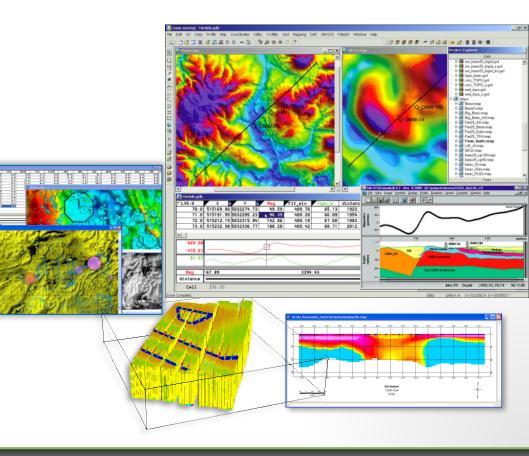


Geoscience software for:

- Geophysics
- Geochemistry
- Geology
- GIS



How does Geosoft use EM & Electrical methods?



IP & DC resistivity

- QC, processing and 3D pseudosection visualizeation
- 3D inversion

FDEM

- Visualization and basic processing
- FDEM pseudo 3D inversion
- TDEM for UXO EM61 MK2, (3-4 time gates)
- Import, processing, target picking, depth estimates 7 forward modelling
 TDEM for UXO Geometrics Metal Mapper
- Dynamic surveys for target locating
 - Processing, target picking, depth estimates, high level classification (21 time gates)
- Static surveys for classification
 - Ordinance classification (122 time gates)

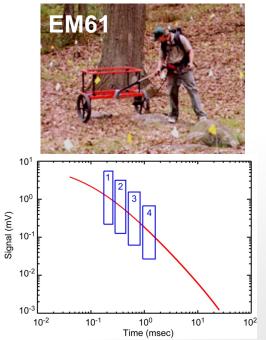
Conventional EM Sensors

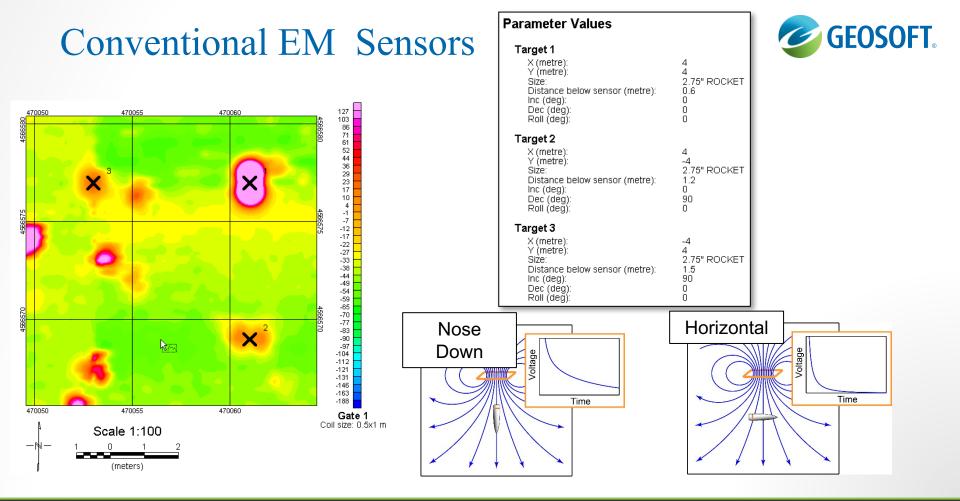
GEOSOFT.

Not usually good for classification

- Coarse measurement of eddy current decay (four time windows or gates)
- Point response measured at series of locations must be combined to fully interrogate target
- Small sensor location errors (~1 cm) compromise ability to estimate polarizability

(some simple case exceptions)

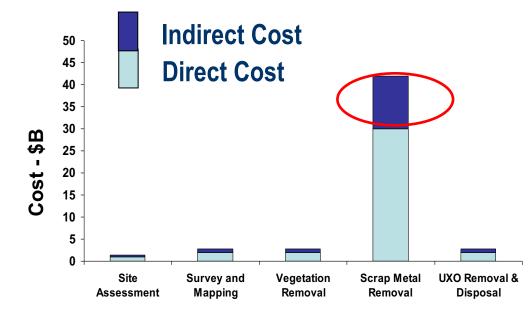




Why Do Classification?



Munitions Response Typical Cost Breakout



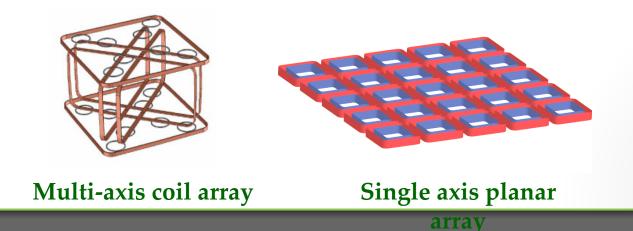
Advanced EM Sensors



Designed for Classification

To observe the complete EM response pattern the object must be excited and measured from all directions

- multi-axis coil sensors or
- single axis coil arrays



Advanced EM Sensors



MetalMapper

- 3 multi-axis transmitters
- 7 multi-axis receivers



MetalMapper 2x2

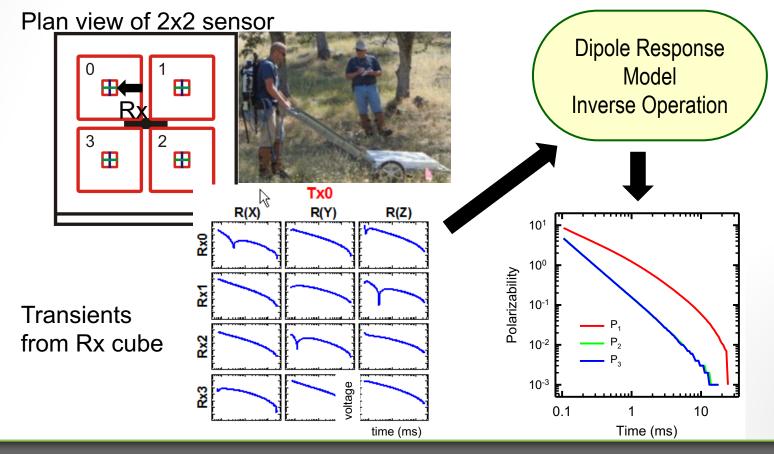
- 4 coil transmitter array
- 4 multi-axis receivers

Typical static survey mode, 122 gates over 25ms



Extracting 'Intrinsic' Features





Polarizability's

The solution for classification – intrinsic features

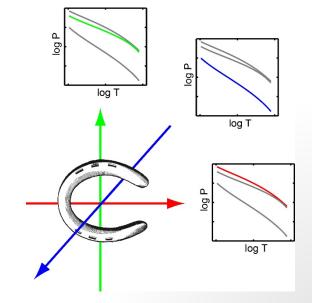
EM response is decomposed into components along three orthogonal principal axis directions

- Principal axis *directions* correspond to fundamental excitation modes of target
- Magnetic *polarizabilities* are specific responses to unit excitation along each of target's principal axis

Principal axis polarizabilities

- Completely describe EM response of target
- Intrinsic to the source



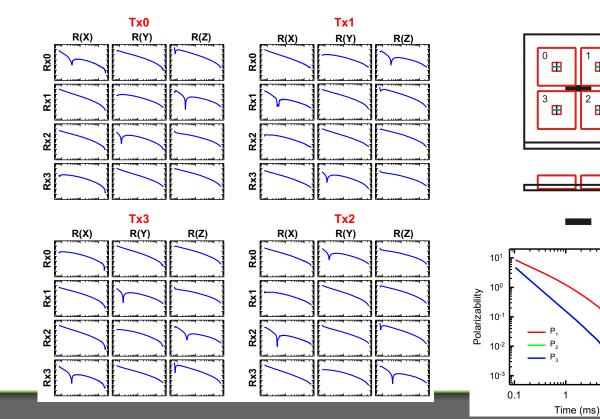


Measured Decays Convolve Intrinsic Response with Relative Position and Orientation – Position "A"



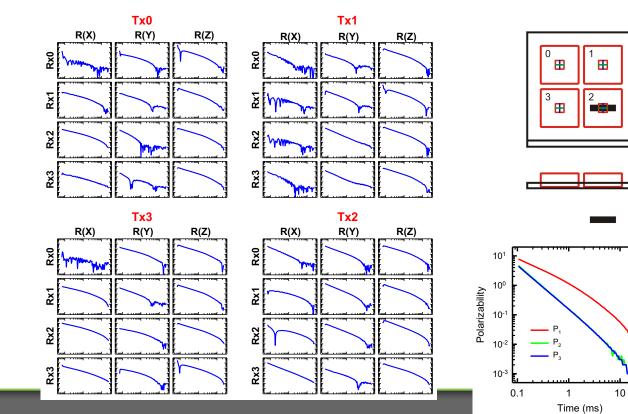
B

10



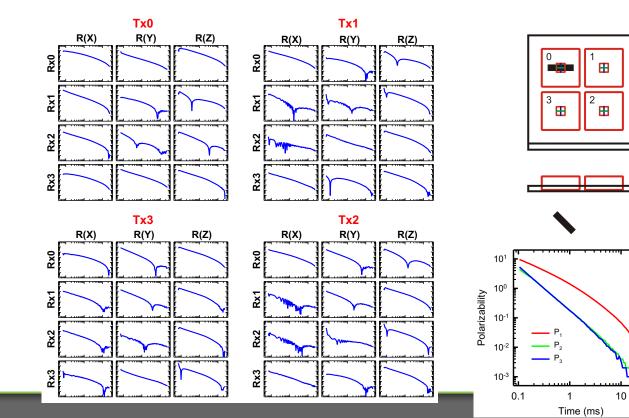
Measured Decays Convolve Intrinsic Response with Relative Position and Orientation – Position "B"





Measured Decays Convolve Intrinsic Response with Relative Position and Orientation – Position "C"





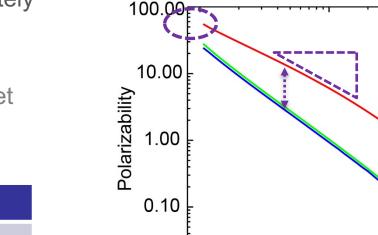
Principal axis polarizabilities completely describe EM response of target

intrinsic to the target

Polarizabilities

 invariant to burial depth or target orientation

Polarizability Property	Target Property	
Decay Rate	Wall Thickness	
Relative Magnitude	Shape	
Total Magnitude	Size (volume)	



0.01

0.1

37mm projectile

1.0 Time (msec)



10.0

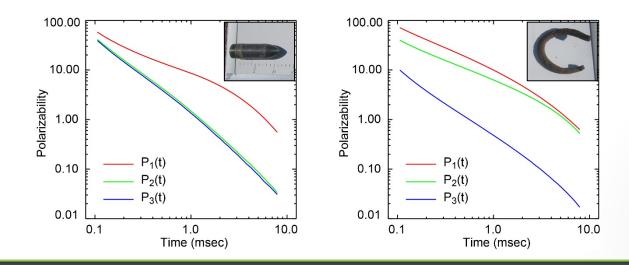
Classification



Signature Matching

What an unknown target "looks like" in EM sense

 Compares polarizability against bank of signatures for expected munitions and other training objects



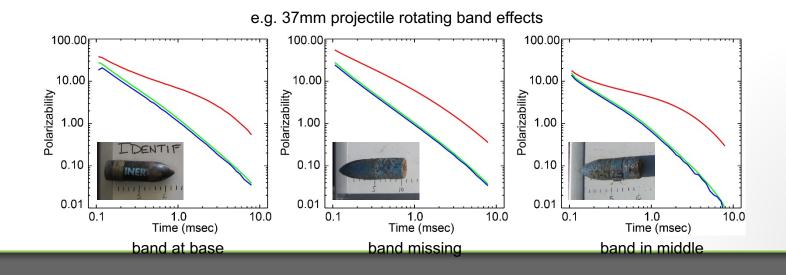
Classification



Signature Variability

EM signatures of nominally identical items can differ

• Different subtypes, damage, inversion errors due to noise Matching procedures must tolerate some variability



Ranked Source List



Classify and Rank Sources

- Combine match metric
- Size and Decay
- Signal amplitude
- Source to array distance

Anomaly ID	Dig on First Pass	Туре	Comment		'
2498	Y		Unable to extract reliable parameters		
247	Y	105 mm			
1114	Y	4.2 in	High likelihood TOI		
69	Y	155 mm			
811	Y	81 mm		First	
313	N		Unable to classify	Pass Threshold	
883	N				Ĩ
	N				
	N				
	Ν		High likelihood not TOI		
	N				
	N				
	Ν				
	N				
	N				
	Ν				

Initial Ranked Anomaly List

Final Ranked Anomaly List

	Anomaly ID	Dig	Туре	
	2498	Y		
	247	Y	105 mm	
	1114	Y	4.2 in	
	69	Y	155 mm	
]	811	Y	81 mm	
	313	Y	105 mm	Final
	883	Ν		Threshold
		N		
		Ν		
		Ν		
		Ν		
	S	Ν		
	····	Ν		
		Ν		
		Ν		
		Ν		

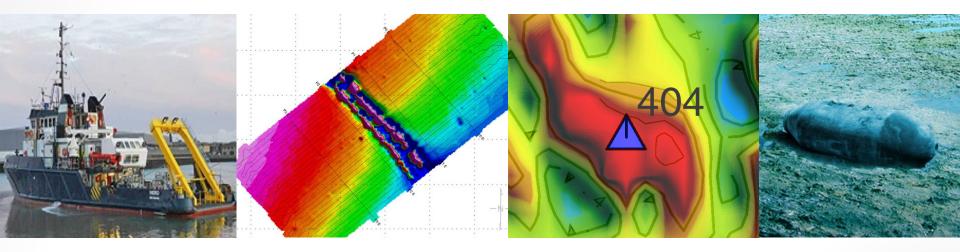
Future plans and challenges?



- Marine EM
 - Develop our current tools for EM61 to be marine compatible
 - Work with Geometrics to develop an advanced EM system for classification

• 3D TDEM inversion





Please visit Geosoft at Booth G8

or visit www.Geosoft.com