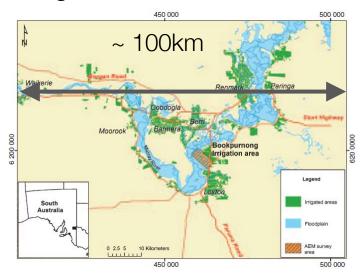
EM: Inductive Sources





Motivation

Large areas to be covered



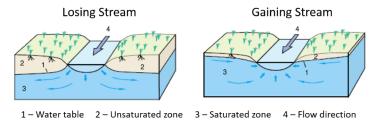
Rugged terrain



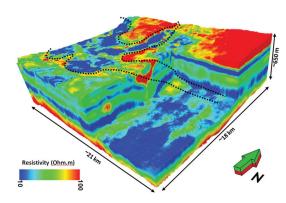
Minerals



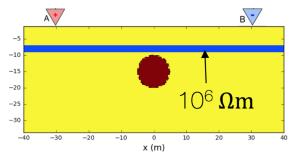
Groundwater



High resolution near surface



Shielding problem



Outline

Setup

- Basic experiment
- Transmitters, Receivers

Time Domain EM

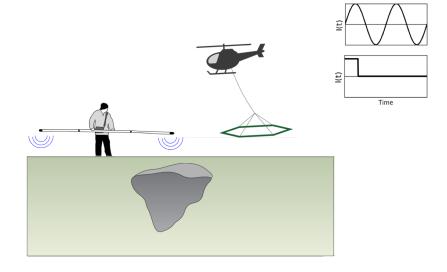
- Vertical Magnetic Dipole
- Propagation with Time
- Case History Groundwater, Minerals, Hydrocarbons
- Horizontal magnetic dipole

Frequency Domain EM

- Vertical Magnetic Dipole
- Effects of Frequency
- Case History Groundwater, Minerals

Important questions

- What is the target?
 - at the surface? At depth?. 1D, 2D, 3D?
- Transmitter
 - Location: surface? in the air?
 - Waveform: frequency or time?
 - "Size" and orientation?
- Exciting the target
 - Conductivity of the target and host
 - Geometry of the target (Coupling)
- Receiver and data
 - What fields to measure?
 - What instrument?
- Where to collect data? How many? How accurate?
- What is depth of investigation?
- What is the "footprint" of the transmitter"
 - These are questions of SURVEY DESIGN

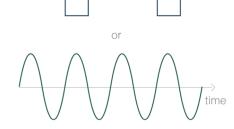


Basic Experiment

waveform

Transmitter:

Produces a primary magnetic field

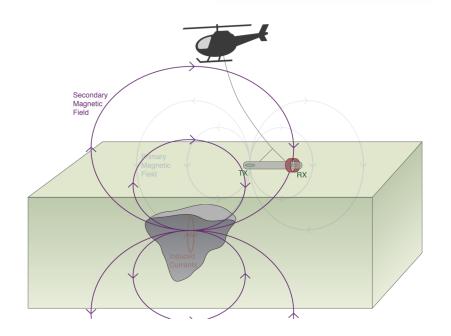


Exciting the target:

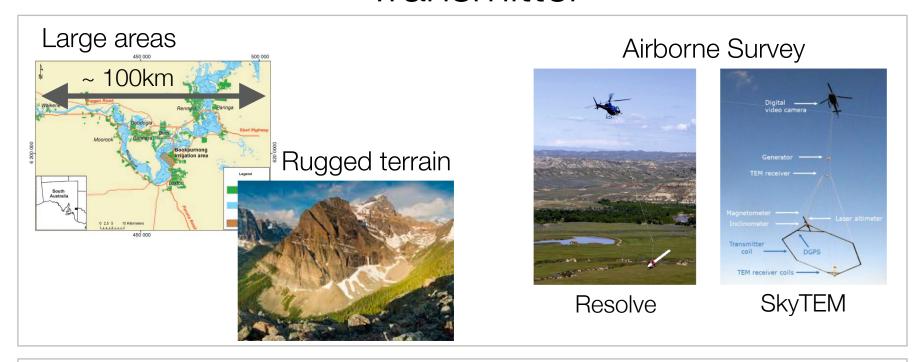
- Time varying magnetic fields generate electric fields everywhere
- Producing currents in conductors

Receiver:

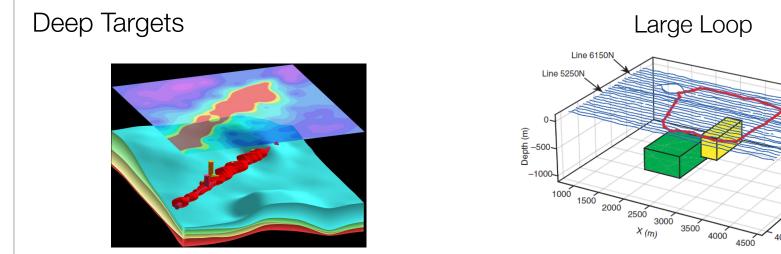
Induced currents produce secondary magnetic fields



Transmitter

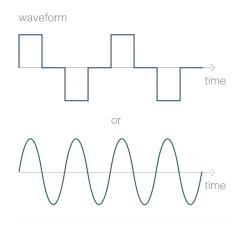


6



Transmitter

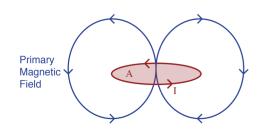
Time or frequency?



Key factor is moment

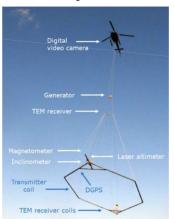
m = I (current) A (area) N (# of turns)

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left(\frac{3\mathbf{r}(\mathbf{m} \cdot \mathbf{r})}{|\mathbf{r}|^5} - \frac{\mathbf{m}}{|\mathbf{r}|^3} \right)$$



Airborne Survey

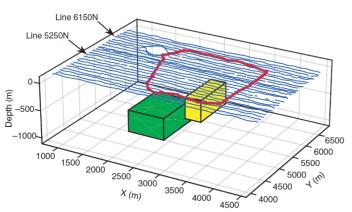




Resolve

SkyTEM

Large Loop

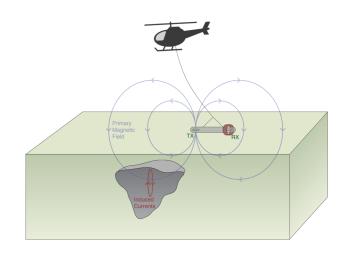


Exciting the target

Primary field from a loop

 $\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left(\frac{3\mathbf{r}(\mathbf{m} \cdot \mathbf{r})}{|\mathbf{r}|^5} - \frac{\mathbf{m}}{|\mathbf{r}|^3} \right)$

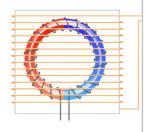
- Fields fall off
 - 1/r³ geometric decay
 - Attenuation
- Want to be as close as possible to target
 - Ground based systems
 - Helicopter
 - Fixed wing aircraft
- Always concerned about coupling



Receiver and Data

Magnetometer

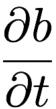
- Measures:
 - Magnetic field
 - 3 components
- eg. 3-component fluxgate

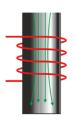


Fluxgate

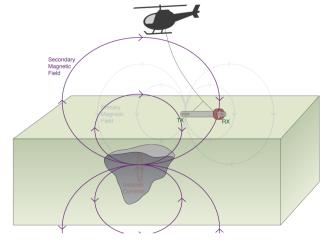
Coil

- Measures:
 - Voltage
 - Single component that depends on coil orientation
 - Coupling matters
- eg. airborne frequency domain.
 - ratio of Hs/Hp is the same as Vs/Vp



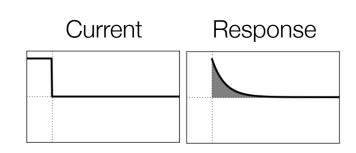


Coil

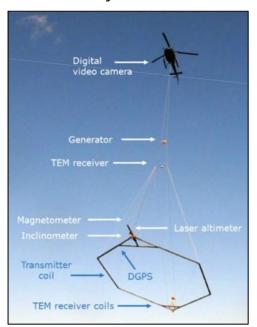


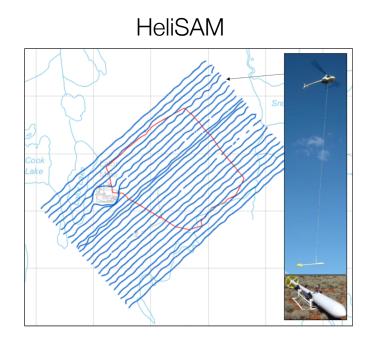
Receiver: Time Domain

- Primary field has off-time
- Measure secondary fields
- Receivers can be mounted on transmitter loop or above it



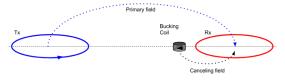
SkyTEM



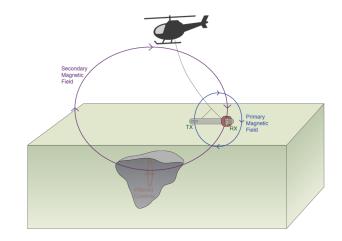


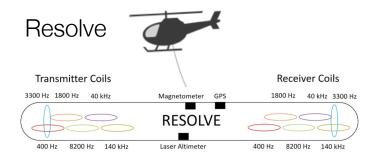
Receiver: Frequency Domain

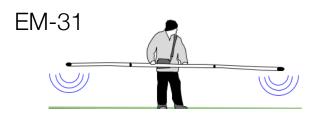
- Primary field
 - always "on"
 - large compared to secondary fields
- Primary removal
 - Compute and subtract
 - Bucking coil



- Main requirement:
 - Know positions of Tx and Rx
 - Keep them in one unit





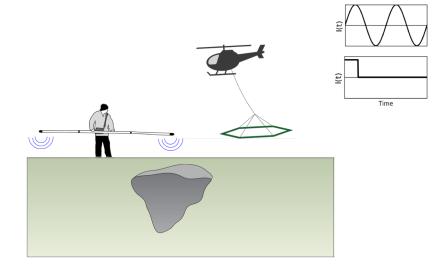


Important questions

- What is the target?
 - at the surface? At depth?. 1D, 2D, 3D?
- Transmitter
 - Location: surface? in the air?
 - Waveform: frequency or time?
 - "Size" and orientation?
- Exciting the target
 - Conductivity of the target and host
 - Geometry of the target (Coupling)
- Receiver and data
 - What fields to measure?
 - What instrument?

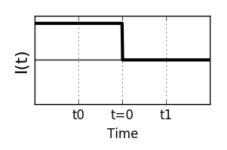


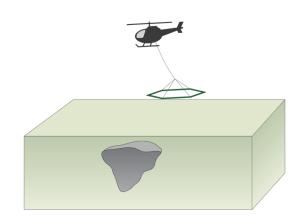
- What is depth of investigation?
- What is the "footprint" of the transmitter"
 - These are questions of SURVEY DESIGN

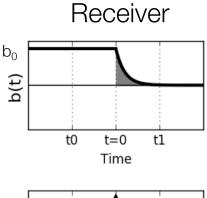


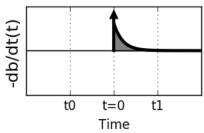
EM with Inductive Sources: Time Domain

Transmitter current







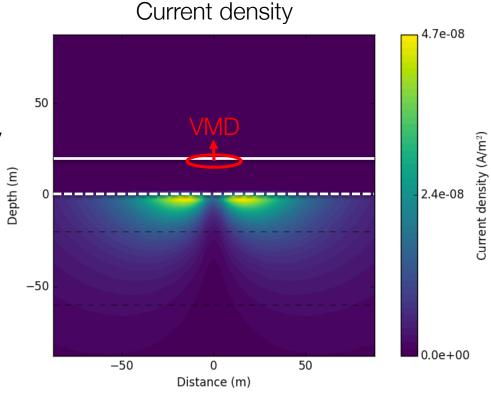


time	b	${ m db/dt}$
t < 0	b_0	0
t = 0	b_0	$-b_0\delta(t)$
t > 0	secondary	secondary

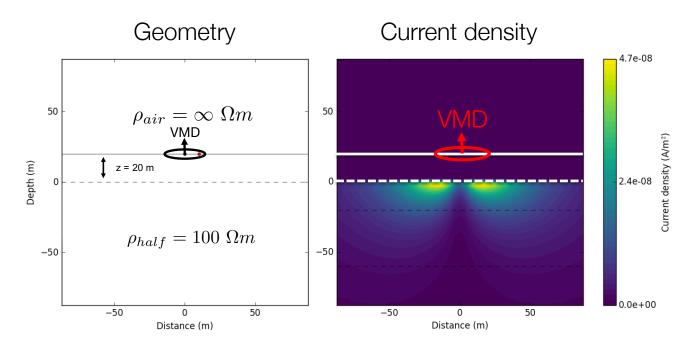
 $\delta(t)$: Dirac-delta function

Footprint of Airborne EM system

- What volume of earth is "seen" by the airborne system?
 - Where are the currents?
- Currents depend on
 - Transmitter
 - Waveform: time or frequency
 - Background conductivity
- Simple case: loop source over homogeneous earth



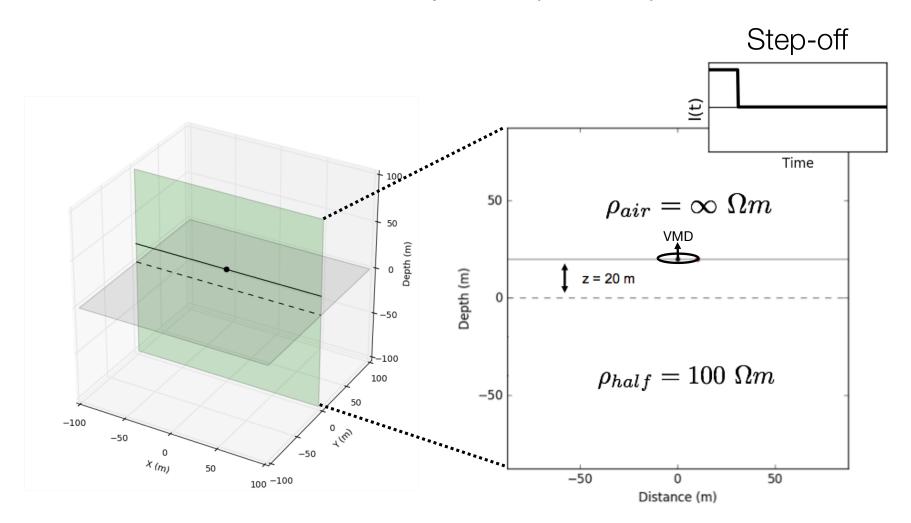
Vertical Magnetic Dipole (VMD)



Some questions

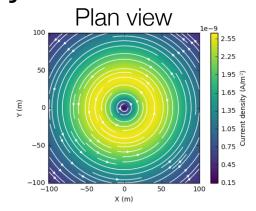
- Where, and how strong, are the currents?
- How do they depend upon the conductivity?
- What do the resulting magnetic fields look like?

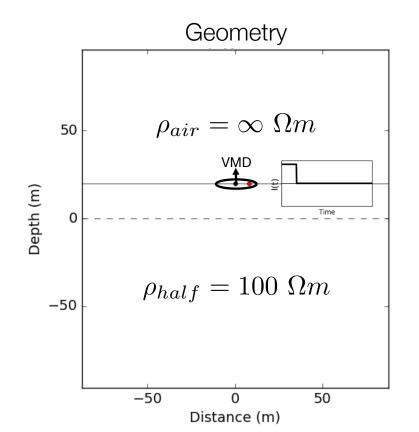
Vertical Magnetic Dipole over a halfspace (TDEM)

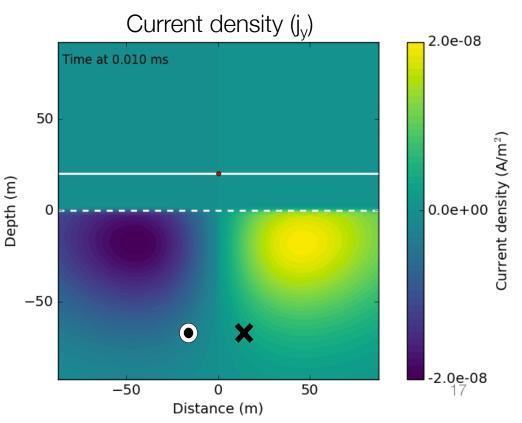


Current Density

• Time: 0.01ms

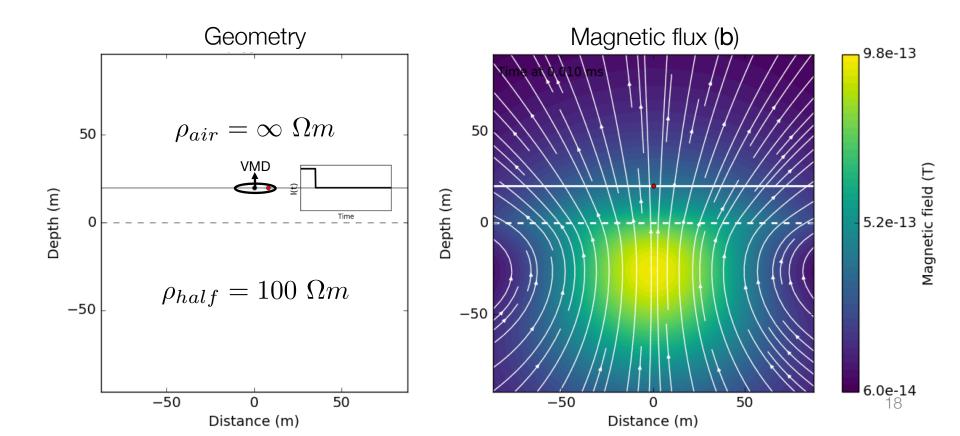






Magnetic flux density

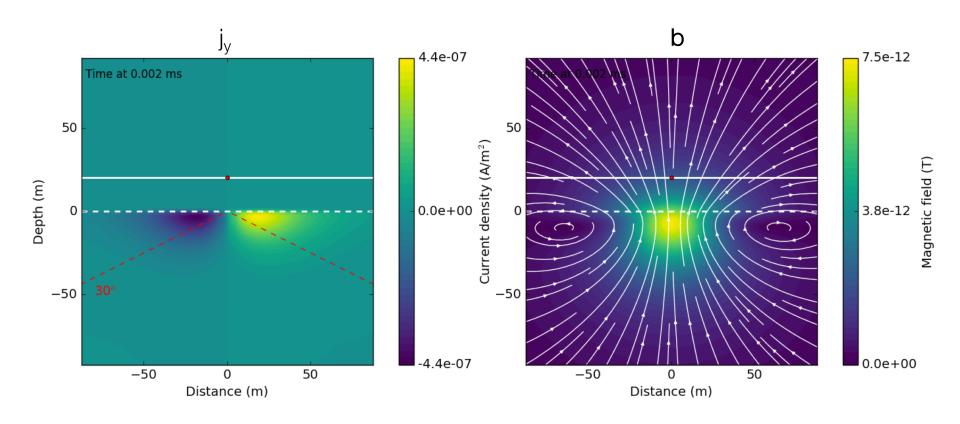
• Time: 0.01ms



• Time: 0.002ms

$$d = 1260\sqrt{t\rho}$$

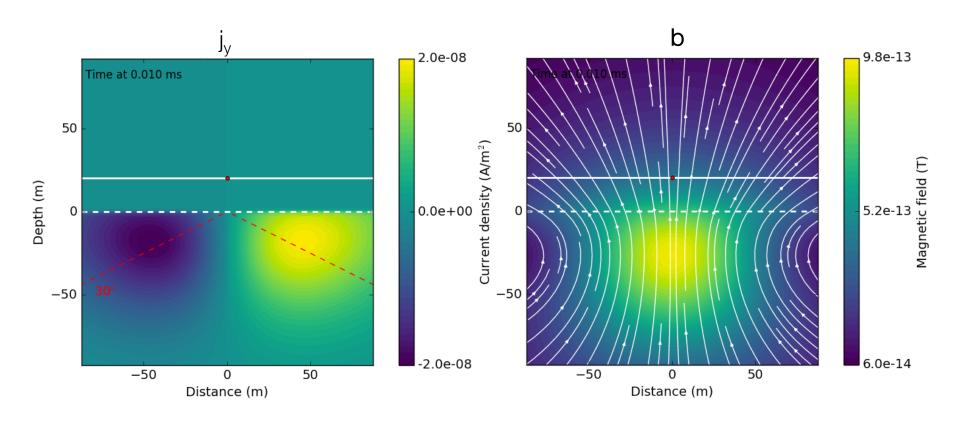
diffusion distance = 18 m



• Time: 0.01ms

$$d = 1260\sqrt{t\rho}$$

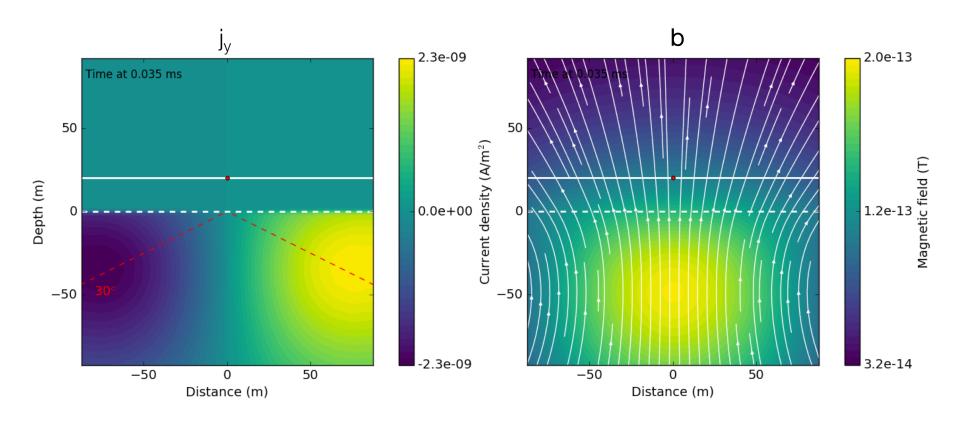
• diffusion distance = 38 m



• Time: 0.035ms

$$d = 1260\sqrt{t\rho}$$

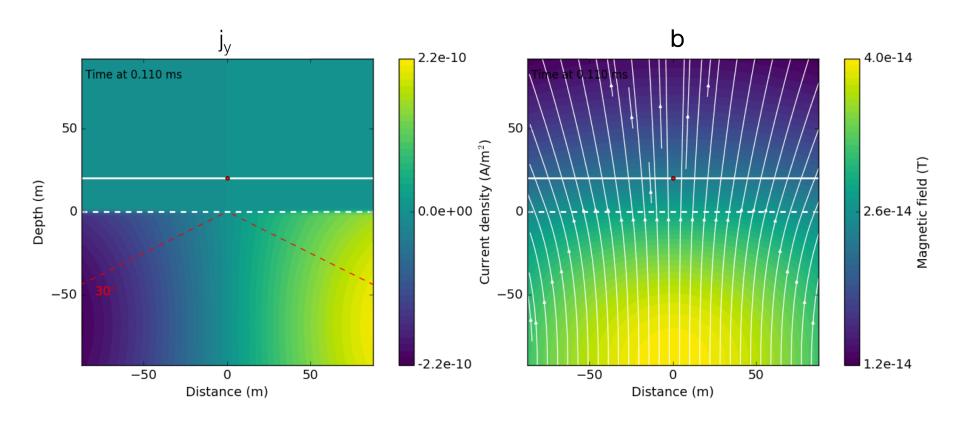
diffusion distance = 75 m



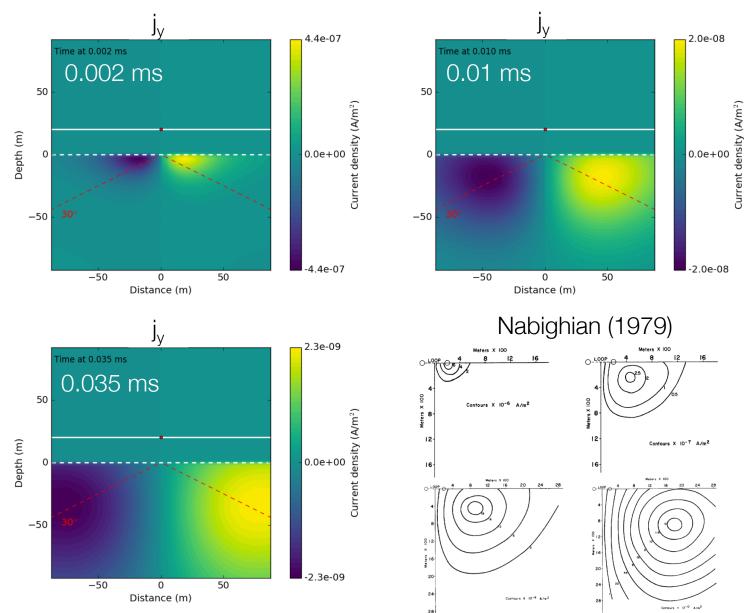
• Time: 0.110ms

$$d = 1260\sqrt{t\rho}$$

diffusion distance = 132 m

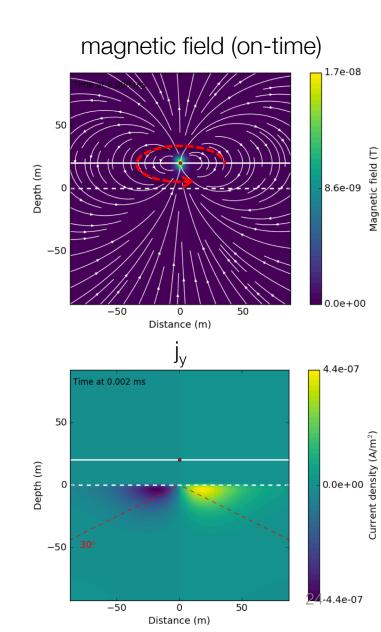


Summary: propagation through time



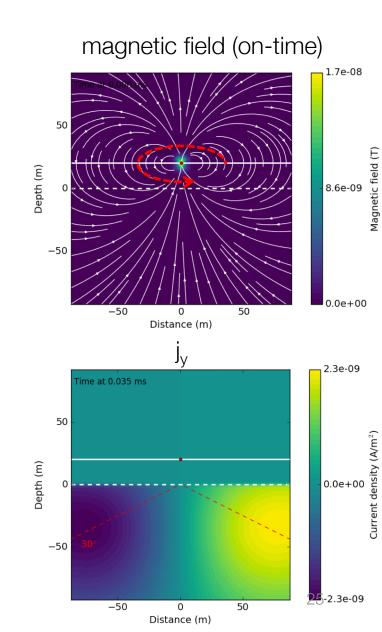
Important points

- Currents flow in same plane as transmitter currents
- Currents diffuse outward downward
- Each transmitter has a "footprint"
- Max resolution controlled by earliest time
- Depth of investigation controlled by latest time



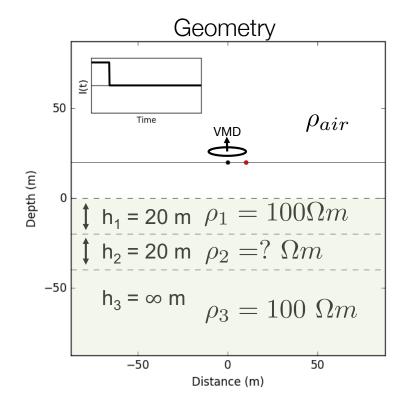
Important points

- Currents flow in same plane as transmitter currents
- Currents diffuse outward downward
- Each transmitter has a "footprint"
- Max resolution controlled by earliest time
- Depth of investigation controlled by latest time



Layered earth

- 3 layers + air,
- ρ_2 varies



- Four different cases:
 - Halfspace

$$\rho_2 = 100 \Omega m$$

- Resistive

$$\rho_2 = 1000 \Omega m$$

Conductive

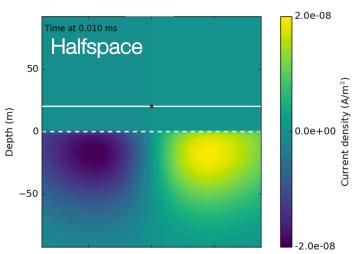
$$\rho_2 = 10 \Omega m$$

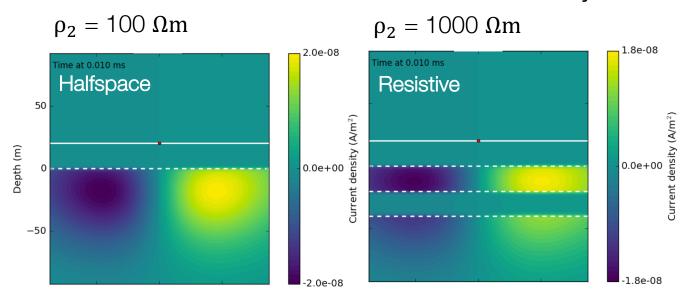
- Very conductive

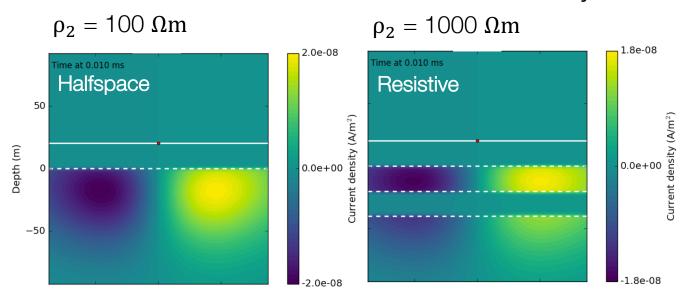
$$\rho_2 = 1 \Omega m$$

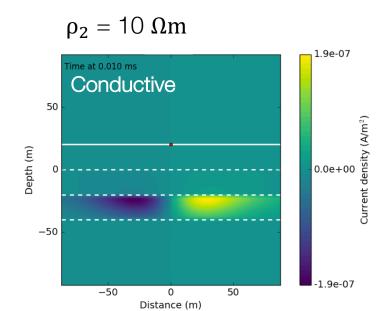
- Fields
 - j_y off-time
 - **b** off-time

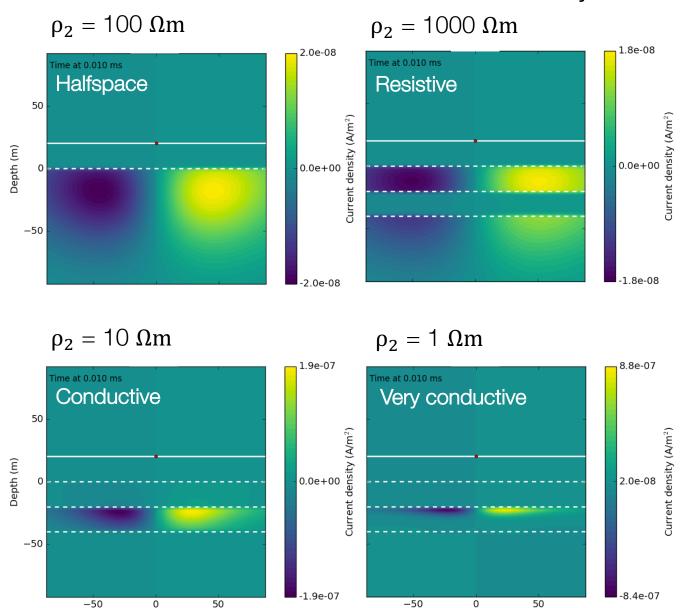
$$\rho_2 = 100 \ \Omega m$$







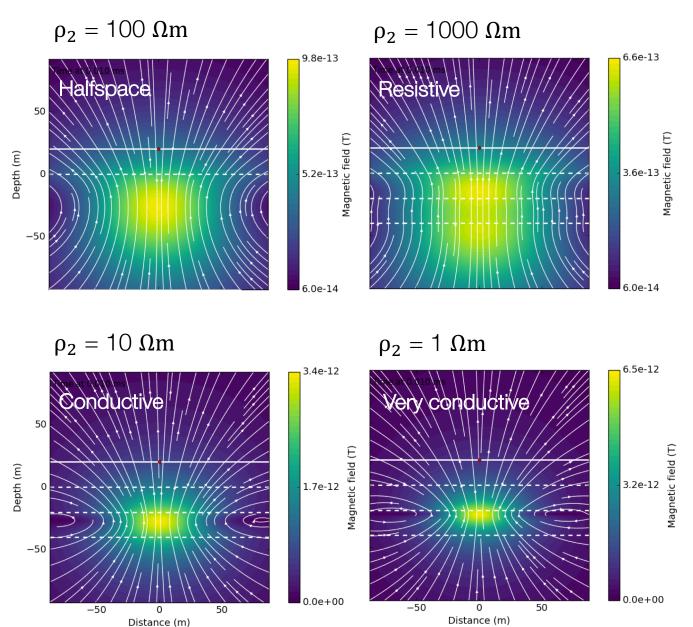




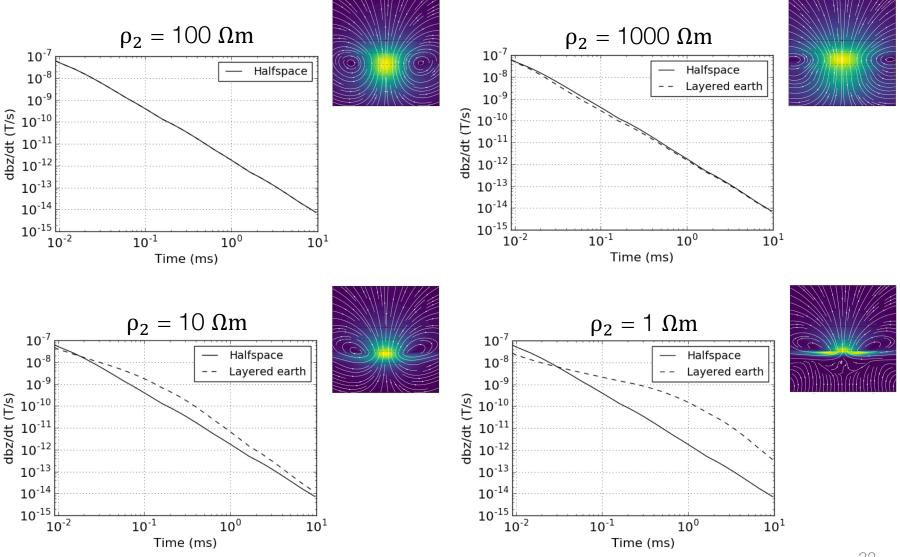
Distance (m)

Distance (m)

Layered earth mag. fields (b)

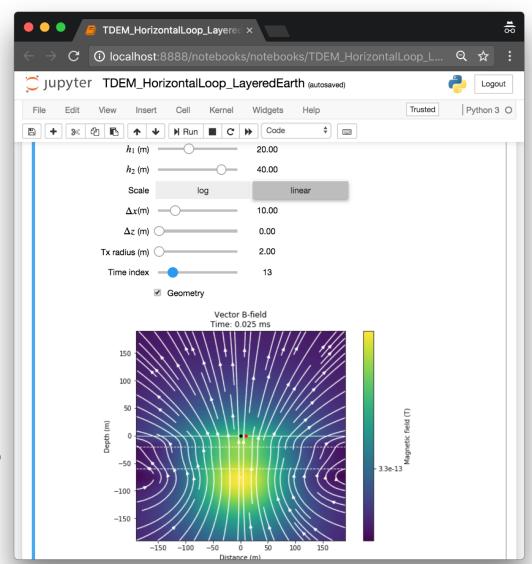


db₇/dt sounding curves



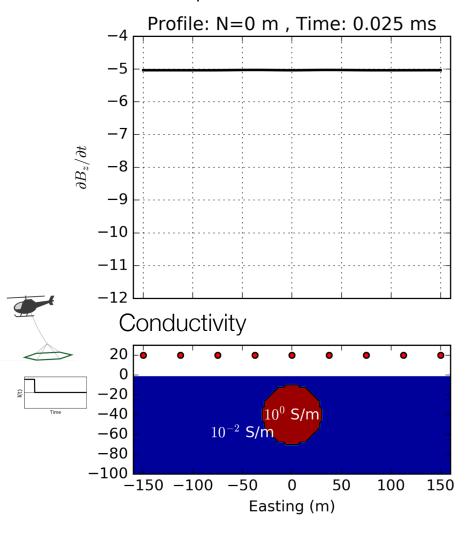
App: VMD over a layered earth (demo)

- TDEM_HorizontalLoop_Layered Earth
- Parameters:
 - Layer resistivities
 - Layer thicknesses
 - Source height, source receiver separation
- View:
 - Model
 - Electric field, magnetic field, current density through time
 - data

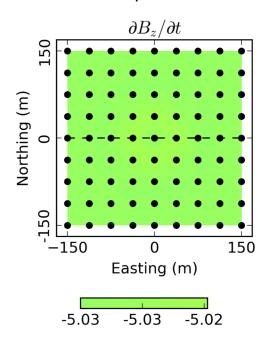


Airborne example: conductive sphere

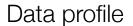
Data profile

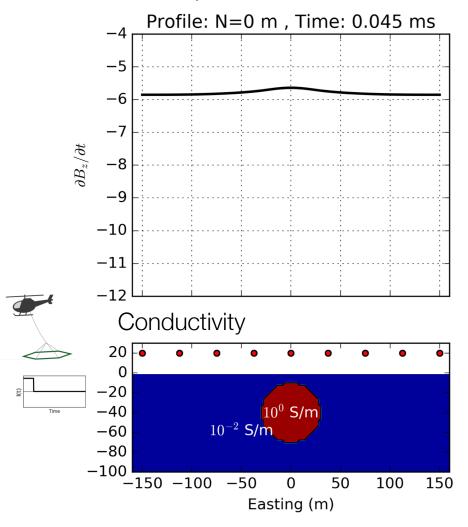


Data map

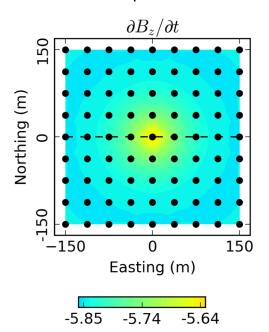


Airborne example: conductive sphere

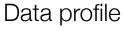


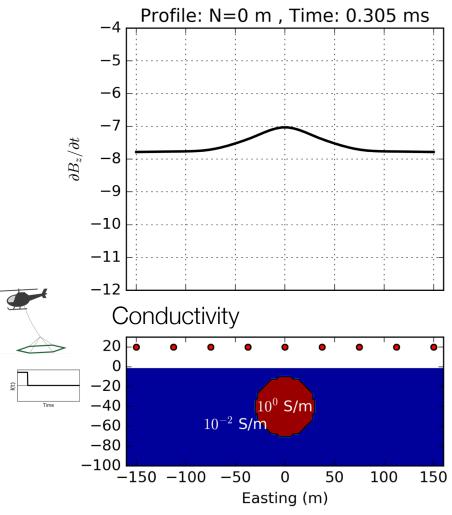


Data map

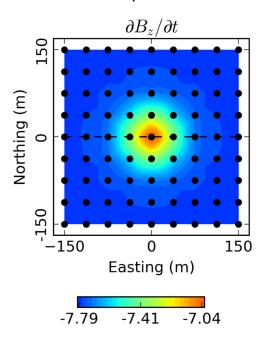


Airborne example: conductive sphere

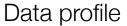


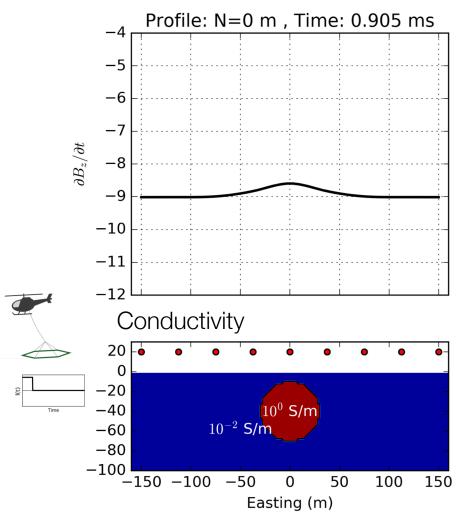


Data map

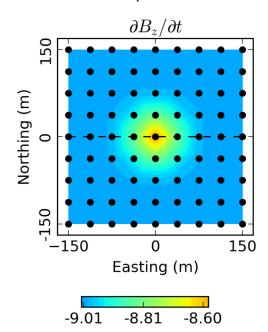


Airborne example: conductive sphere



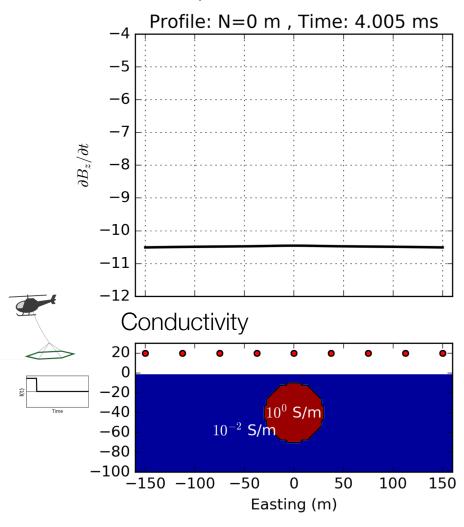


Data map

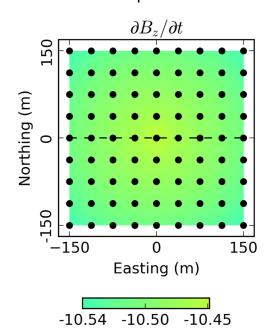


Airborne example: conductive sphere

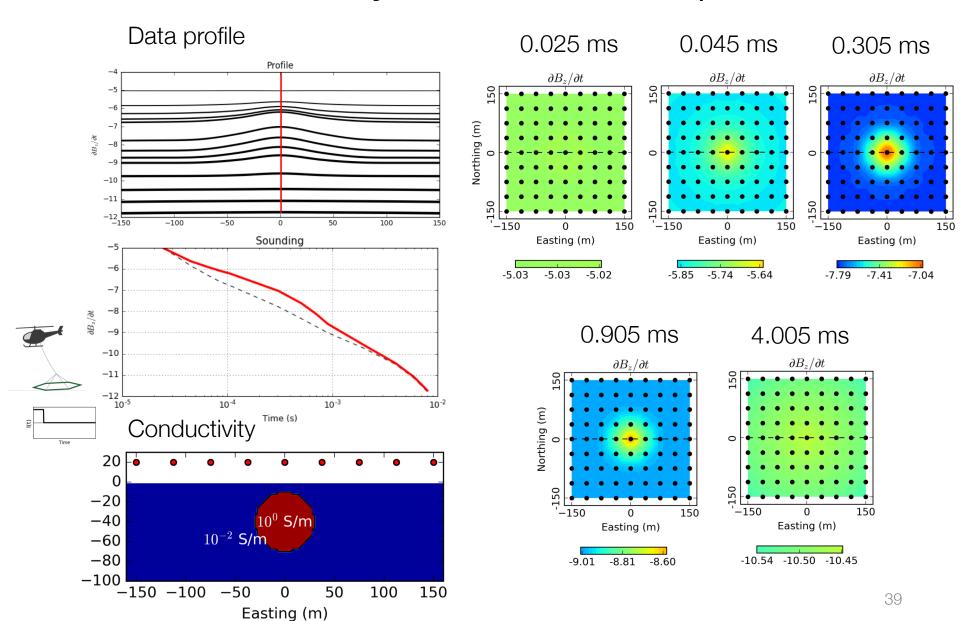




Data map

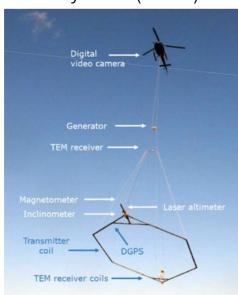


Summary: airborne example



Some Airborne TDEM Systems

SkyTEM (2006)



Area = 314 m^2

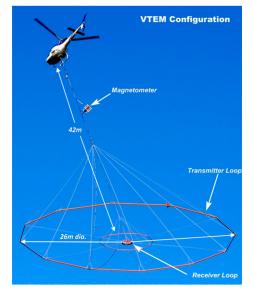
Peak dipole moment:

- HM: 113040 NIA

- LM: 12560 NIA



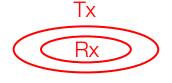
VTEM (2007)

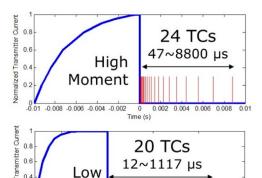


Area = 535 m^2

Peak dipole moment:

- 503,100 NIA





Moment

Peak current: 90 A

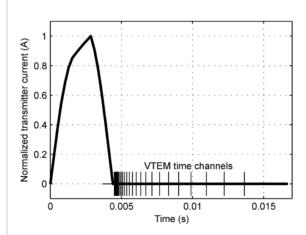
Turns: 4

On-time: 10 ms Off-time: 10 ms

Peak current: 40 A

Turns: 1

On-time: 0.8 ms Off-time: 1.45 ms

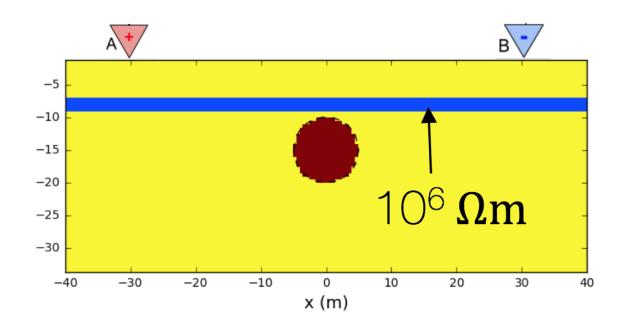


Peak current: 235 A

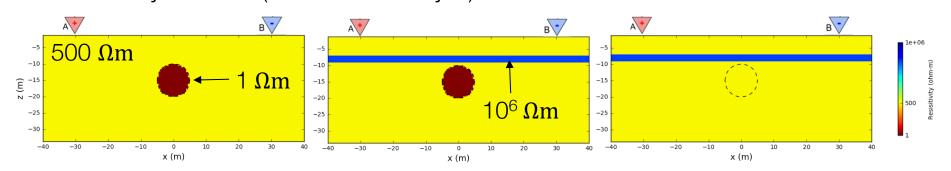
Turns: 4

On-time: 4.5 ms Off-time: 9.1 ms

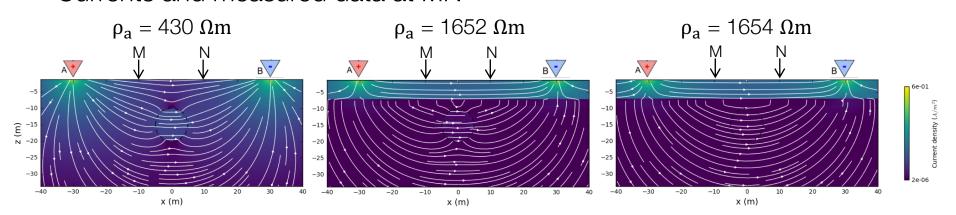
Back to the "shielding" problem



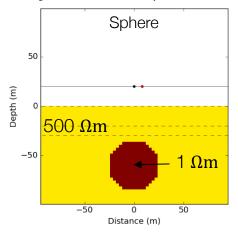
Resistivity models (thin **resistive** layer)



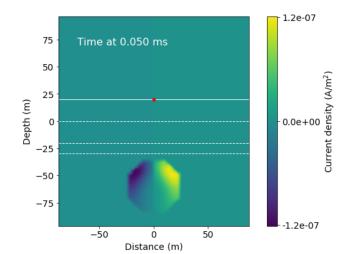
Currents and measured data at MN



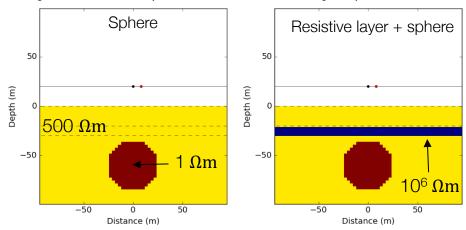
Resistivity models (thin resistive layer)



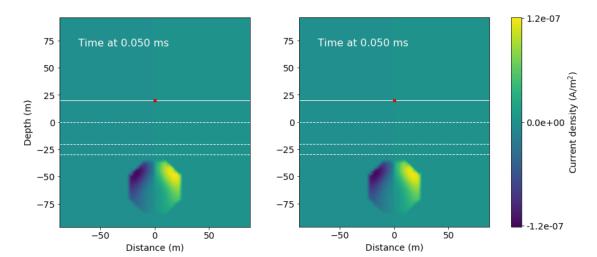
Currents (J_y)



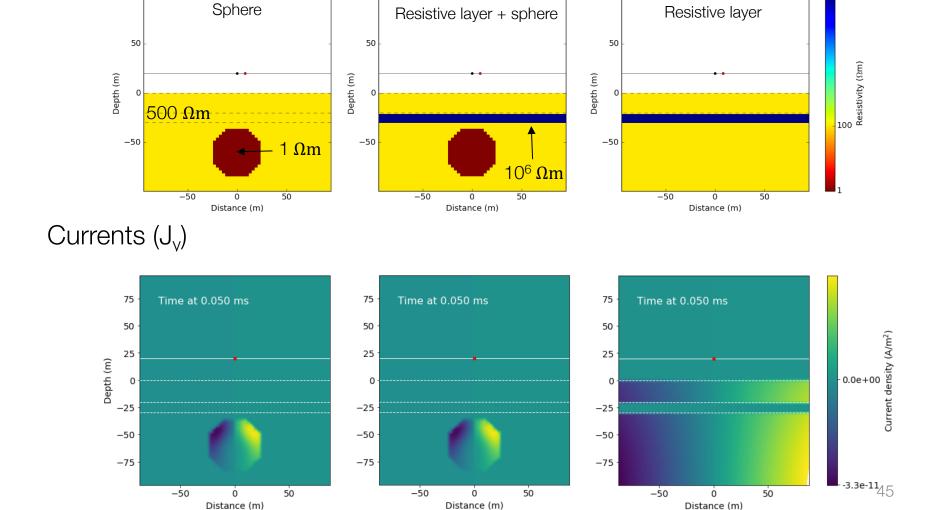
Resistivity models (thin resistive layer)

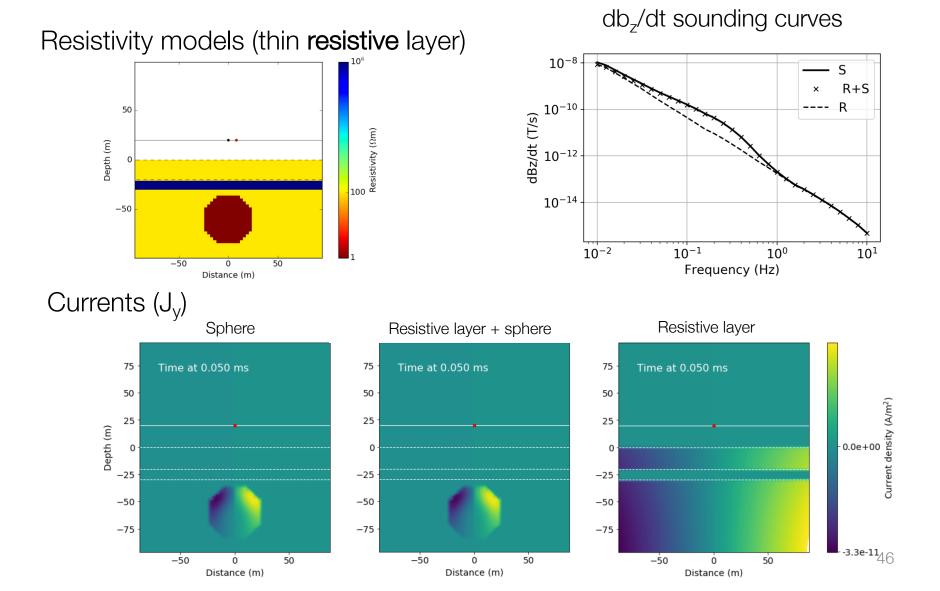


Currents (J_v)



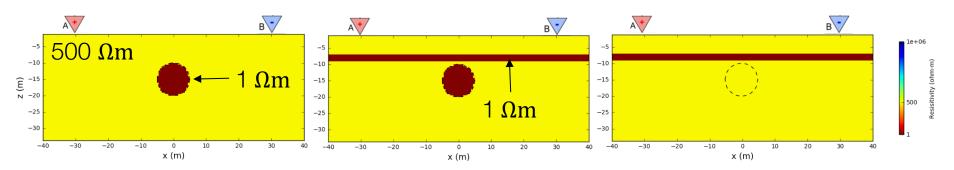
Resistivity models (thin resistive layer)



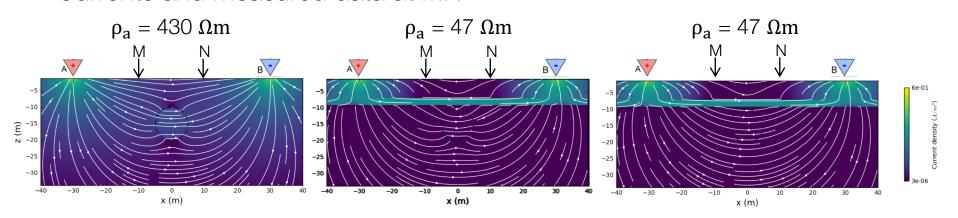


Shielding: DC with conductive layer

Resistivity models (thin conductive layer)

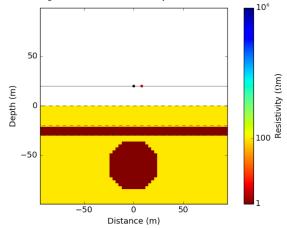


Currents and measured data at MN

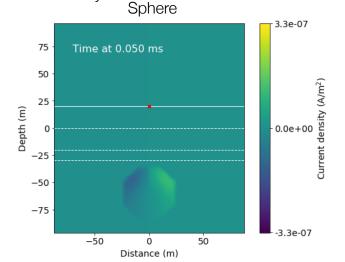


Shielding: EM with conductive layer

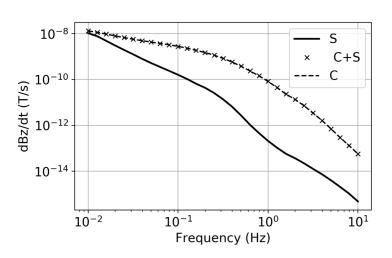
Resistivity models (thin conductive layer)



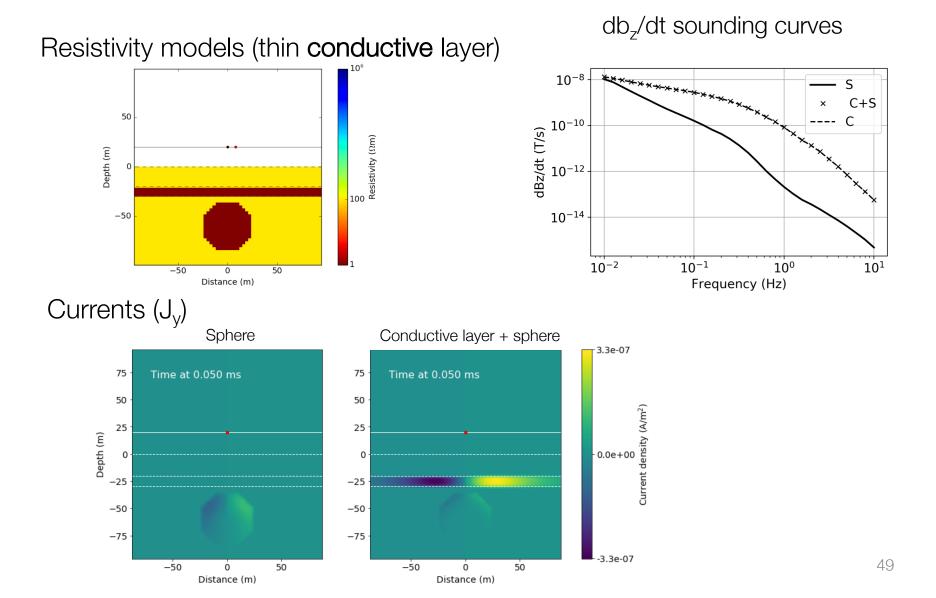
Currents (J_y)



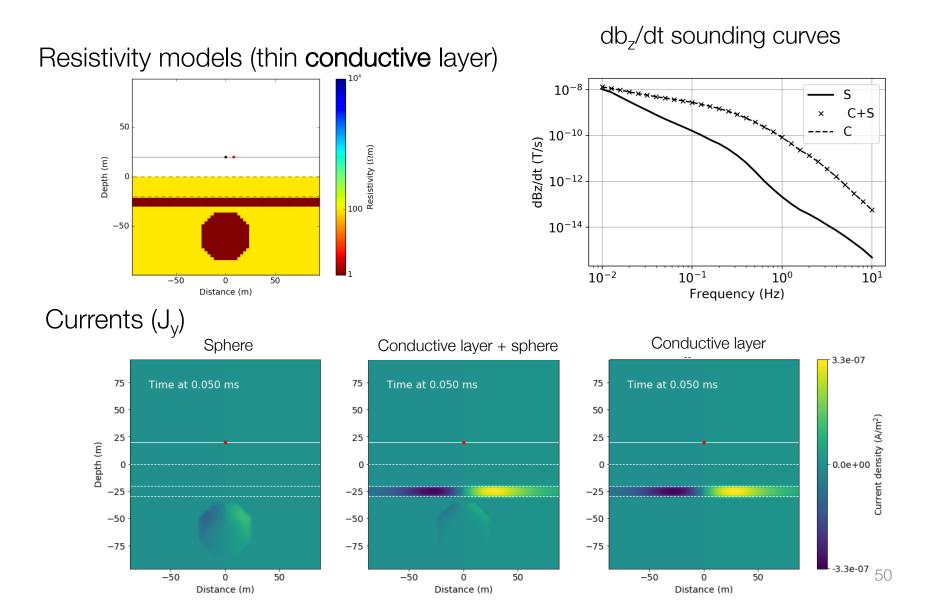
db_z/dt sounding curves



Shielding: EM with conductive layer

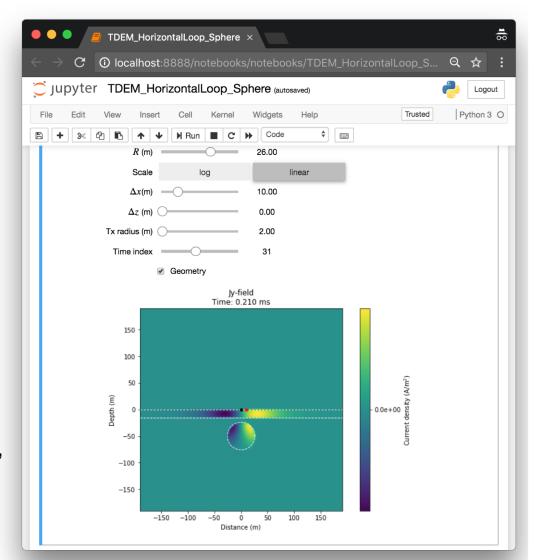


Shielding: EM with conductive layer



App: VMD over sphere with overburden

- TDEM_HorizontalLoop_Sphere
- Parameters:
 - Resistivities of layer, background sphere
 - Geometry of sphere, layer
 - Source height, source receiver separation
- View:
 - Model
 - Electric field, magnetic field, current density through time
 - data



Outline

Setup

Time Domain EM

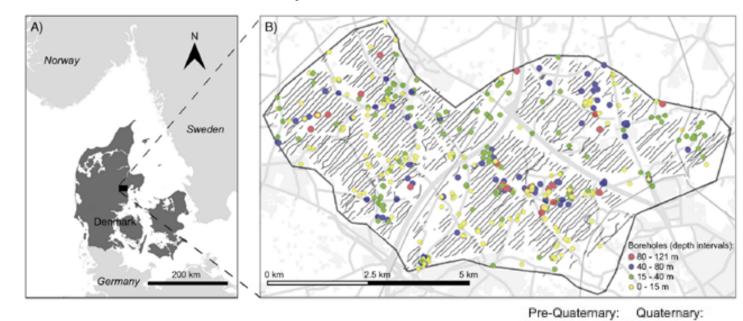
- Vertical Magnetic Dipole
- Propagation with Time
- Effects of Background Conductivity
- Transmitters and receivers
- Decay Curves
- Case History: Groundwater, Minerals, Hydrocarbons
- Horizontal magnetic Dipole

Case History: Kasted

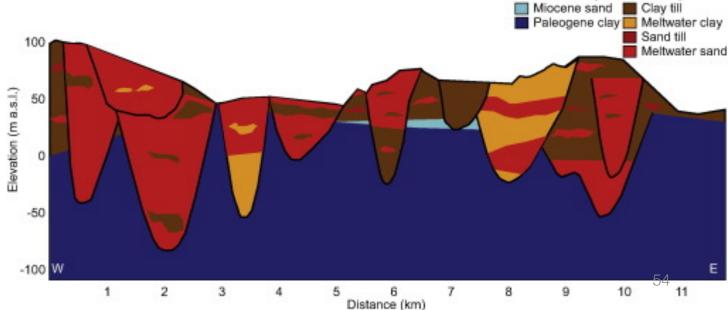
Vilhelmsen et al. (2016)

Setup

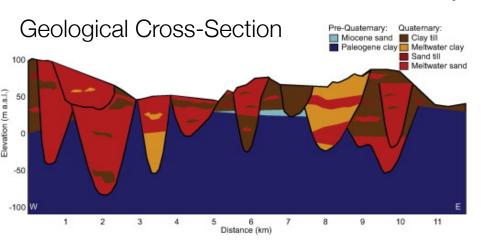
- A) Survey Area: Kasted, Demark
- B) Borehole locations



Local Geology: W-E cross-section



Properties



Geological Units	Resistivity (Ωm)
Palaeogene Clay	1-10
Clay Till	25-60
Sand Till	>50
Meltwater Sand and Gravel	>60
Glaciolacustrine Clay	10-40
Miocene Silt and Sand	>40
Miocene Clay	10-40
Sand	>40
Clay	1-60

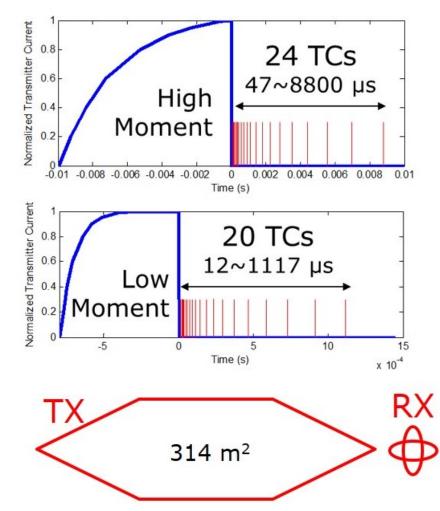
- Buried valleys with clays beneath
- Infill (water-bearing): coarse sand and gravel
- Clays are conductive (1-40 Ωm)
- Water-bearing sands and gravels are more resistive (>40 Ωm)

SkyTEM System

Instruments Transmitter Receiver

Survey

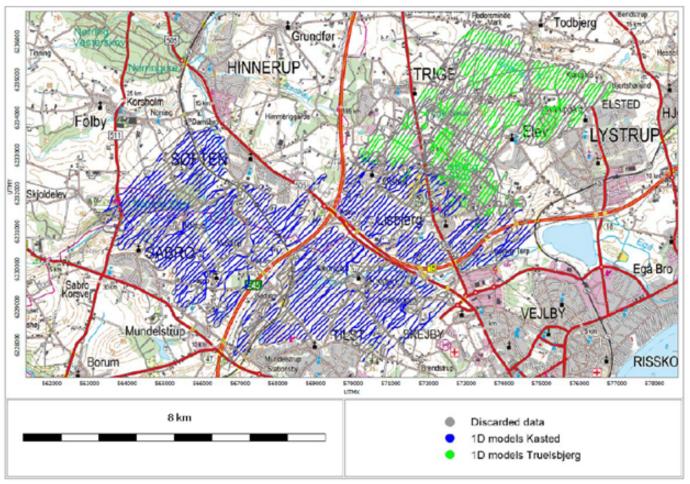
System Configuration



- Low moment (LM) used to image near surface structures
- High moment (HM) used to image deeper structures

Data

Blue: data used for Kasted study



- 333 line km of data, 100 m line-spacing
- Data points with strong coupling to cultural noise were removed (~30%)

Processing (inversion)

Spatially constrained 1D inversion → quasi-3D approach

1000

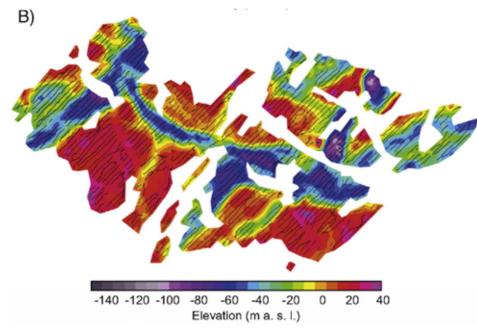
9,500 soundings were inverted using 25 layers

Depth slice 5 m above sea-level

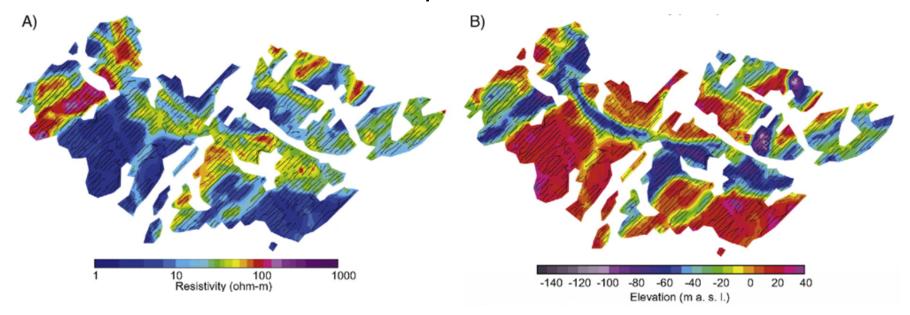
A)

Resistivity (ohm-m)

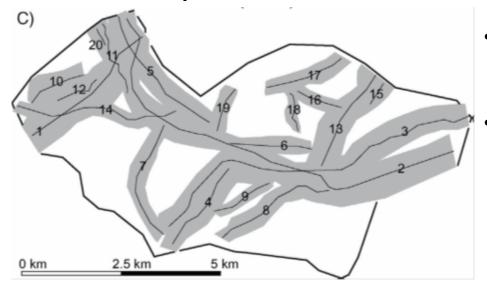
Approximate depth to the top of Paleogene clay layer



Interpretation

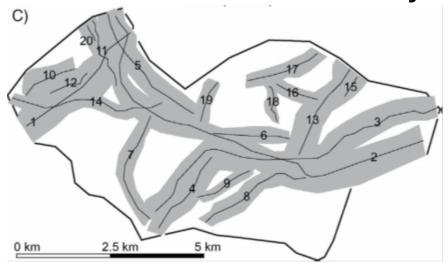


Delineation of valley structures

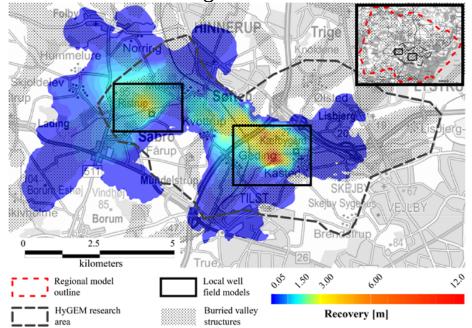


- Inversion results used to construct geological model.
- Delineated 20 buried and cross-cutting valley structures.

Synthesis



MODFLOW-USG groundwater model



- 3D geologic model incorporated into MODFLOW-USG groundwater modeling tool
- Extracted water from 2 wells.
- Downdraw between the two wells correlated with the resistive valley structures

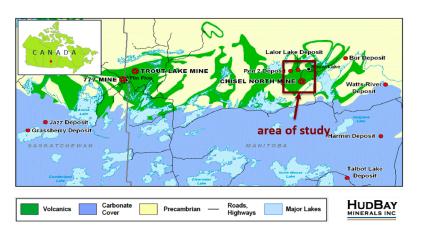
Case History: HeliSAM at Lalore

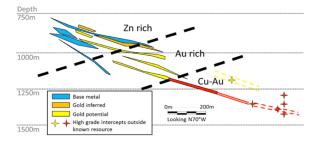
Yang & Oldenburg, 2016

Setup

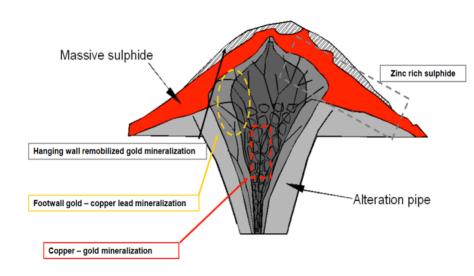
Geological framework

- Zinc-rich massive sulfides (Cap)
- Cu-Au sulfides: (stringers) within pipe
- Disseminated sulfides around deposit





Typical cross-section

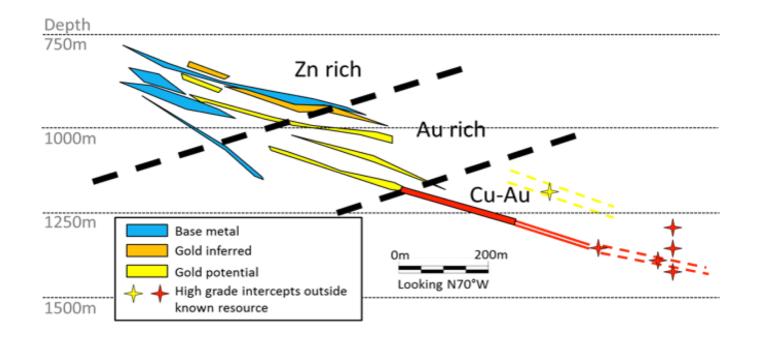


Goal:

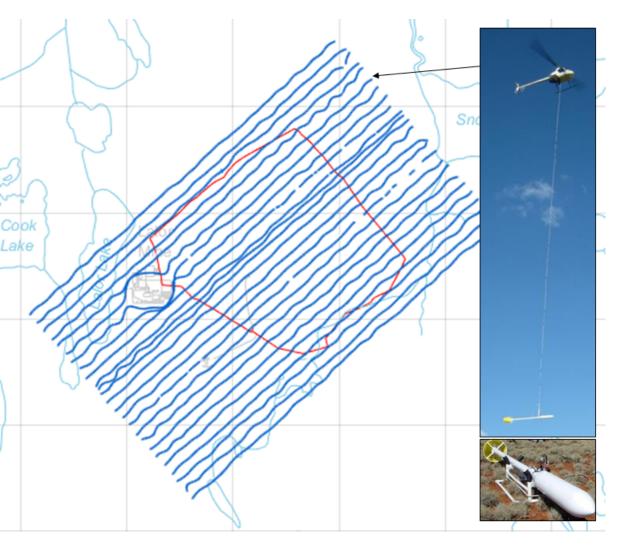
- Find deposits
- TDEM to find deeper off-hole targets

Properties

Rocks/minerals	Resistivity
volcanics	~1000 Ωm
sulfides	~ 1 Ωm



Survey: HeliSAM



Transmitter: (Red)

Ground loop (~2km)

Waveform: 7.5 Hz, 50%

Ramp turn-off 0.4ms

Receiver:

Cesium Vapor Mag

• 16 Time Ch: 0.42-27 ms

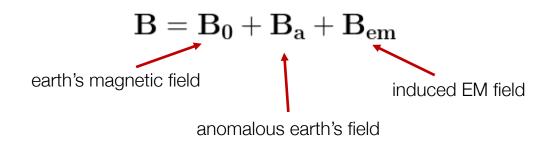
Flight lines: (Blue)

100 m spacing,

Data every 5 m

Data

Measure total field



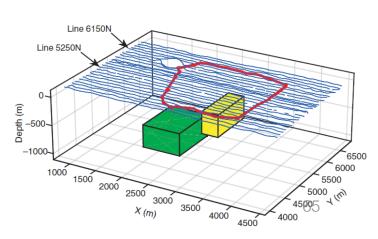
Project secondary fields onto $\hat{\mathbf{B}}_0$

$$\Delta |\mathbf{B}| = |\mathbf{B_0} + \mathbf{B_a} + \mathbf{B_{em}}| - |\mathbf{B_0}|$$
$$\approx (\mathbf{B_a} + \mathbf{B_{em}}) \cdot \hat{\mathbf{B}_0}$$

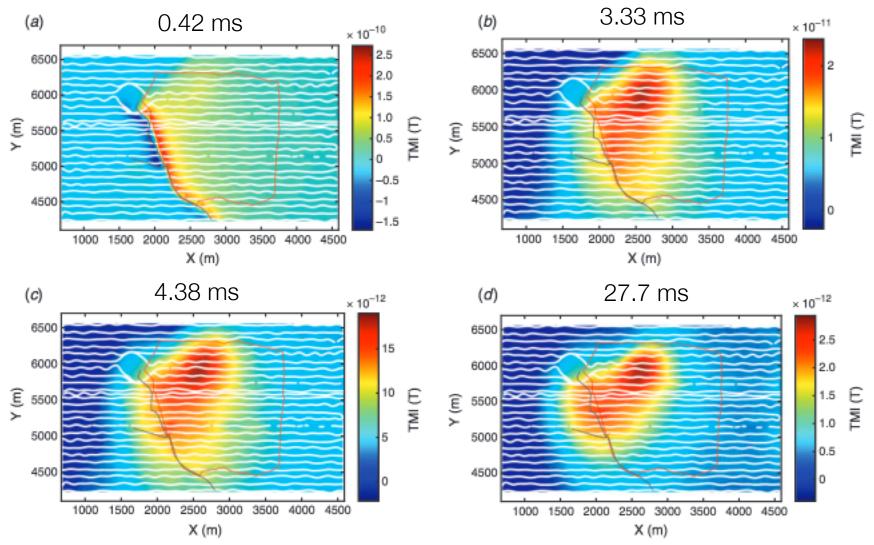
- Change polarity on TX
- Subtract to obtain HeliSAM data

$$\Delta |\mathbf{B}| \approx \mathbf{B_{em}} \cdot \hat{\mathbf{B}}_0$$



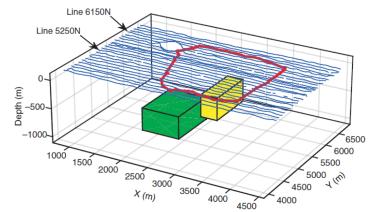


Data



Processing: Inversion of Late Time Data

- Discard early time data
 - Contaminated by infrastructure
- Invert Time Ch 8-16 (4.44-28 ms)
- Inversion needs a "warm start"
 - Maxwell used to generate 2 prisms



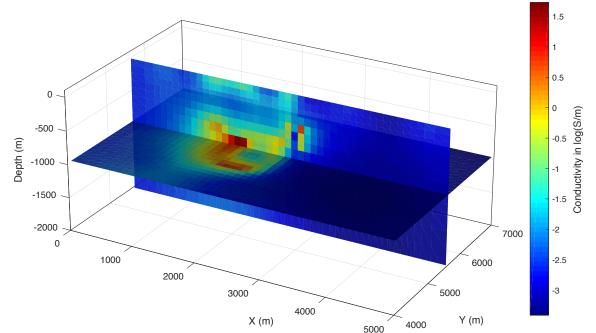
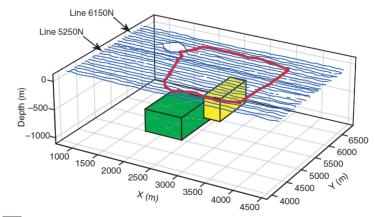
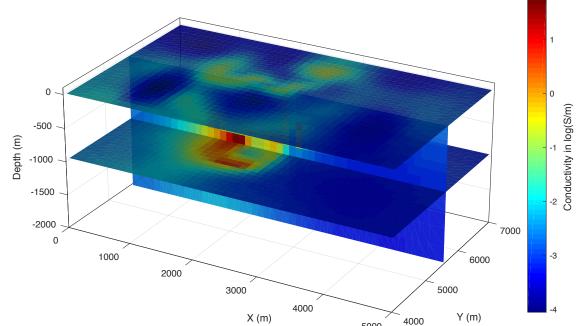


Image deep structure

Processing: Inversion of Late Time Data

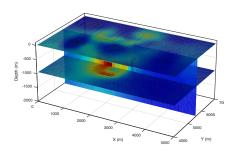
- Discard early time data
 - Contaminated by infrastructure
- Invert Time Ch 8-16 (4.44-28 ms)
- Inversion needs a "warm start"
 - Maxwell used to generate 2 prisms





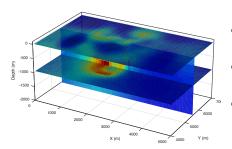
- Image deep structure
- See near surface conductive features

Processing: Inversion of Early Time Data

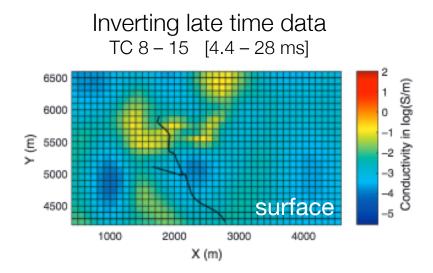


- Late-time inversion sees deep structure
- Some conductive features near surface
- What is the effect of throwing away the early time data?

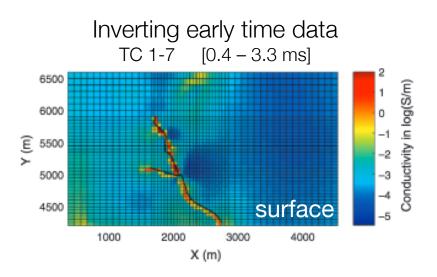
Processing: Inversion of Early Time Data



- Late-time inversion sees deep structure
- Some conductive features near surface
- What is the effect of throwing away the early time data?



 erroneous near surface structure

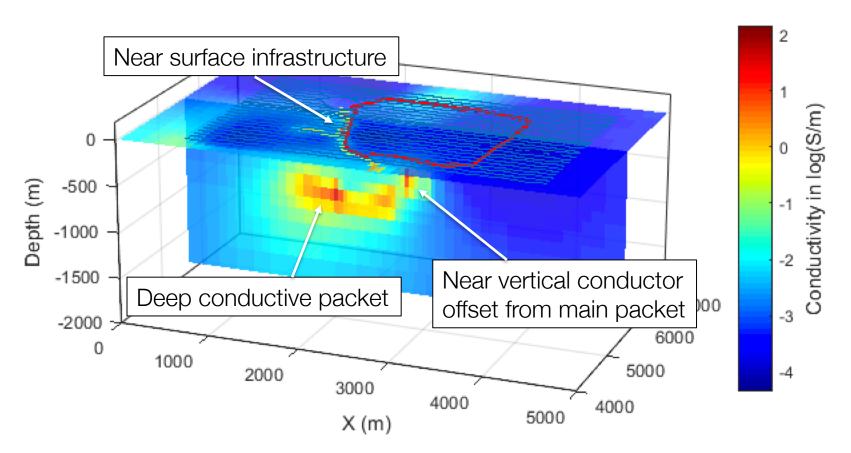


 information about infrastructure and near-surface conductivity

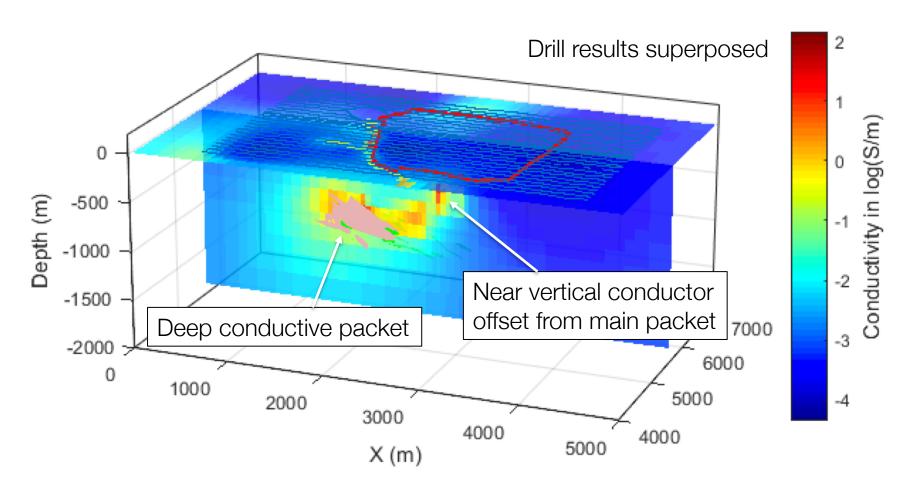
Processing: Inversion of all time channels

Starting and reference model:

- High conductivity from early time inversion
- Two conductive blocks

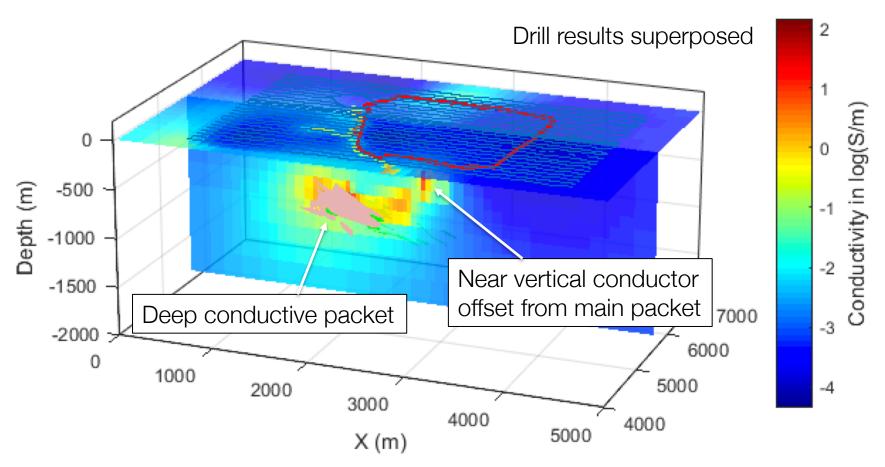


Synthesis



- Imaged main known conductive bodies
- Second conductor: recently drilled and contained sulfides (argillite)

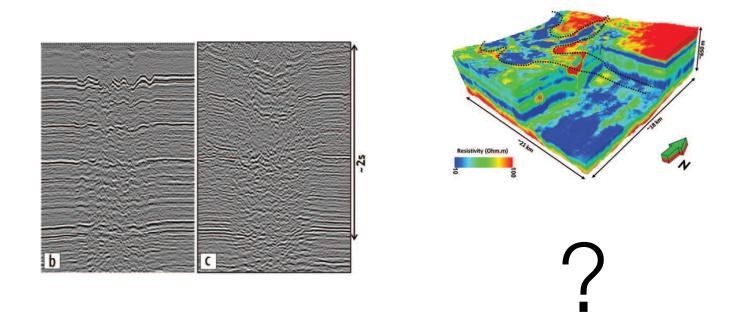
Takeaways



- Early time data:
 - constrain near surface structure infrastructure
 - Improved inversion for late time
- Warm start of inversion was necessary for deep conductors

Case History: Wadi Sahba

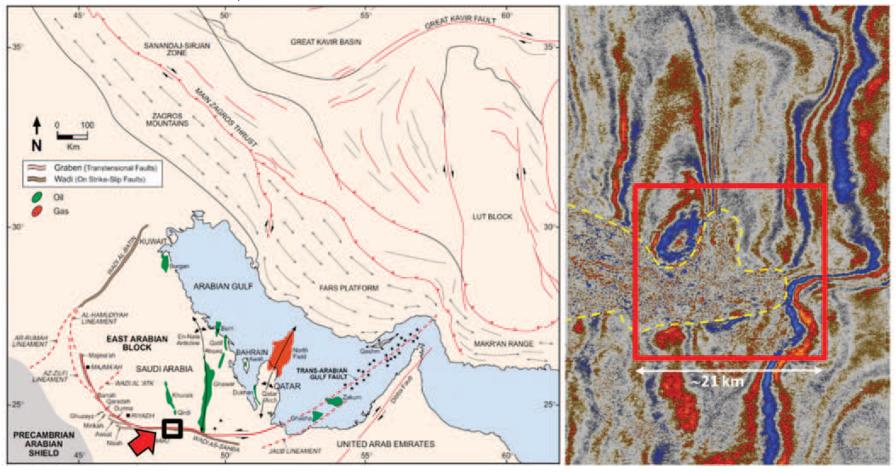
Colombo et al. 2016



Setup

Location of Wadi area, Saudi Arabia

Seismic slice

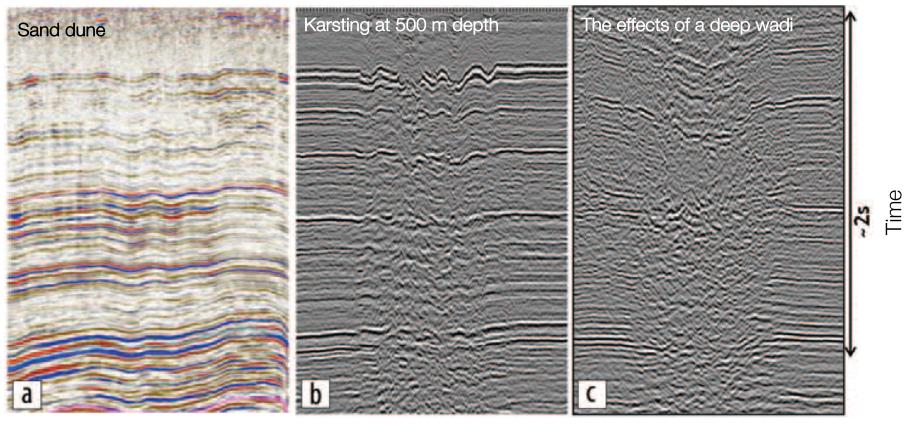


 Oil and gas exploration in the Middle East: Focus is now stratigraphic traps and low relief structures

75

Challenges for processing seismic data

Example seismic sections



Distance

Strong effects from near surface anomalies even after static corrections

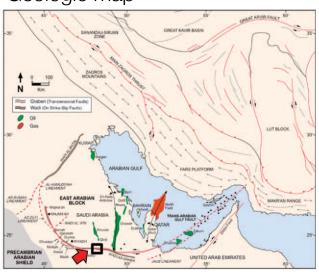
Properties

P-velocity and conductivity:

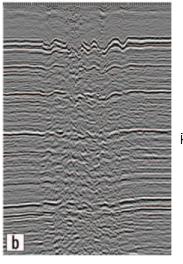
 $v_p = g(\phi)$ v_p : P-velocity $\sigma = f(\phi)$ ϕ : porosity

- Poor seismic data:
 - strong scattering effects probably caused by flower faults
 - velocity inversions (high to low v_p)
- From previous multi-physics analyses:
 - strong structural similarity between the inverted resistivity, and the existing seismic results

Geologic map

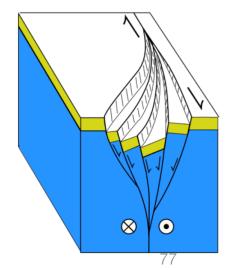


Seismic section



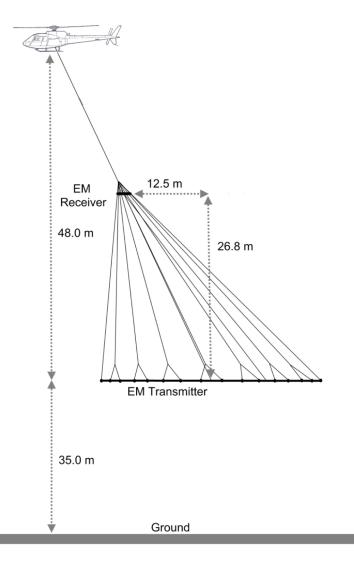
Distance

Flower faults

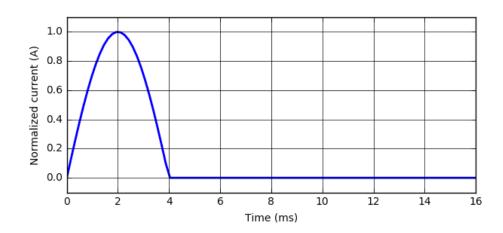


Survey

HELITEM

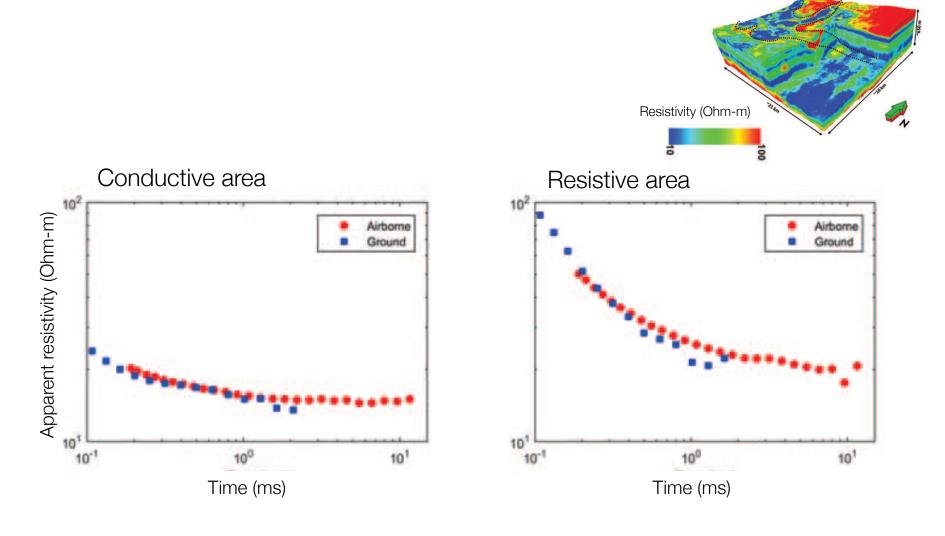


System Configuration

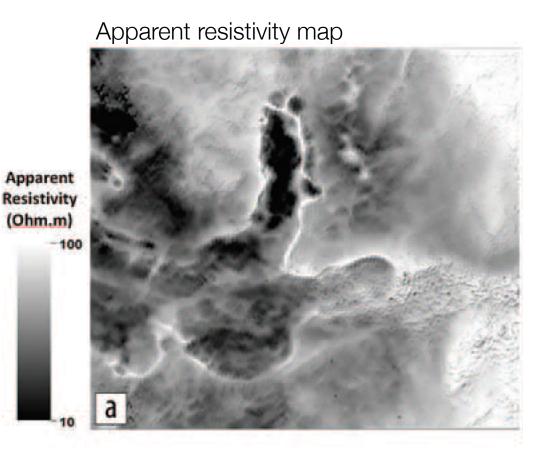


- Peak Tx current: 1200 A
- Dipole moment: 1.7x10⁶ A-m²
- Stacked TEM curve spacing: ~2.7 m
- Total soundings: ~1.6 million

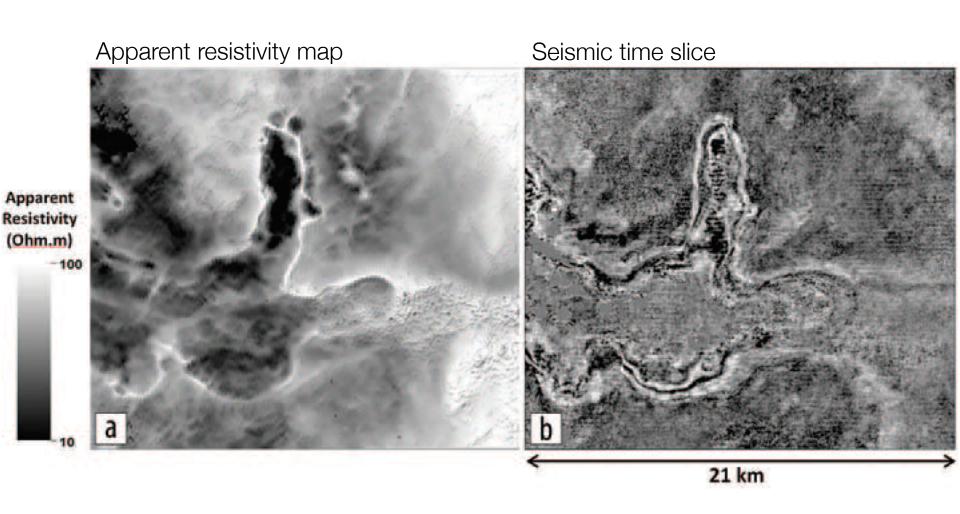
Comparisons: airborne and ground EM



EM data

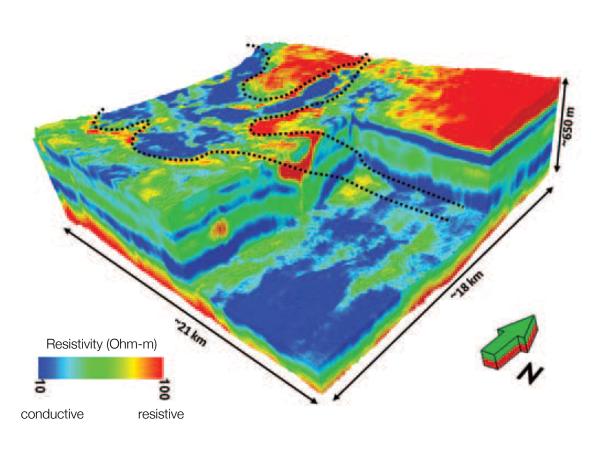


Comparison: EM and Seismic data



Processing: EM inversion

Conductivity model



- 1D inversion for each sounding location
- Lateral constraint is used

Cooperative inversion: Seismic + EM

How EM can help seismic tomography inversion?

Velocity (v_p): high to low (significant challenge)

Conductivity (σ): high to low

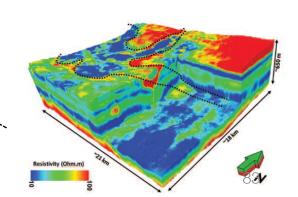
$$v_p = g(\phi)$$
 ϕ : porosity $\sigma = f(\phi)$

 \mathbf{m}_s : Slowness

 \mathbf{m}_{σ} : Conductivity

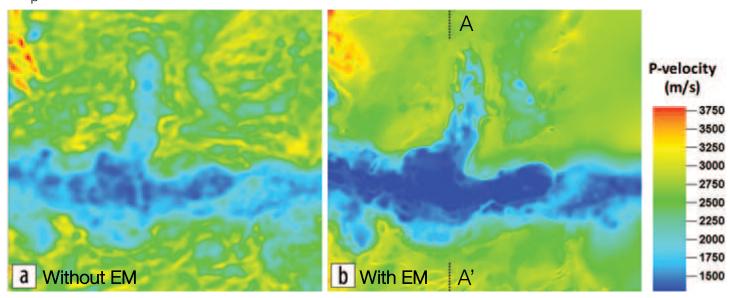
$$\psi(\mathbf{m}_{s}, \mathbf{m}_{\sigma}) = \psi_{m}(\mathbf{m}_{s}) + \frac{1}{\lambda_{1}} \psi_{d}(\mathbf{m}_{s}) + \frac{1}{\lambda_{2}} \psi_{x}(\mathbf{m}_{s}, \mathbf{m}_{\sigma}) + \frac{1}{\lambda_{3}} \psi_{rp}(\mathbf{m}_{s}, \mathbf{m}_{\sigma})$$

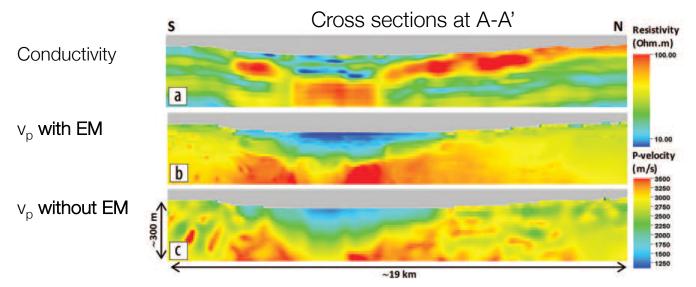
$$\|
abla \mathbf{m_s} imes
abla \mathbf{m}_{\sigma}\|_2^2$$
 Gallardo and Meju, 2004



Cooperative inversion: Seismic + EM

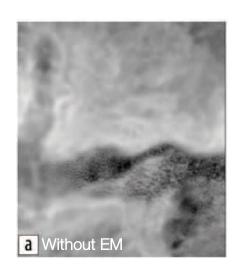
V_p depth slices at 340 m below sea level

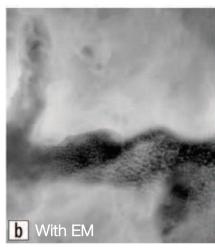




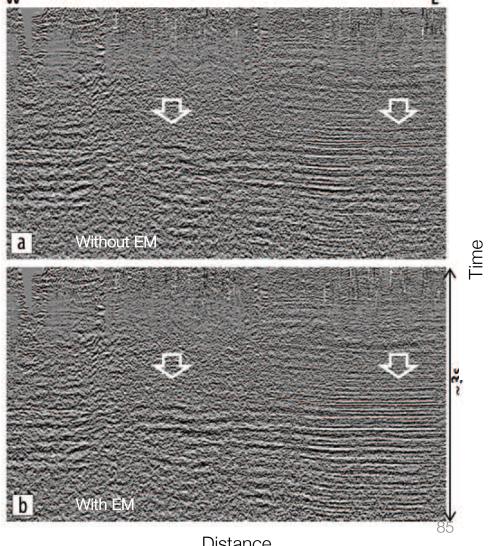
Static correction

Estimated statics on plan map





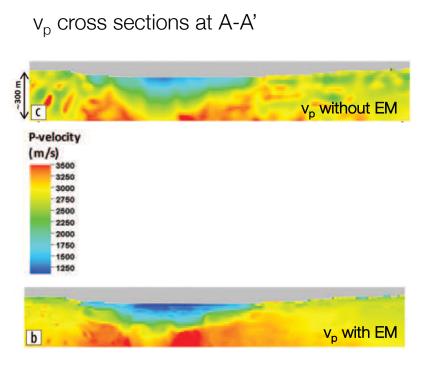
Static corrected sections

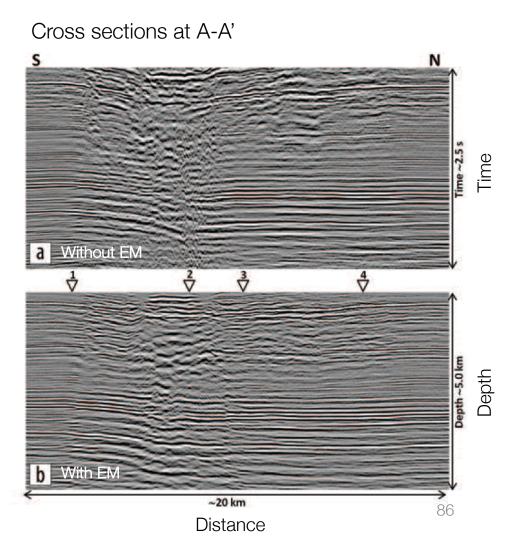


Distance

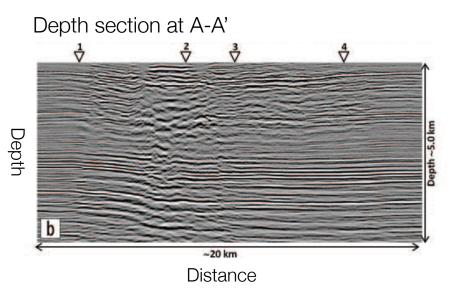
Pre-stack depth migration

• Impact of the improved v_p model to a pre-stack depth migration:

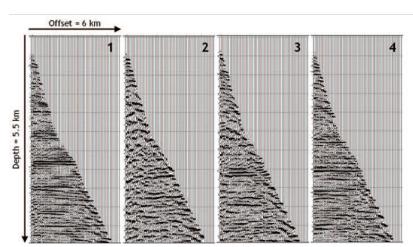




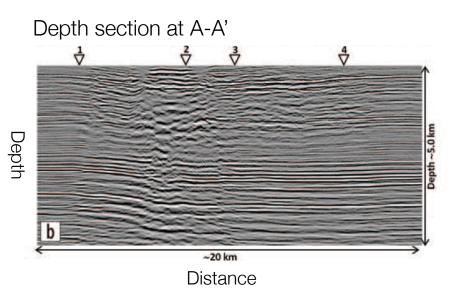
Interpretation and Synthesis



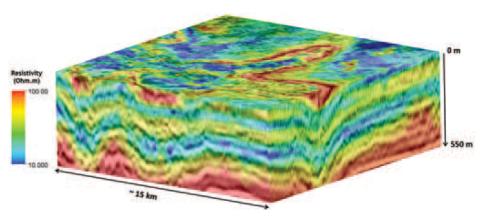
Common image gathers



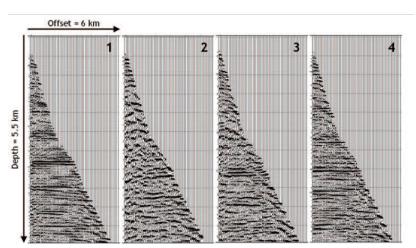
Interpretation and Synthesis



3D prestack depth migration co-rendered with EM

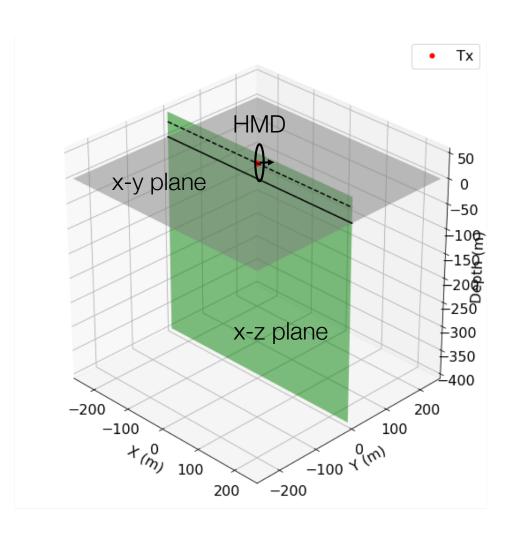


Common image gathers

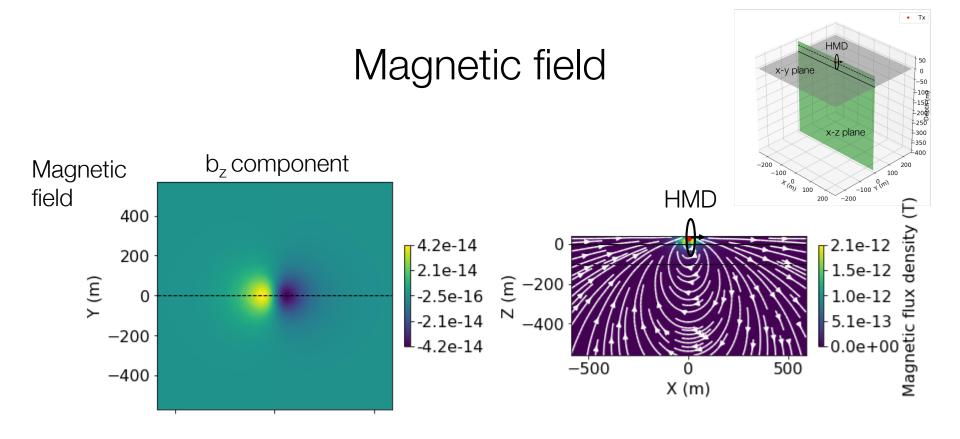


- High resolution near surface conductivity from EM improves velocity model
- Helps seismic imaging:
 - Static correction
 - Pre-stack depth migration

Horizontal Magnetic Dipole (HMD)



- Same physical principles as VMD, but different source geometry
- Focus on magnetic field and currents
- Different coupling for conductive targets

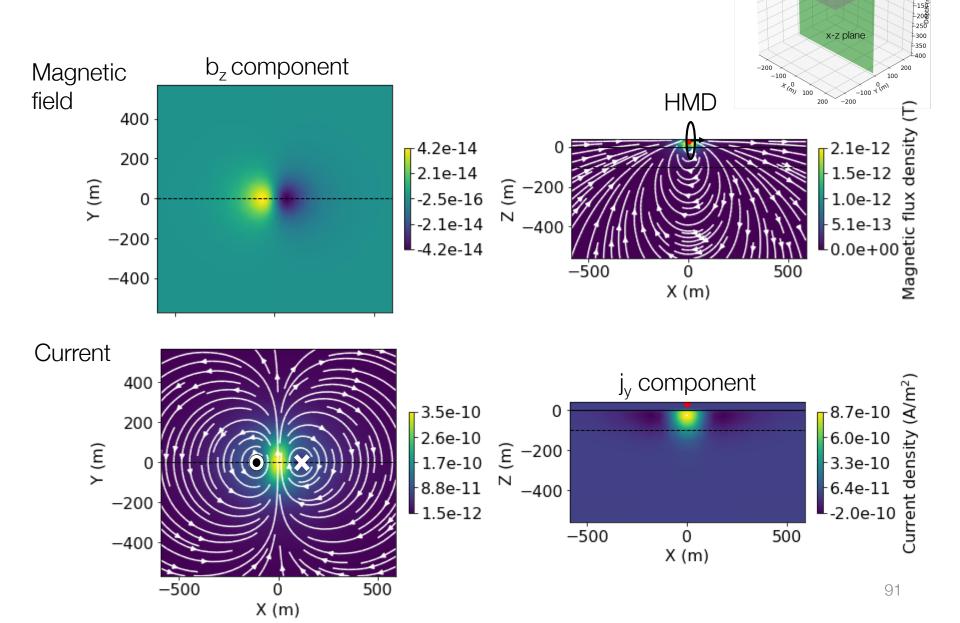


What currents can generate these magnetic fields?

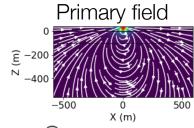
Magnetic field and Current

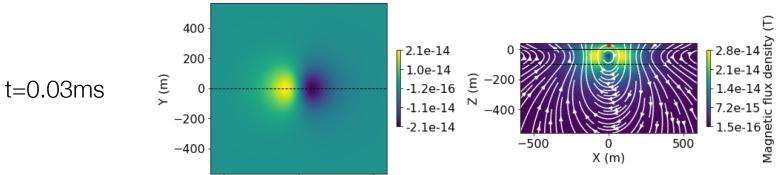
HMD

x-y plane

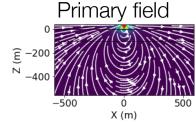


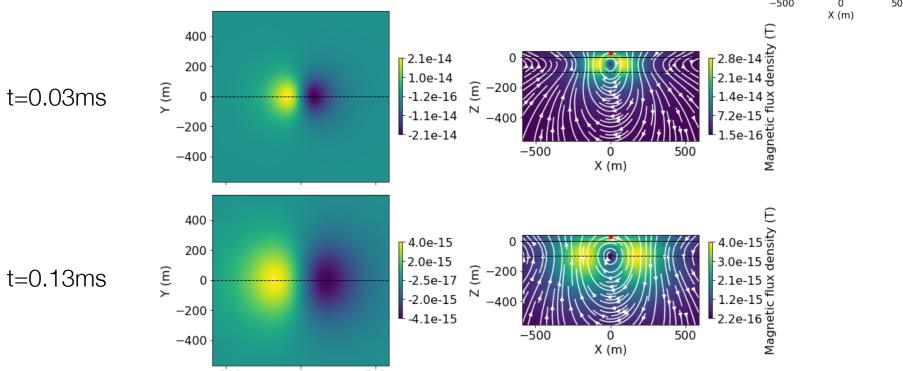
Magnetic field in time



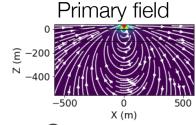


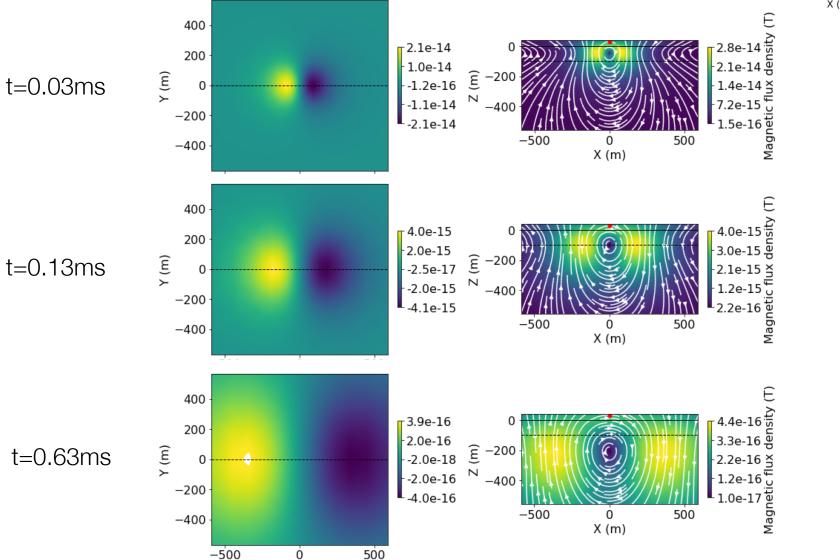
Magnetic field in time





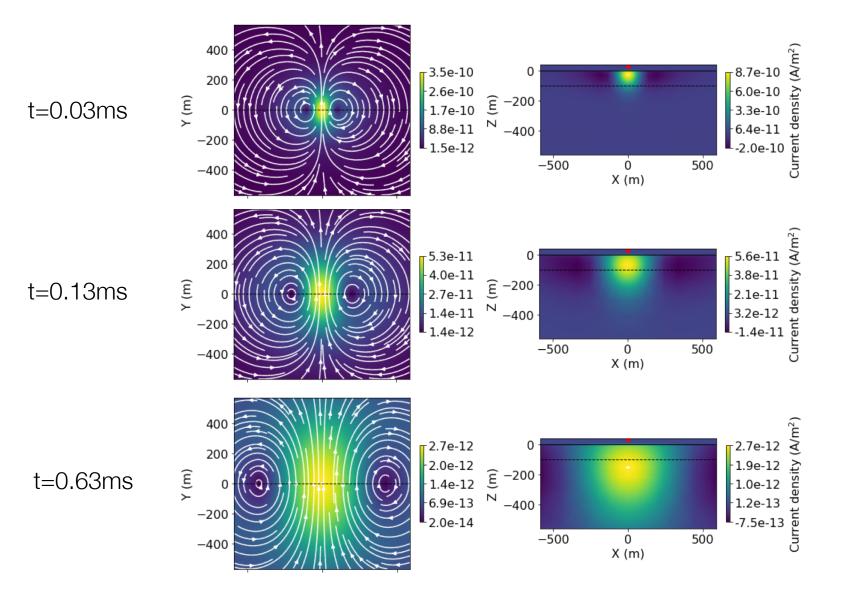
Magnetic field in time





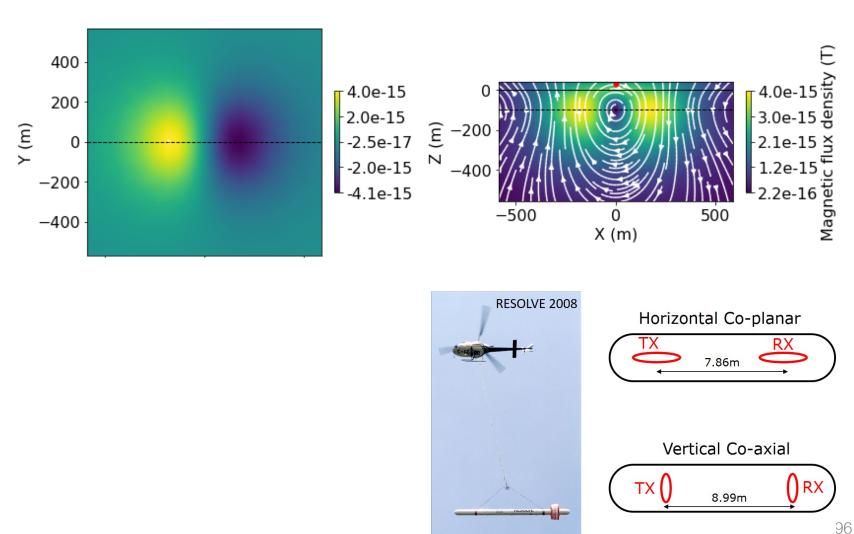
X (m)

Current in time



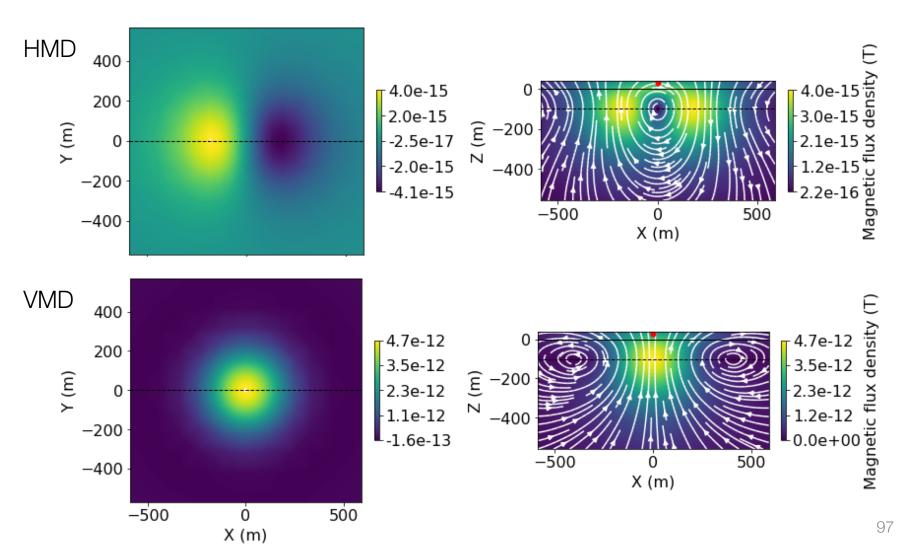
Data: where and what to measure?

Magnetic field at 0.63 ms



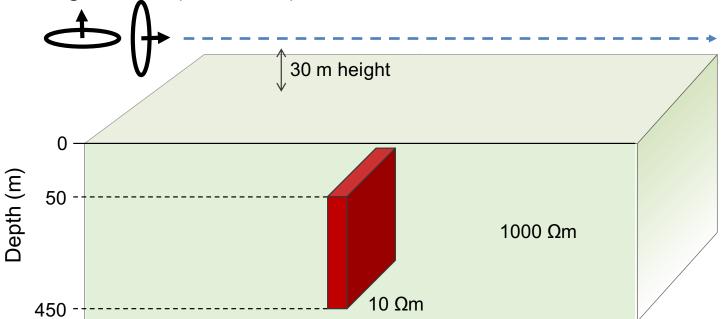
How different from VMD?

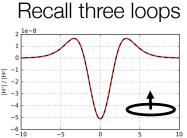
Magnetic field at 0.63 ms



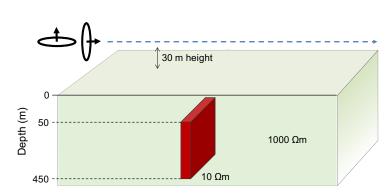
Coupling to a vertical plate

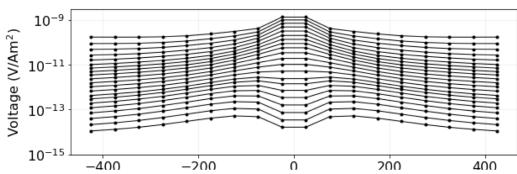
- Assume coincident loop case (Tx and Rx are coincident)
 - Both VMD and HMD
- Consider a profile line data (multiple time channels)
- Imagine how profile response will look like?



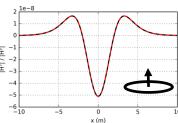


VMD vs. HMD: profile line data

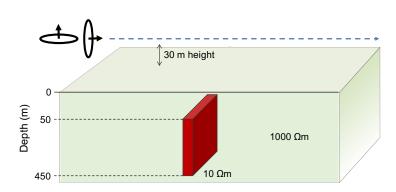


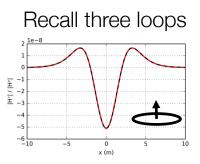


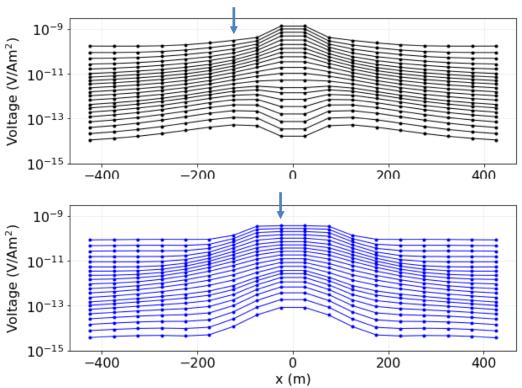




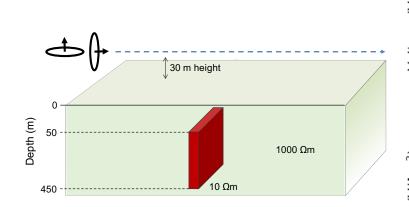
VMD vs. HMD: profile line data

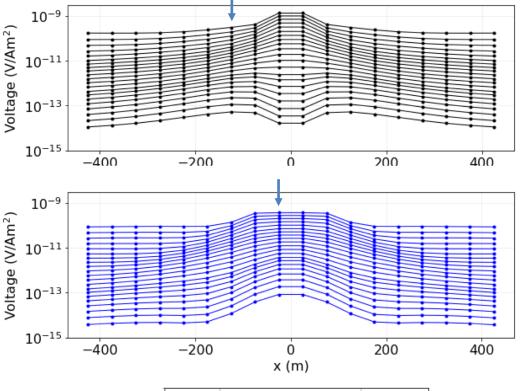




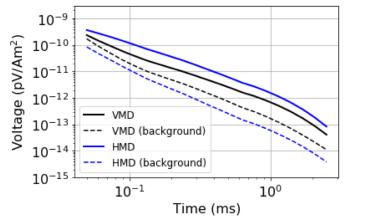


VMD vs. HMD: time decays





HMD is better coupled to the vertical conductor



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End of inductive source (TDEM)

Setup

Time Domain EM

- Vertical Magnetic Dipole
- Propagation with Time
- Effects of Background Conductivity
- Transmitters and receivers
- Decay Curves
- Case History: Groundwater, Minerals, Hydrocarbons
- Horizontal magnetic Dipole

Next up: Frequency domain EM

