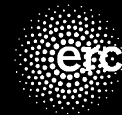


SIMULATION OF FACILITY EFFECTS ON MAGNETIC NOZZLE EXPANSIONS

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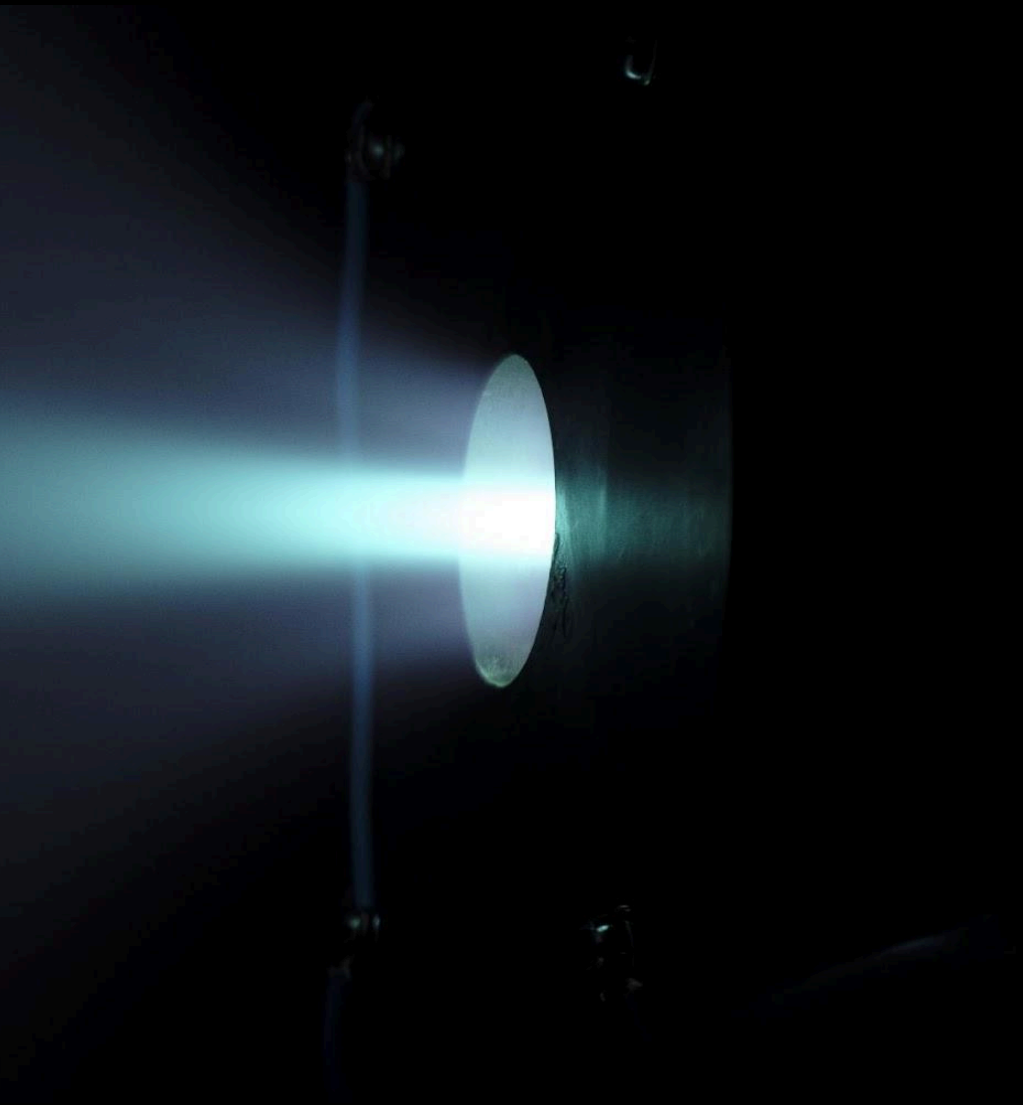
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PlasmaTech 2023



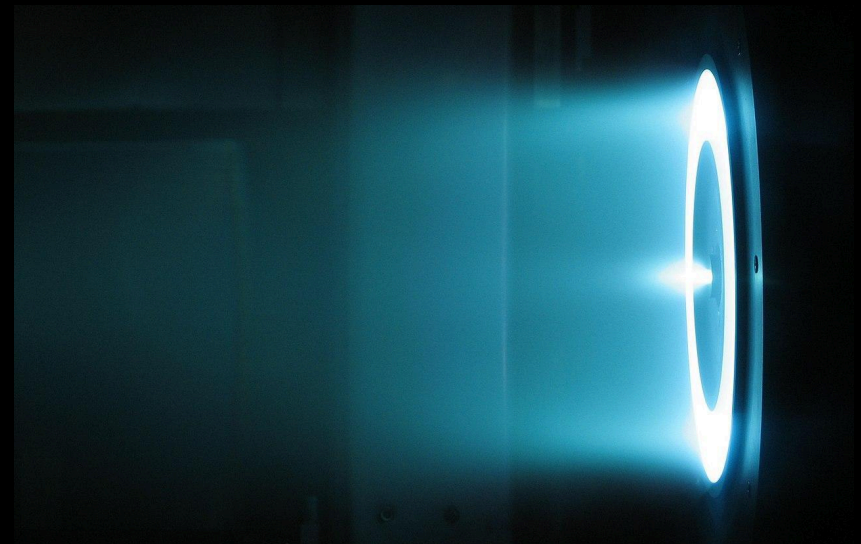
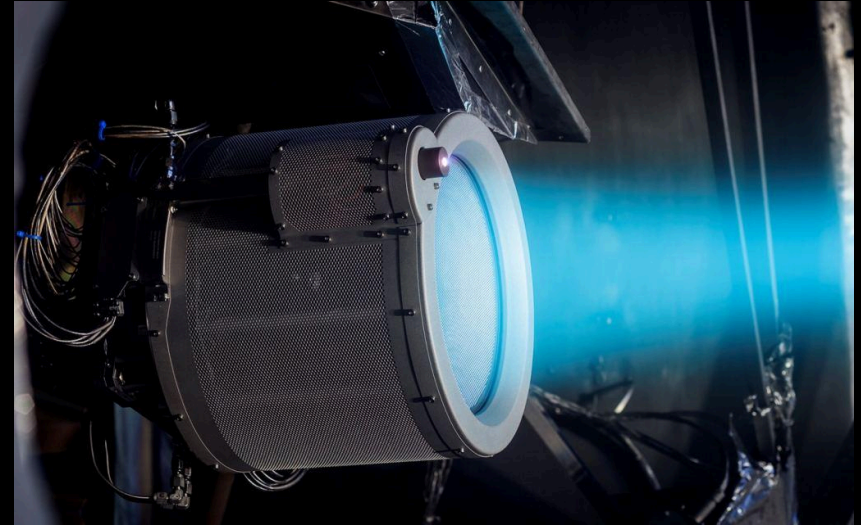
CONTENTS

- Motivation:
 - Electric Propulsion
 - Electrodeless Plasma Thrusters
- Objectives
- Model
 - Collision frequencies
 - Simulation Setup
- Results
- Discussion



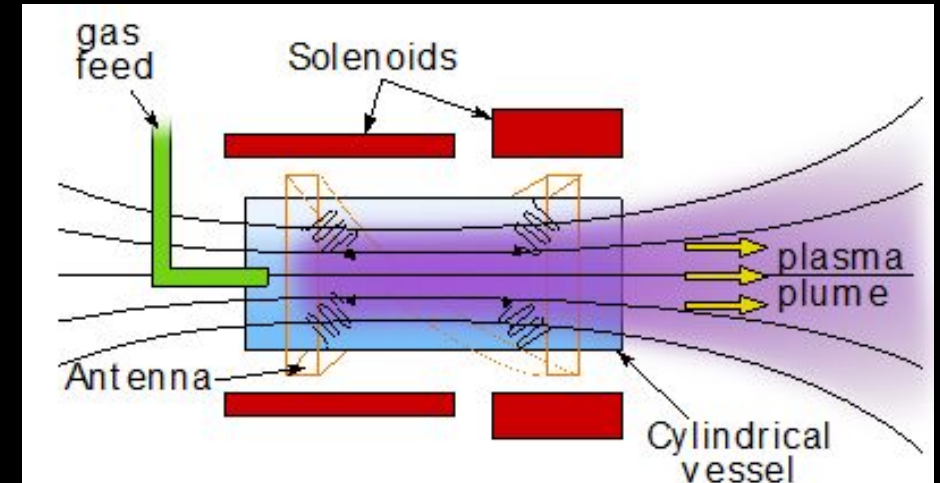
INTRODUCTION TO ELECTRIC PROPULSION

- Advantages over chemical propulsión:
 - Higher specific impulse
 - Higher efficiencies
 - Lower propellant mass.
- Electric Propulsion Devices:
 - Mature Technologies:
 - Gridded Ion Thruster
 - Hall Effect Thruster
 - Development:
 - Electrodeless plasma thrusters (EPTs)



ELECTRODELESS PLASMA THRUSTERS

- Operational principle:
 - Energizing electrons via electromagnetic waves.
 - Acceleration of plasma in a magnetic nozzle.
- Advantages:
 - No plasma-wetted electrodes:
 - Longer thruster lifetimes.
 - Use of alternative propellants.
 - Simple electronics.
 - Better scalability to lower Powers.
- Expansion of plasma in the magnetic nozzle:
 - Convergent-Divergent magnetic field.
 - Confinement and magnetic thrust thanks to Lorentz force.
 - Convert electron thermal energy into ion kinetic energy via ambipolar electric field.
 - Detachment from closed magnetic lines downstream.



OBJECTIVES

- Ground testing of EP devices induces facility effects.
 - Effect of background pressure has been studied in other EP devices.
 - Still poor knowledge of MN response to backpressure.
- First assessment of the effect of background pressure on MN performance, taking into account late ionization in the plume.
 - Magnetic thrust.
 - Behaviour of plasma properties.



MODEL

Two-Fluid Model:

- Quasineutral plasma
- Massless, polytropic, fully magnetized electrons.
 - $p_e = n_e^\gamma$
- Cold, singly-charged ions
- Ionization collisions with neutral background.
- $\beta = 0$, negligible self induced magnetic field.

$$\begin{aligned}\frac{\partial n}{\partial t} + \nabla \cdot (n \mathbf{u}_i) &= S \\ \frac{\partial n \mathbf{u}_i}{\partial t} + \nabla \cdot (n \mathbf{u}_i \otimes \mathbf{u}_i) &= -n \nabla \phi + n \mathbf{u}_i \times \mathbf{B} \\ \frac{\partial n}{\partial t} + \nabla \cdot (n \mathbf{u}_e) &= S \\ 0 &= -\nabla n T_e + n \nabla \phi - n \mathbf{u}_e \times \mathbf{B}\end{aligned}$$

- Under given assumptions electron equations are found to be algebraic:
 - Electron momentum equation can be solved a priori \rightarrow Thermalized potential (H_e)

$$\begin{aligned}H_e &= \frac{\gamma}{\gamma - 1} (n^{\gamma-1} - 1) - \phi \\ u_{ye}(\psi_B) &= \frac{-1}{B} \frac{\partial H_e}{\partial \mathbf{1}_\perp} = -\frac{\partial H_e}{\partial \psi_B}\end{aligned}$$

- Ion equations are similar to Euler eqs.
 - Forcement in momentum eqs. given by:
 - Thermalized potential:
 - Encapsulates ambipolar electric field.
 - Ion magnetization, low importance.
 - Source term in continuity eq. given by collisionality.

COLLISION FREQUENCIES

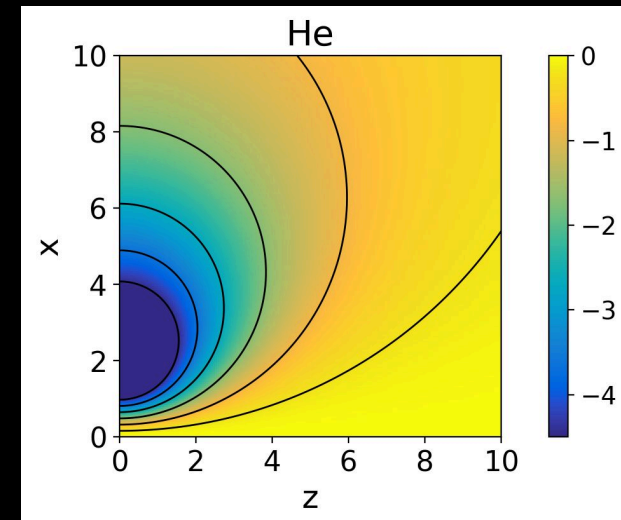
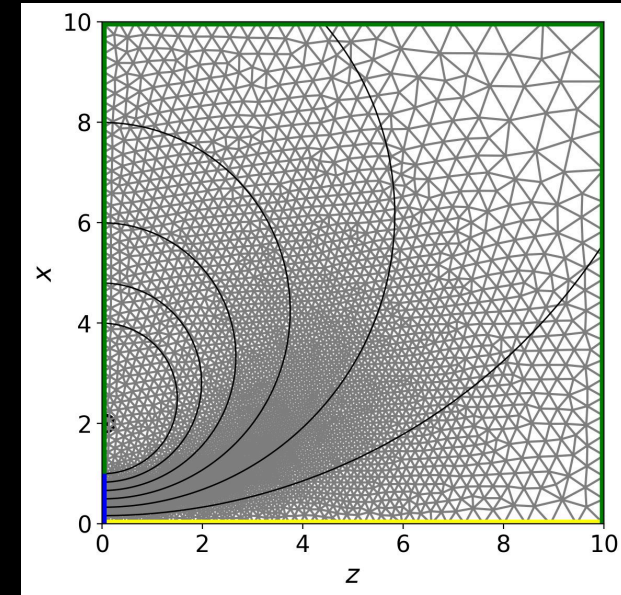
- Collision model in continuity equation:
 - $S = \nu n$
- Uniform background of neutrals.
 - Only valid for low collisionalities.
- One free parameter (collision frequency).
 - Depends on:
 - Cross section.
 - Neutral density.
 - Velocity.
- Can be given by:

$$\nu = \sigma n_n v_e$$

- Typical values:
 - $\sigma \approx 10^{-19} \text{ m}^2$
 - $p \approx 1.3 \cdot 10^{-4} \text{ pa} \rightarrow n_n \approx 3.1 \cdot 10^{16} \text{ m}^{-3}$
 - $v_{th} \approx 1.3 \cdot 10^6 \frac{\text{m}}{\text{s}}$
 - $\nu \approx 4.1 \cdot 10^3 \text{ s}^{-1}$
 - $\nu_0 = \frac{v_0}{R_0} \approx 1.5 \cdot 10^5 \text{ s}^{-1}$
- After non dimensionalization:
 - $\frac{\nu}{\nu_0} \approx 0.03$

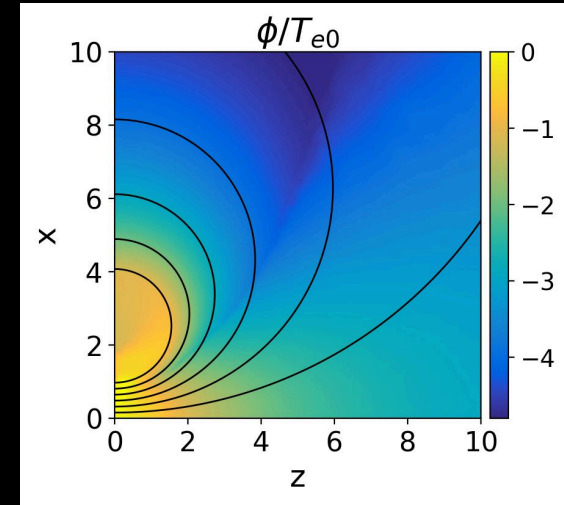
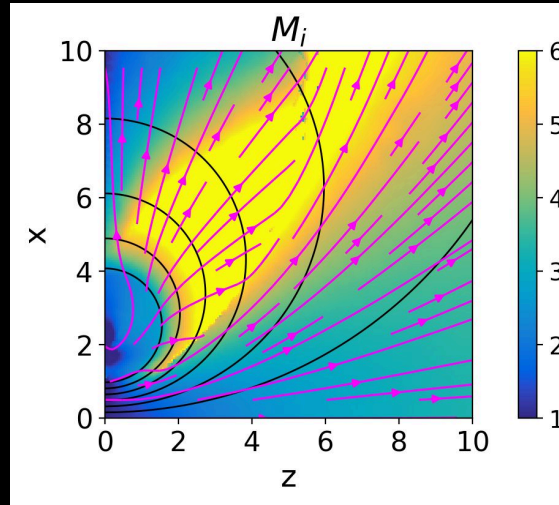
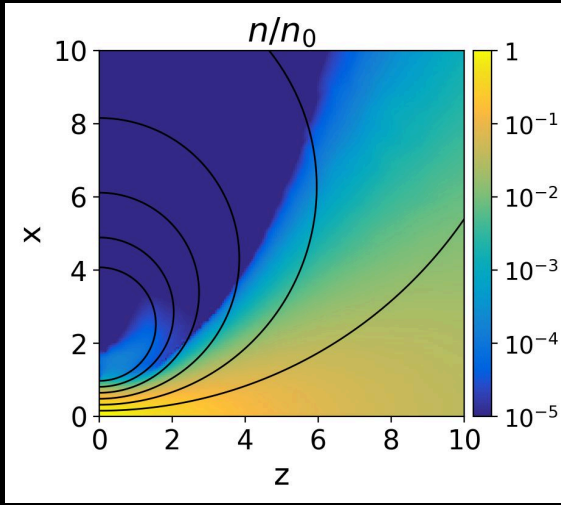
SIMULATION SETUP

- Numerical setup:
 - Discontinuous Galerkin discretization (FEniCS)
 - Runge Kutta time-stepping
 - Unstructured mesh (Gmsh):
 - Cell diameter such that the nozzle throat is resolved in 40 cells.
 - Order 1 elements.
- Physical parameters:
 - Gaussian density profile: $n(0) = n_0$ and $n(R_0) = 10^{-3}n_0$
 - Coil radius: $R_L = 2R_0$
 - Sonic axial velocity
 - $\gamma_e = 1.2$
 - Collisionalities: $\nu \in [0, 0.01, 0.03, 0.06]$

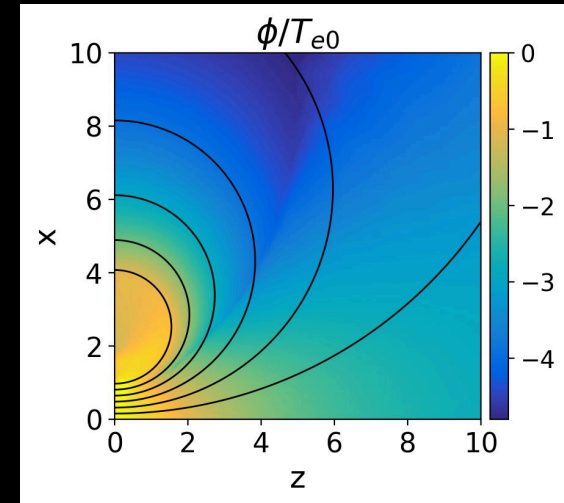
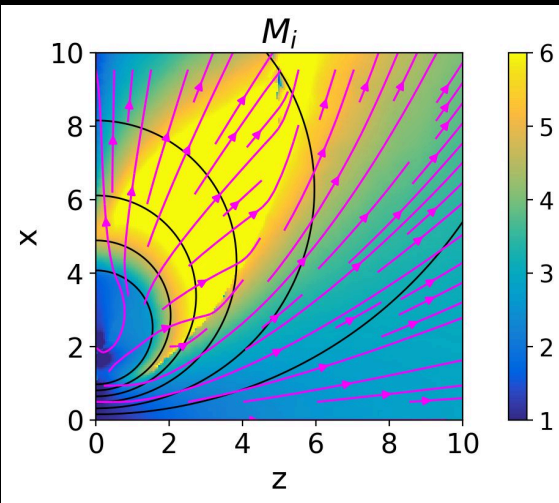
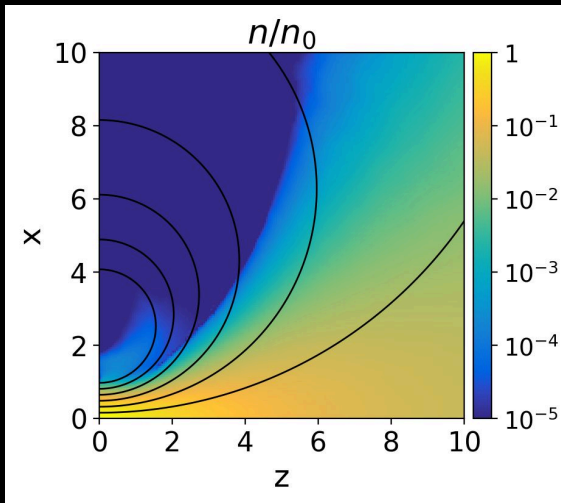


RESULTS - PLASMA PROPERTIES MAPS

Collisionless case

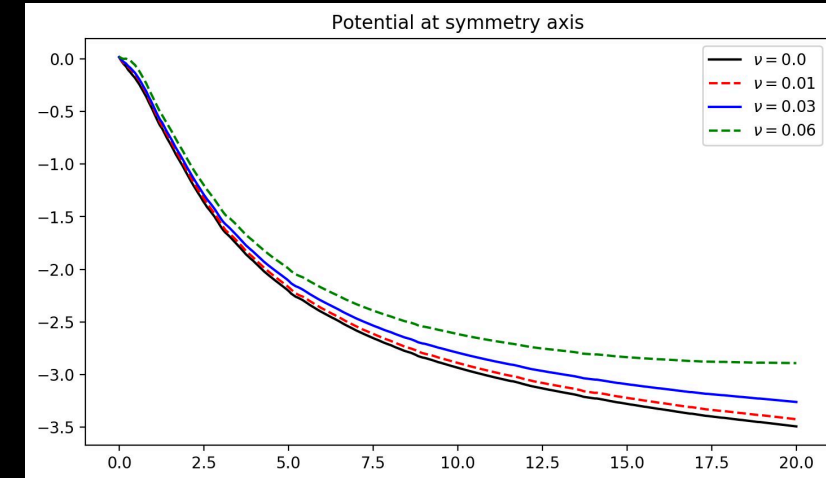
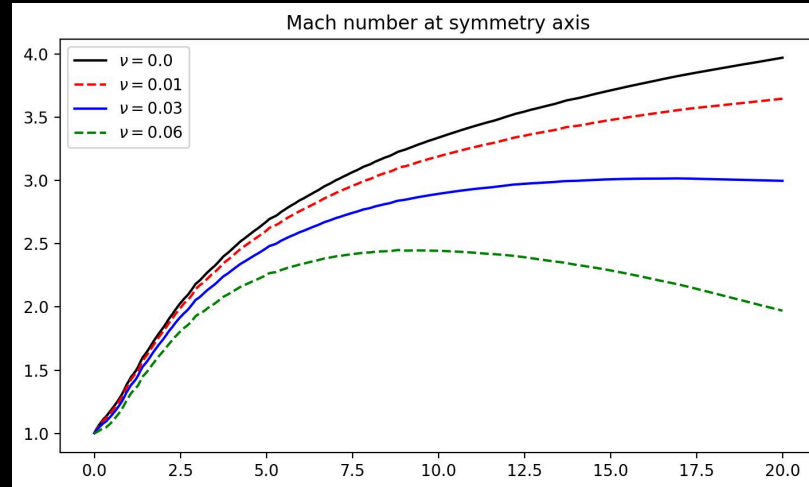
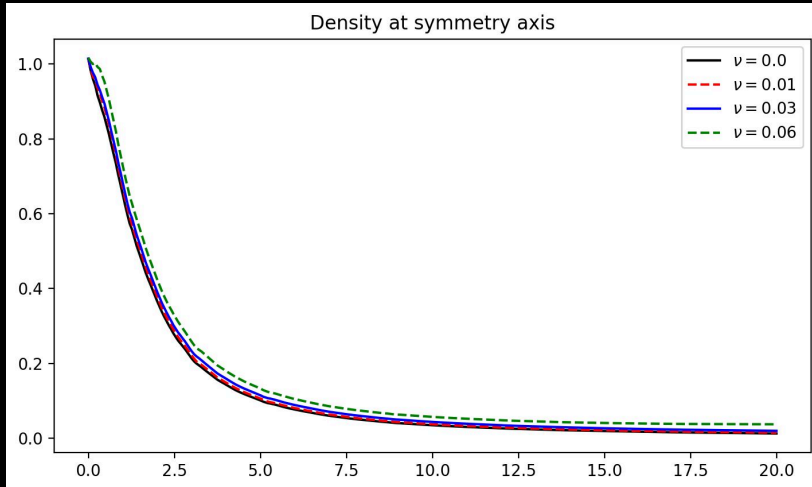


Nominal case



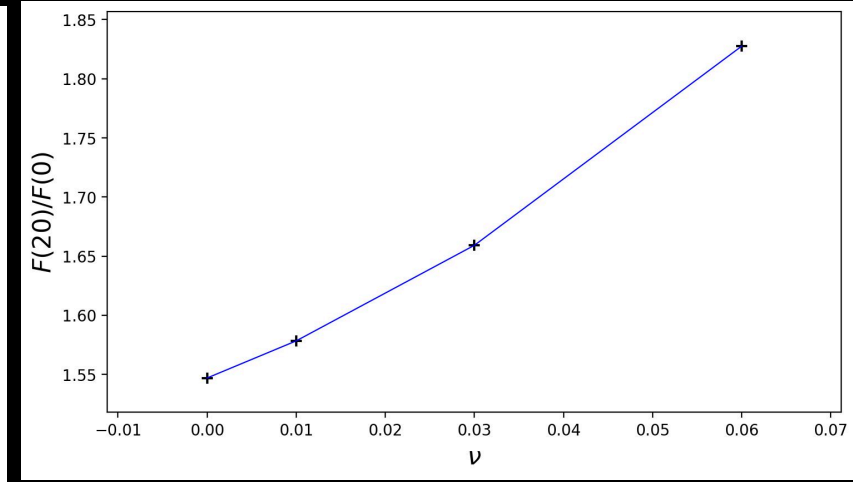
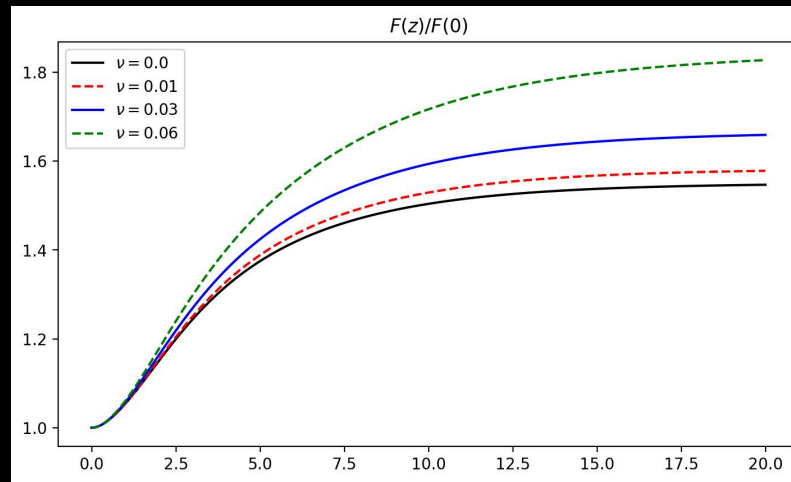
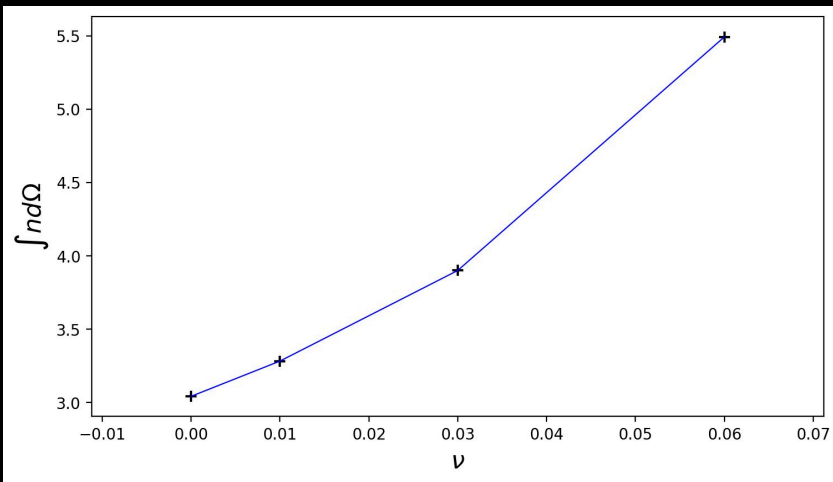
RESULTS - AXIAL BEHAVIOUR

- Density at symmetry axis increases.
- Lower final ion velocity with increasing collisionality:
 - 50% drop of ion mach number over the tested ranges.
- Lower potential drop:
 - 20% drop over tested ranges.



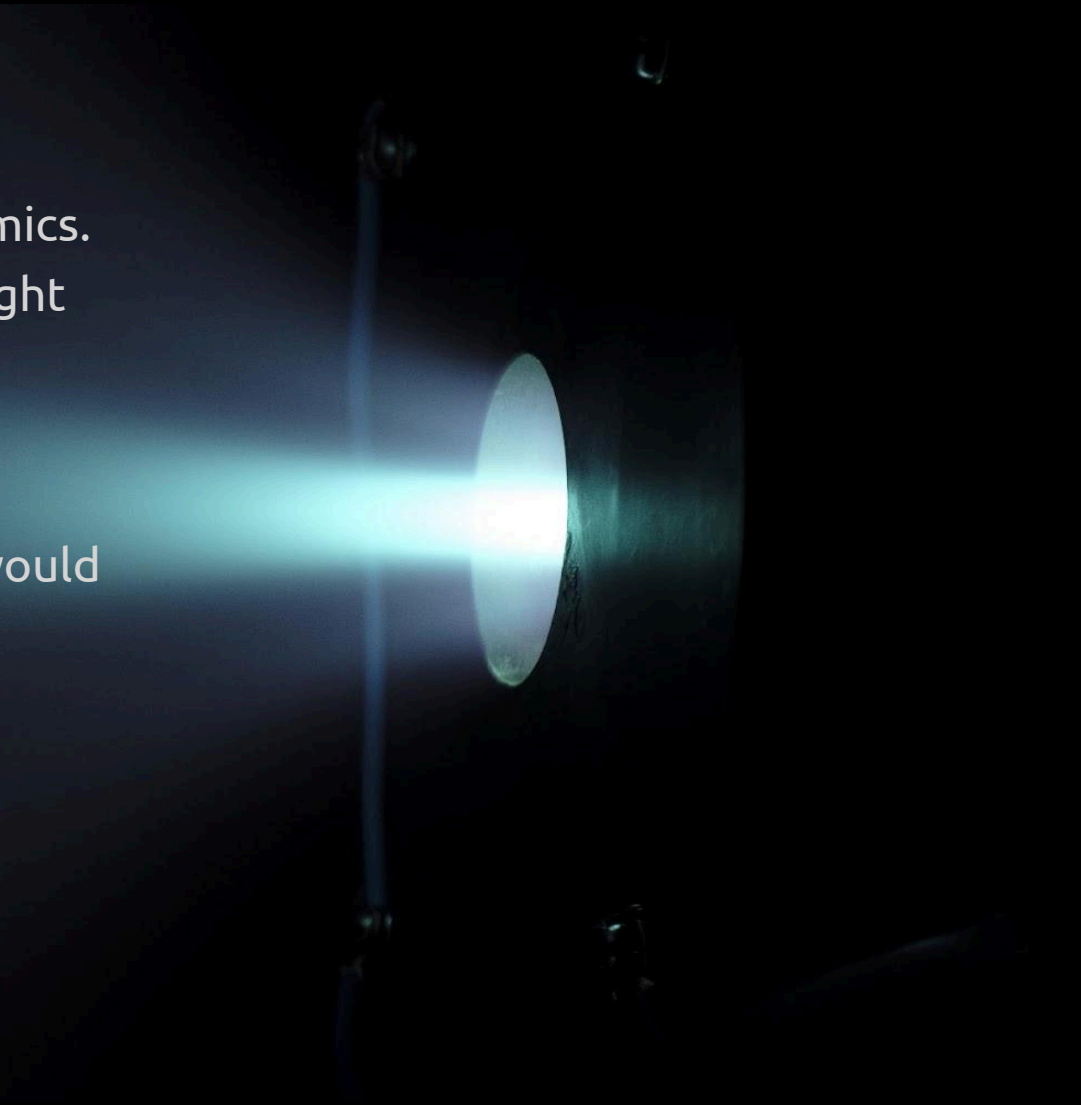
RESULTS - GLOBAL PARAMETERS

- Total mass in the domain increases by ~ 80%
 - More plasma subject to ambipolar acceleration.
 - Total thrust increases by ~ 20%
- Stabilization of the magnetic force happens further downstream for increasing collisionality.
 - Plasma expansion takes a longer distance.



DISCUSSION

- First step for the study of background pressure on nozzle performance.
 - Characterization of main effects on total thrust.
 - Background pressure, has a noticeable effect on dynamics.
 - Augmented thrust due to background pressure might mask in-space behaviour.
 - Very low pressures needed for ground testing.
- Limitations:
 - Including collisions in electron momentum equations would yield lower confinement.
 - Non consistent simulation of neutrals:
 - Neutral depletion
 - Other types of collisions could also play a role:
 - CEX, excitation collisions...



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This project has received funding from the European Research Council (ERC) under the European Union's Horizon 2020 research and innovation programme (grant agreement No 950466)



THANK YOU!



EXTRA SLIDES

METHODOLOGY: THE DG-FEM METHOD

- Finite Element Method with traits of Finite Volumes.
- Discretise the domain in k cells D_k and assume a local solution described by a polynomial.
 - Don't assume continuity at cell interfaces.
- Enforce the satisfaction of the conservation law weakly through multiplication by test functions.
- Use of a numerical flux to approximate the physical flux between discontinuous cell interfaces.

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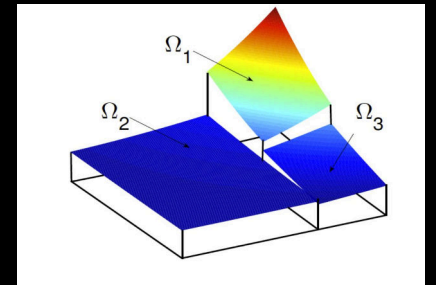
$$\partial_t u_i + \nabla_j F_{ij} = f_i$$

$$\int_{D_k} v_i \partial_t u_i d\Omega + \int_{D_k} v_i \nabla_j F_{ij} d\Omega = \int_{D_k} v_i f_i d\Omega$$

$$\int_{D_k} v_i \partial_t u_i d\Omega + \int_{\partial D_k} F_{ij} v_i n_j d\Omega - \int_{D_k} F_{ij} \nabla_j v_i d\Omega = \int_{D_k} v_i f_i d\Omega$$

$$\int_{\Omega} v_i \partial_t u_i d\Omega - \int_{\Omega} F_{ij} \nabla_j v_i d\Omega + \int_{\partial\Omega_{ext}} F_{ij} v_i n_j ds$$

$$+ \int_{\partial\Omega_{int}} H_{ij} n_j (v_i^+ - v_i^-) ds = \int_{\Omega} v_i f_i d\Omega$$



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