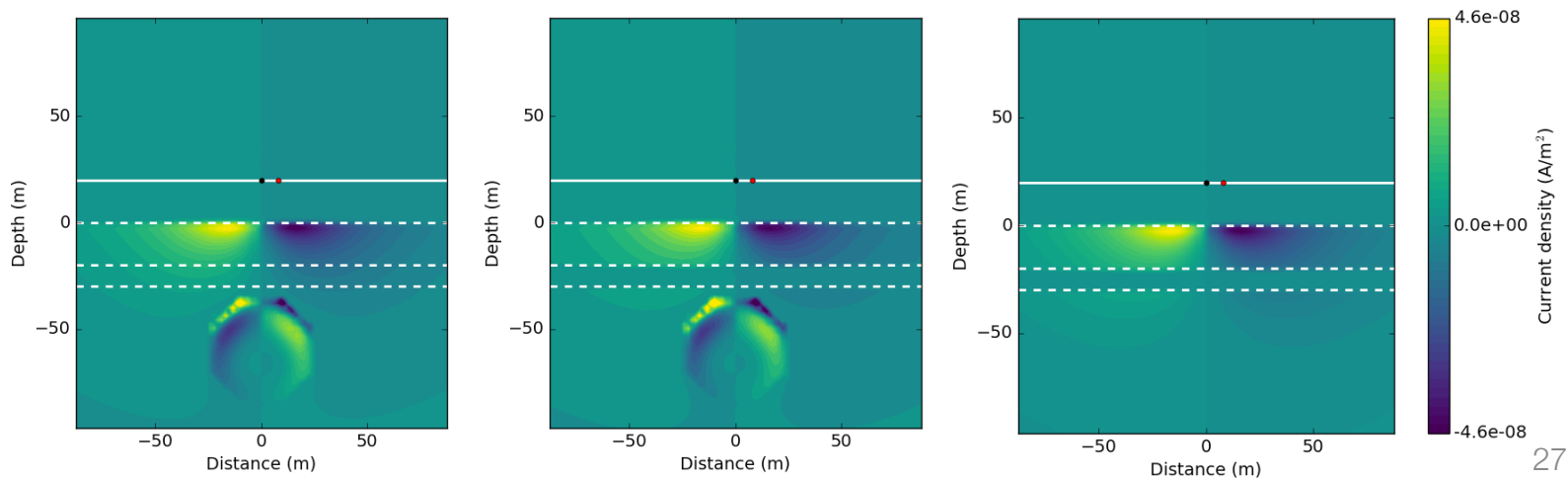


# Shielding: EM with resistive layer

## Resistivity models (thin **resistive** layer)

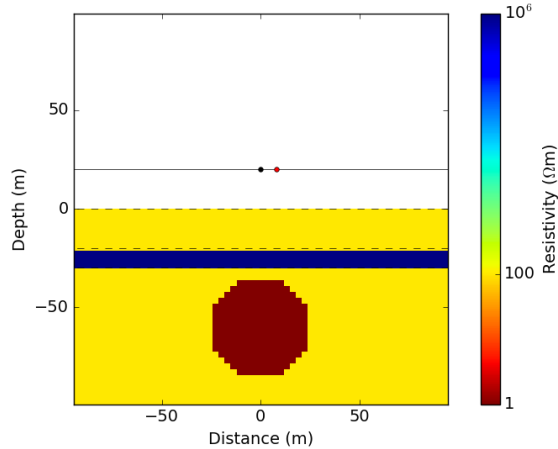


## Currents ( $J_y$ imag)

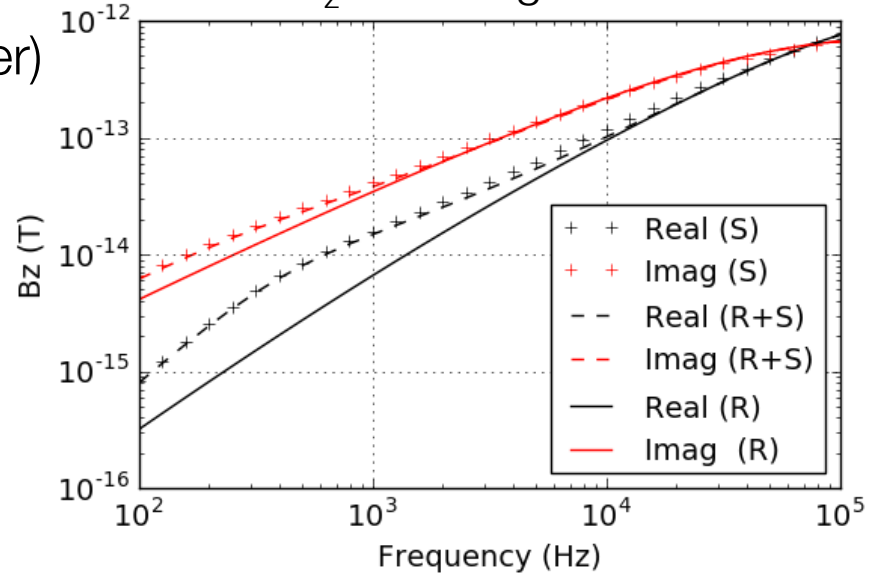


# Shielding: EM with resistive layer

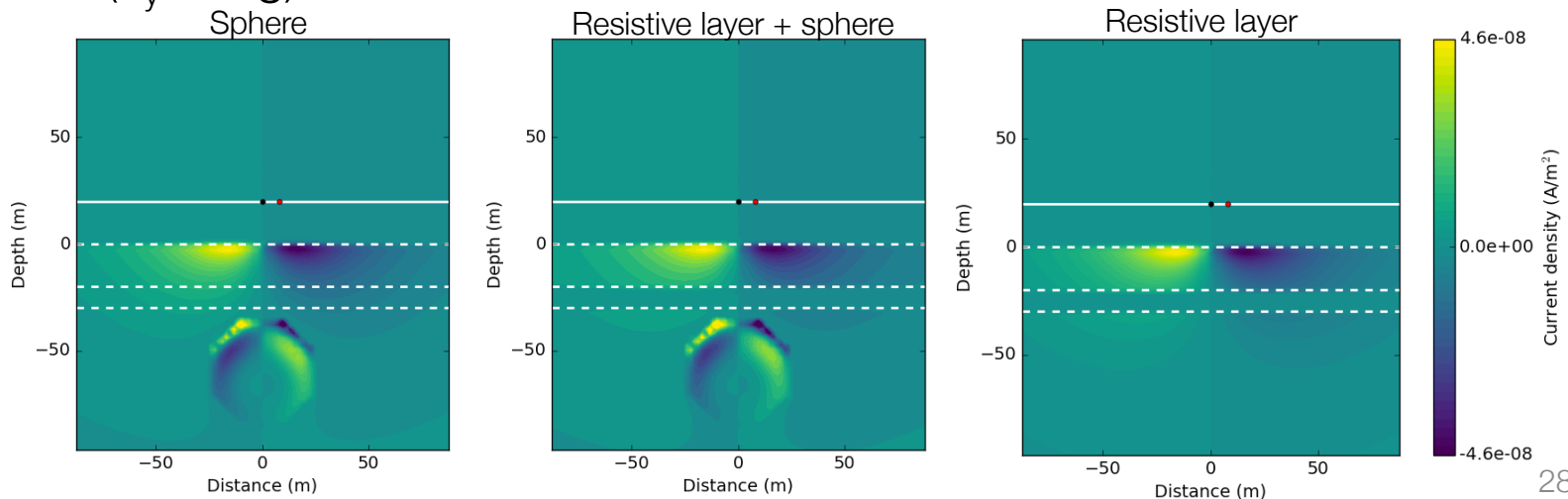
Resistivity models (thin **resistive** layer)



$B_z$  sounding curves

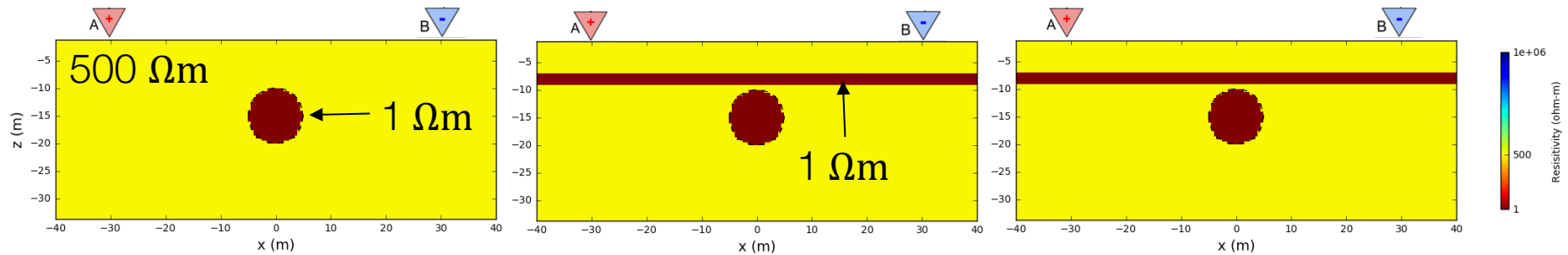


Currents ( $J_y$  imag)

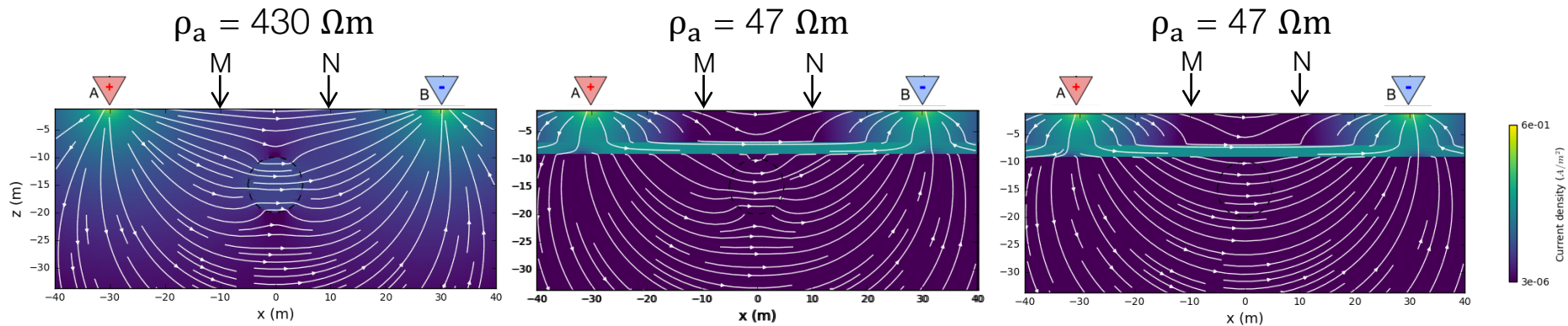


# Shielding: DC with conductive layer

Resistivity models (thin **conductive** layer)

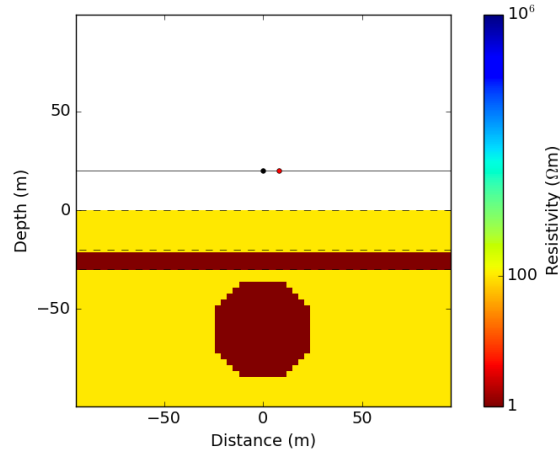


Currents and measured data at MN

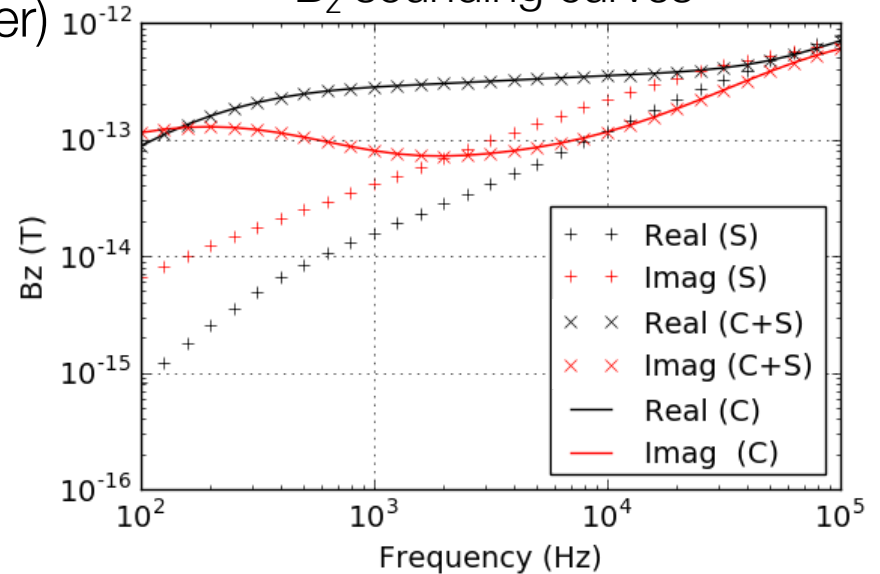


# Shielding: EM with conductive layer

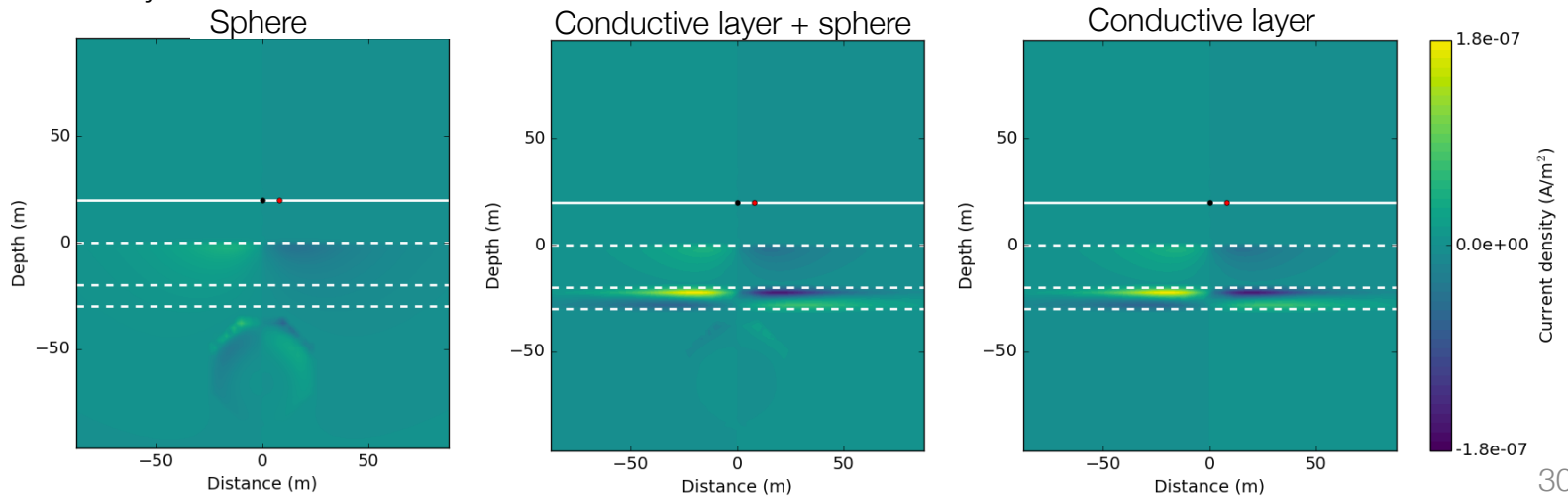
Conductivity models (thin **resistive** layer)



$B_z$  sounding curves



Currents ( $J_y$  imag)



# Outline

## Setup

- Basic experiment
- Transmitters, Receivers

## Frequency Domain EM

- Vertical Magnetic Dipole
- Effects of Frequency
- Questions
- Case History – Groundwater

## Time Domain EM

- Vertical Magnetic Dipole
- Propagation with Time
- Case History – Near surface geology

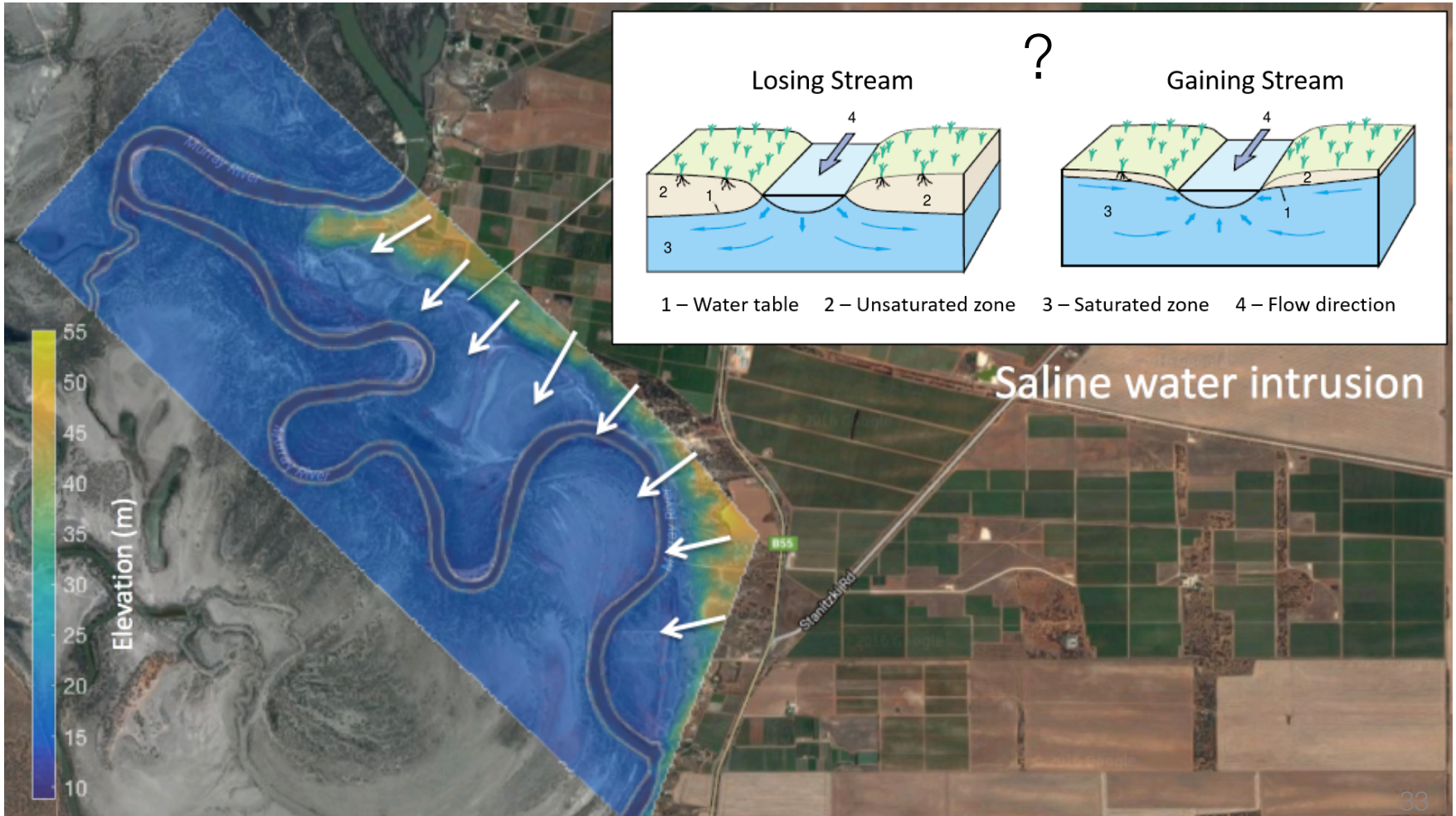
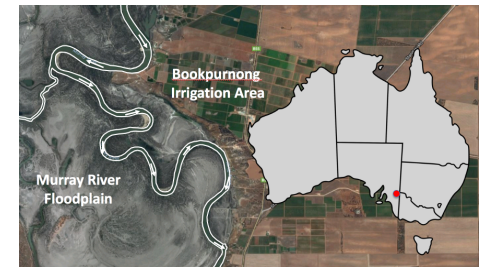
# Case History: Bookpurnong

Viezzoli et al., 2009



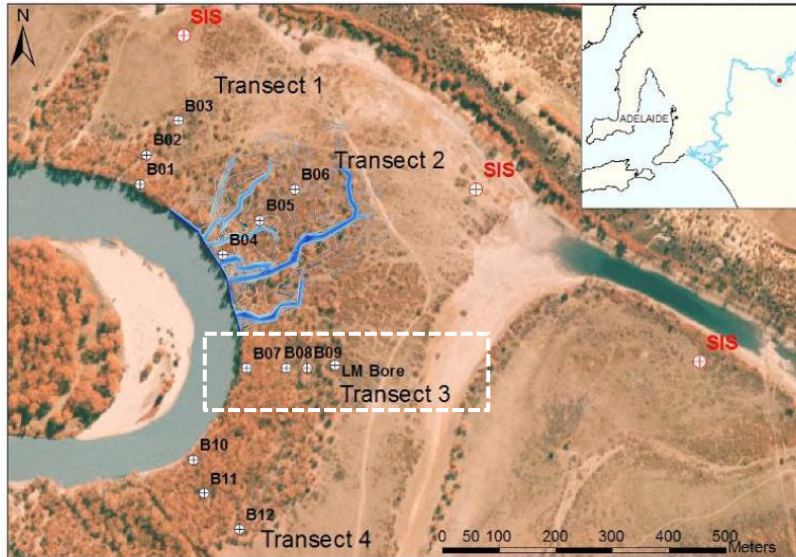
# Setup

- Geoscience Australia project
- Characterizing river salination



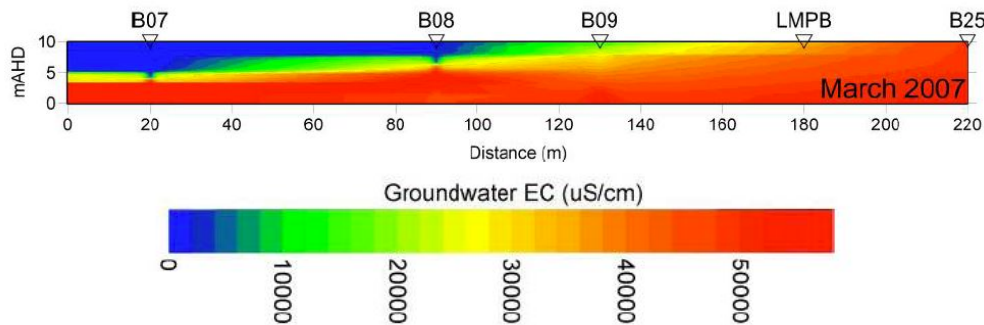
# Properties

Location map for salinity measurements



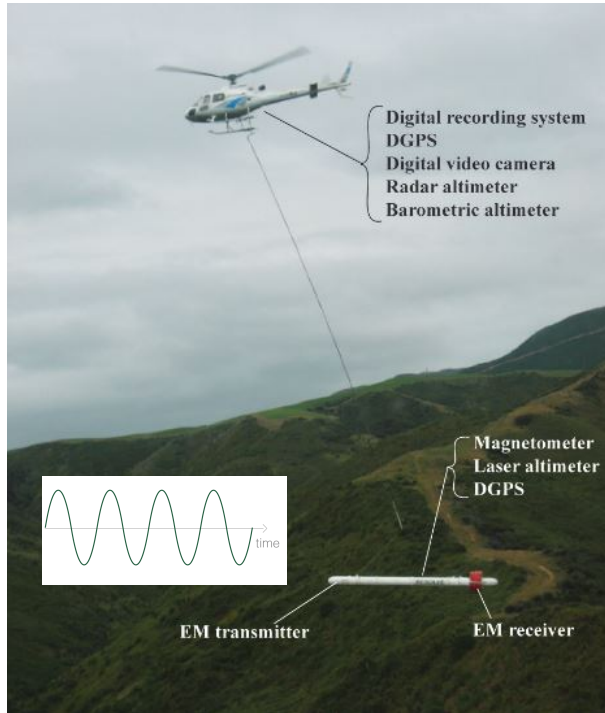
Unit	Conductivity
Saline water	High, 3 - 5 S/m
Fresh water	Low, 0.01 S/m

Conductivity from salinity measurements



# Survey

Resolve system (2008)



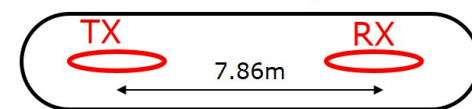
Flight lines



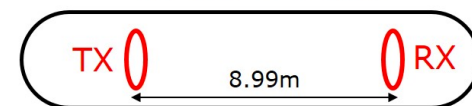
Horizontal Co-planar (HCP) frequencies:  
 - 382, 1822, 7970, 35920 and 130100 Hz

Vertical Co-axial (VCA) frequencies:  
 - 3258 Hz

Horizontal Co-planar



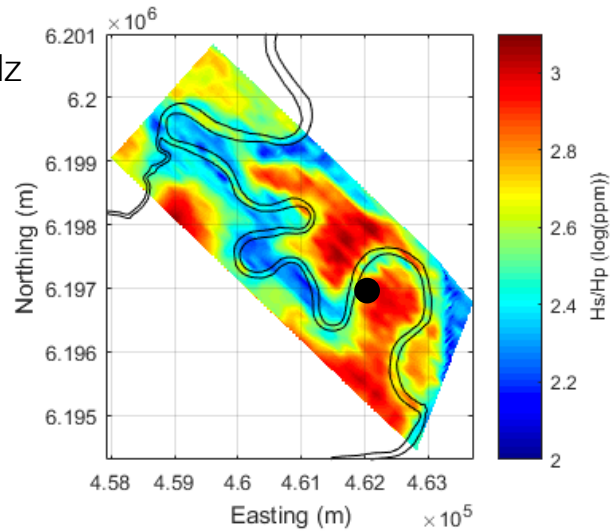
Vertical Co-axial



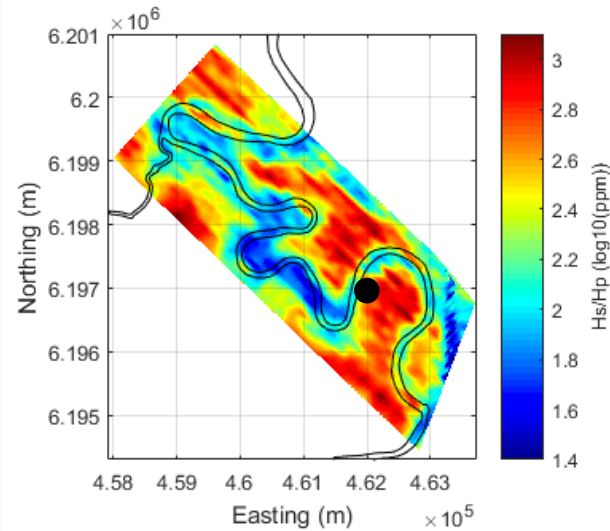
# Horizontal Co-planar (HCP) data

## In-Phase (Real)

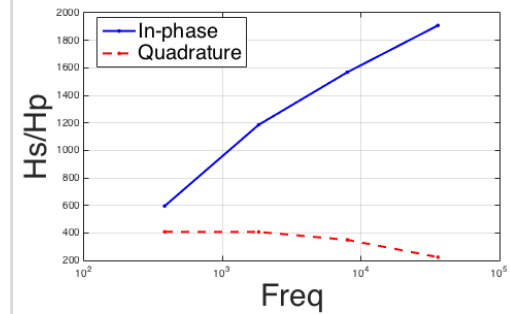
382 Hz



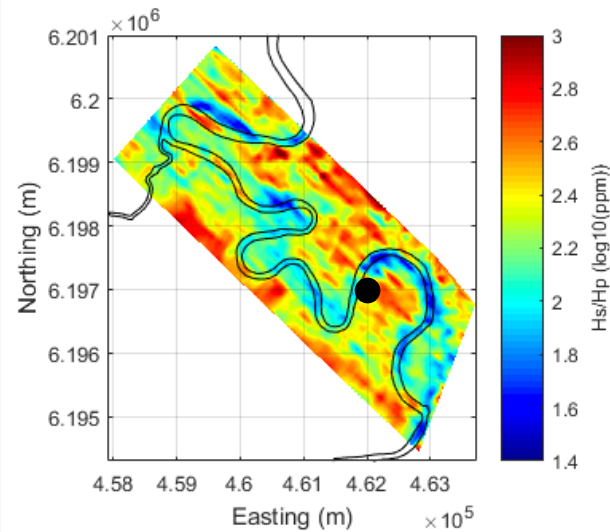
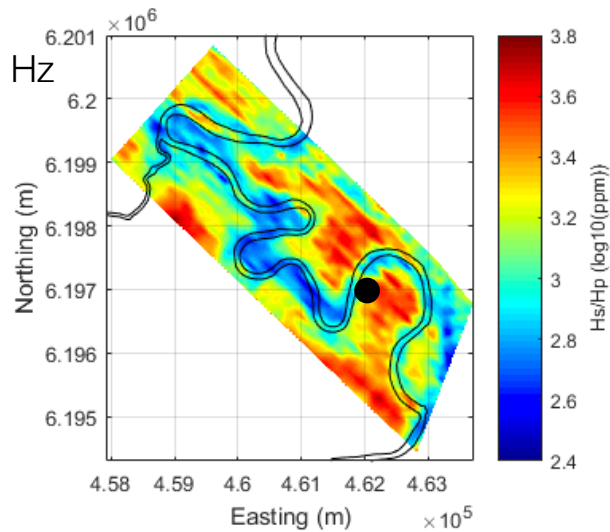
## Quadrature (Imaginary)



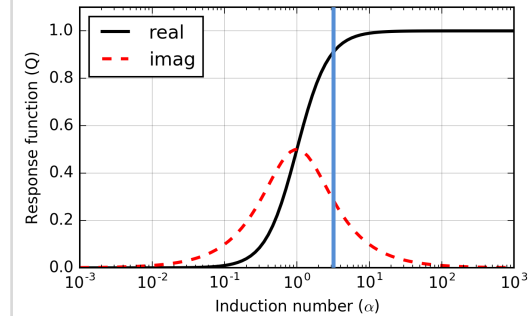
## Sounding curve



35920 Hz

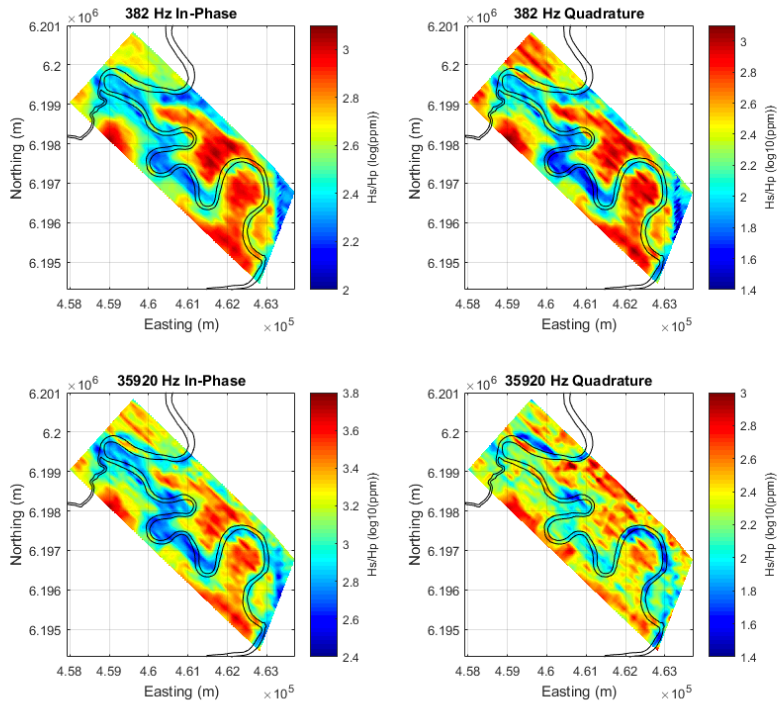


## Response curve

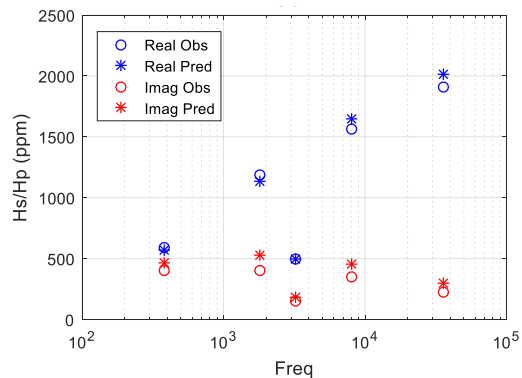


# Processing: 1D inversion

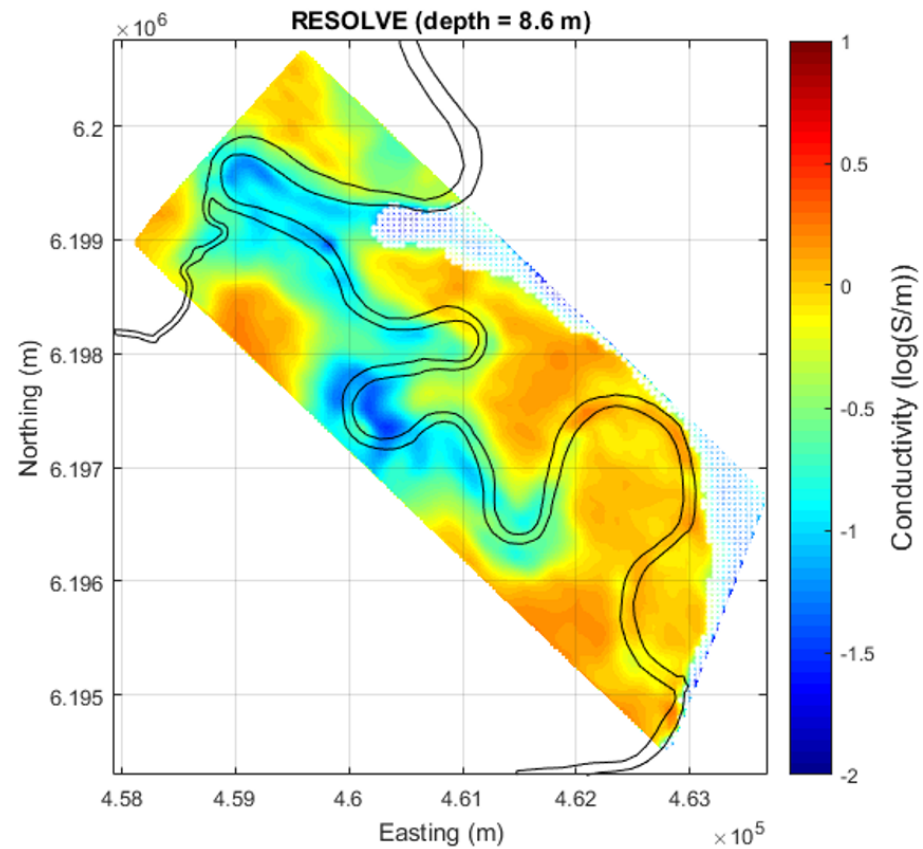
## Data



## Data fit

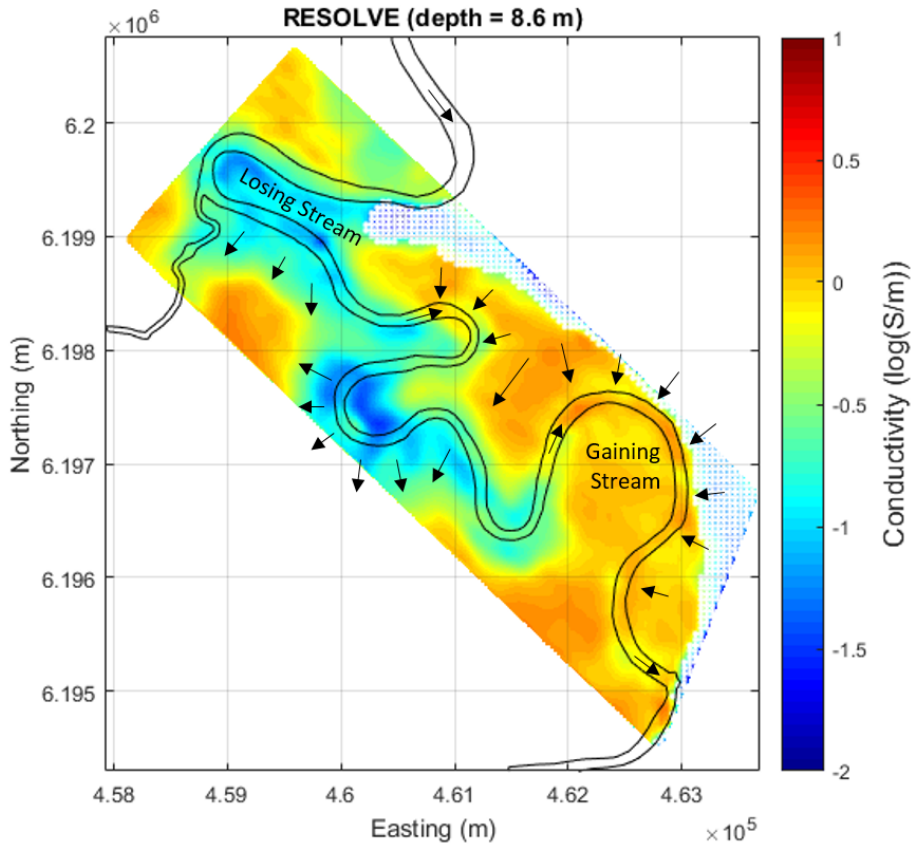


## Conductivity model (stitched)

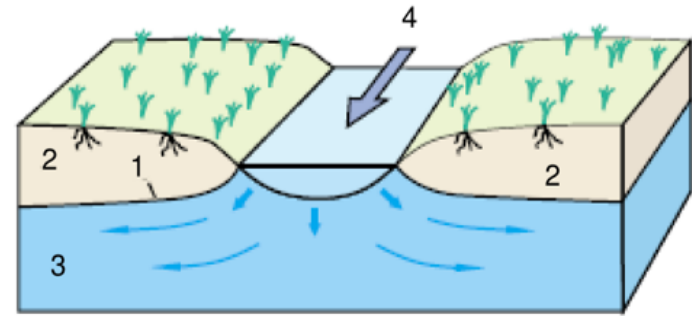


# Interpretation

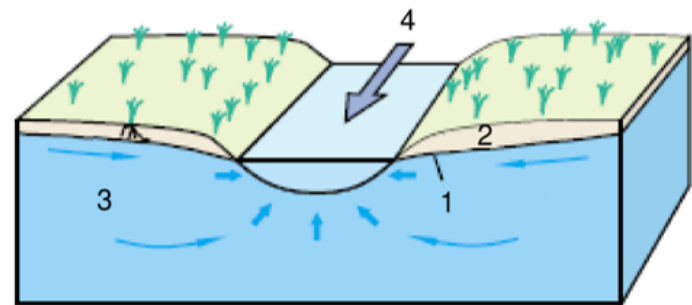
Conductivity model (stitched)



Losing Stream



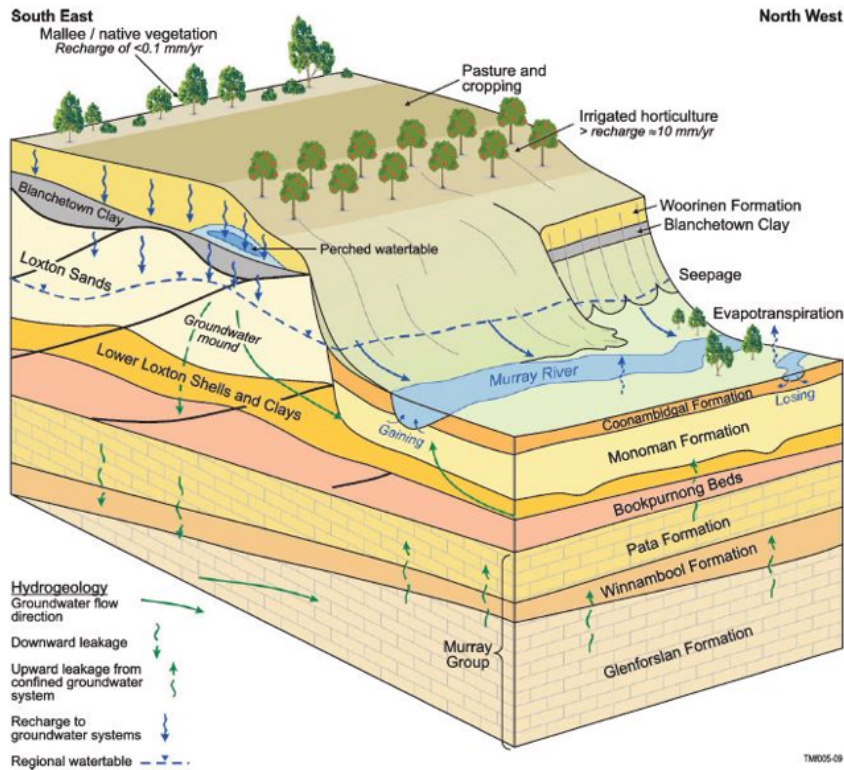
Gaining Stream



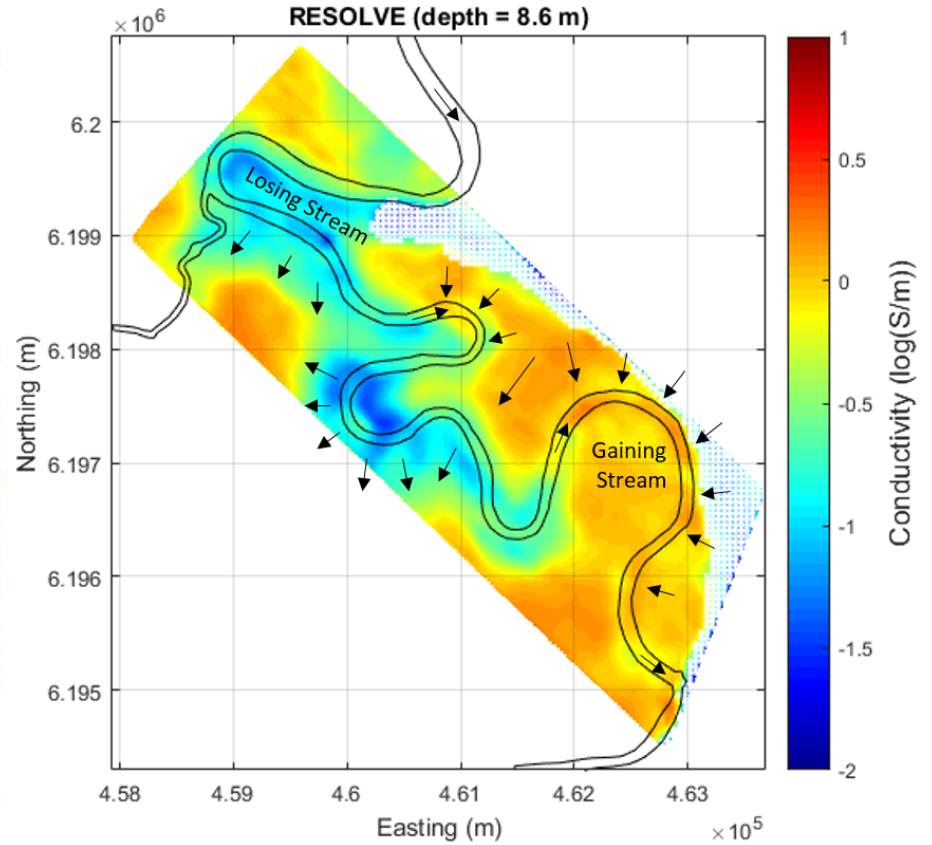
- 1 – Water table
- 2 – Unsaturated zone
- 3 – Saturated zone
- 4 – Flow direction

# Synthesis

## Hydrological model



## Conductivity model (stitched)



# Outline

## Setup

- Basic experiment
- Transmitters, Receivers

## Frequency Domain EM

- Vertical Magnetic Dipole
- Effects of Frequency
- Case History – Ground water

## Time Domain EM

- Vertical Magnetic Dipole
- Propagation with Time
- Case History – Near surface geology

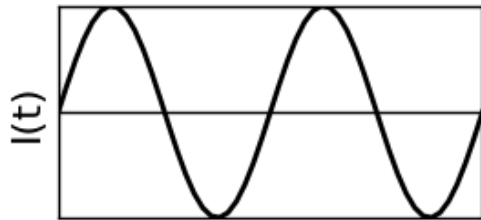


# EM with Inductive Sources

- Induction principles are the same for
  - FDEM: Frequency domain EM
  - TDEM: Time domain EM

Transmitter current

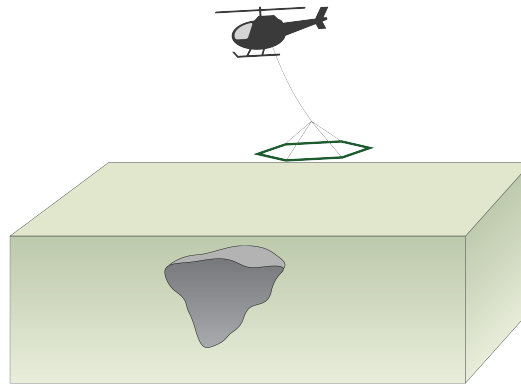
FDEM



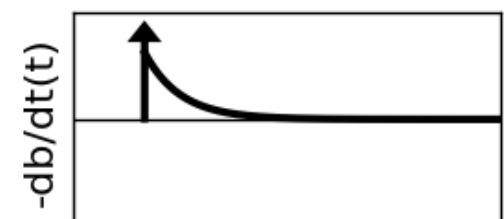
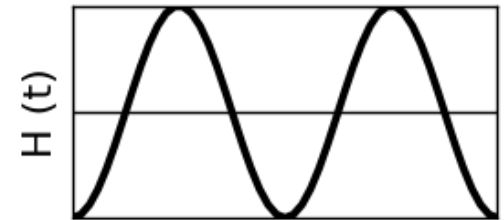
TDEM



Time



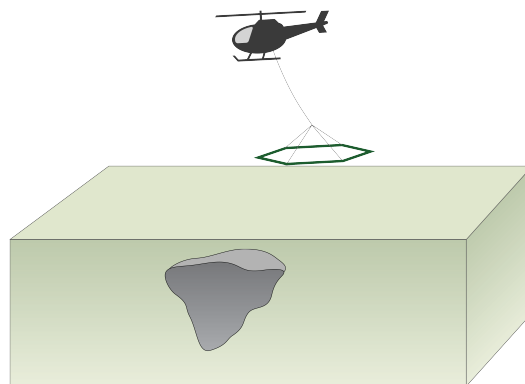
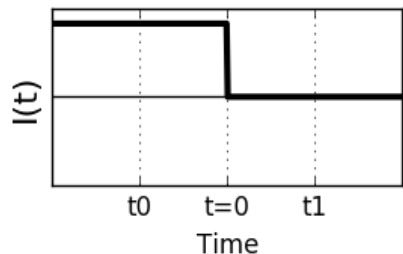
Receiver



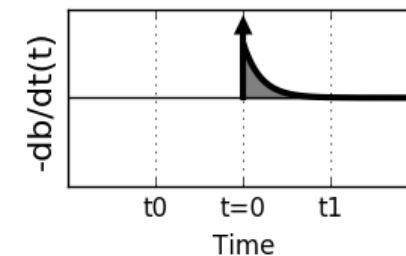
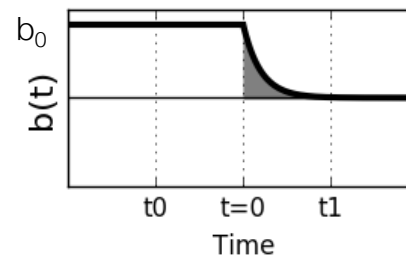
Time

# EM with Inductive Sources: Time Domain

Transmitter current



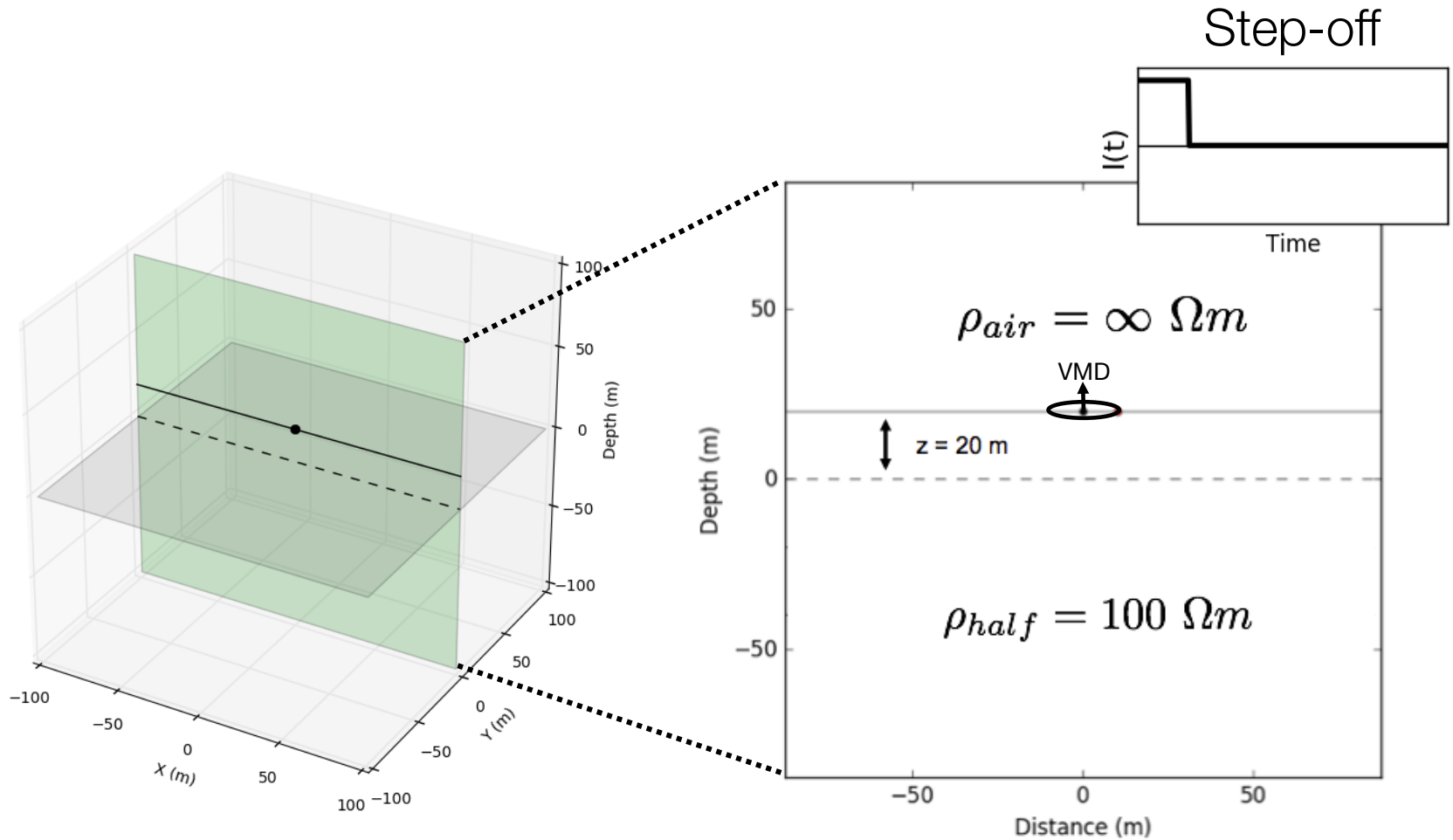
Receiver



<b>time</b>	<b>b</b>	<b>db/dt</b>
$t < 0$	$b_0$	0
$t = 0$	$b_0$	$-b_0\delta(t)$
$t > 0$	secondary	secondary

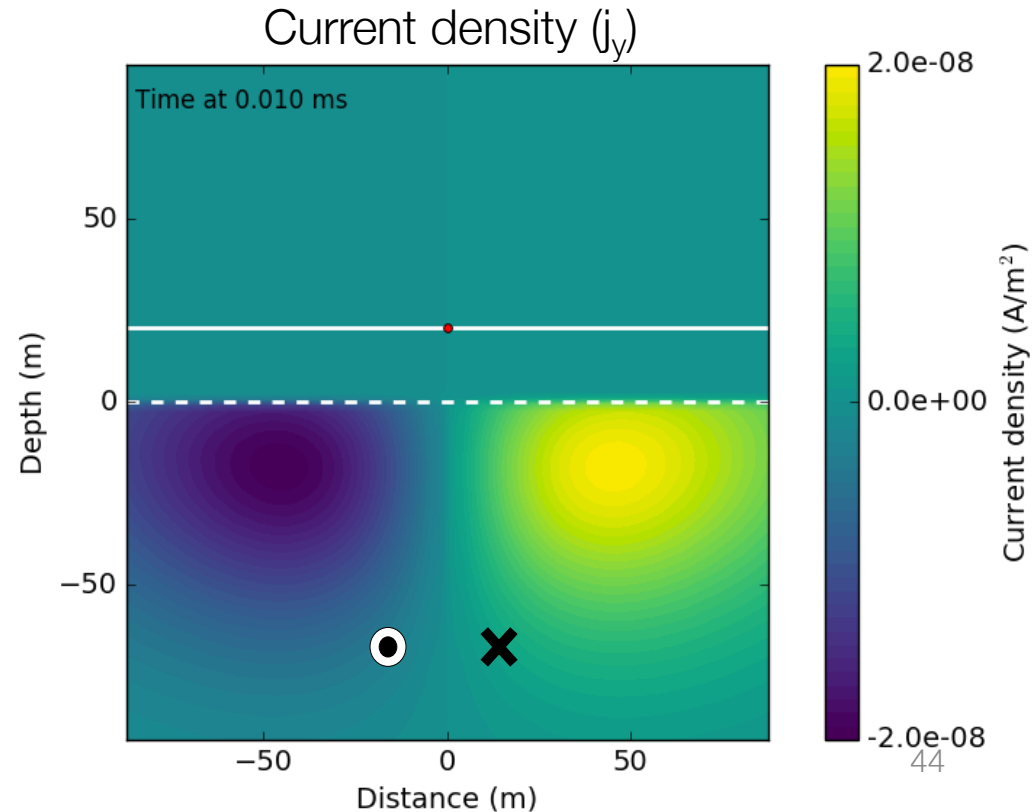
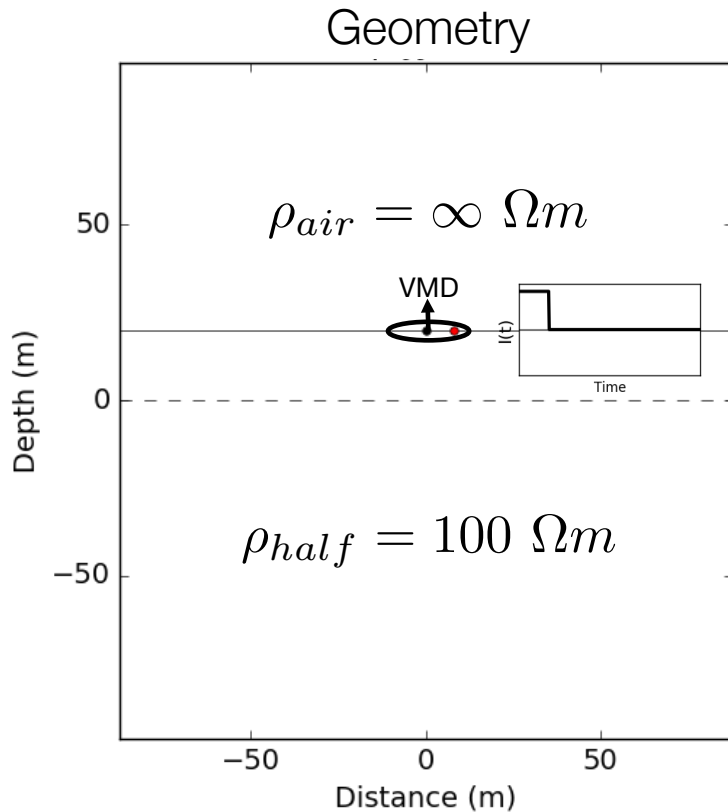
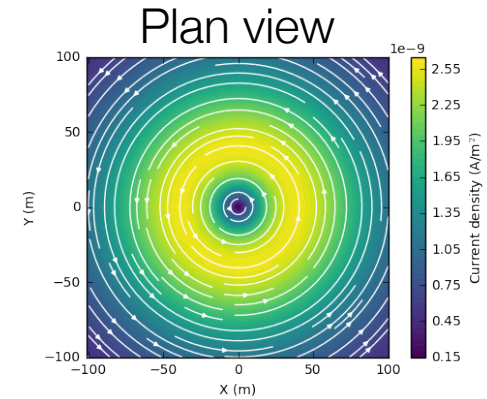
$\delta(t)$ : Dirac-delta function

# Vertical Magnetic Dipole over a halfspace (TDEM)



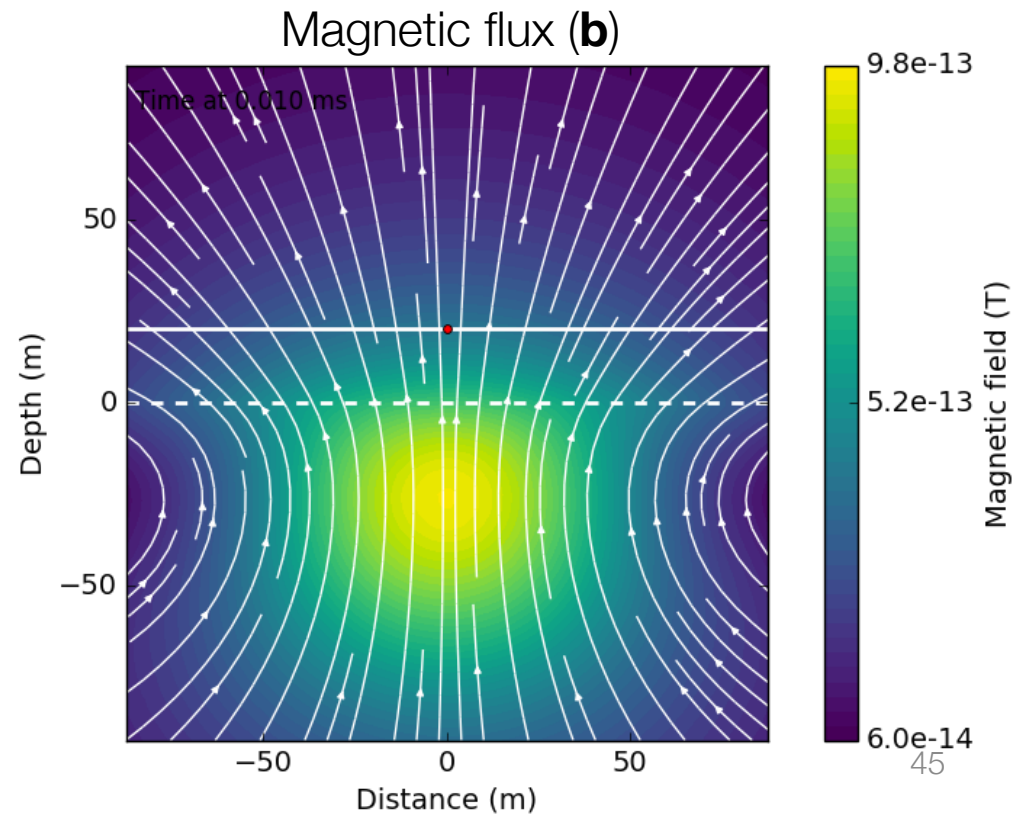
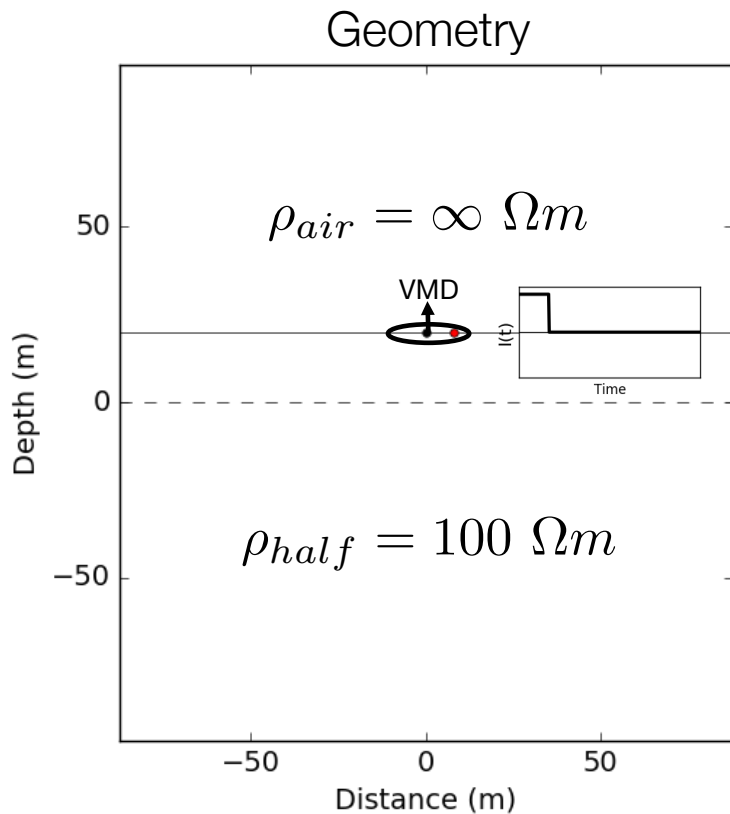
# Current Density

- Time: 0.01ms



# Magnetic flux density

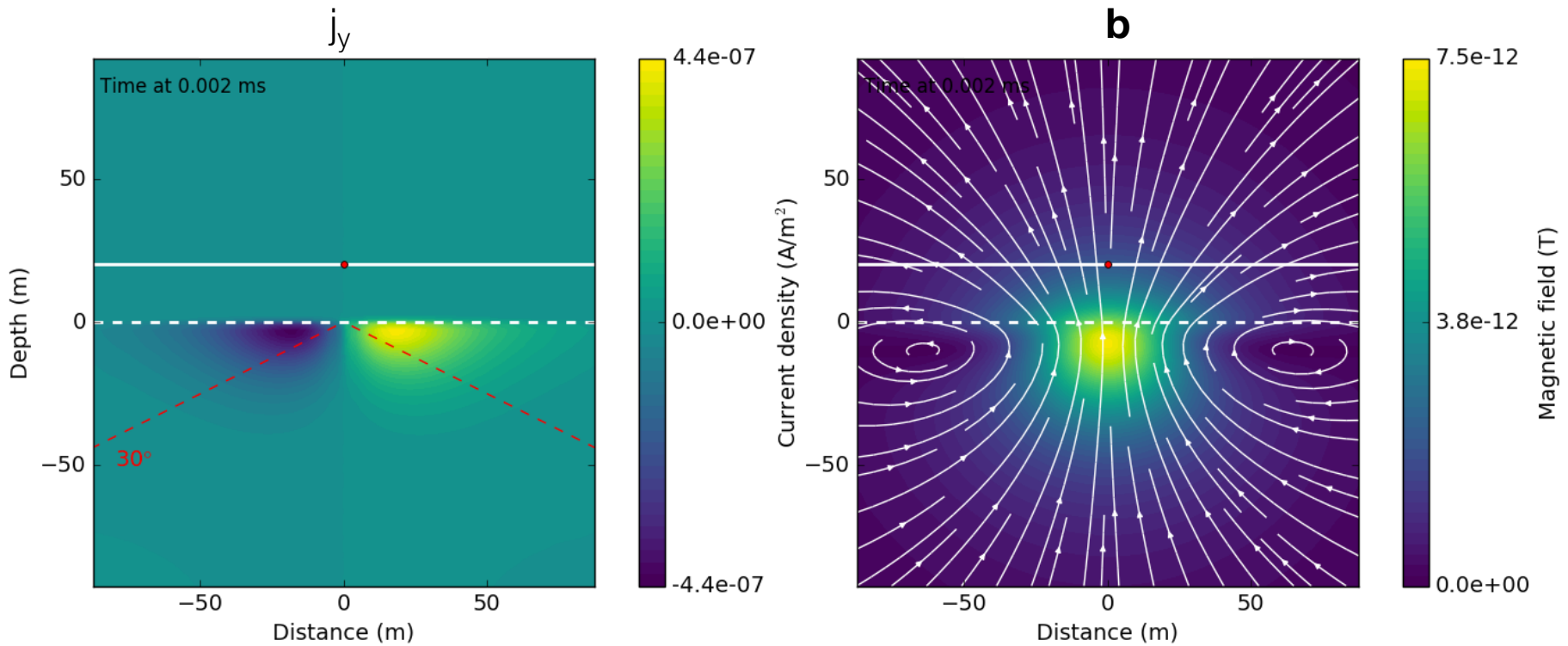
- Time: 0.01ms



# Propagation through time

- Time: 0.002ms
- diffusion distance = 18 m

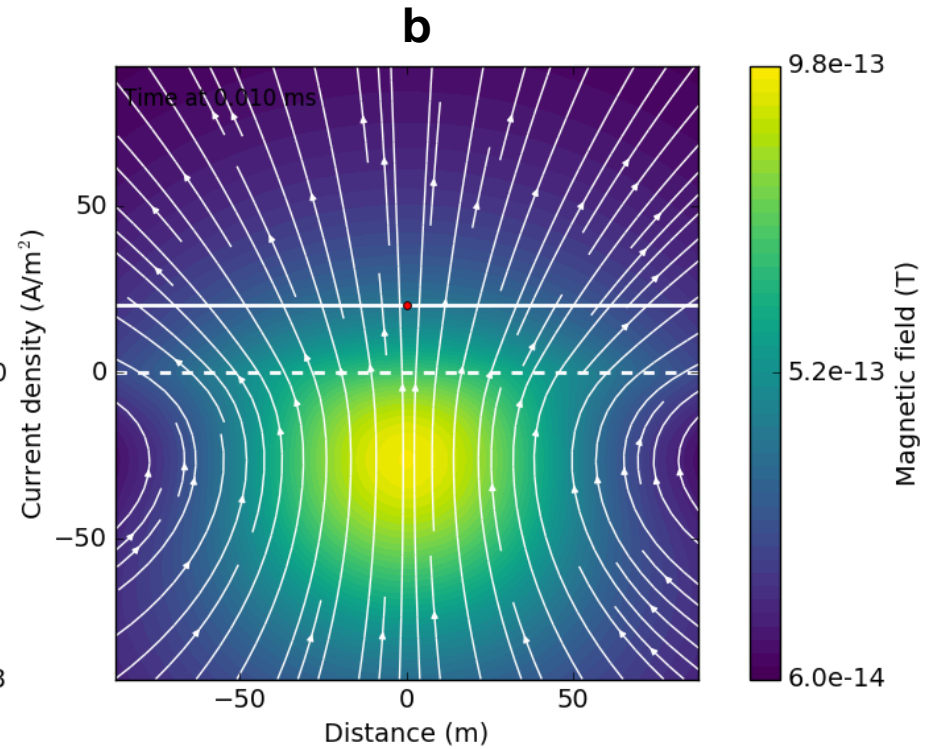
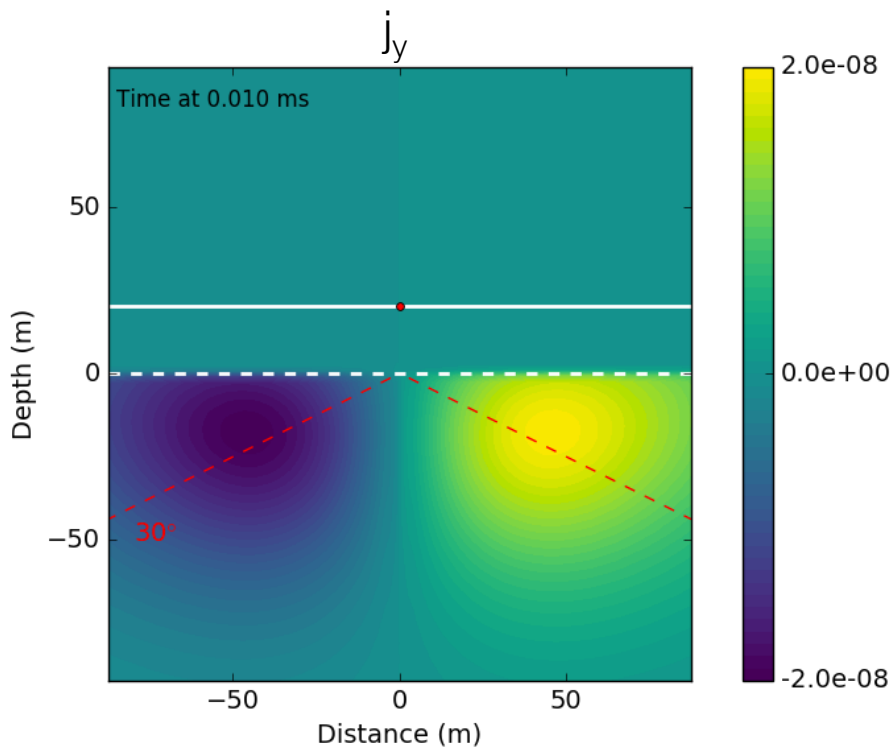
$$d = 1260\sqrt{t\rho}$$



# Propagation through time

- Time: 0.01ms
- diffusion distance = 38 m

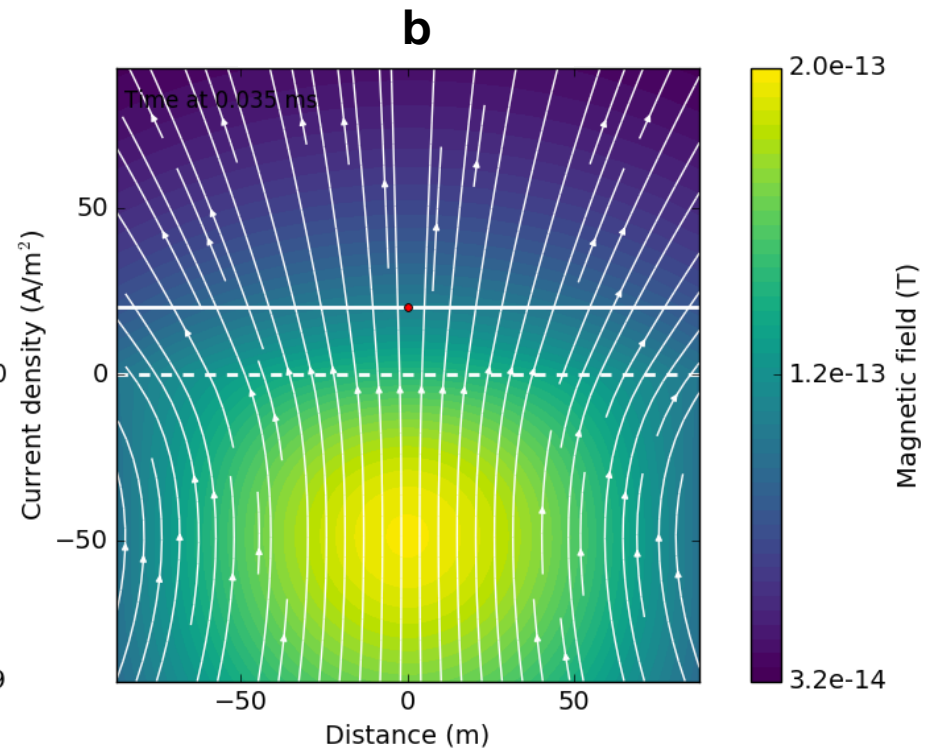
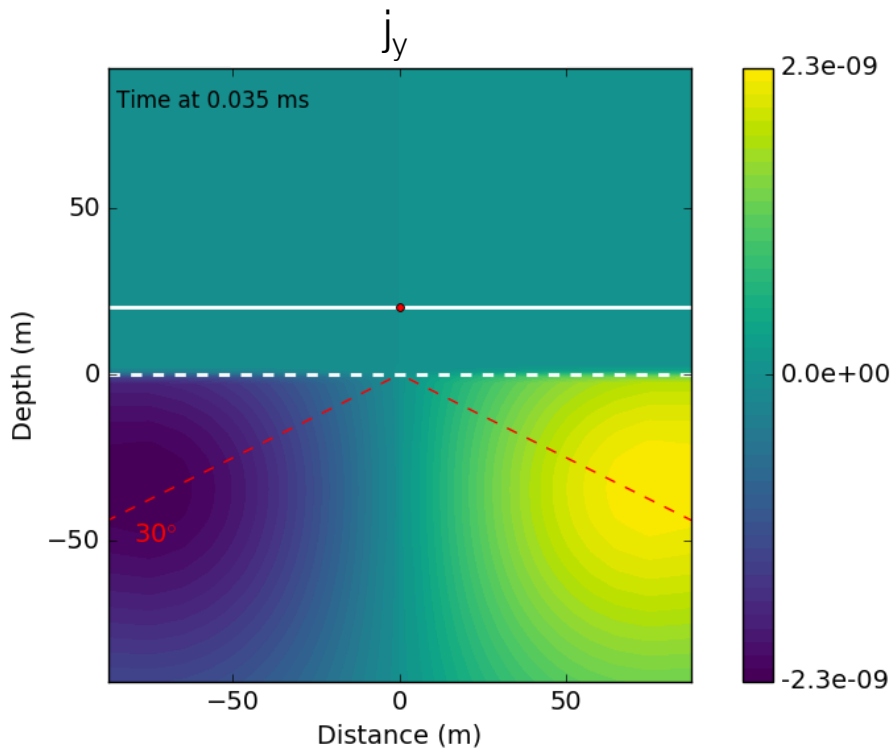
$$d = 1260\sqrt{t\rho}$$



# Propagation through time

- Time: 0.035ms
- diffusion distance = 75 m

$$d = 1260\sqrt{t\rho}$$

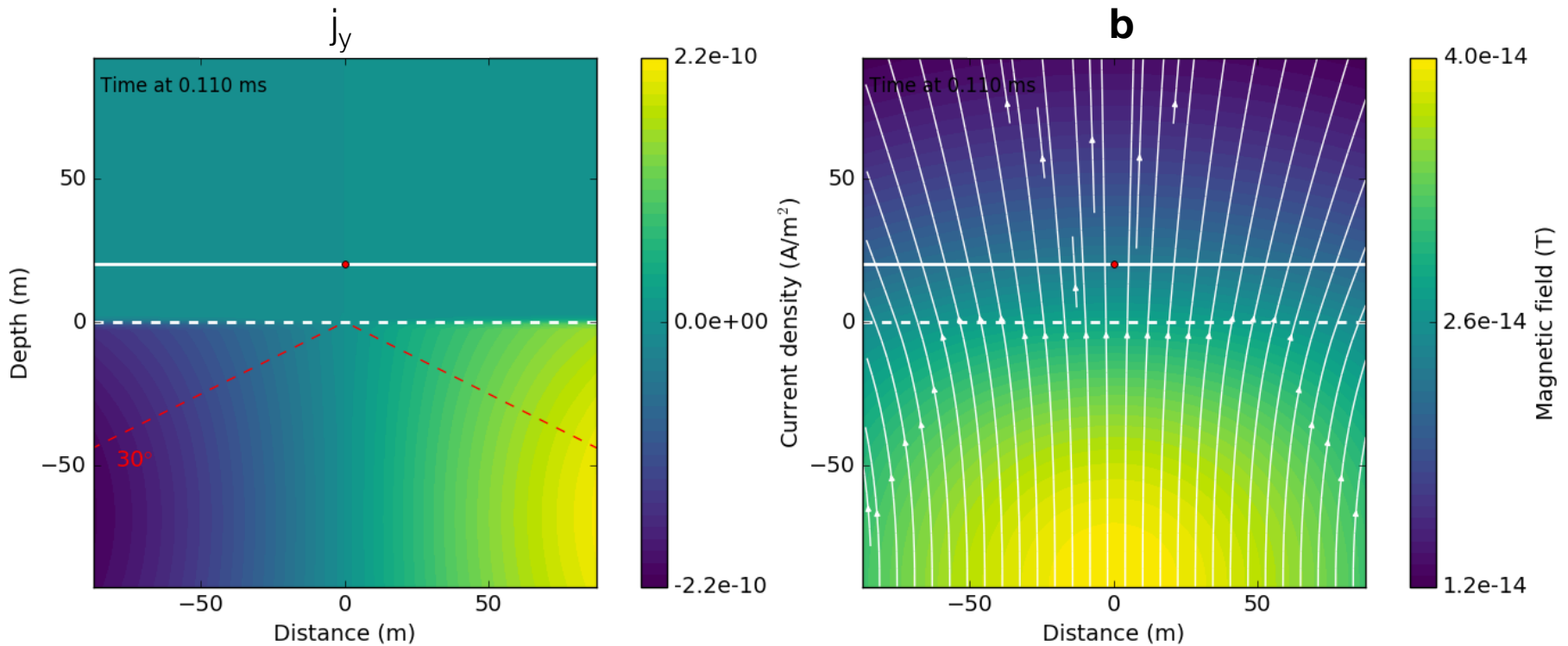




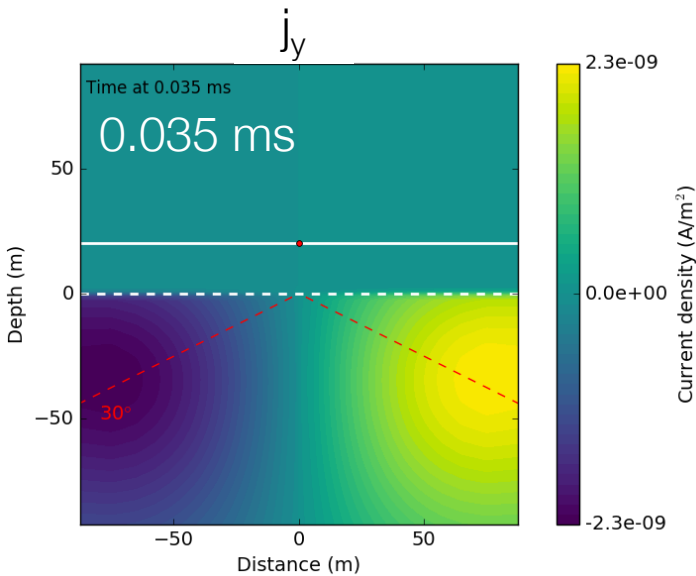
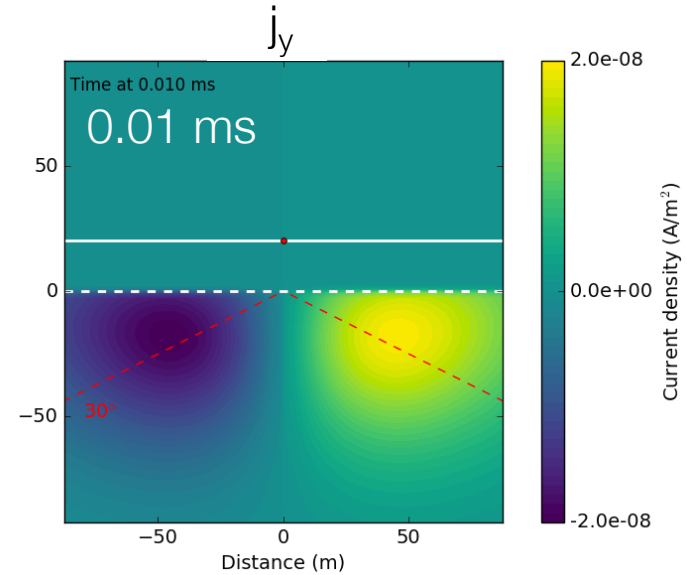
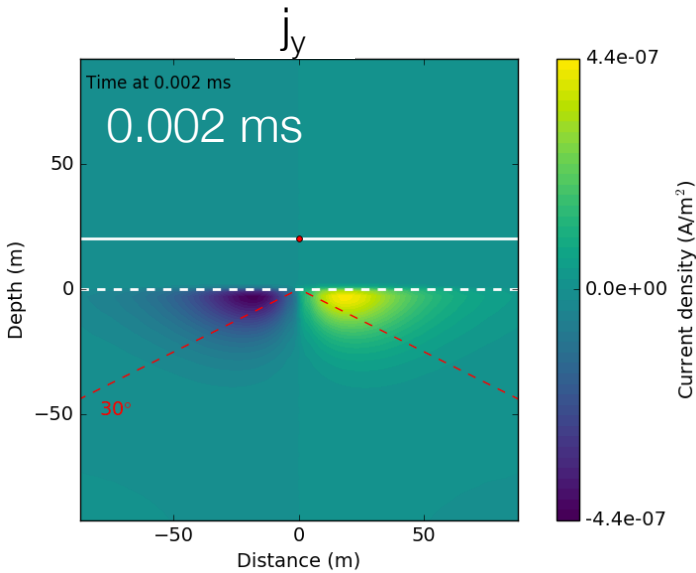
# Propagation through time

- Time: 0.110ms
- diffusion distance = 132 m

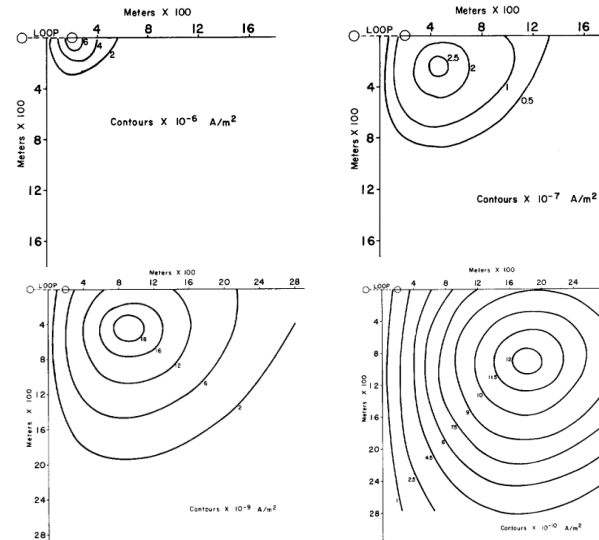
$$d = 1260\sqrt{t\rho}$$



# Summary: propagation through time



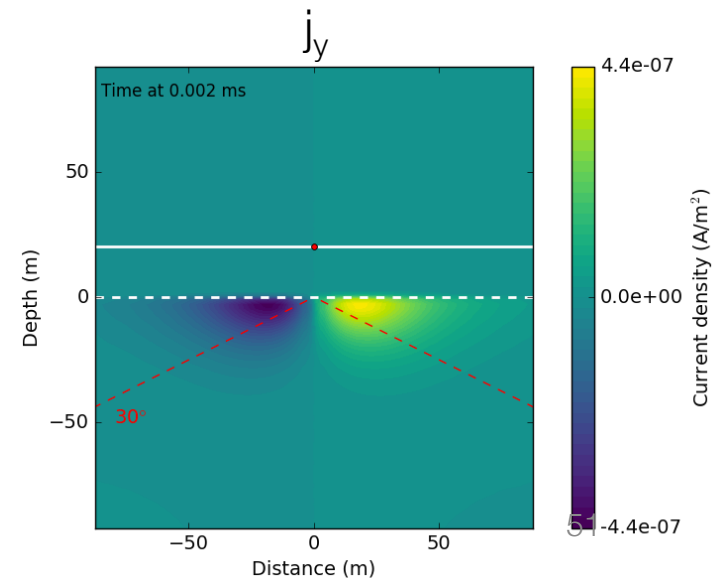
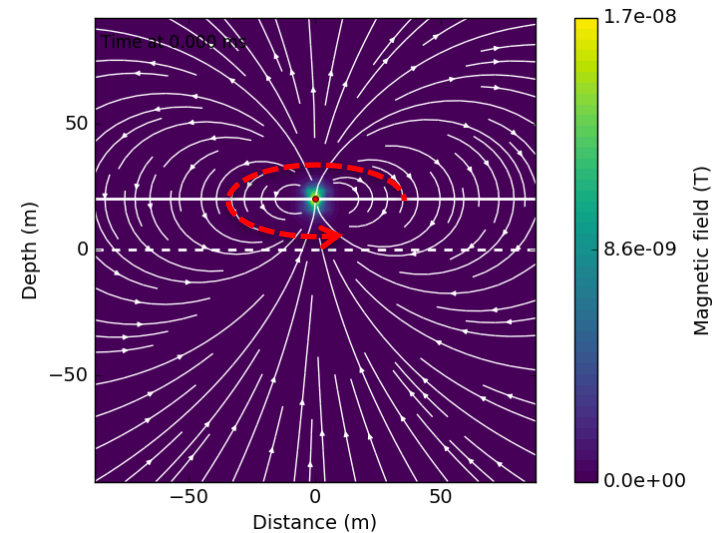
## Nabighian (1979)



# Important points

- Currents flow in same plane as transmitter currents
- Currents diffuse outward downward
- Each transmitter has a “footprint”
- Max resolution controlled by earliest time
- Depth of investigation controlled by latest time

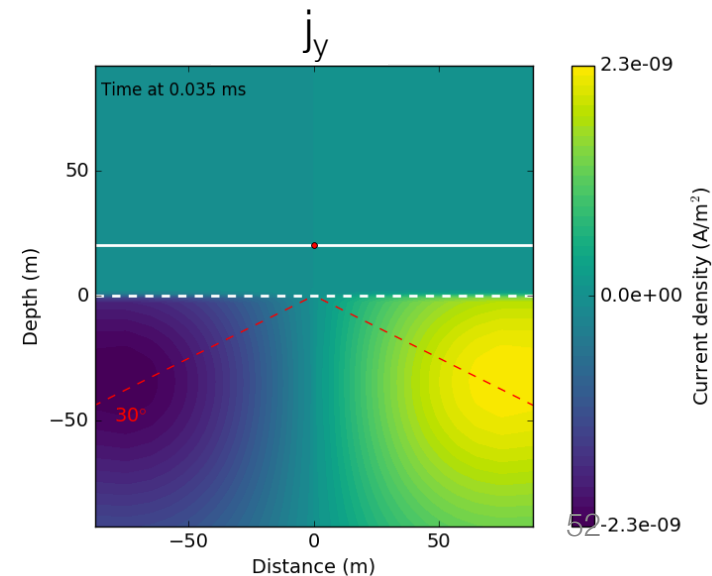
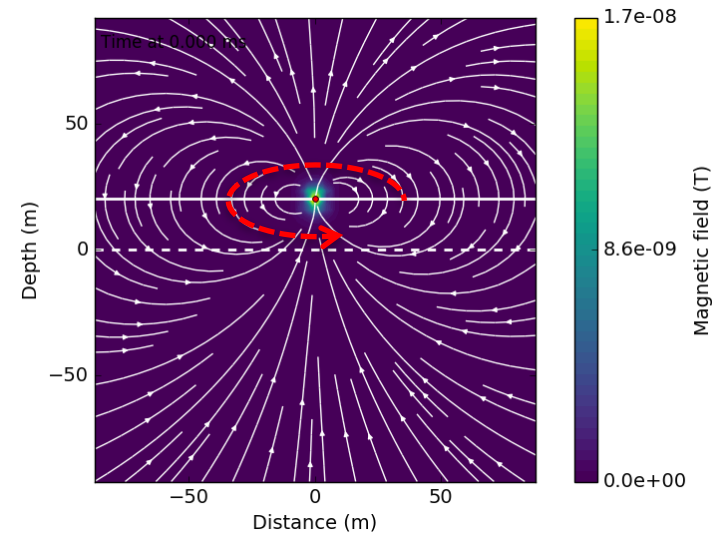
magnetic field (on-time)



# Important points

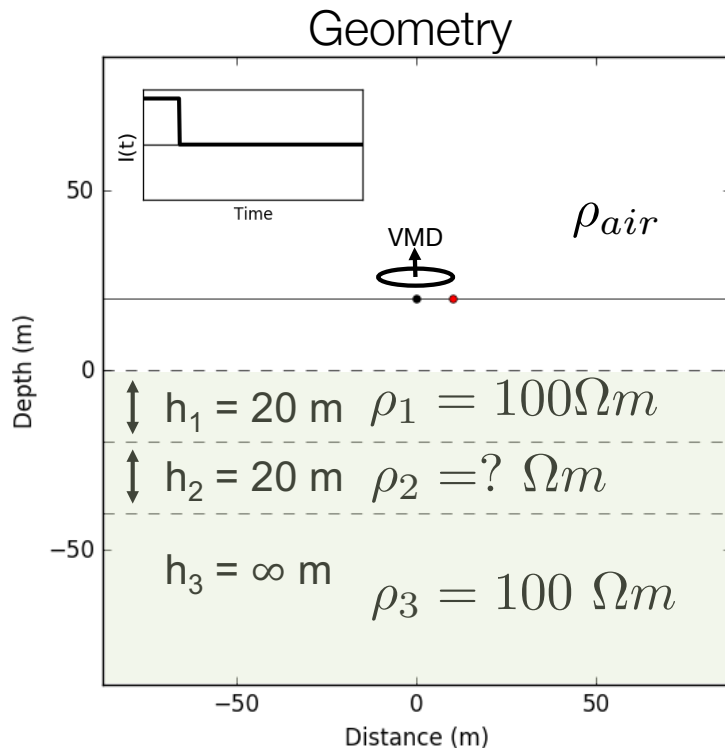
- Currents flow in same plane as transmitter currents
- Currents diffuse outward downward
- Each transmitter has a “footprint”
- Max resolution controlled by earliest time
- Depth of investigation controlled by latest time

magnetic field (on-time)



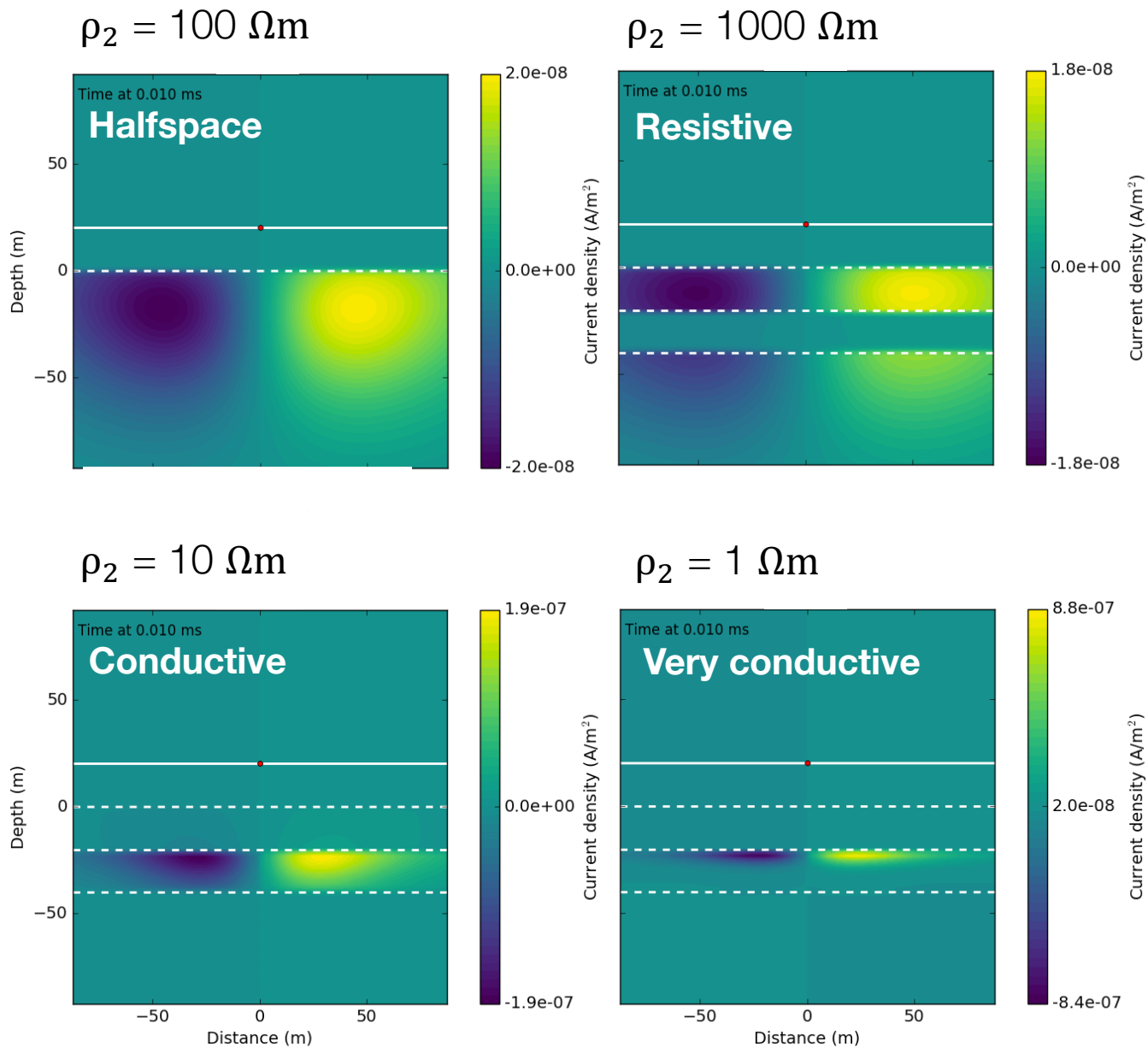
# Layered earth

- 3 layers + air,
- $\rho_2$  varies

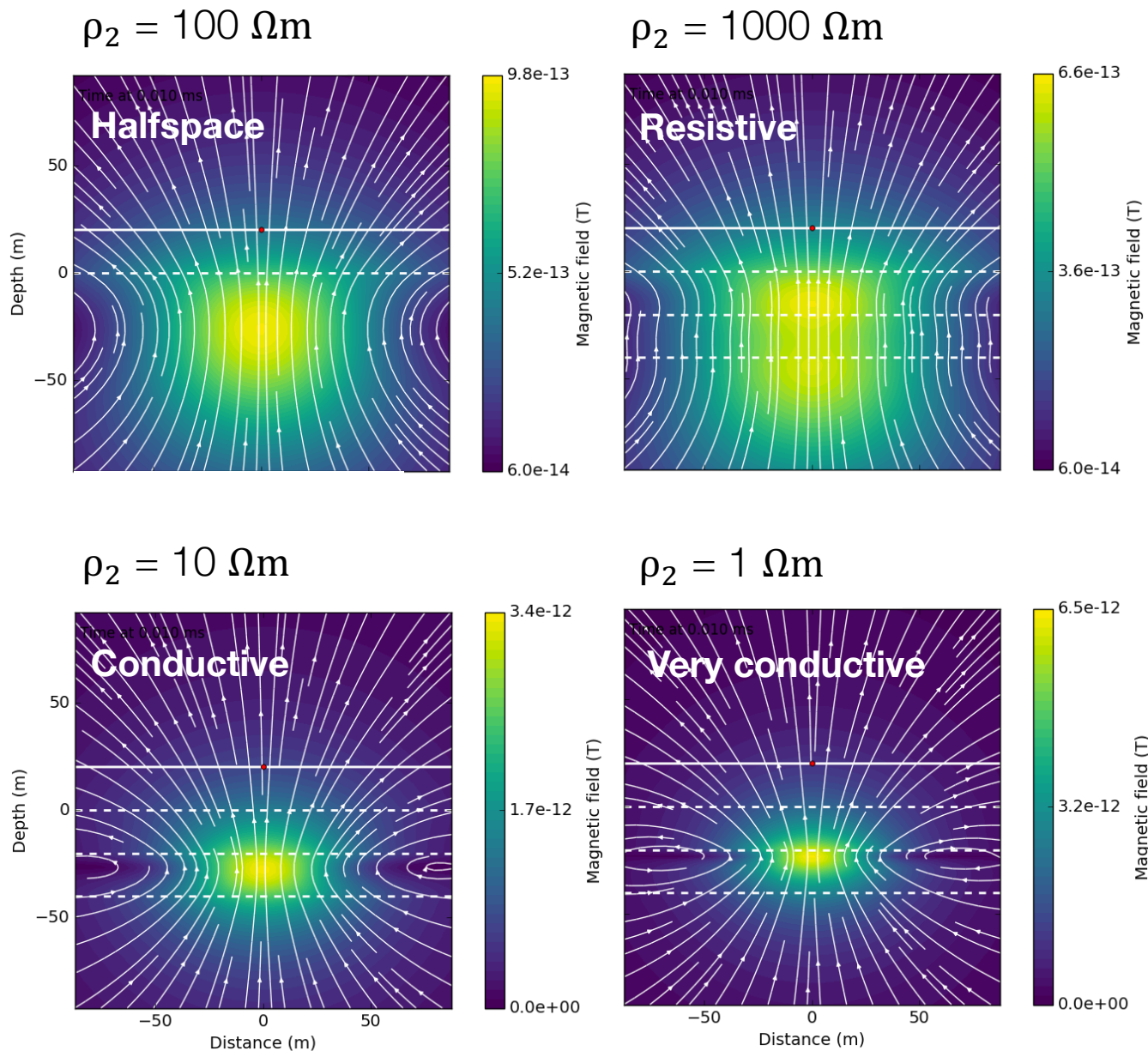


- Four different cases:
  - Halfspace
    - $\rho_2 = 100 \Omega m$
  - Resistive
    - $\rho_2 = 1000 \Omega m$
  - Conductive
    - $\rho_2 = 10 \Omega m$
  - Very conductive
    - $\rho_2 = 1 \Omega m$
- Fields
  - $j_y$  off-time
  - **b** off-time

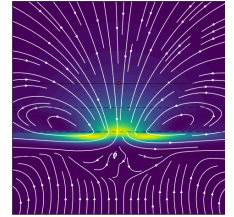
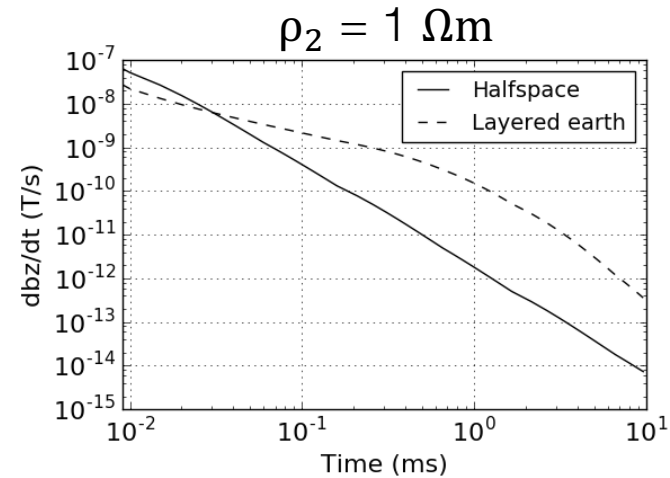
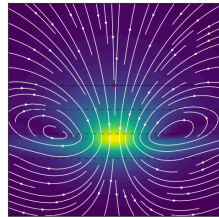
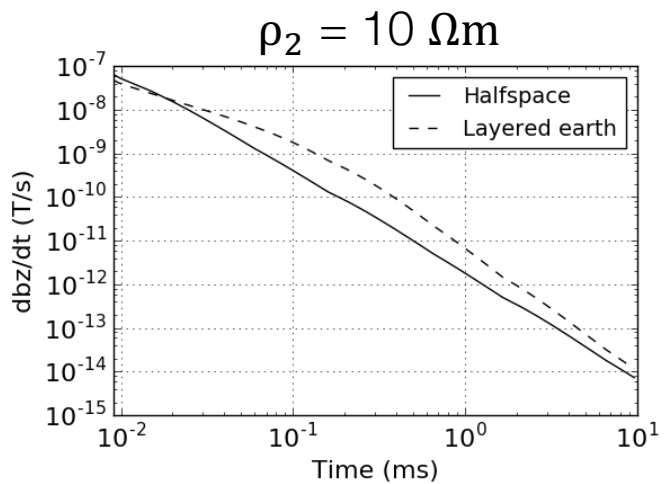
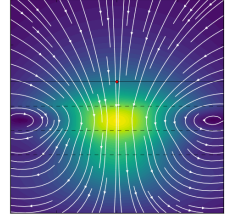
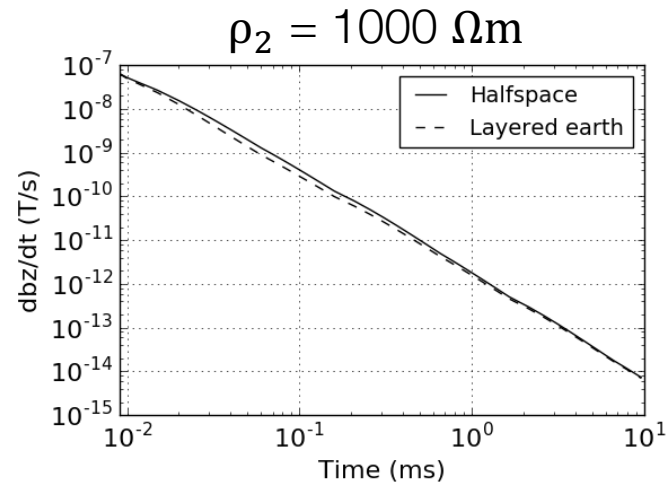
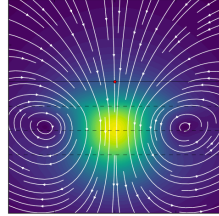
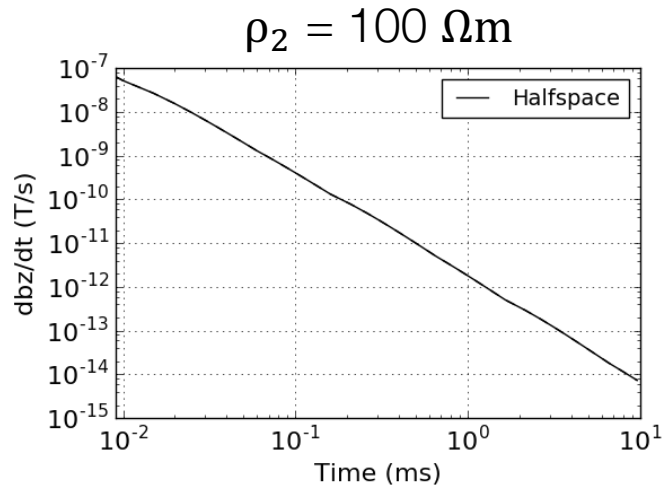
# Layered earth currents ( $j_y$ )



# Layered earth mag. fields (**b**)



# $db_z/dt$ sounding curves

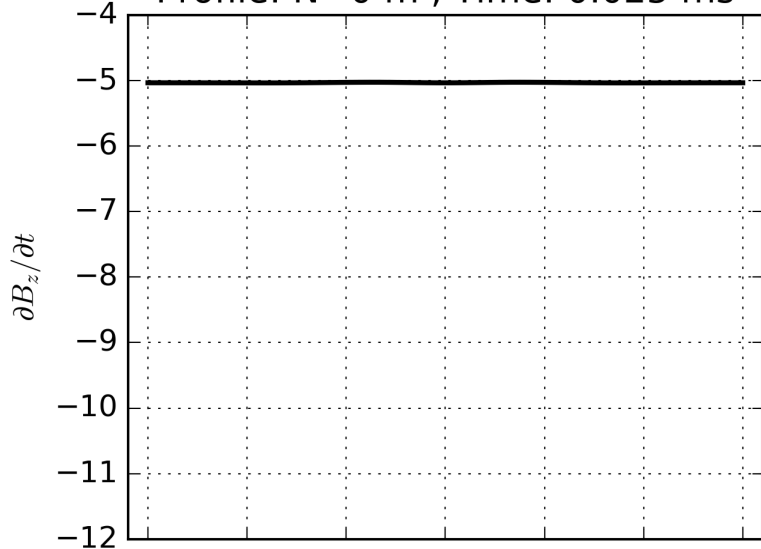




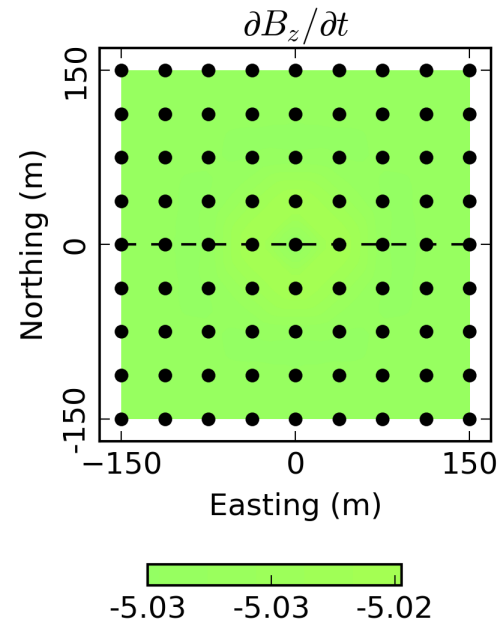
# Airborne example: conductive sphere

Data profile

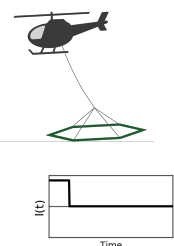
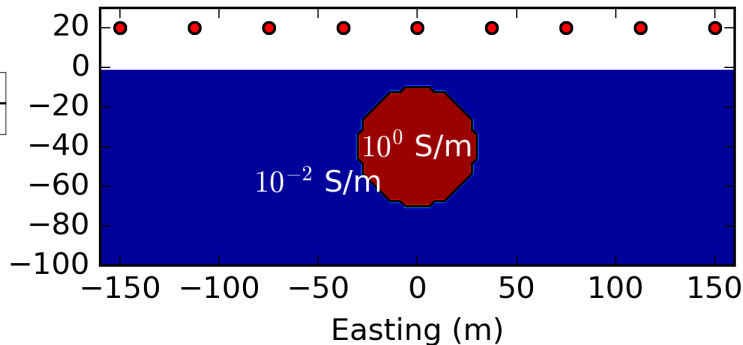
Profile: N=0 m , Time: 0.025 ms



Data map



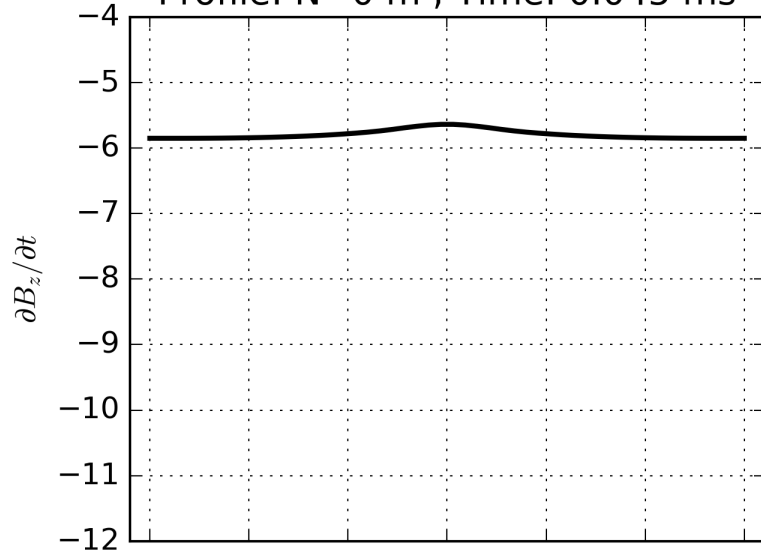
Conductivity



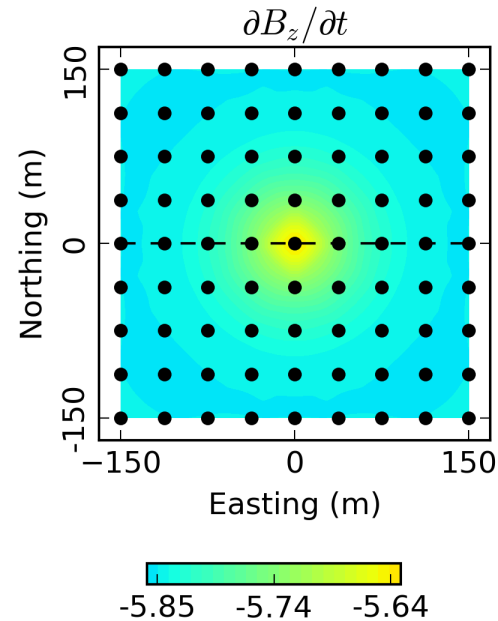
# Airborne example: conductive sphere

Data profile

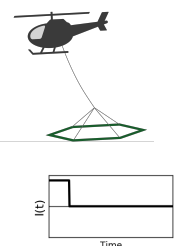
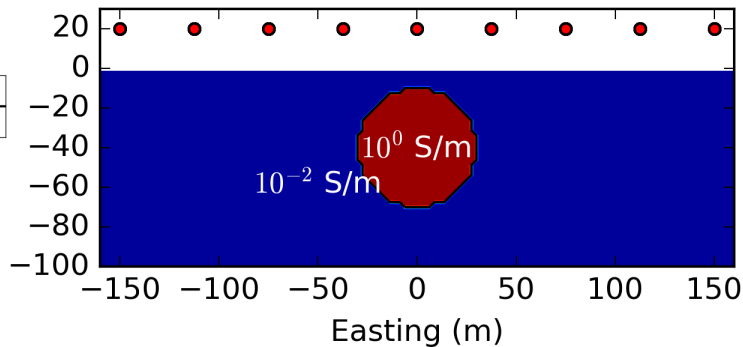
Profile: N=0 m , Time: 0.045 ms



Data map



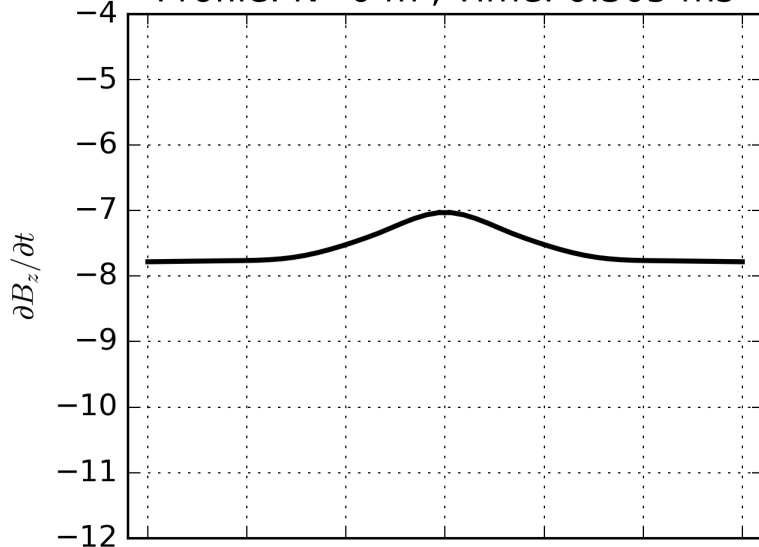
Conductivity



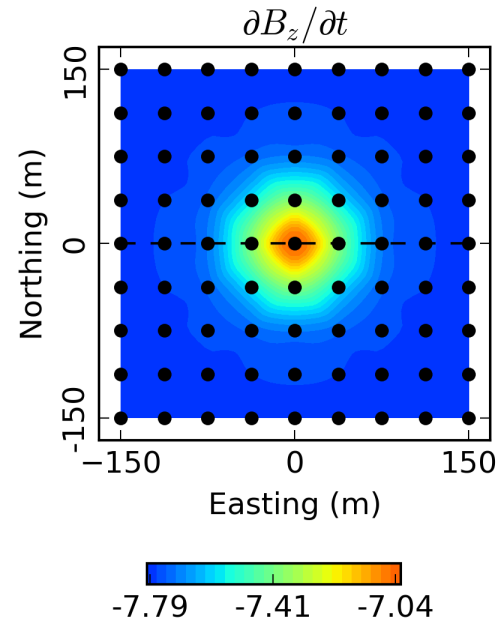
# Airborne example: conductive sphere

Data profile

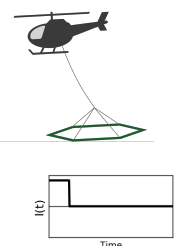
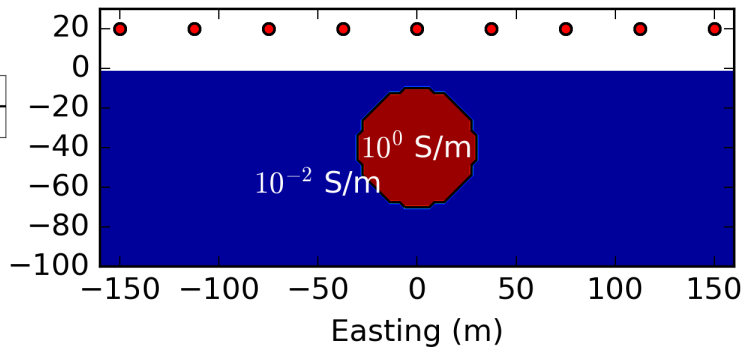
Profile: N=0 m , Time: 0.305 ms



Data map



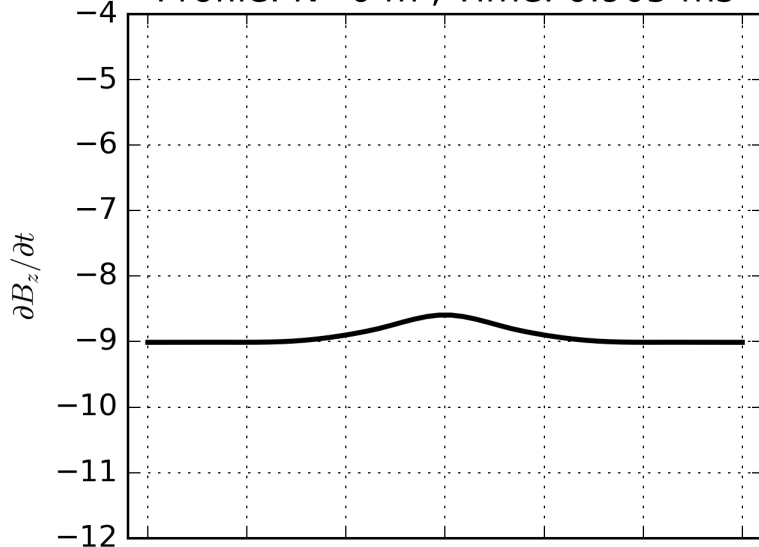
Conductivity



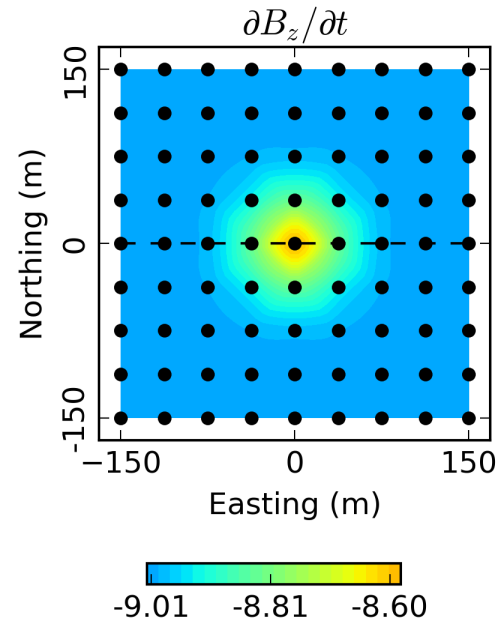
# Airborne example: conductive sphere

Data profile

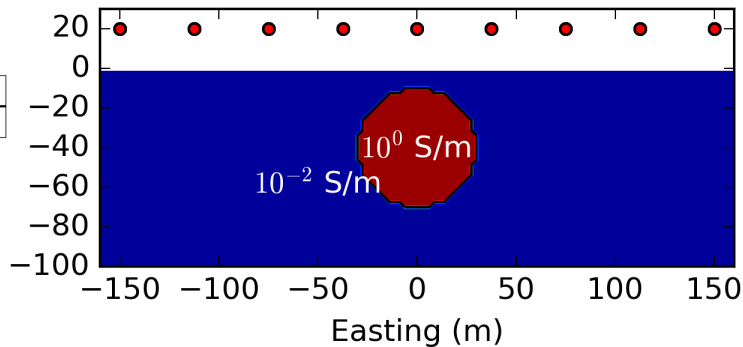
Profile: N=0 m , Time: 0.905 ms



Data map



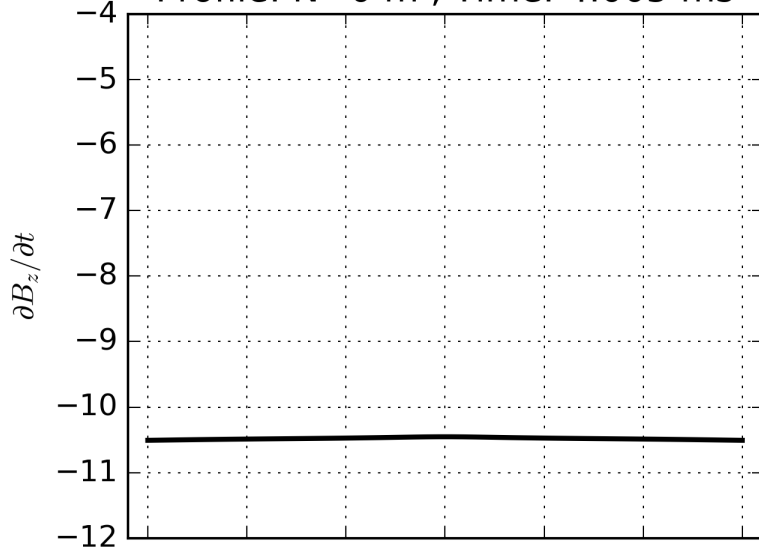
Conductivity



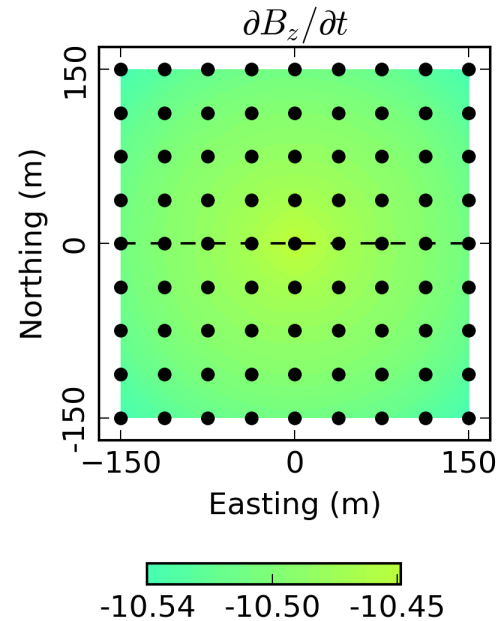
# Airborne example: conductive sphere

Data profile

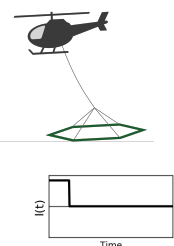
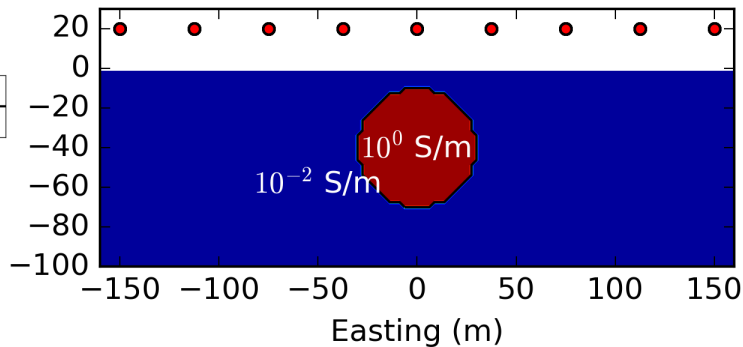
Profile: N=0 m , Time: 4.005 ms



Data map

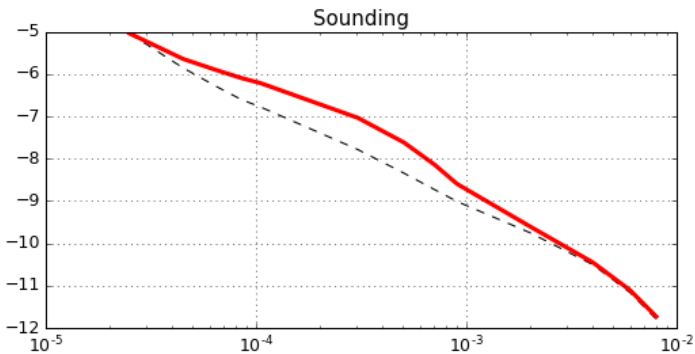
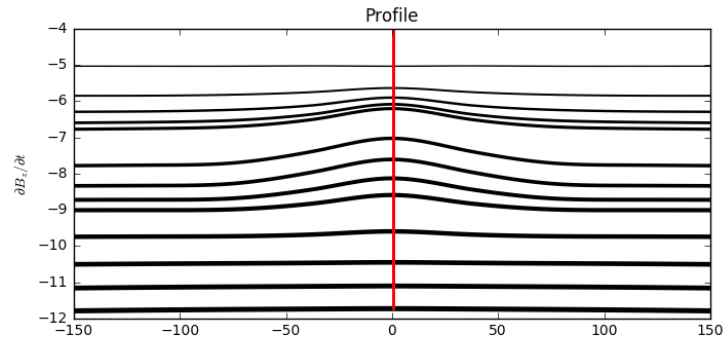


Conductivity

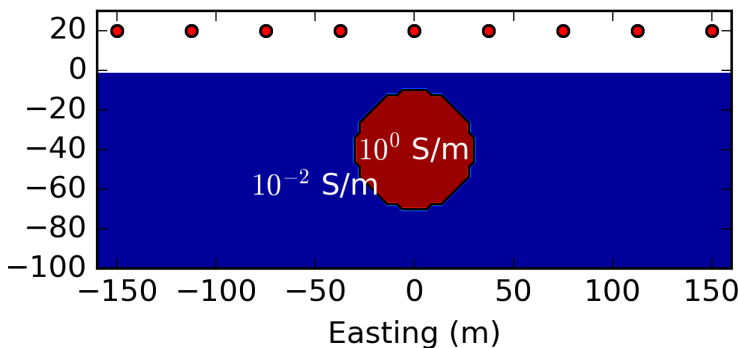


# Summary: airborne example

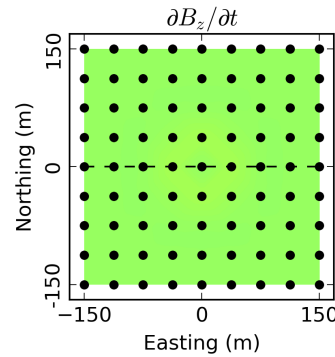
Data profile



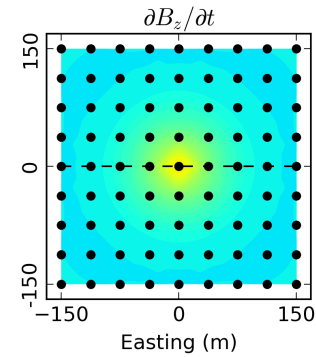
Conductivity



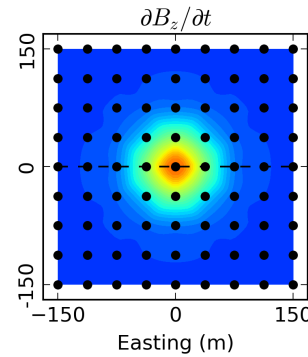
0.025 ms



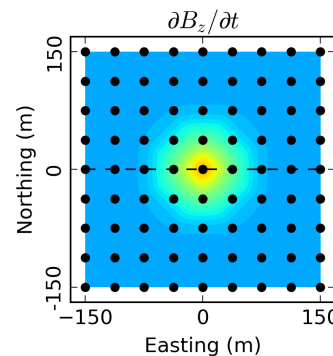
0.045 ms



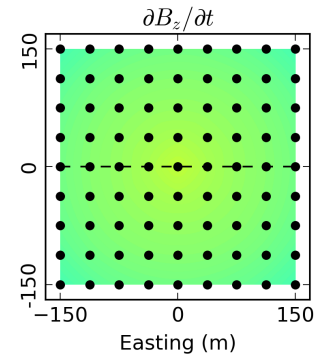
0.305 ms



0.905 ms



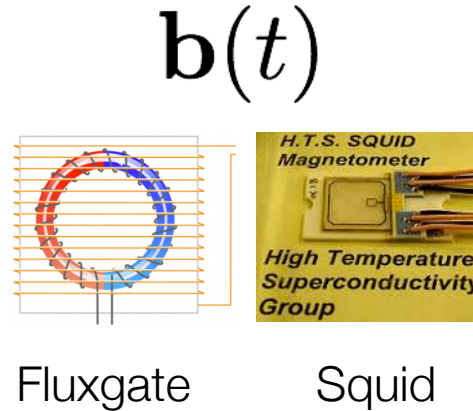
4.005 ms



# TDEM Receiver

## Magnetometer

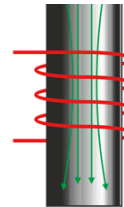
- Measures:
  - Magnetic field
  - 3 components
- eg. 3-component fluxgate



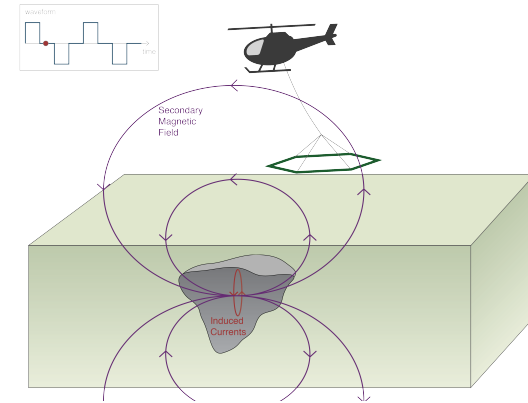
## Coil

- Measures:
  - Voltage
  - Single component that depends on coil orientation
    - Coupling matters
- Airborne TDEM: measure  $db/dt$

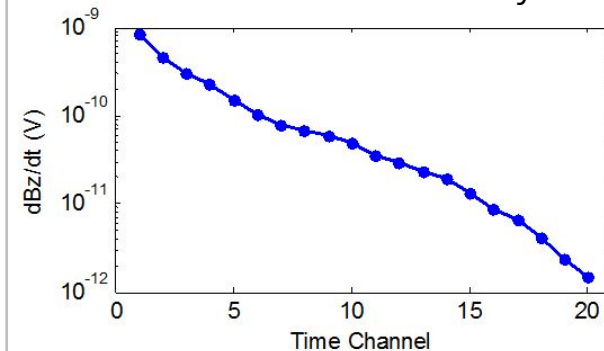
$$\frac{\partial b}{\partial t}$$



Coil

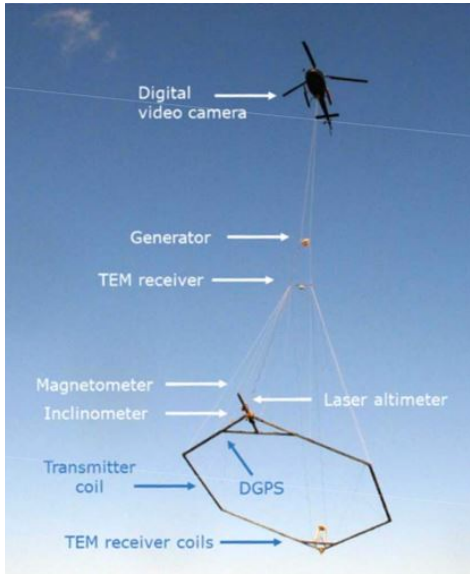


Measured decay



# Some Airborne TDEM Systems

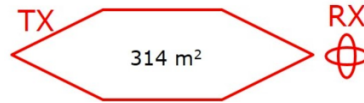
## SkyTEM (2006)



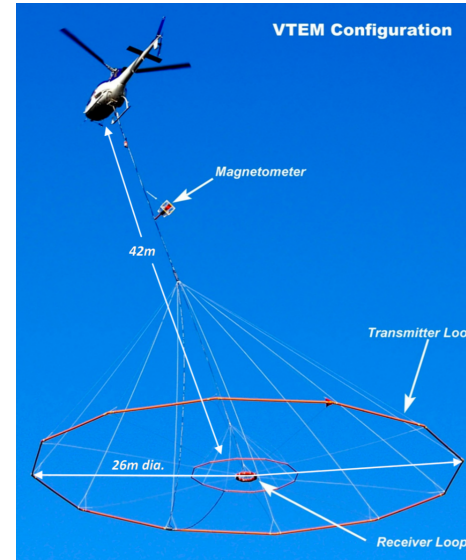
Area = 314 m<sup>2</sup>

Peak dipole moment:

- HM: 113040 NIA
- LM: 12560 NIA



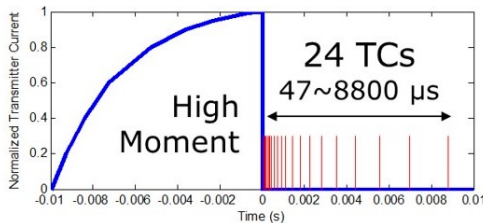
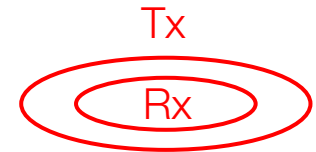
## VTEM (2007)



Area = 535 m<sup>2</sup>

Peak dipole moment:

- 503,100 NIA

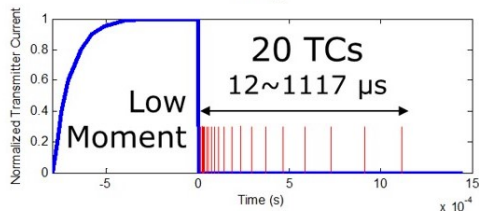


Peak current: 90 A

Turns: 4

On-time: 10 ms

Off-time: 10 ms

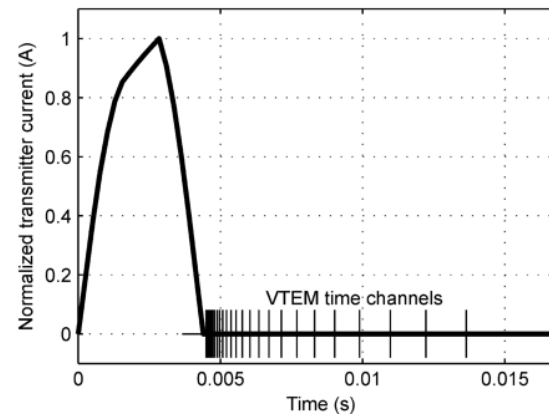


Peak current: 40 A

Turns: 1

On-time: 0.8 ms

Off-time: 1.45 ms



Peak current: 235 A

Turns: 4

On-time: 4.5 ms

Off-time: 9.1 ms



# Outline

Setup

Frequency Domain EM

Time Domain EM

- Vertical Magnetic Dipole
- Propagation with Time
- Effects of Background Conductivity
- Transmitters and receivers
- Decay Curves
  
- Questions
  
- Case History – Near surface geology

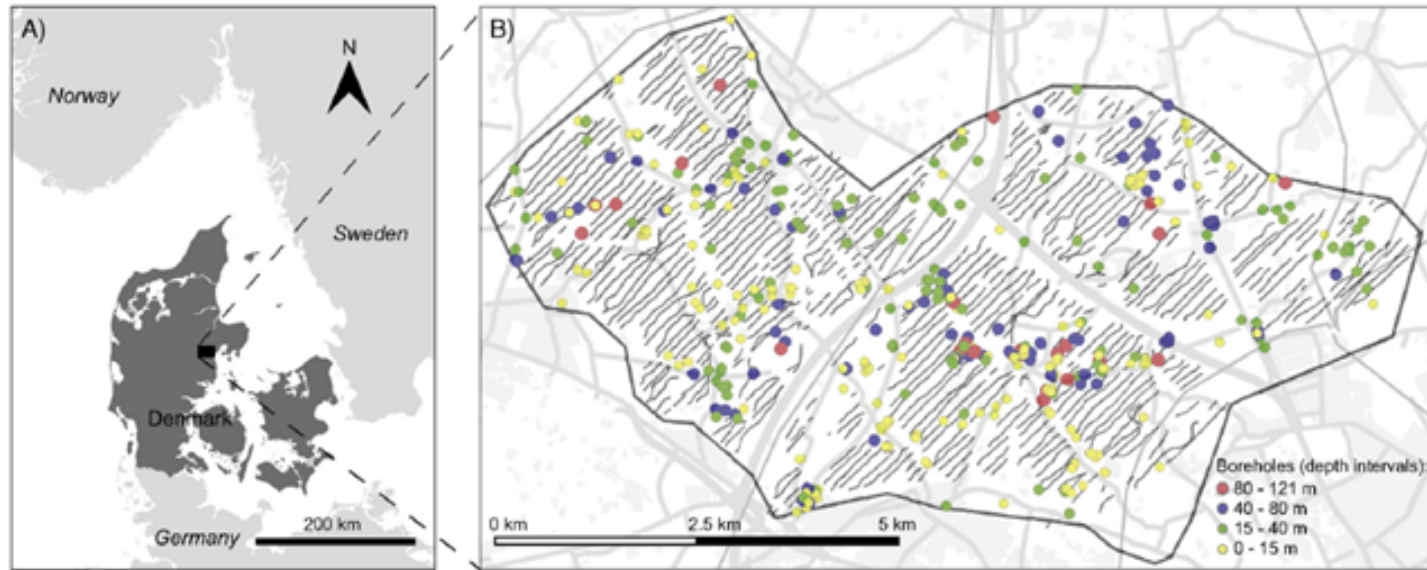
# Case History: Kasted

Vilhelmsen et al. (2016)

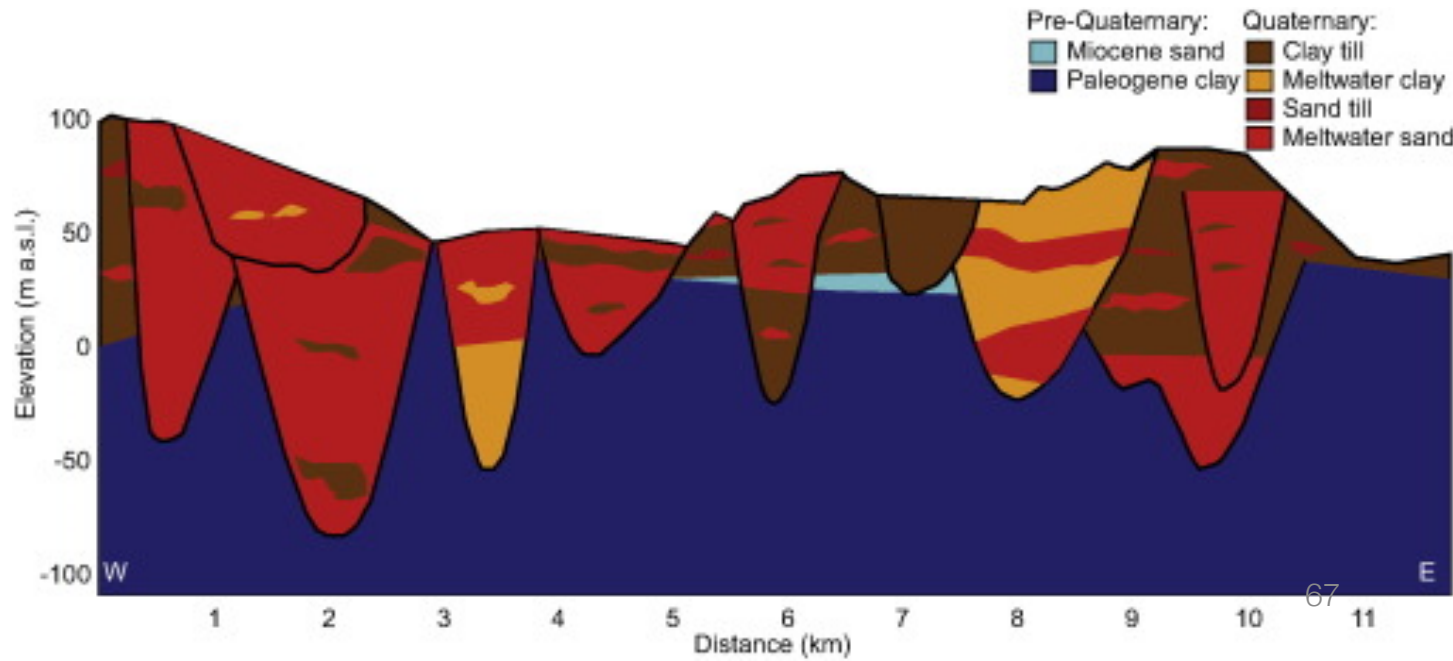
# Setup

A) Survey Area:  
Kasted, Denmark

B) Borehole locations

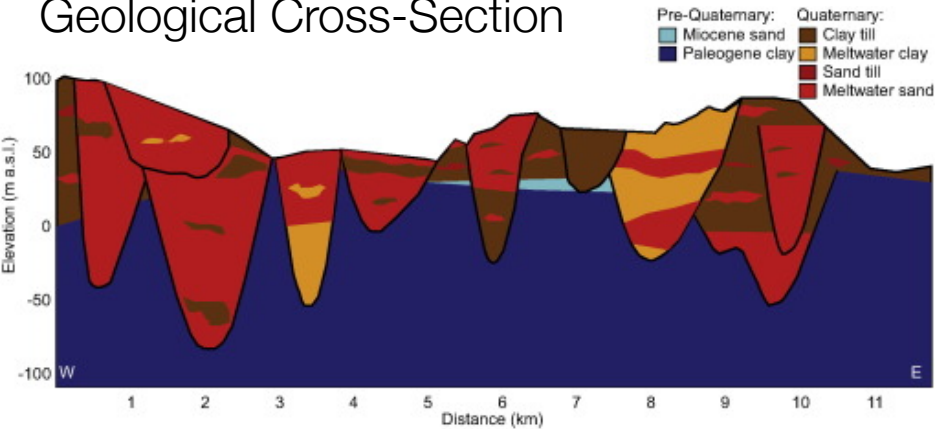


Local Geology:  
W-E cross-section



# Properties

## Geological Cross-Section

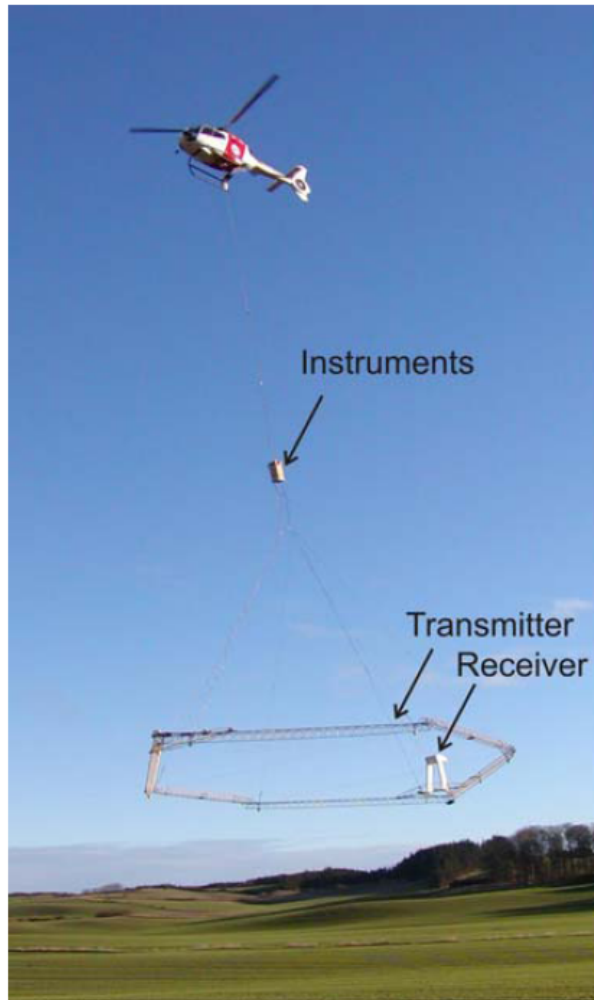


- Buried valleys with clays beneath
- Infill (water-bearing): coarse sand and gravel
- Clays are conductive (1-40  $\Omega m$ )
- Water-bearing sands and gravels are more resistive (>40  $\Omega m$ )

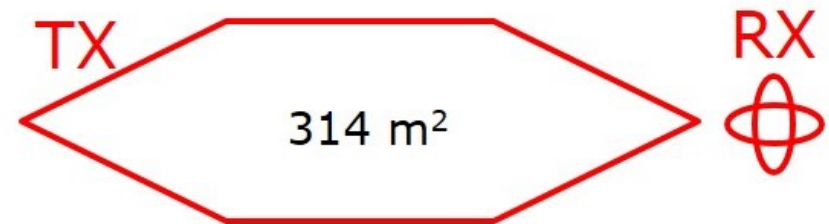
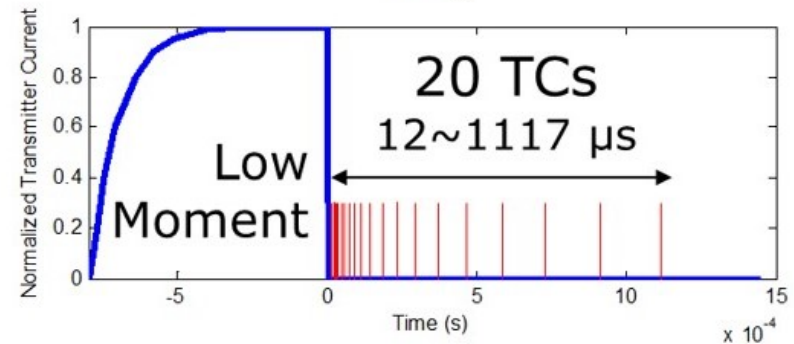
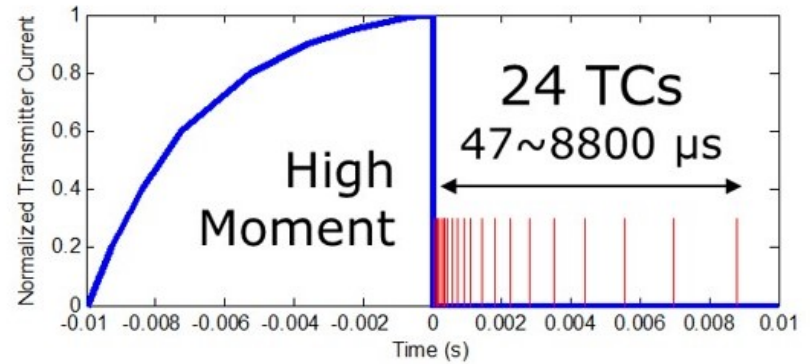
Geological Units	Resistivity ( $\Omega m$ )
Palaeogene Clay	1-10
Clay Till	25-60
Sand Till	>50
Meltwater Sand and Gravel	>60
Glaciolacustrine Clay	10-40
Miocene Silt and Sand	>40
Miocene Clay	10-40
Sand	>40
Clay	1-60

# Survey

## SkyTEM System



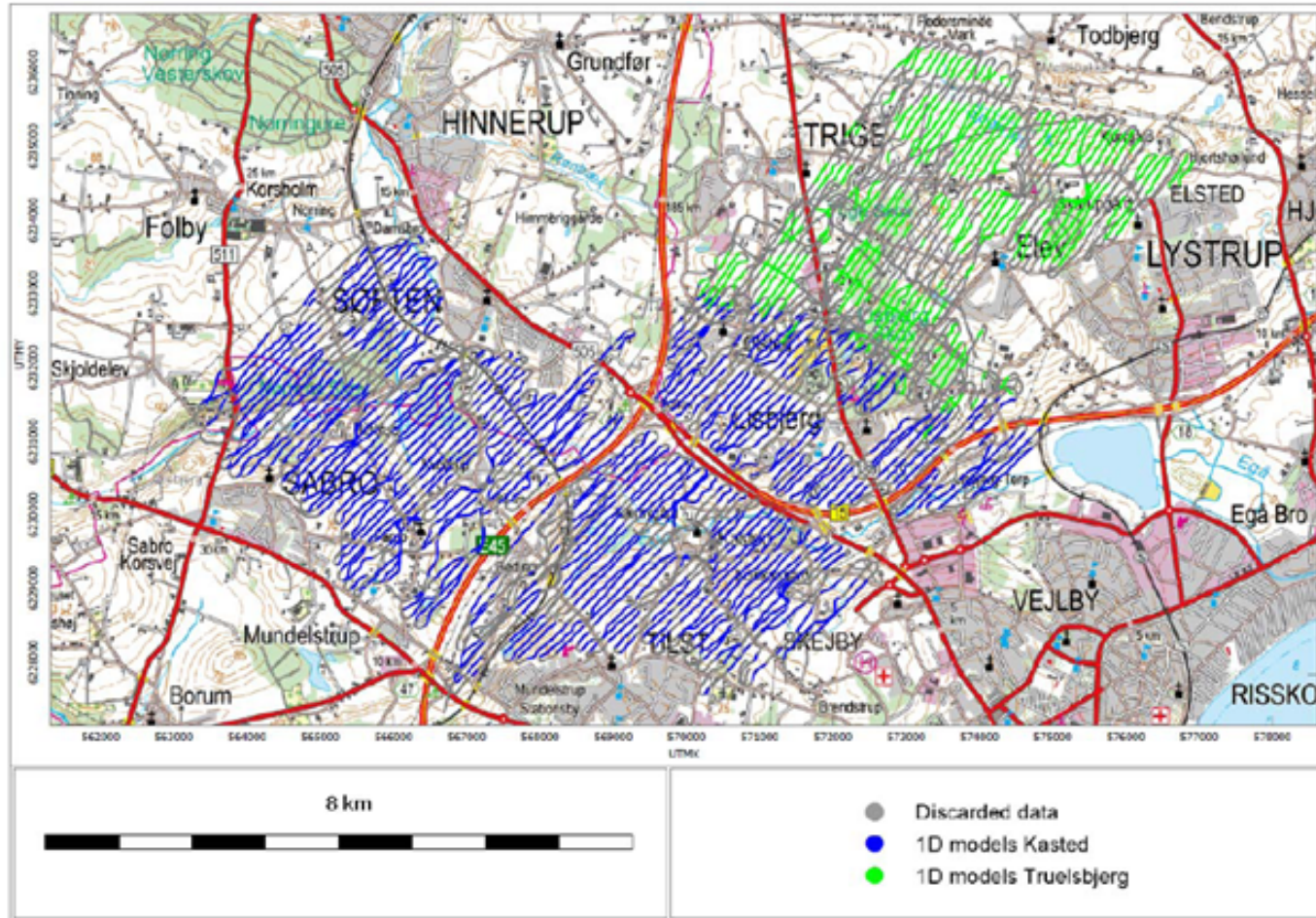
## System Configuration



- Low moment (LM) used to image near surface structures
- High moment (HM) used to image deeper structures

# Data

Blue: data used for Kasted study

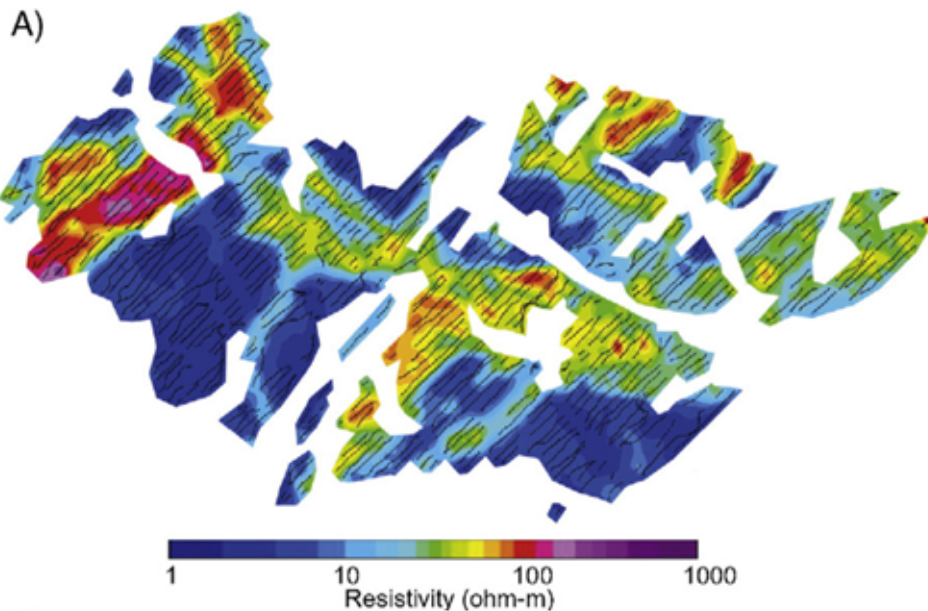


- 333 line km of data, 100 m line-spacing
- Data points with strong coupling to cultural noise were removed (~30%)

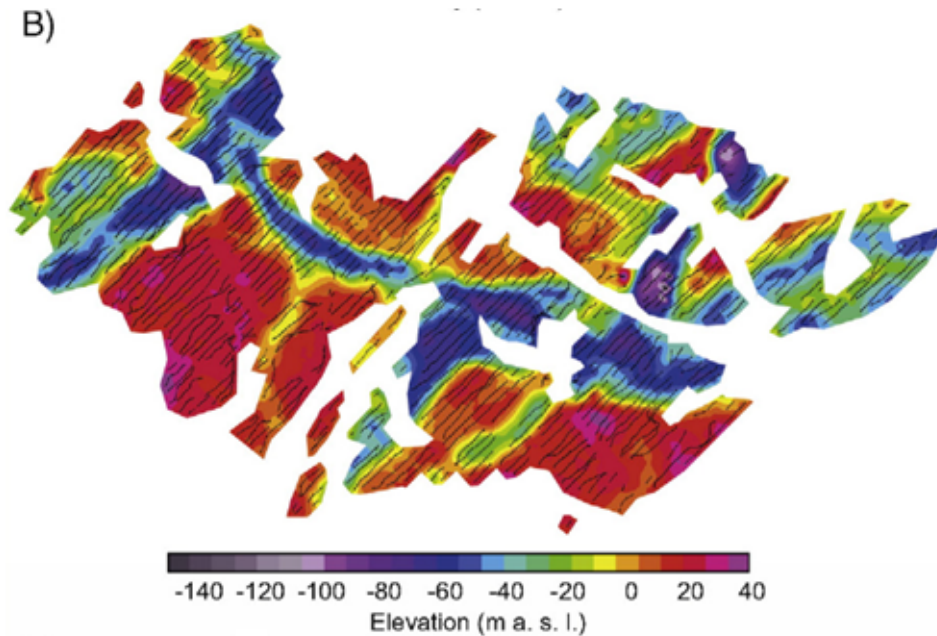
# Processing (inversion)

- Spatially constrained 1D inversion → quasi-3D approach
- 9,500 soundings were inverted using 25 layers

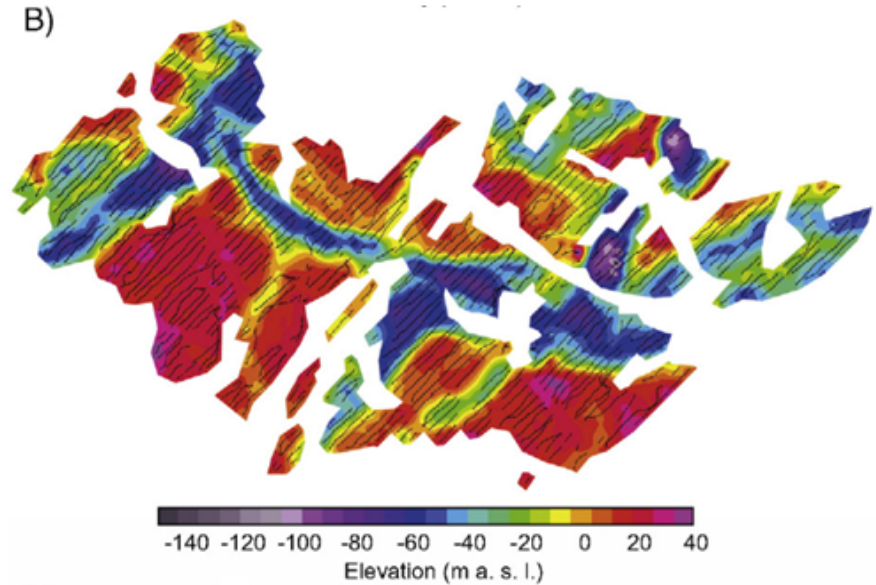
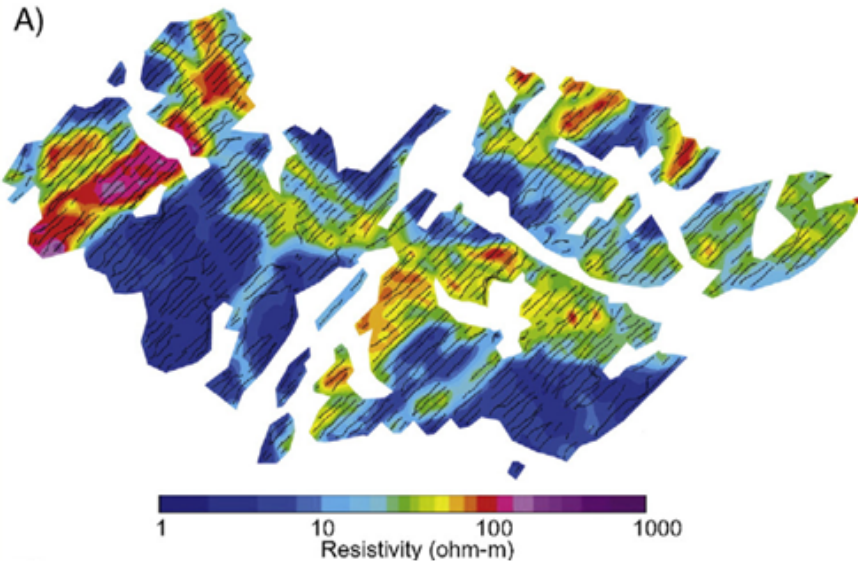
Depth slice 5 m above sea-level



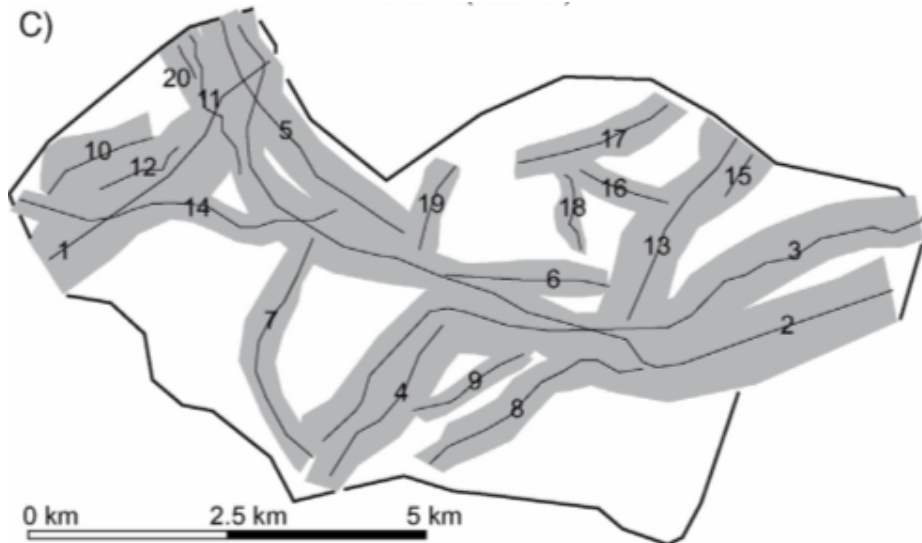
Approximate depth to the top of Paleogene clay layer



# Interpretation



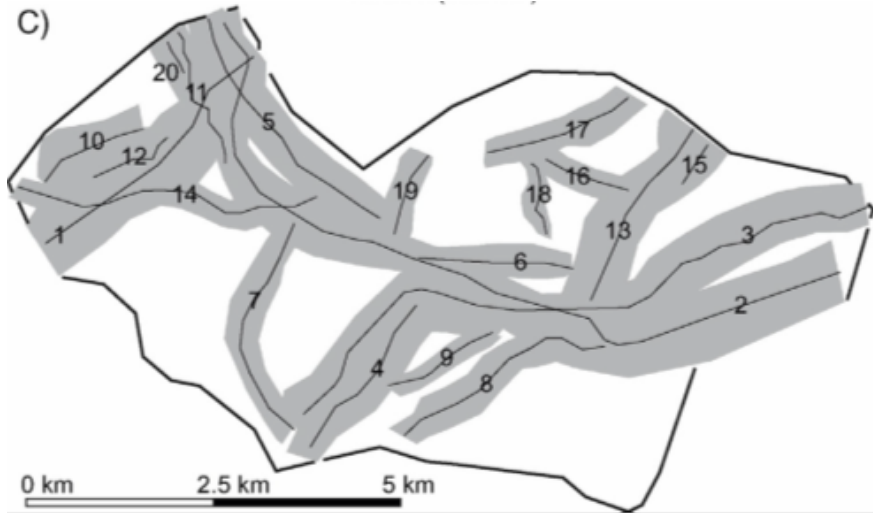
## Delineation of valley structures



- Inversion results used to construct geological model.
- Delineated 20 buried and cross-cutting valley structures.



# Synthesis

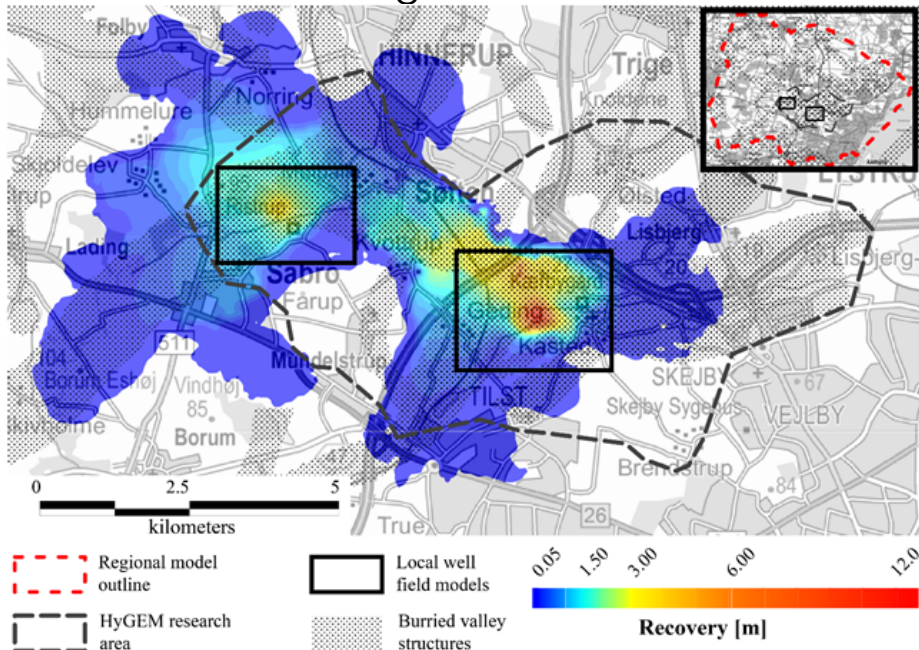


- 3D geologic model incorporated into MODFLOW-USG groundwater modeling tool

- Extracted water from 2 wells.

MODFLOW-USG groundwater model

- Dewatering between the two wells correlated with the resistive valley structures



# End of Inductive Sources

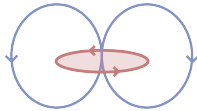
Next up



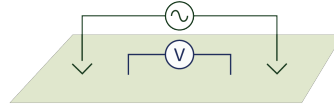
DC Resistivity



EM  
Fundamentals



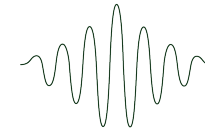
Inductive  
Sources



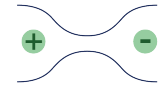
Grounded  
Sources



Natural  
Sources



GPR



Induced  
Polarization



The  
Future

Lunch: Play with apps