

NOKIA




CONTAINER**lab**

Running networking labs with Docker UX

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NANOG'83

 @ntdvps
@karimtw_

How do we run networking labs today?

Network emulation SW



- + Purpose built & proven
- + Free versions available
- + UI
- VM-centric
weak containers support
- Heavy and not open*
- UI

VM orchestrators



- + Common in Med/Large Ent
- Integration effort
- VM centric
- Clean datapath is challenging
- No UI, no CLI

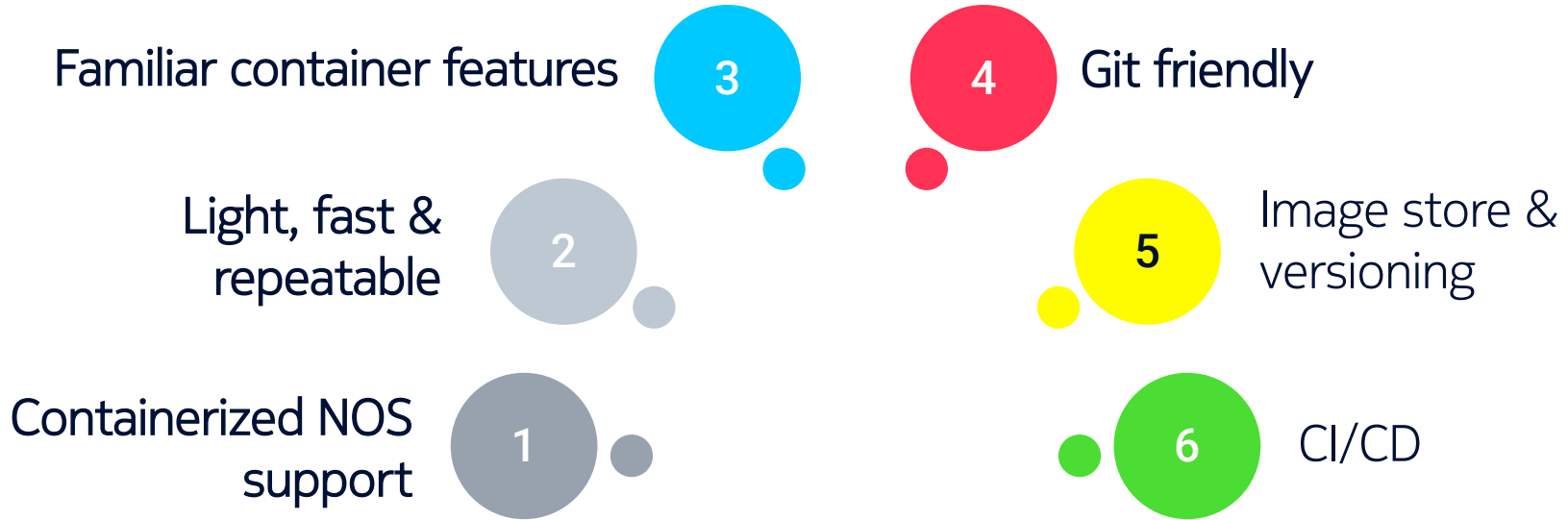
Custom automation solutions



- + Tailored for you
- Tailored for only you

Benefits of using container-based labs

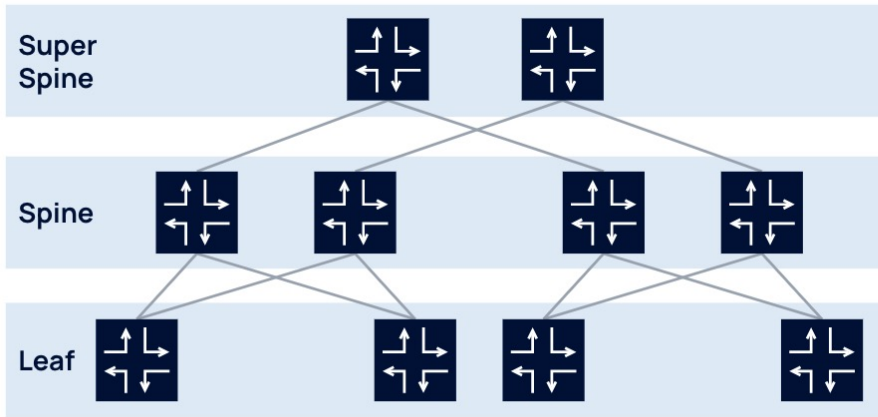
What do we gain by moving away from VMs?



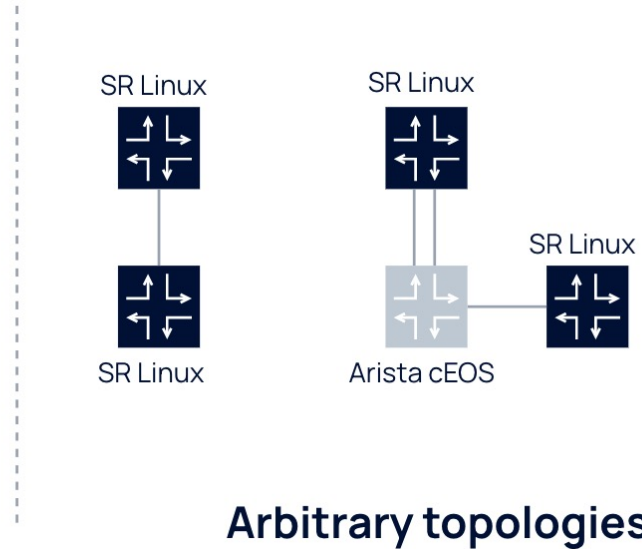
Containerlab

Role & purpose

containerlab provides a framework and CLI for setting up networking labs with container-based nodes.



3/5-stage CLOS topologies



Arbitrary topologies



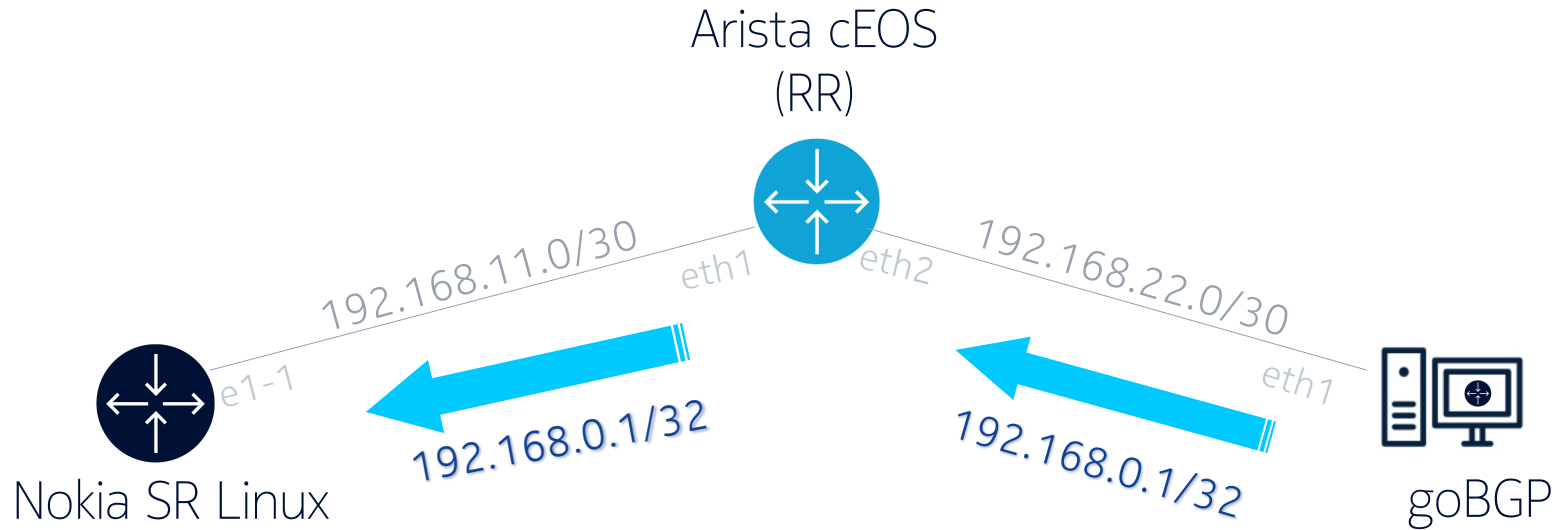
Containerlab Basics

- 1 Install containerlab
- 2 Getting to know topology definition syntax
- 3 Deploy and manage a lab
- 4 Access & configure lab nodes
- 5 Configuration persistency
- 6 Packaging and sharing

Containerlab

Learn by doing

Creating **Nokia SR Linux** + **Arista cEOS** BGP route-reflection lab



Installation

```
# download and install the latest release
```

```
bash -c "$(curl -sL https://get-clab.srlinux.dev)"
```

```
Setting up containerlab (0.16.2) ...
```

```
          _  _      _  _      _  _      _  _
  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _  _
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```

```
version: 0.16.2
commit: 3087f30
date: 2021-08-11T06:22:45Z
source: https://github.com/srl-labs/containerlab
rel. notes: https://containerlab.srlinux.dev/rn/0.16/#0162
```

Supported platforms

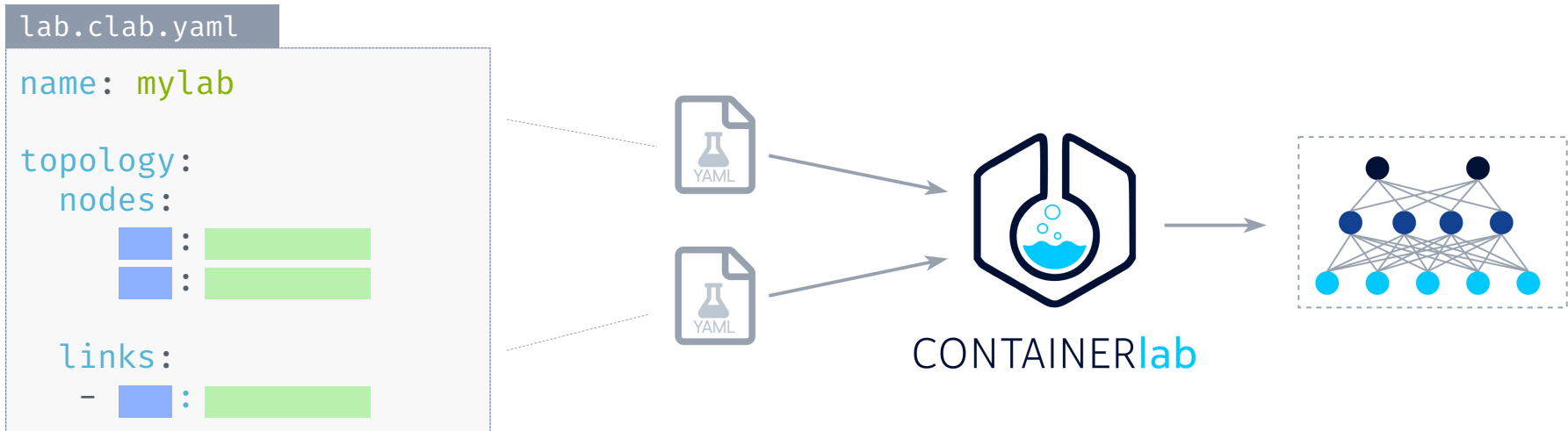


Containerlab

Getting to know topology definition syntax

IaC approach

Lab topology is defined in YAML



[topology definition file](#)

Writing topology definition

Basic nodes configuration

rr.clab.yml

```
name: rr
```

```
topology:
```

```
  nodes:
```

```
    srlinux:
```

```
      kind: srl
```

```
      image: ghcr.io/nokia/srlinux
```

1

Node definition container.
Container name will be the node name.
[Read more](#)

2

Kinds define the flavour of the node, it says if the node is a specific containerized Network OS or something else.
[Read more](#)

3

Image specifies container image to use for this node.
[Read more](#)



[topology definition file](#)

Writing topology definition

Add nodes

topology definition

```
name: rr

topology:
  nodes:
    srlinux:
      kind: srl
      image: ghcr.io/nokia/srlinux
    ceos:
      kind: ceos
      image: ceos:4.25.0F
    gobgp:
      kind: linux
      image: ghcr.io/hellt/network-
multitool
```

logical view

ceos



srlinux



gobgp

Writing topology definition

Add links

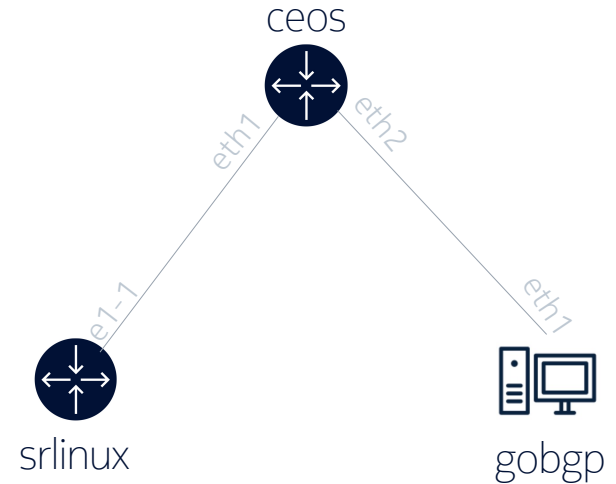
topology definition

```
name: rr

topology:
  nodes:
    srlinux:
      kind:
      image:
    ceos:
      kind:
      image:
    gobgp:
      kind:
      image:
  links:
    - endpoints: ["srlinux:e1-1", "ceos:eth1"]
    - endpoints: ["ceos:eth2", "gobgp:eth1"]
```

Linux interface
name

logical view



Containerlab

Deploy

```
# executed in a directory where rr.clab.yml is present
```

```
$ containerlab deploy -t rr.clab.yml
```

#	Name	Container ID	Image	Kind	State	IPv4 Address	IPv6 Address
1	clab-rr-ceos	b58c42293c82	ceos:4.25.0F	ceos	running	172.20.20.2	2001:172:20:20::2
2	clab-rr-gobgp	0419fba1976c	ghcr.io/hellt/network-multitool	linux	running	172.20.20.3	2001:172:20:20::3
3	clab-rr-srlinux	244aa33b261c	ghcr.io/nokia/srlinux	srl	running	172.20.20.4	2001:172:20:20::4



Containerlab

Access lab nodes

#	Name	Container ID	Image	Kind	State	IPv4 Address	IPv6 Address
1	clab-rr-ceos	b58c42293c82	ceos:4.25.0F	ceos	running	172.20.20.2	2001:172:20:20::2
2	clab-rr-gobgp	0419fba1976c	ghcr.io/hellt/network-multitool	linux	running	172.20.20.3	2001:172:20:20::3
3	clab-rr-srlinux	244aa33b261c	ghcr.io/nokia/srlinux	srl	running	172.20.20.4	2001:172:20:20::4

1 exec container process

```
docker exec -it <container-name> <process-name>
```

Example:

```
1) docker exec -it clab-rr-srlinux sr_cli
```

```
2) docker exec -it clab-rr-gobgp bash
```

2 connect to SSH server

```
ssh <user>@<address>
```

Example:

```
1) ssh admin@clab-rr-ceos
```

```
2) ssh admin@172.20.20.4
```

Containerlab

Configuring nodes

CLI

Connect to the CLI and do it the old way

gNMI/JSON-RPC/Netconf

Prepare config snippets in JSON/YAML and let gnmic do its magic

Config mount

Mount config file by the path the NOS expects to read config from

3rd party cfg mgmt tools

Scrapli
Ansible
Nornir
etc...

Containerlab config engine

Templates based, embedded configuration engine

Containerlab

Saving configuration

```
# executed in a directory where rr-lab.yml is present
```

```
> containerlab save -t rr.clab.yml
```

```
INFO[0000] Parsing & checking topology file:  
rr.clab.yml
```

```
INFO[0000] saved cEOS configuration from ceos node  
to /root/nlnog21-demo/clab-rr/ceos/flash/conf-  
saved.conf
```

```
INFO[0001] saved SR Linux configuration from  
srlinux node. Output:
```

```
/system:
```

```
    Saved current running configuration as initial  
(startup) configuration  
'/etc/opt/srlinux/config.json'
```



Perform **lab-scoped**
configuration save
in a single sweep



Containerlab

Lab directory

```
~/demo/clab-rr$ tree -L 2
clab-rr
├── ansible-inventory.yml
├── ca
│   ├── root
│   └── srlinux
├── ceos
│   └── flash
├── srlinux
│   ├── config
│   └── topology.yml
```

7 directories, 2 files

Lab directory name: **clab-rr**

fixed prefix

lab name



Containerlab

Working with persistent configurations and mounted directories

topology definition

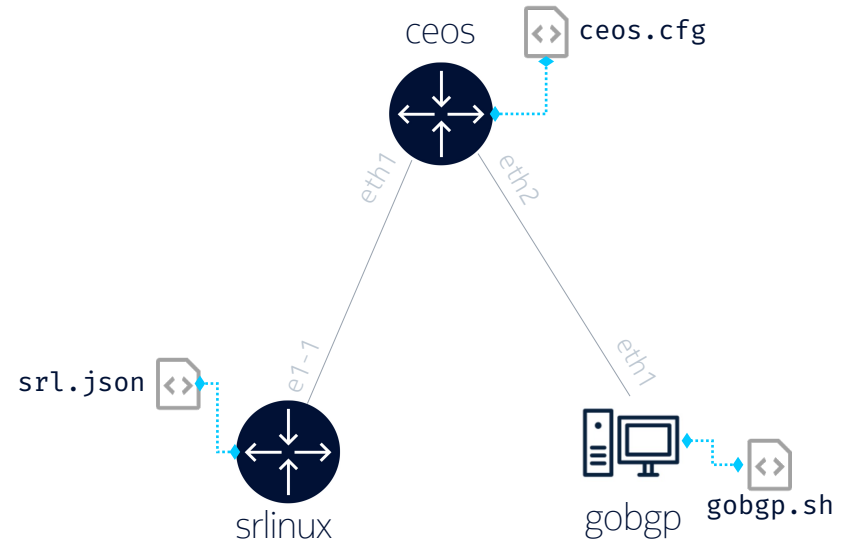
```
name: rr

topology:
  nodes:
    srlinux:
      startup-config: srl.json
    ceos:
      startup-config: ceos.cfg
    gobgp:
      binds:
        - gobgp.sh:/gobgp.sh
  links:
    - endpoints: ["srlinux:e1-1", "ceos:eth1"]
    - endpoints: ["ceos:eth2", "gobgp:eth1"]
```



[configuration artifacts](#)

logical view



Containerlab

Getting back to that Infrastructure-as-Code claim



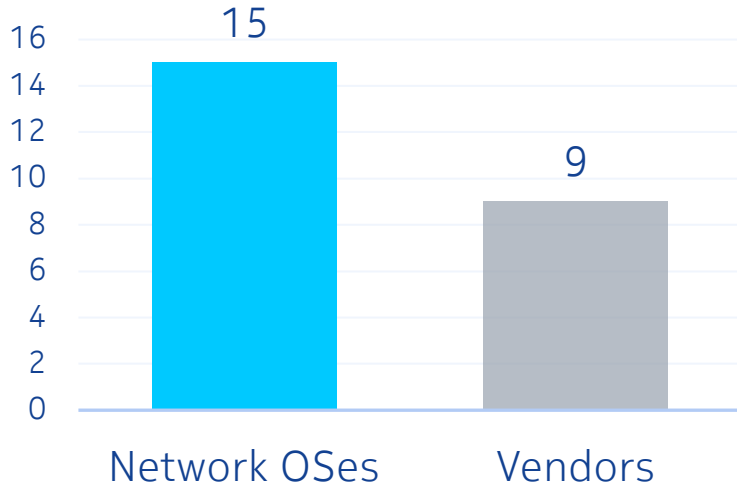
github.com/hellt/clab-nanog83-intro

From **zero** to **hero** in a minute

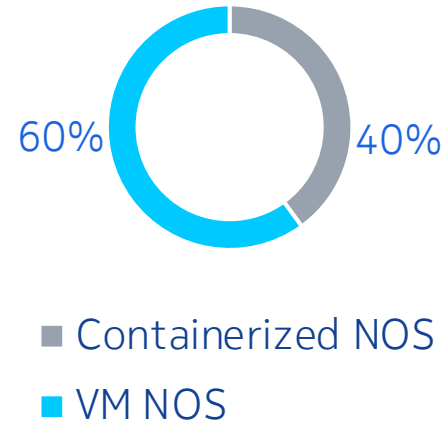
Multivendor and open

Both container- and VM-based Network OSes

Supported vendors and OSes



NOS type



NOKIA

JUNIPER
NETWORKS

ARISTA

CISCO

SONIC



MikroTik

NVIDIA


paloalto
NETWORKS

DELL


Multivendor and open

Both container- and VM-based Network OSes

NOKIA

 srl
vr-sros

JUNIPER
NETWORKS

 crpd
vr-vmx
vr-vqfx

ARISTA

 ceos
vr-veos


CISCO

vr-xrv9k
vr-csr


SONIC

 sonic-vs
frr



NVIDIA

 cvx

 **paloalto**
NETWORKS

vr-pan

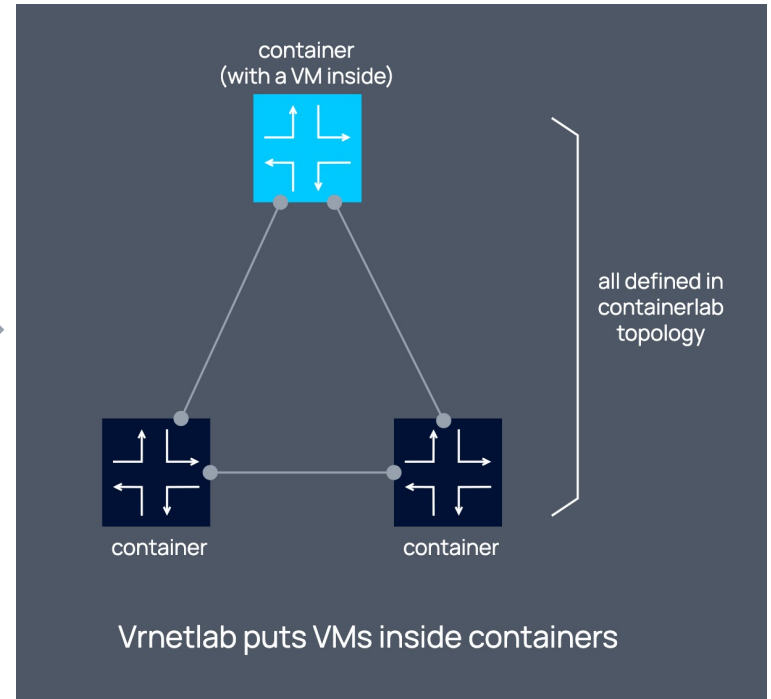
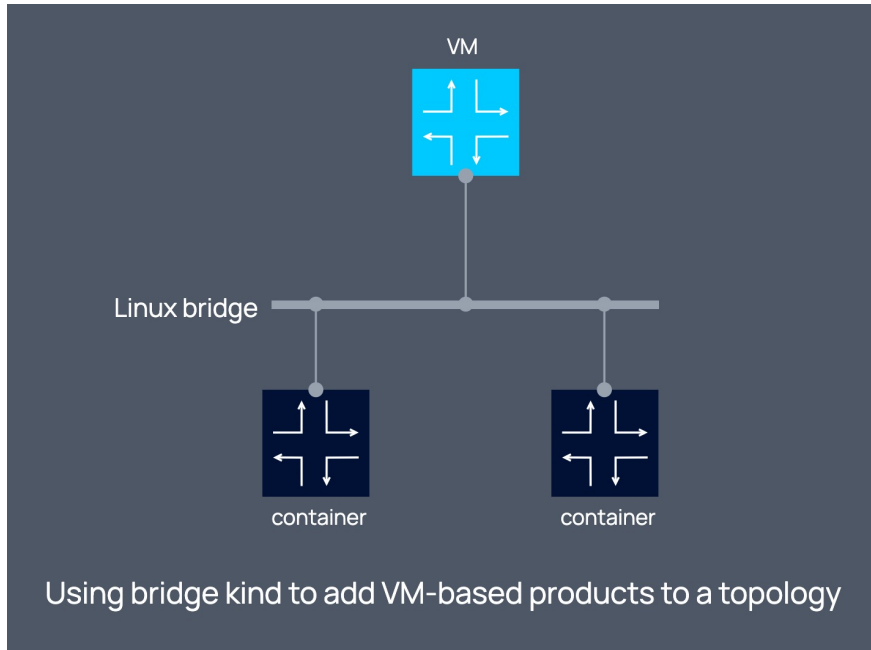


vr-ftosv

 Containerized NOS

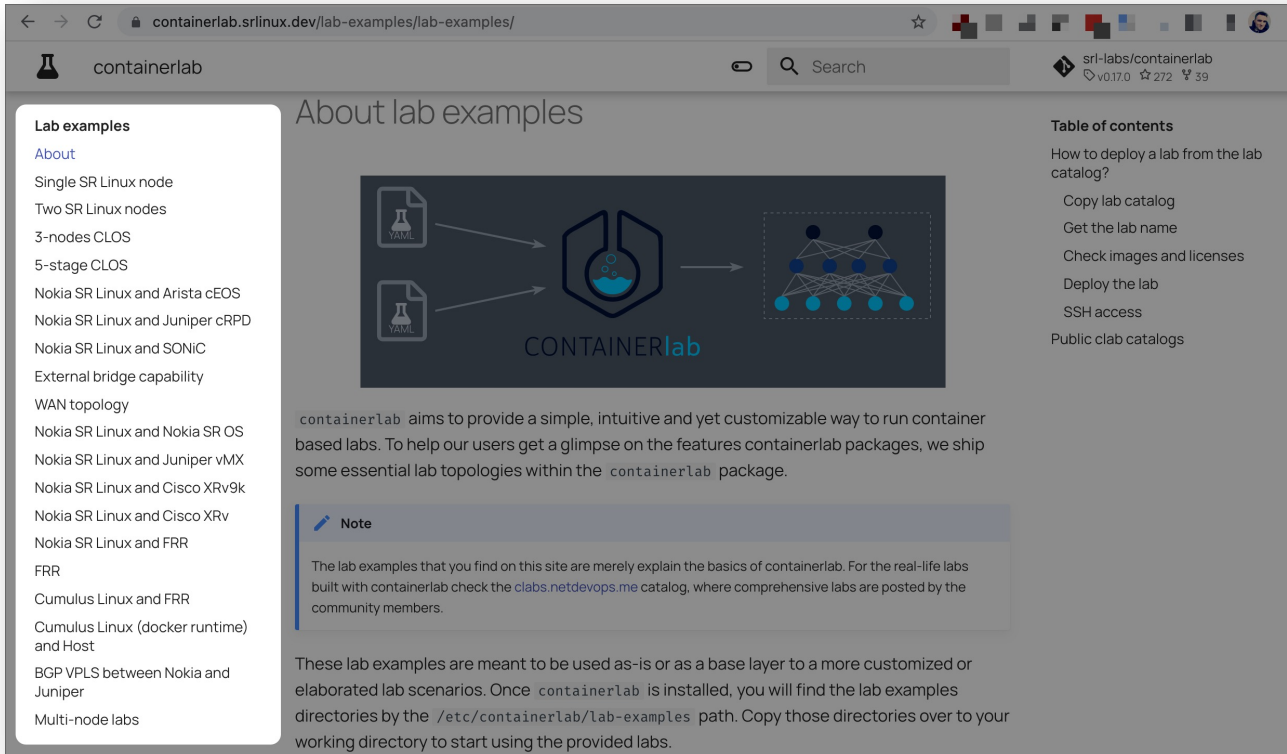
VMs in containers 🤯

Onboard VM based nodes



Multivendor and open

Basic examples to get you started with your favorite OS



The screenshot shows the website containerlab.srlinux.dev/lab-examples/lab-examples/. The page title is "About lab examples". On the left, there is a sidebar titled "Lab examples" with a list of links: About, Single SR Linux node, Two SR Linux nodes, 3-nodes CLOS, 5-stage CLOS, Nokia SR Linux and Arista cEOS, Nokia SR Linux and Juniper cRPD, Nokia SR Linux and SONIC, External bridge capability, WAN topology, Nokia SR Linux and Nokia SR OS, Nokia SR Linux and Juniper vMX, Nokia SR Linux and Cisco XRv9k, Nokia SR Linux and Cisco XRv, Nokia SR Linux and FRR, FRR, Cumulus Linux and FRR, Cumulus Linux (docker runtime) and Host, BGP VPLS between Nokia and Juniper, and Multi-node labs. The main content area features a diagram with two "YAML" files on the left, an arrow pointing to a central "CONTAINERlab" logo (a flask with a blue liquid), and another arrow pointing to a network diagram on the right. Below the diagram, the text reads: "containerlab aims to provide a simple, intuitive and yet customizable way to run container based labs. To help our users get a glimpse on the features containerlab packages, we ship some essential lab topologies within the containerlab package." A "Note" box contains the text: "The lab examples that you find on this site are merely explain the basics of containerlab. For the real-life labs built with containerlab check the clabs.netdevops.me catalog, where comprehensive labs are posted by the community members." On the right side, there is a "Table of contents" section with links: "How to deploy a lab from the lab catalog?", "Copy lab catalog", "Get the lab name", "Check images and licenses", "Deploy the lab", "SSH access", and "Public clab catalogs".

Advanced class



Node configuration options

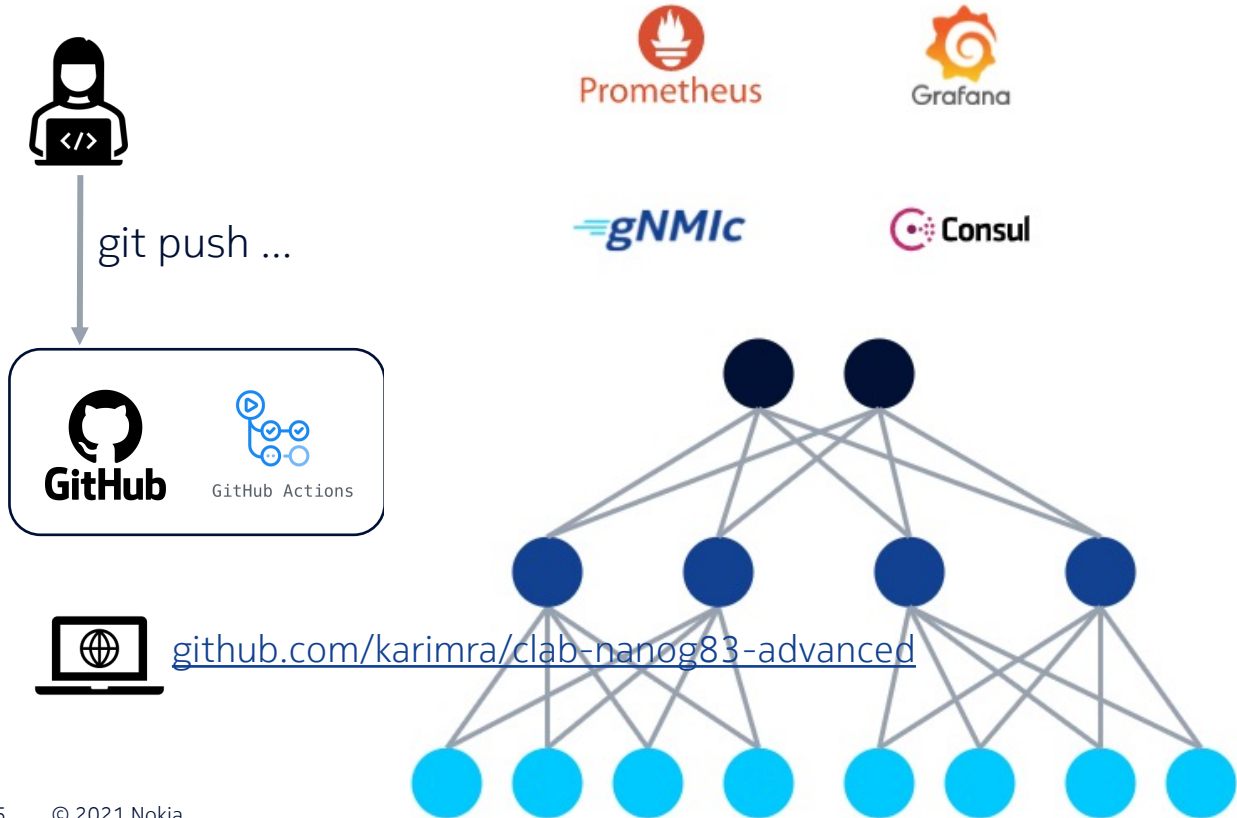
Lots of options for flexible node configurations

```
topology:
  nodes:
    node1: # node name
      kind: srl
      type: ixrd2
      image: ghcr.io/nokia/srlinux
      startup-config: /root/mylab/node1.cfg
      binds:
        - /usr/local/bin/gobgp:/root/gobgp
        - /root/files:/root/files:ro
      ports:
        - 80:8080
        - 55555:43555/udp
        - 55554:43554/tcp
      user: test
      env:
        ENV1: VAL1
      cmd: /bin/bash script.sh
      labels:
        clab: isCool
      mgmt_ipv4: 172.20.20.100
```



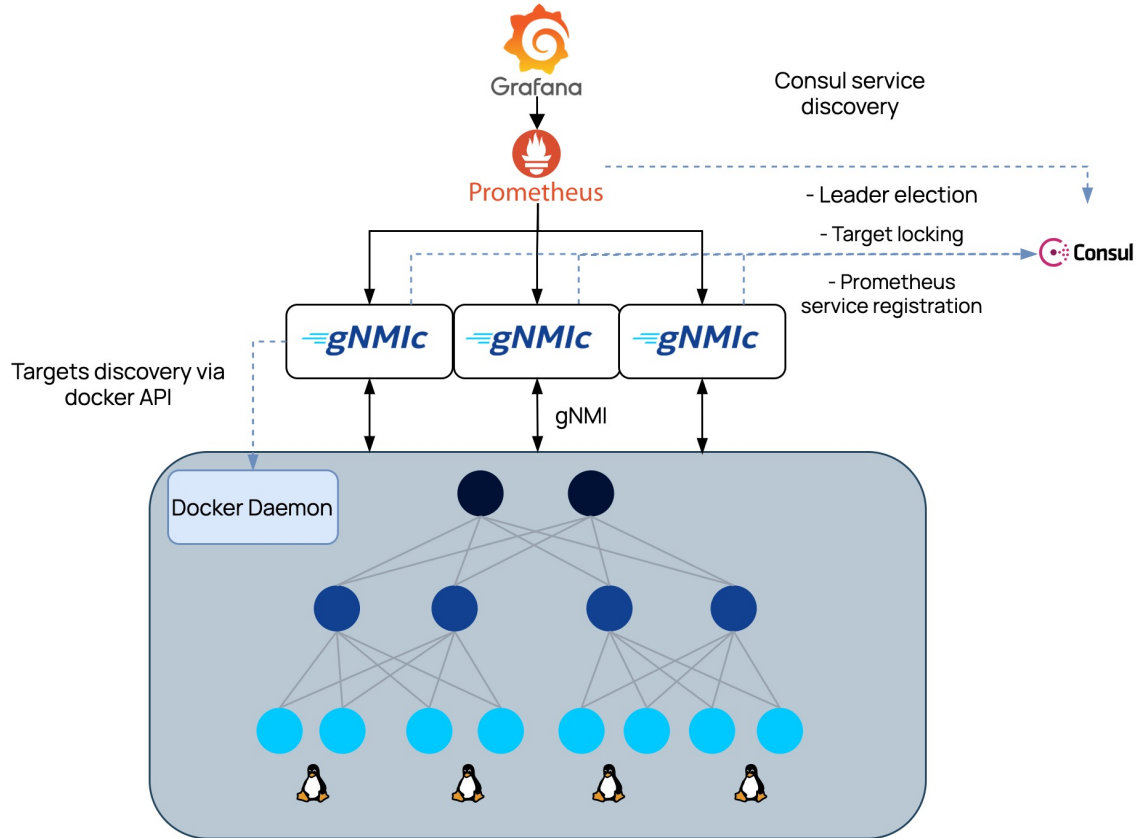
Containerlab

A bit more advanced example – streaming telemetry



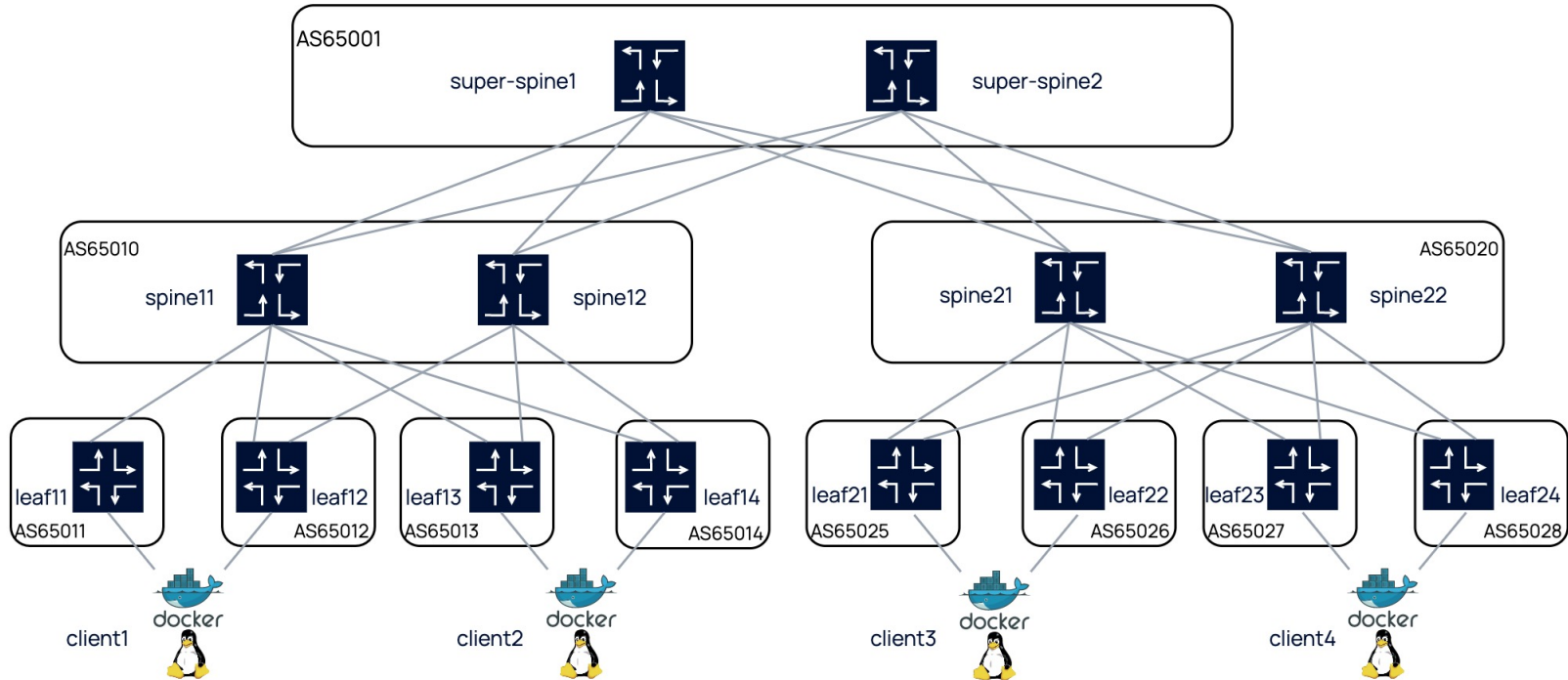
Containerlab

Advanced example - telemetry stack



Containerlab

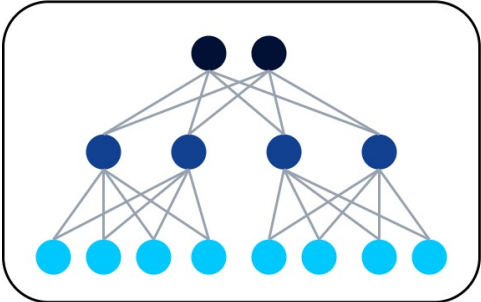
Advanced example - topology



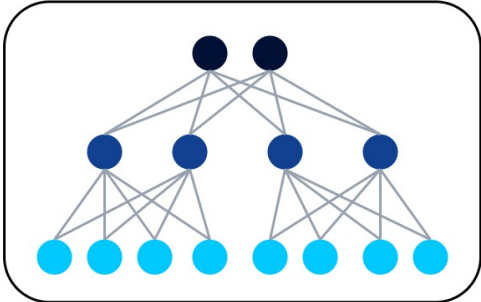
Containerlab

Multiple labs

telemetry lab

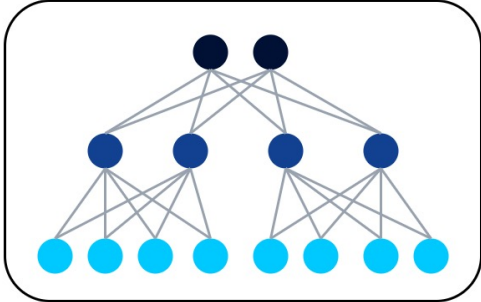


Lab1



Lab2

...



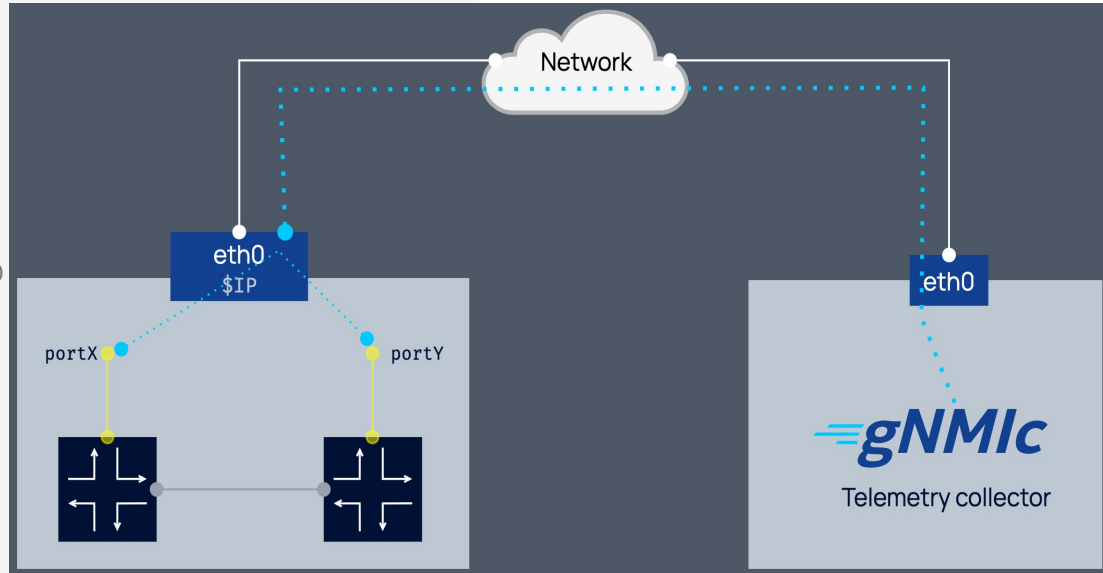
LabN

Advanced networking options

Exposing a service via host

```
name: telemetry

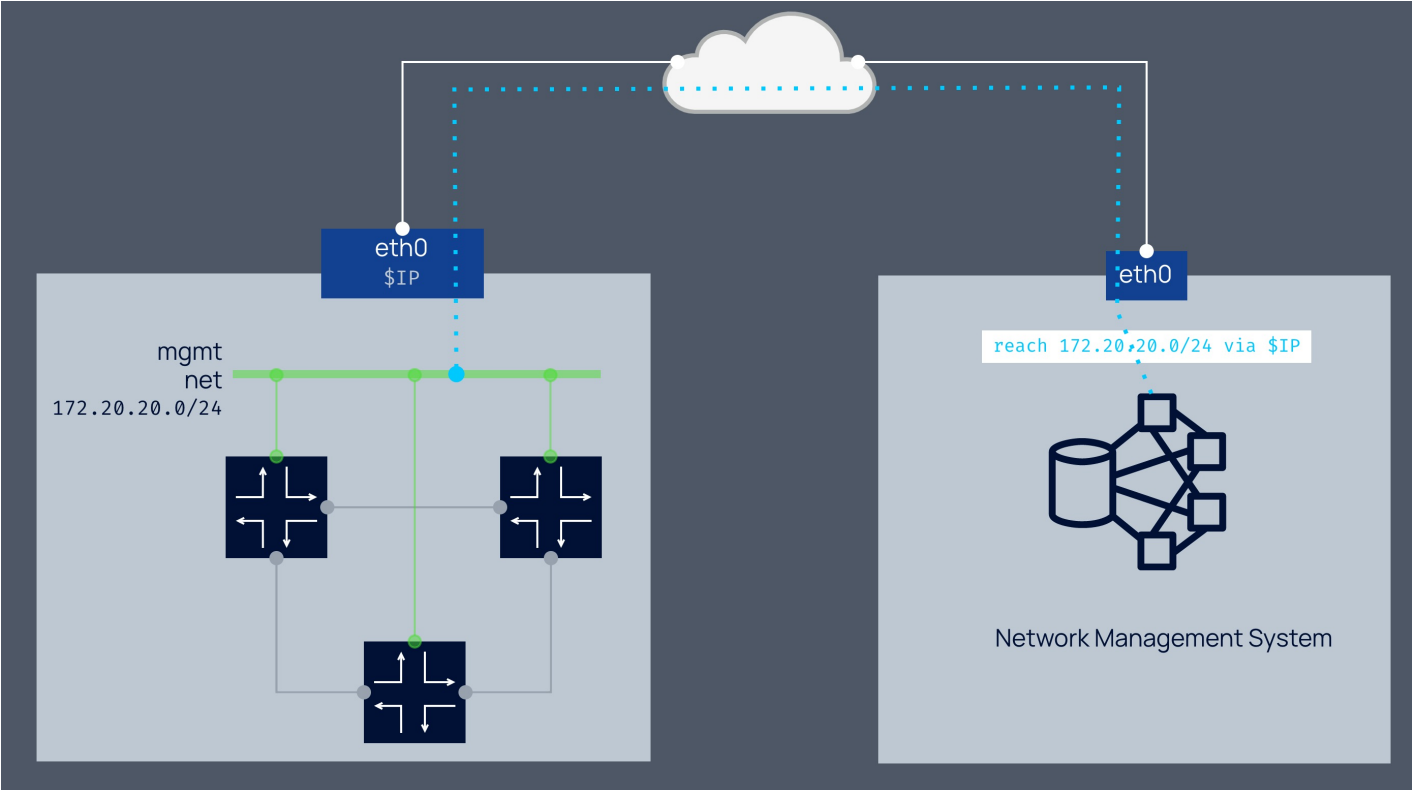
topology:
  nodes:
    ceos:
      kind: ceos
      image: ceos:latest
      ports:
        # host port 57401 is mapped to port 57400
        - 57401:57400
      srl:
        kind: srl
        image: srl:latest
        license: lic.txt
        ports:
          - 57402:57400
  links:
    - endpoints: ["ceos:eth1", "srl:e1-1"]
```



[read more on this](#)

Advanced networking options

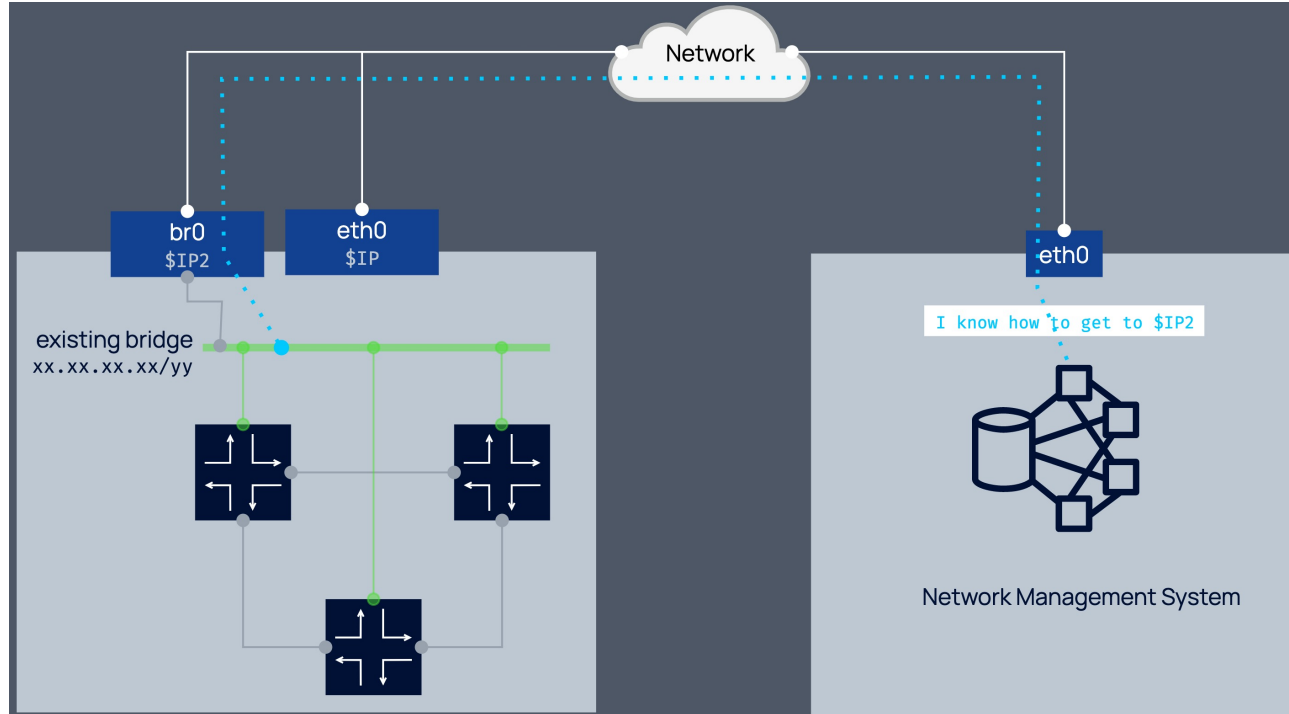
Exposing a management net



Advanced networking options

Exposing a management net (existing bridge)

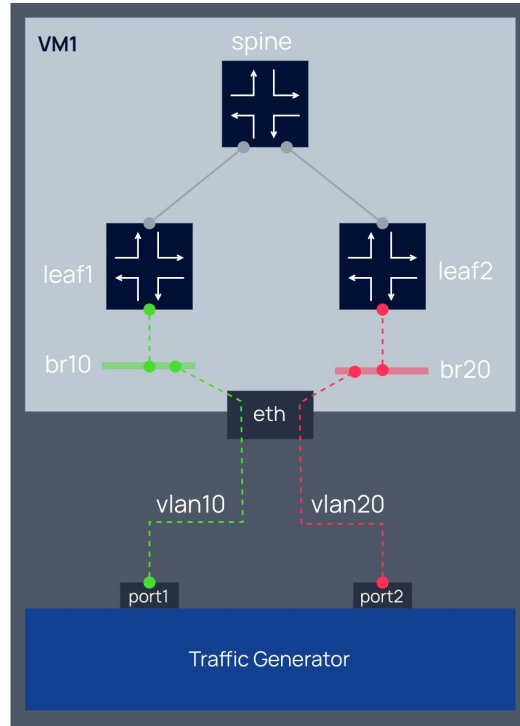
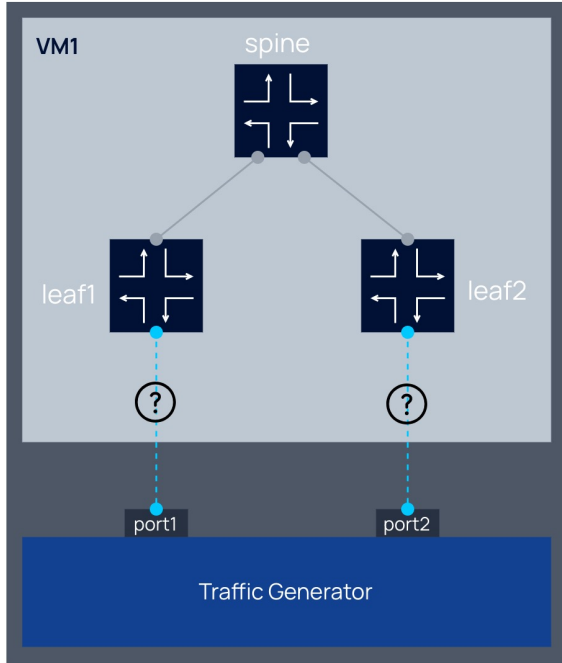
```
mgmt:  
[ bridge: existing-br  
  ipv4_subnet: 10.11.12.0/24  
topology:  
  nodes:  
    node1:  
      mgmt_ipv4: 10.11.12.10  
    node2:  
      mgmt_ipv4: 10.11.12.11
```



[read more](#)

Advanced networking options

Connecting to non-clab managed nodes



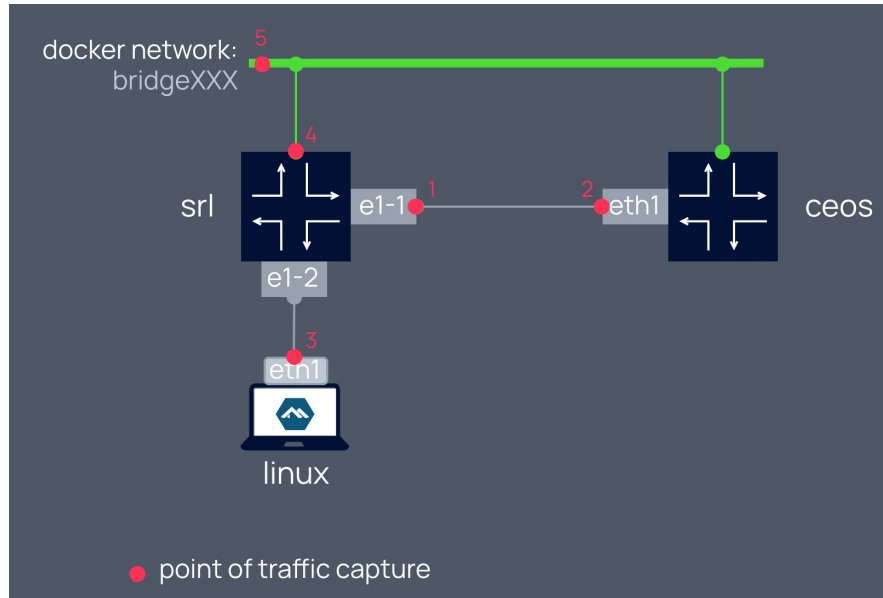
```
topology:
  nodes:
    leaf1:
    leaf2:
    br10:
      kind: bridge
    br20:
      kind: bridge
  links:
    - endpoints: ["leaf1:e1-2", "br10:l1"]
    - endpoints: ["leaf2:e1-2", "br20:l2"]
```



[read more](#)

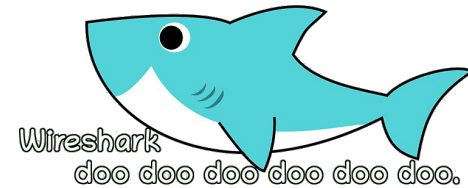
Packet capture

pcapng or it didn't happen



Command to capture at point #1

```
ssh $clab_host "ip netns exec $clab-pcap-srl  
tcpdump -U -nni e1-1 -w -" | wireshark -k -i -
```



[read more](#)

Containerlab

Not versus, but with others

Network emulation SW



- + Purpose built & proven
- + Free versions available
- + UI
- VM-centric
weak containers support
- Heavy and semi-open
- UI

Containerlab



CONTAINERlab

- + First class support for containerized NOSes
- + Transparent datapath
- + Git friendly & better image sharing and handling
- + Repeatable lab builds and CI friendly
- + Small footprint, open, free and fast
- Fewer traditional NOS supported
- No UI

Containerlab

Sounds interesting, what's next?

- 1 Explore containerlab.srlinux.dev documentation portal
- 2 Try to create a lab with the Network OS dearest to your heart
- 3 Missing feature, a problem, a nice idea? Reach out to us via Github [Issues/Discussions](#)
- 4 Join our [growing community on Discord](#)
- 5 Give containerlab [repo](#) a 🌟 and grab a containerlab sticker
- 6 Check out google/kne project for container-based labs at scale



CONTAINERlab

<https://containerlab.srlinux.dev>