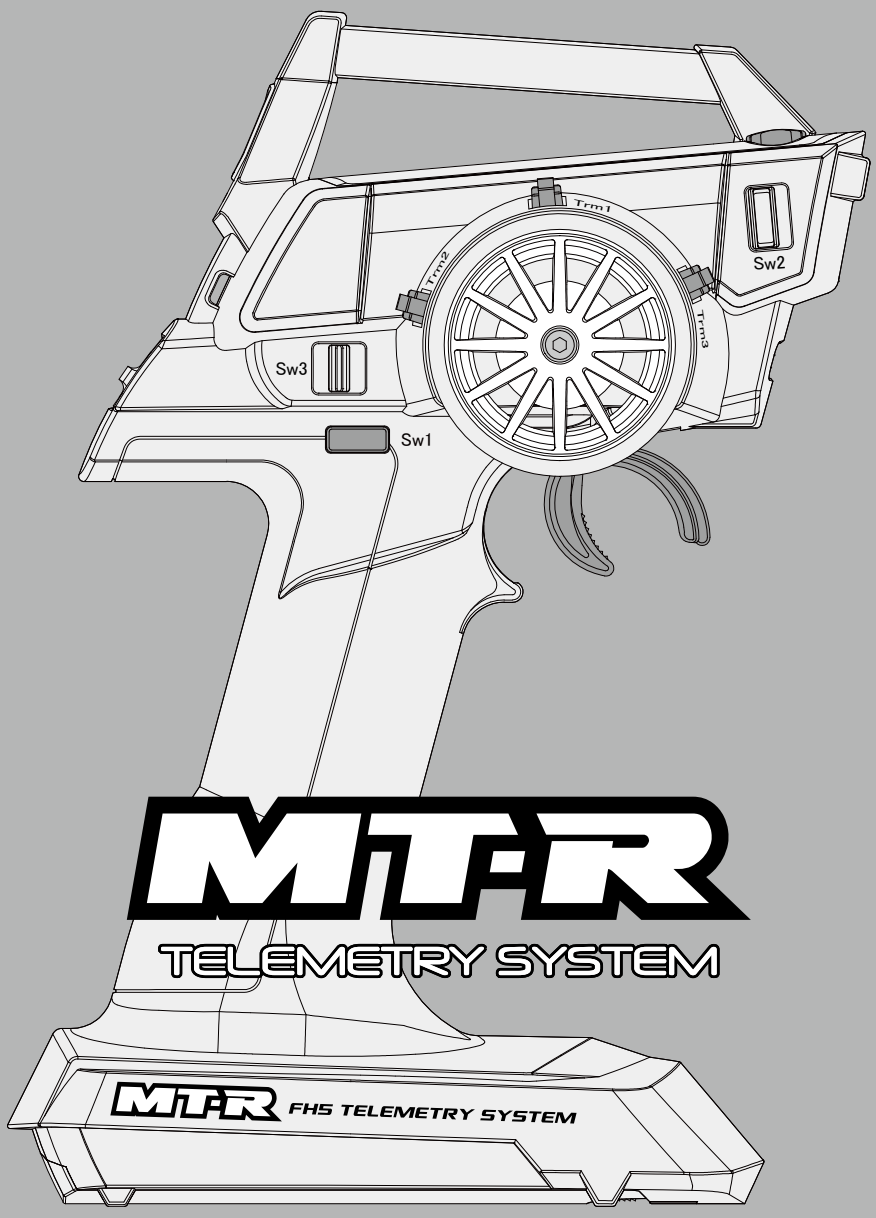
SANWA

USER MANUAL



MT-R

TELEMETRY SYSTEM

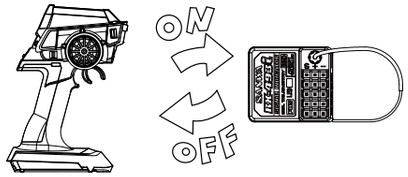
Safe Handling and Precautions

To use your purchased R/C System properly and safely, please read this instruction carefully and make sure to follow the precautions. Improper use of the product or negligence of following safety precautions can cause trouble to others or harm to the user.

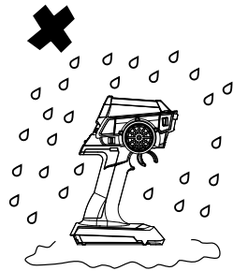
■ For safety, please make sure to follow each of the precautions below.

⚠ Warning　Precautions for Installation and Operation

- When turning the power switch of R/C System on, please turn on in order of 1.Transmitter → 2.Receiver. And when turning the power switch off, please do so in order of 1.Receiver→2.Transmitter.
- ☆ If you reverse the order of the switches, it causes sudden high rotation of the engine and the motor and it's extremely dangerous.



- Please use electrical noise countermeasure on the body of your car.
- ☆ If metals rub against each other, it causes electrical noise which may lead to abnormal performance. Please be sure that all screws and nuts are not loose.
- ☆ Nitro or gas engine and electric motor can cause noise also. Please use a noise countermeasure such as a plug with resistor or noise killer condenser.
- Please make sure to run a performance check (signalreception test) of R/C System before operation. When it moves abnormally or it doesn't move, please don't operate. Even if the test result on a desk is normal,please be cautious when operating for the first time especially, since the radio wave arrival distance varies depending on the installation method of the receiver, how the antenna is set, the direction of the transmitter antenna is facing and geography.
- Never operate on a rainy day.
- ☆ The interior of the transmitter is built with sensitive electronic parts. If water runs on the surface of the case and enters inside, it can cause abnormal performance or malfunction and it can be dangerous.
- ☆ If the receiver or a servo sinks in the water, immediately collect it and dry the interior. When the interior is dry, please submit it to the Sanwa Service for inspection even if it performs normally.



- The receiver is a precise instrument. Please do not add a strong impact or vibration.
- ☆ Use a thick sponge to prevent vibrations. Install the receiver as far as possible from the speed controller, motor and the battery.
- When installing the receiver on a metallic chassis or a carbon chassis, use three layers of double adhesive tape pieces to keep the receiver from touching the chassis.
- When there is a radio disturbance, change the installation location of the receiver or change from a vertical placement to a horizontal placement or vice versa.
- Don't place a motor cord or a battery cord close to the receiver since it can cause abnormal performance.
- Keep the antenna of the receiver out as much as possible. And keep it straight and stretched. Don't cut the extra length of the line or bend it.
- ☆ It's dangerous when the antenna is short since the range of travelling becomes narrow.
- ☆ Never cut the antenna.

- Don't place the antenna close to a motor cord or a battery cord.
- Using a conductive piano wire on a metallic chassis or carbon chassis can cause abnormal performance from electrical noise. Don't place a piano wire close to the chassis.

⚠ Warning　Careful When Driving

When operating an RC car, please make sure to follow the following notes and avoid giving trouble to others.

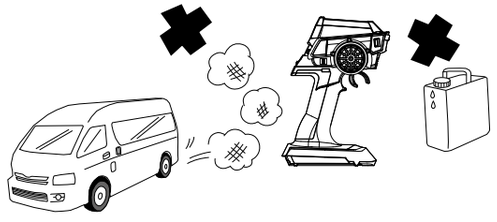
- Maintain the body of the car (boat) in a perfect condition and check the safety.
- Do not operate an RC car in a crowd or on a public road.
- Make sure to disconnect the connector of the power battery and remove the power battery from the car after operation.
- When operating simultaneously with other RC users, make sure to have a control staff and follow the instruction of the control staff.
- Try not to interfere with other people's operation.
- Be sure to apply for a radio control insurance.
- For application to apply a radio control insurance, inquire a radio control operator registration agency.
- Be sure to install a "muffler (sound absorber)" with a silencing effect on an engine car.
- Don't start engine early in the morning.
- Please make sure to clean the location used for operation before you leave.

⚠ Caution　About Usage

- Do not use this RC system for other than model use.
- Since this product is manufactured for models based on the Radio Law in each country, it cannot be used in countries other than your original place of purchase.

⚠ Caution　Daily Care

- When the exhaust of the engine or fuel is on the radio, wipe it with a soft, dry cloth. When it gets dirty, please wipe it with a tightly squeezed clean soft cloth impregnated with water or neutral detergent. Thinner, benzene, alcohol, motor cleaner, brake cleaner, etc. may cause surface finish to deteriorate or degenerate, so please do not use.

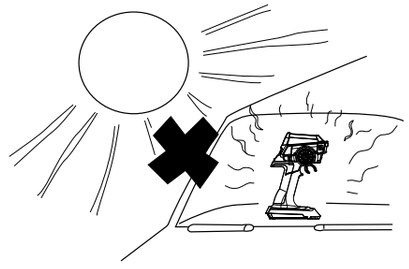


⚠ Caution　Handling Transmitter

- Please do not hit, drop or cause strong shocks. In addition, if you touch the transmitter, receiver, servo, FET speed controller, etc. with hands applied with tire traction agent, it will cause breakdown or case deformation.

⚠ Caution　About Storage

- Do not store in following places.
  - ☆ Extremely hot place or extremely cold place.
  - ☆ A place that is exposed to direct sunlight for a long time. Especially if you leave it in a place where direct sunlight hits like in a closed car window, the interior temperature becomes 80 0 C or more depending on the season, so please be careful as it may cause deformation or breakdown.
  - ☆ A place with high humidity, poor ventilation.
  - ☆ A place with considerable vibrations.
  - ☆ Places with high dust places subjected to steam or hot air.
  - ☆ A place that gets exhaust gas from an engine or a place near the fuel tank.



Meaning of the mark

⚠ **Caution**　Things you are expected to do to prevent accidents and injuries.

⚠ **Warning**　Things that you should follow in order to prevent break down.

Safe Handling and Precautions

⚠ Warning Note Precautions for Safe Use

- 2.4 GHz frequency band is not only used for radio control. This frequency band is shared with ISM (Industry, Science and Medical) band. It can be affected by microwave ovens, wireless LAN, digital cordless telephones, audio equipment, Bluetooth of game machines or cell phones and short-range communication such as VICS. Also, be cautious about being affected by amateur radio and premises radio stations for moving body identification since this frequency band is used for them as well. When a harmful radio frequency interference is done to an existing radio station, stop the transmission of the radio frequency immediately and take a measure to avoid the interference.
- For RC circuit, minimize the use of equipment that can affect 2.4 GHz systems and make sure to check the safety beforehand. Also, follow the instruction of the facility manager.
- When operating the models behind a building or a steel tower, blocking the direction of radio wave transmission can cause reduction of operation response or loss of control. Always operate within the range you can visually check.
- Don't grab the transmitter antenna. Doing so can be dangerous since it can weaken the radio signal output and narrow the range of operation.
- Don't attach any metal parts around the antenna of the transmitter.
- If you have the transmitter's antenna extremely close to a servo or speed controller other than the receiver, it can cause malfunction but it is an influence of a strong high frequency output and it is not abnormal.
- The receiver is a precise instrument. Don't subject it to strong impact or vibrations. Use a thick sponge to prevent vibrations.
- Keep the antenna wire of the receiver out as much as possible. And keep it straight and stretched. Don't cut the extra length of the antenna line or bend it.
- Keep the antenna wire of the receiver out as much as possible. And keep it straight and stretched. Don't cut the extra length of the antenna line or bend it.
- Don't place the antenna wire of the receiver close to a electrical noise source like a motor wire or a battery wire.
- When installing the receiver on a metallic chassis or a carbon chassis, use layers of double adhesive tape pieces to keep the receiver from touching the chassis as much as possible.

INDEX

■Structure and the Standard of the Set • 5
- ●Structure of The Set (5)
- ●Set Specification (5)

■Before Using • 6-7
- ●Adjusting Tension of The Steering and Throttle (6)
- ●Adjusting The Adjustable Trigger (7)
- ●About The Power Source, Bind (7)

■Names of Each Part of The Transmitter • 8

■Connections and Installation of Receiver • 9,10
- ●About Receiver, And How to Handling The Antenna (9)
- ●About Connection Setup (10)

■Before Driving A RC Car • 13-16
- ●How To Place Servo Horn (13)
- ●How To Set Reverse [REV] (13)
- ●How To Set Sub Trim [SUB-T] (14)
- ●Sub Trim and Trim Differences (14)
- ●How To Set End Point Adjustment [EPA] (15)
- ●How To Set Dual Rate [D/R] (16)

■How To Use Each Feature • 11,12,17-52
- ●About Key Operation (11)
- ●About the Display Panel (12)
- ●About the Menu Structure (17)
- ●Setting [SETTING] (18-34)
  - • Dual Rates (D/R) (18)
  - • Speed [SPEED](19)
  - • Curve [CURVE] (20)
  - • Fail Safe [F/S] (21)
  - • Base [BASE] (22-24)
  - • Reverse [REV] (22)
  - • Sub Trim [SUB-T] (22)
  - • End Point Adjustment [EPA] (23-24)
  - • Function [FUNC] (25-28)
  - • Trim [TRIM] (25)
  - • Anti-Lock Brake [ALB] (26)
  - • Offset [OFFSET] (27)
  - • Throttle Type [TH TYPE] (28)
- ●AUX [AUX] (29-34)
  - • Step AUX [STEP AUX] (29)
  - • Point AUX [POINT AUX](30)
  - • 4 Wheel Steering [4WS] (31)
  - • Motor On Axle [MOA] (32)
  - • AUX Mixing [AUX-MIX] (33)
  - • Code AUX [CODE AUX] (34)
- ●Model [MODEL] (35-38)
  - • Model Select [MODEL SELECT] (35)
  - • Model Name [MODEL NAME](36)
  - • Model Copy [MODEL COPY] (37)
  - • Model Clear [MODEL CLEAR] (38)
- ●Timer [TIMER] (39-40)
  - • Lap Timer [LAP TIMER] (39)
  - • Interval Timer [INT TIMER](40)
  - • Down Timer [DOWN TIMER] (40)
- ●Telemetry [TELEMETRY] (41-42)
  - • Logger[LOGGER] (41)
  - • Alert Setting [ALERT SETTING] (42)
  - • Telemetry Setting [TELEMETRY SETTING](42)
- ●System [SYSTEM] (43-48)
  - • Bind [BIND] (43-44)
  - • Key Assign Switch [KEY ASSIGN SW](45)
  - • Key Assign Trim [KEY ASSIGN TRIM] (46)
  - • Buzzer [BUZZER] (47)
  - • Battery [BATTERY] (47)
  - • LCD [LCD] (48)
  - • Calibration [CALIBRATION] (48)
- ●Setup Wizard (49-50)
- ●About Quick Setup Wizard (51-52)

■Assign Function List • 53

■Transmitter LED Indication List • 54

■Index • 55

■When this happens... • 56

■Service and Support • 57

■FCC Compliance Statement • 58

Structure and the Standard of the Set

STRUCTURE OF THE SET

	MT-R RX-493i PC (Primary Component)
<A> Transmitter	TX-4101
<B> Receiver	RX-493i
<C> Servo	–
<D> Accessories	Brake Trigger +1/+2 x each 1 Receiver Dust Cover x 1 User Manual x 1 Bind Plug x 1 Antenna Pipe x 1

●ご使用になる前にセットの内容をお確かめください。

SET SPECIFICATION

<A> Transmitter

Product No.	TX-4101
Output Display	Digital display (Power Source Vooltage Display)
Modulation	2.4GHz Spectrum Spread System
Power Source	AA BATT x4 (Corresponding VOLT:TDC4.8 - 7.4V)
Weight	366 g

<B> Receiver

Product No.	RX-493i
Modulation	2.4GHz Spectrum Spread System
Size	26.0x23.2x14.0mm
Power Source	DC3.7～7.4V
Weight	6.2 g

*Be careful with the input voltage.
If voltage above allowable oltage is inputted, the transmitter will be damaged.

Before Using

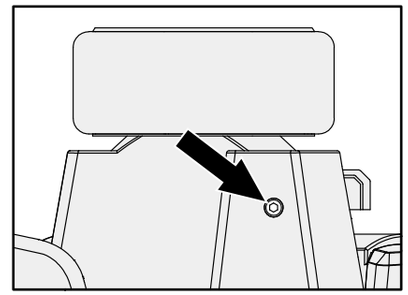
ADJUSTING THE STEERING AND THROTTLE TENSION

MT-R can adjust the tension of the steering/throttle trigger to match operation of the steering/throttle to the user's preference.

Adujsting the Steering Tension

By inserting a hex wrench driver (1.5mm) to the place where the arrow is pointing at in the illustration on the right and turning, you can adjust the tension of the steering spring.

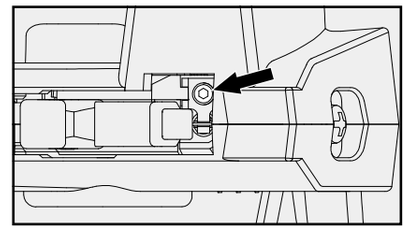
*The spring tension is the softest at the time when the product is shipped out from the factory. As you tighten with a hexagon wrench driver (1.5mm), the spring tension will be hardened.



Adjusting the Throttle Trigger Tension

By inserting a hex wrench driver (1.5mm) to the place where the arrow is pointing at in the illustration on the right and turning, you can adjust the tension of the throttle spring.

*Please do CALIBRATION when changing steering and throtte tention. (p.48)



ADJUSTING THE ADJUSTABLE TRIGGER

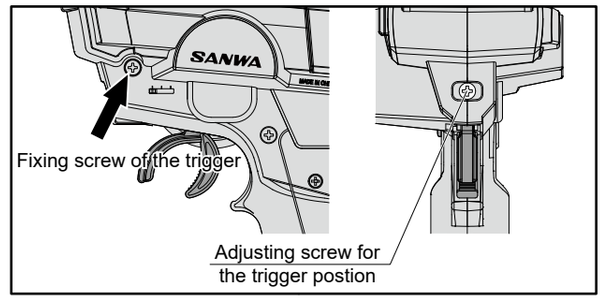
MT-R can adjust the throttle trigger position fiting to the user's hand size.

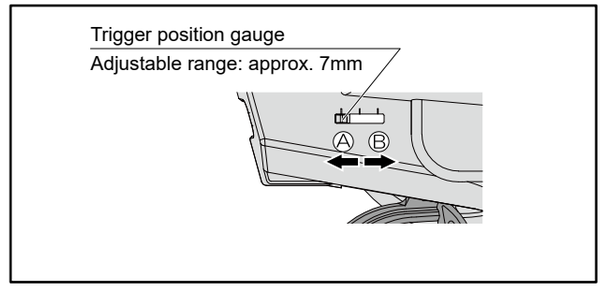
Adjusting the trigger position

Loosen the fixing screws of the trigger on the back of the transmitter. Then, adjust the adjusting screw of the trigger position on the back of the transmitter to set the trigger at the position of your preference. When you turn the adjusting screw of the trigger position clockwise, the trigger position gauge moves to the direction A. By turning it counter clockwise, the trigger position gauge moves to the direction B.

*The range of the trigger movement is 7mm.
If you turn the screw forcefully beyond the range, it can cause malfunction. Once you set the trigger position, tighten the fixing screw and adjusting the trigger is done.

*Be careful with the direction of turning the screw because the trigger position is set at the furthest point of the A side at the factory.





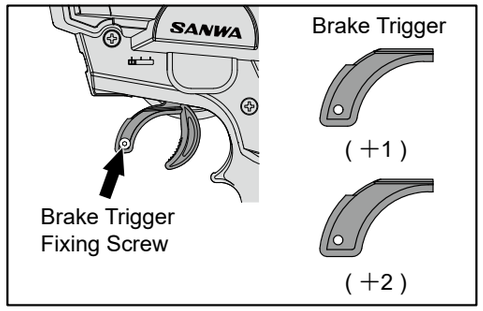
*Setting Advice
Please fit trigger position to your finger naturally.
It would be smoother to operate braking.

ADJUSTING THE ADJUSTABLE TRIGGER

Adjusting the brake trigger

You can adjust brake trigger position accroding to your fingers by replaceing the included brake trigger.
Standard Size, +1 Size, +2 Size is included.

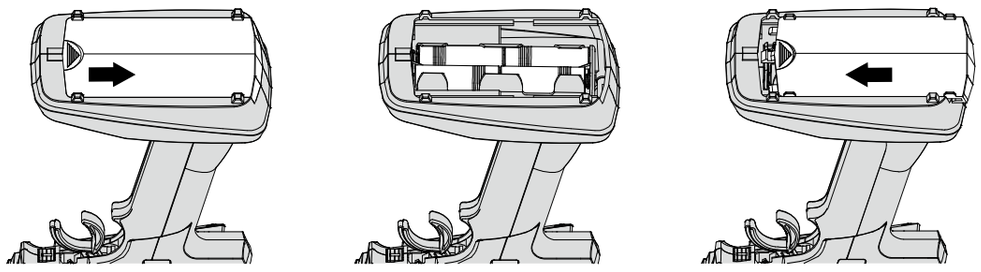
1) Remove the brake trigger fixing screw.
2) Select Brake Trigger according to your fingers.
3) Fix the brake trigger by the screw.



*Setting Advice
If you feel much gaps between a finger with trigger, please change brake trigger to +1 or +2.
After changing the brake trigger size, please check the differences while driving.
Combination of trigger position and brake trigger adjustment would give optimic operation by fiting to personal hand.

ABOUT THE POWER SOURCE

HOW TO PLACE THE TRANSMITTER BATTERIES



<1>Open the battery compartment cover by sliding the cover to the direction of the arrow while pressing it lightly.

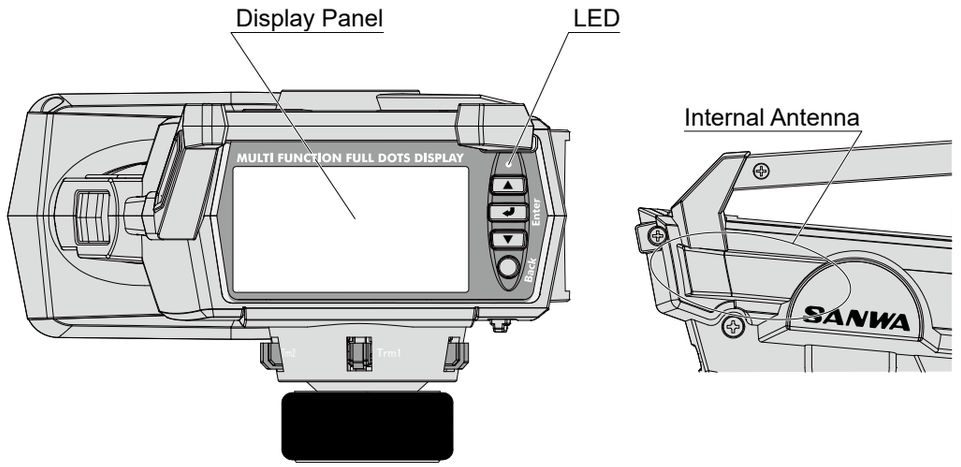
<2>Place 4 size AA batteries. Make sure to observe correct polarities.

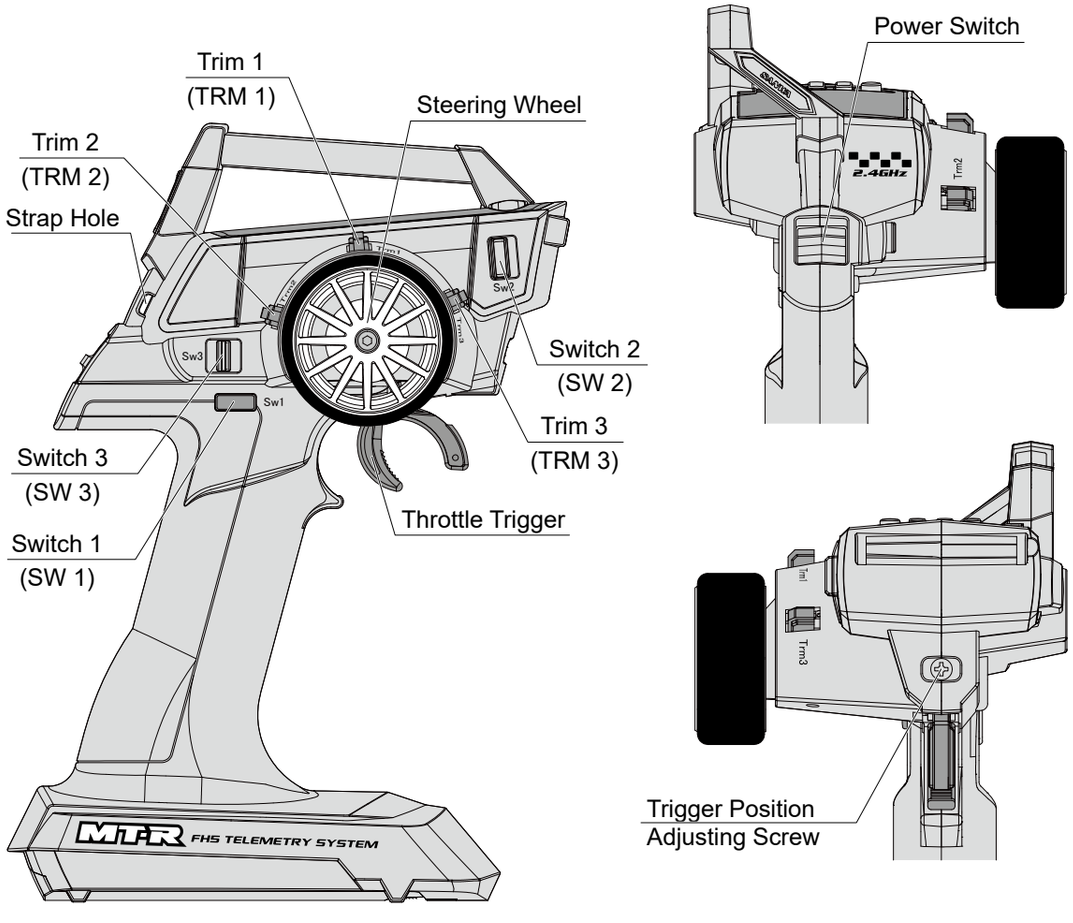
<3>Align the convex part of the battery compartment cover and the groove of the battery compartment, slide the cover to the direction of the arrow and close tightly.

ABOUT BIND

- About Bind
  Each MT-R transmitter has own ID number for transmition. Receiver memorizes the ID number to bind.
  After binding, the transmitter can work with the receicer.eceiver and the antenna are installed.
- BINDING is not done at the factory. Please make sure to complete BINDING before use.
- When the receiver is new, make sure to complete BINDING for the transmitter and the new receiver.
- Make sure to use the set of the transmitter and the receiver that completed BINDING.

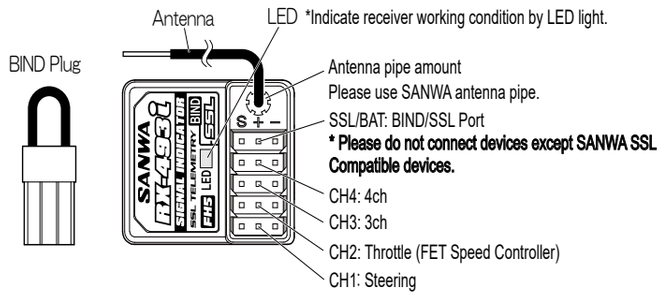
*About details of bind, please refer p.43-44 in this manual.





Connections and Installation of Receiver

ABOUT THE RECEIVER



Indication of Receiver Working Condition by LED light

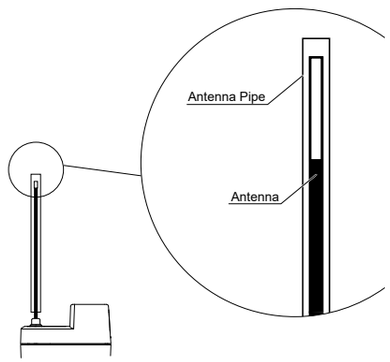
Connected	Blue light On *When binding with 2 transmitter, blue light flush at 2 sec intervals.
NOT Connected	——
In BIND Setting	Blue light flushing Blue light blinking
Battery Fail Safe Working	Blue and red light on
Receiver is not connected in Battery Fail Safe working	Red light on

● RX-493i

RX-493i can evaluate received signal strength and packet delivery ratio from transmitter.
*MT-R cannot check received signal strength and packet delivery ratio.
RX-493i can store 2 transmitter ID Number. It is able to combine using individual transmitter which is different setting in endurance race .
If you bind with 2 different transmitter, the receiver store the different transmitter and can operate by transmitters without re-bind.
*CANNOT operate by the 2 different transmitter at the same time. 2 ID store system is only compatible with M17, MT-5, or MT-R.
Throttle neutral position or operation quantities might be different each transmitter. Please adjust each transmitter setting to fit chassis linkage.
When setting SSL compatible devices by MT-R CODE AUX function, please connect SSL compatible device to SSL port.
MUST set fail-safe setting on each transmitter.
Please set same RF mode and response mode as 1st transmitter when you bind 2nd transmitter. If it was different mode, cannot bind with 2 transmitters.
*If 2nd transmitter was different RF node and response mode from 1st transmitter, 1st transmitter ID No. is deleted and only write 2nd transmitter.
*If you bound 3rd transmitter, 1st transmitter ID No. will be deleted.
*When using first time, please bind with receiver. (p.43)

ABOUT HANDLING THE ANTENNA

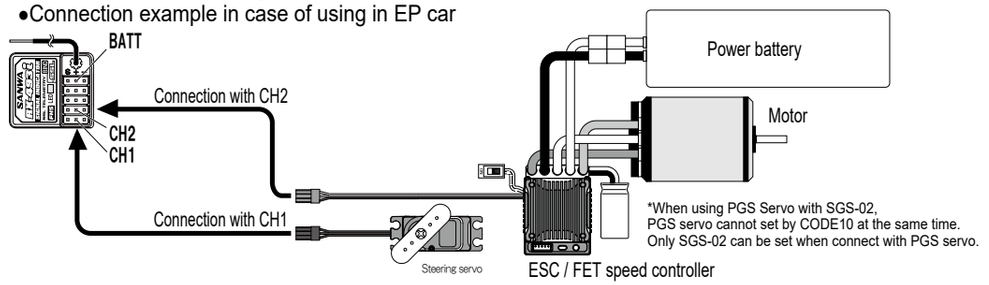
- Reception distance may vary depending on the location where the receiver and the antenna are installed.
- To protect the reception part (3 cm from the top) of the antenna, make sure to place the antenna in the antenna pipe as shown in the right illustration so that the top of the antenna is not exposed outside of the antenna pipe.
- Don't bend the antenna reception part or the antenna coaxial cable because breaking can occur inside.
- Don't pull the coaxial cable forcefully. It may damage the receiver interior.
- Install the antenna on an RC car so that the antenna reception part is in as high place as possible.
- Don't cut or bind the antenna reception part or the antenna coaxial cable since the receiver sensitivity might decrease.
- Keep the receiver antenna away from the motor and the ESC / FET Speed Controller (including cables) and raise it straight.

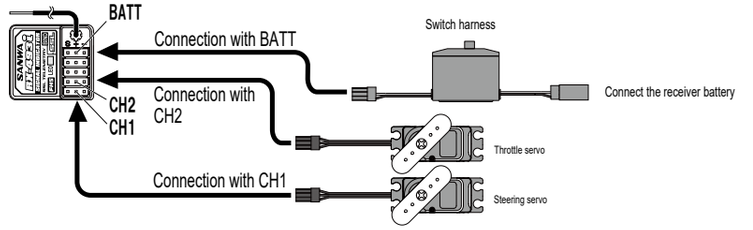


ABOUT CONNECTION SETUP

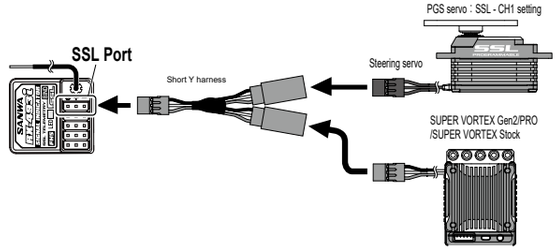
Please refer the below picture for receiver and servo connection

●Connection example in case of using in EP car



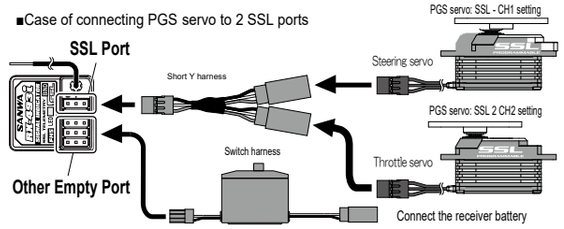


■Case of connecting PGS servo and SUPER VORTEX Gen2/PRO/SUPER VORTEX Stock to SSL port



●Set AUX TYPE of the transmitter for both AUX1, AUX2 to CODE 10.
AUX1 CODE10: Setting of SUPER VORTEX Gen2 / PRO /SUPER VORTEX Stock can be from the transmitter.
AUX2 CODE10: Setting of each of the parameters of PGSⅡ servo can be from transmitter.
Note)In SUPER VORTEX Gen2 / PRO, do not assign function to CODE 10 of AUX2 by code assign of PROGRAM BOX Gen2. It interferes with CODE 10 of AUX2 of PGS servo and suitable setting cannot be done.
Note)Set SSL−CH of PGS servo to [1].
(Factory setting of PGS servo is [1].)
Note)CODE of AUX2 is used for SUPER VORTEX ZERO / SUPER VORTEX TYPE-D / SUPER VORTEX SPORT. It interferes with CODE 10 of AUX2 of PGS servo and suitable setting cannot be done. Therefore, it cannot be used along with SSL of PGS servo.
Note)When Connecting PGS servo with SGS-02 cannot change setting at the same time.
When using SGS-02, Gain connector connect to SSL port.
*Please DO NOT connect another devices except SANWA SSL compatible products.
About setting and connection, please refer manuals of SSL compatible product.

■Case of connecting PGS servo to 2 SSL ports



●Set AUX TYPE of AUX2 of the transmitter to CODE 10.
AUX2 CODE10: Setting of each of the parameters of PGS servo can be done from the transmitter.
Note)Set SSL−CH of PGS servo used in steering servo to [1].
Set SSL−CH of PGS servo used in throttle servo to [2].
(Factory setting of PGS servo is [1].)
Note)In case of setting each parameter by the function of CODE10 of AUX2, setting of PGS servo of SSL−port set by CODE1 of AUX2 can be directly changed from the transmitter.
PGS servo not specified by CODE1 of AUX2 works on the parameters saved inside.

*Please, refer on our Website about any other examples. http://www.sanwa-denshi.co.jp

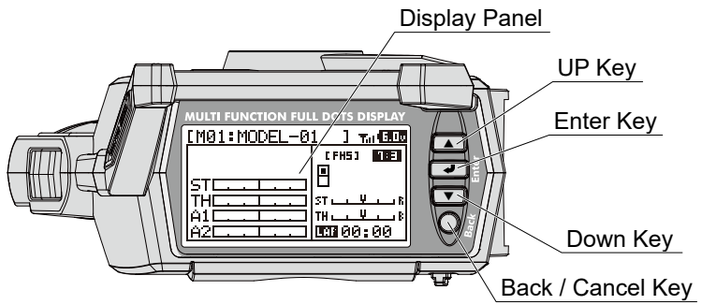
Note

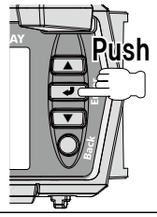
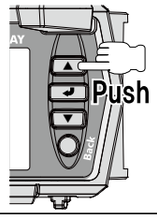
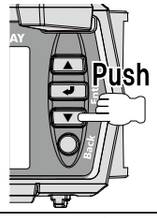
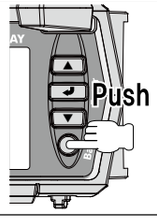
- If the connector is disconnected due to a vibration during operation, it can cause runaway. Connect the connector of the receiver, servos and switches securely.
- Because the receiver is susceptible to vibration, impact and water, make sure to take measures for vibration-proof and waterproof. Negligence of taking these measures can cause runaway.
- When installing the receiver, keep the receiver away from a carbon chassis and metallic chassis.
- If metal parts installed on an RC car touch each other, it can cause noise that affects reception performance and it can cause runaway.
- Make sure to install a noise killer condenser on the brush motor for electric RC cars. Without a noise killer condenser, it can cause noise and runaway.
- For R/C System parts such as the transmitter, receiver, servos, ESC (FET Speed Controller) and transmitter battery, use genuine SANWA products.
*When combining products other than genuine SANWA products, modifying, adjusting or exchanging parts is done at a place other than SANWA, we do not take any responsibility.

How to Use Each Feature

ABOUT KEY OPERATION

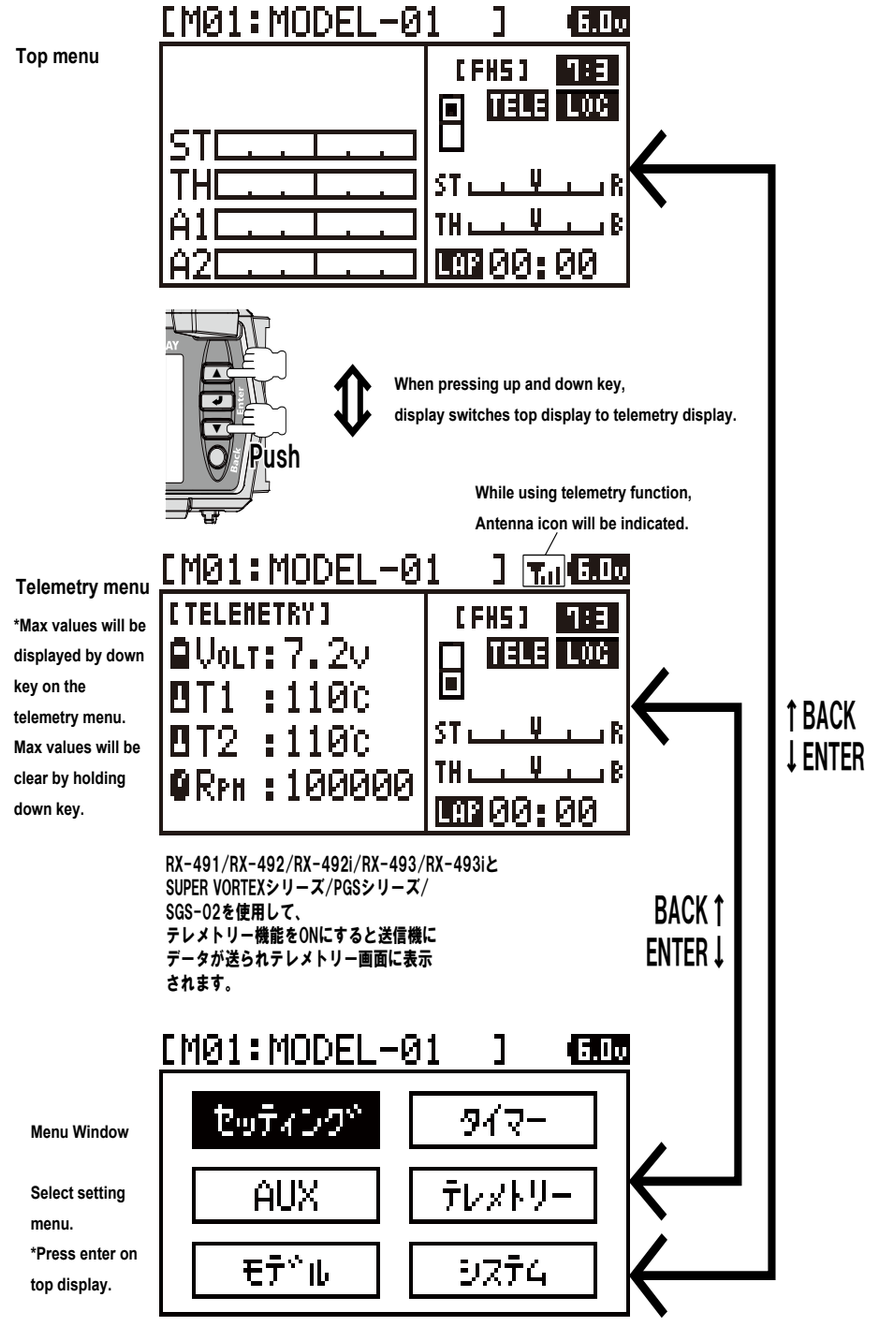
● The user can set up and make a calling easily with each key.



Key Operation	Names	Performance
	Enter	●Moves to the setup screen from the top screen. ●Selects a feature and item to set. *By holding the Enter, the setting goes back to default.
	UP	●The cursor moves upward. ●The setting value increases.
	DOWN	●The cursor moves downward. ●The setting value decreases.
	BACK / CANCEL	●Goes back to one step before. ●Cancel the setting.

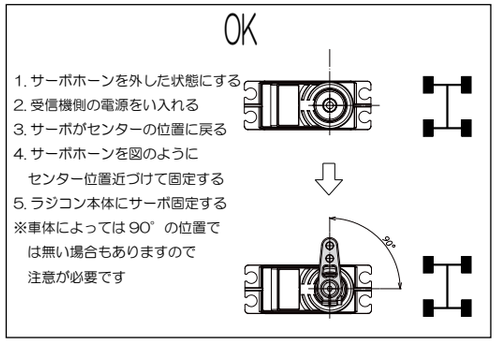
ABOUT DISPLAY PANEL

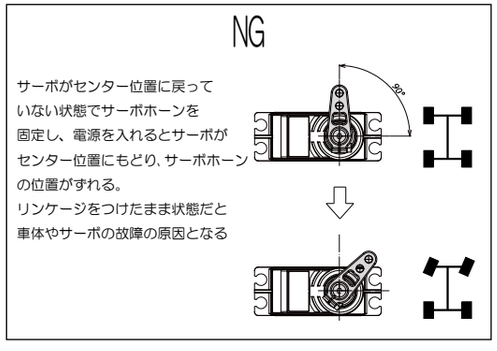
● Each feature of MT-R can be selected directly by each key.
● You can set up each channel feature separately.
● As you turn the power switch on, the top screen launches after the boost screen is displayed(when the boot setting is on). When changing each setting, select the menu by enter operation.



HOW TO PLACE SERVO ARM

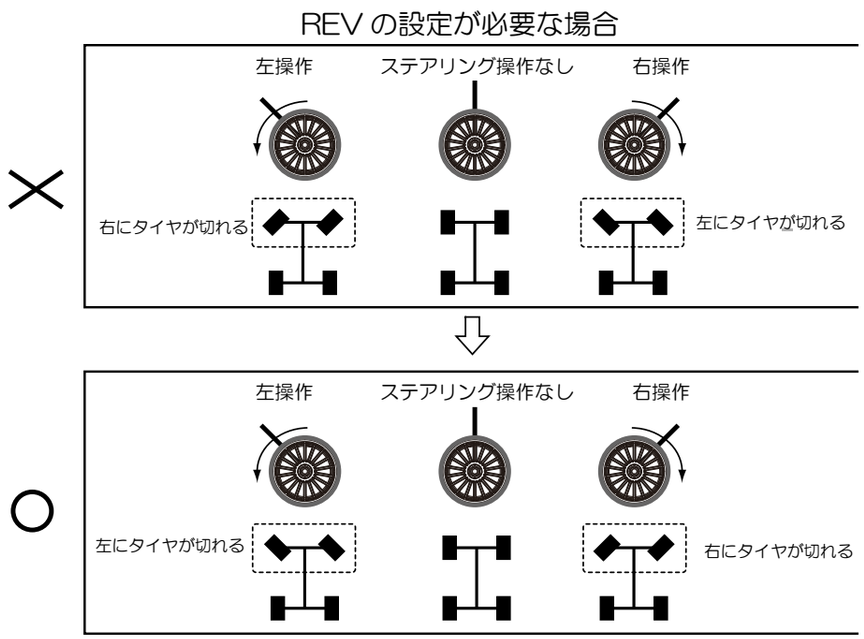
- Turn on binded receiver and transmitter before taking on servo arm.
- Power the servo will be returned neutral position.
- Be sure about transmitter Trim and Sub Trim are no setting (value is 0).
  In case Trim and Sub Trim did not set 0, please set 0 for these setting.
- Please place servo arm on center postion such as the below picture.
  *Servo horn angle may not be 90 degree depend on RC car type.
  Please place servo arm to follow instruction manual of RC car.





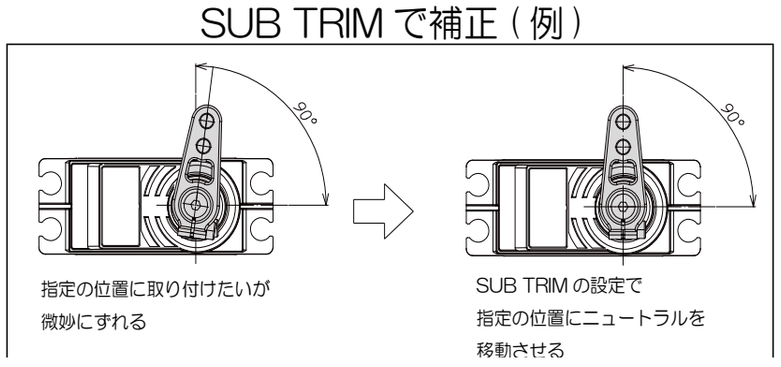
HOW TO SET REVERSE [REV]

- Please check steering operation and tire direction are same after taking on servo arm.
- Please set REVERSE in case steering operation and tire direction are diffrerent. About REVERSE setting please reffer p.22 in this manual.



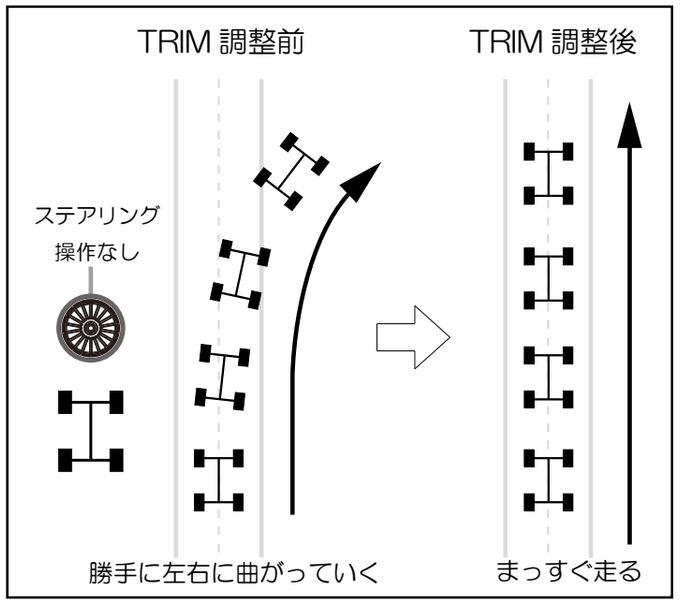
HOW TO SET SUB TRIM [SUB-T]

- In case servo cannot place correctly as 90 degree or RC Car manual instruction, please arrange neutral position by SUB TRIM setting. About SUB TRIM setting, please refer p.22 on this manual.



SUB TRIM AND TRIM DIFFERENCES

- SUB TRIM is for neutral position and mainly used on the pit as taking on servo arm.
  TRIM is for driving arrangement and mainly used while driving such as below picture. Please refer p.22 in this manual.

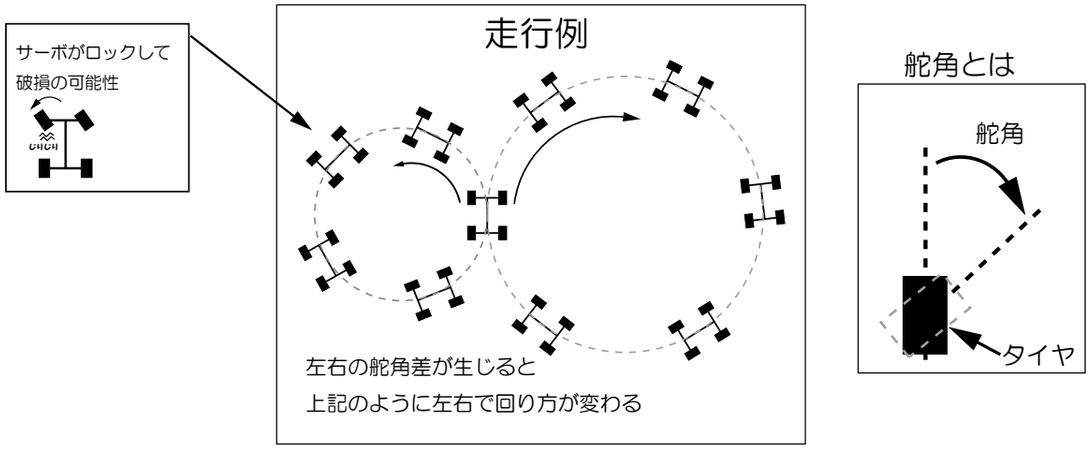


*RC car did not go straight as accident.
TRIM is used for direction alignment.

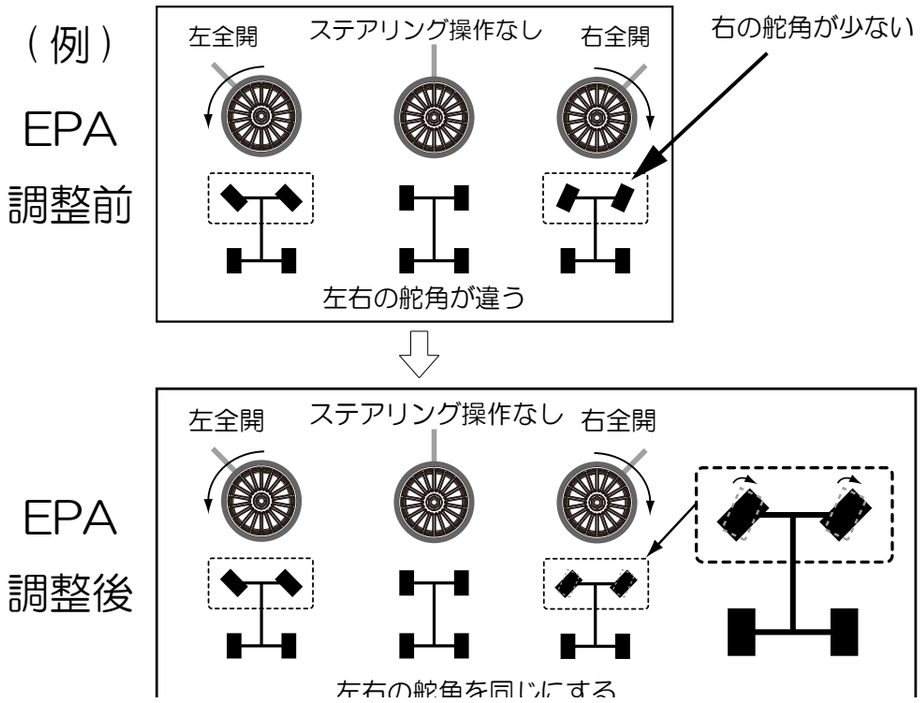
HOW TO SET END POINT ADJUSTMENT [EPA]

● Adjust right and left maximum steering angle are same after setting SUB TRIM.

*In case of not setting EPA, right and left cornering are different as the below picture.
This may be caused to servo broken. Please refer p.23 in this manual.



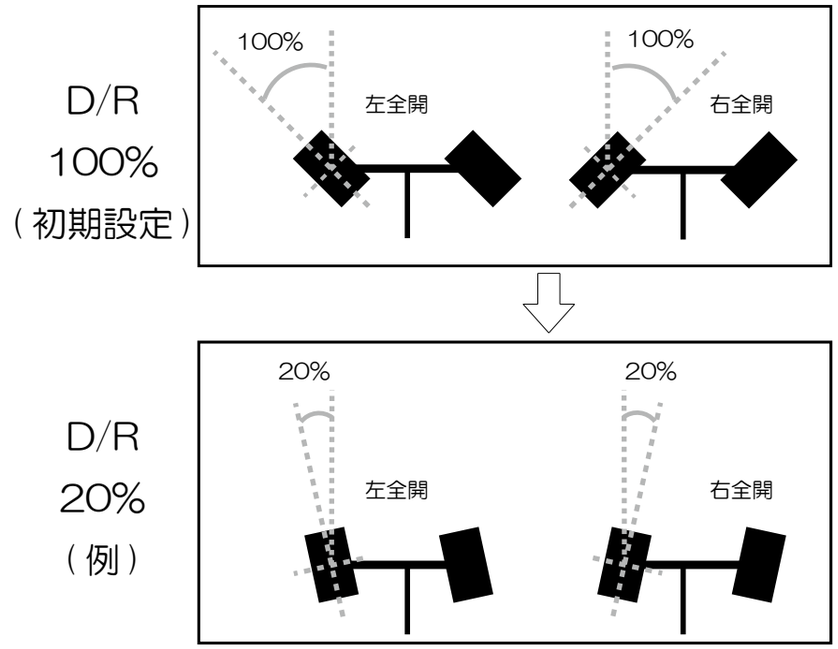
*Please arrange EPA setting as the below picture and make sure same maximum steering angles for both right and left.



HOW TO SET DUAL RATE [D/R]

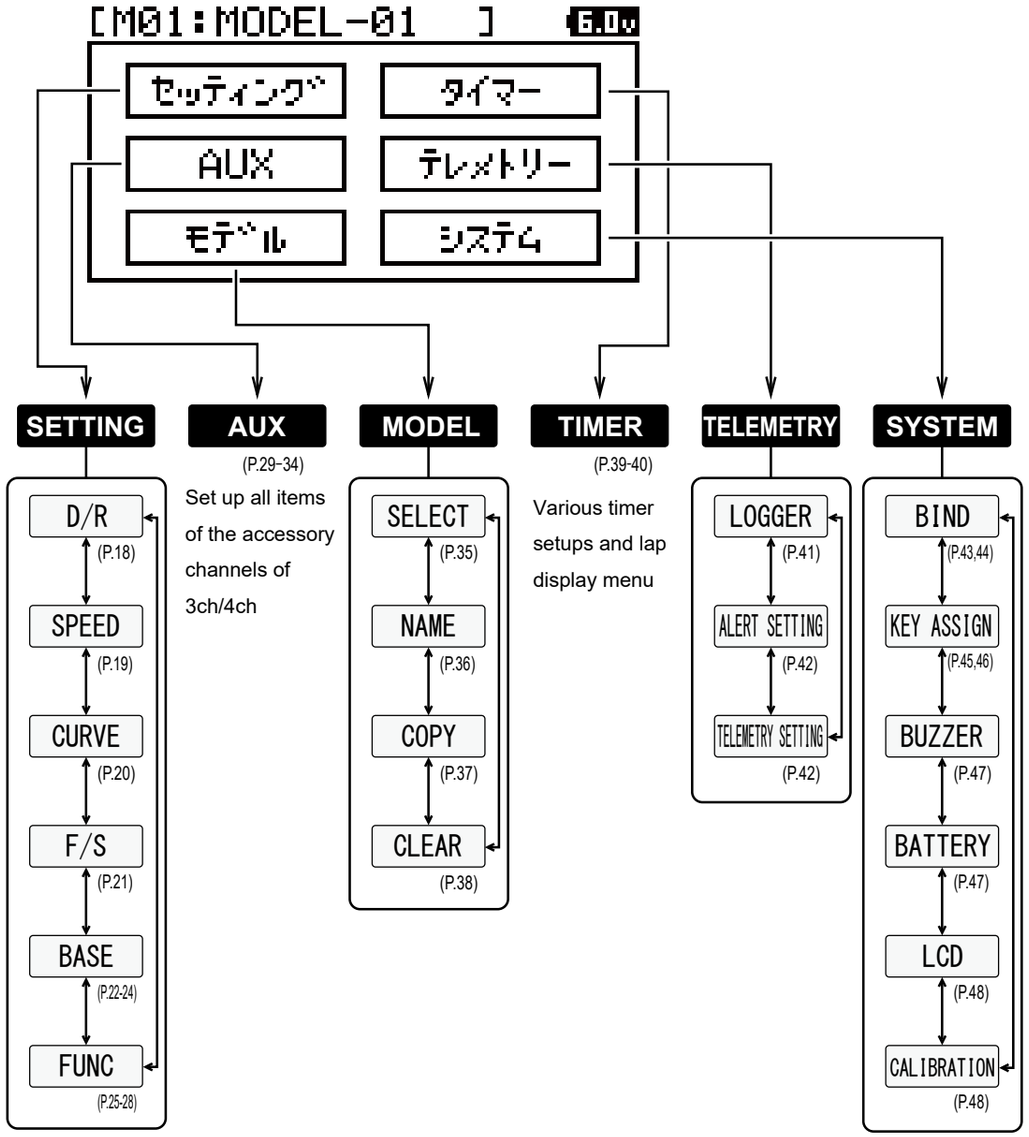
● About Steering Operation

In case RC car is over steering and difficult to drive, DUAL RATE(D/R) adjust maximum steering angle.
EPA adjust each left and right maximum steering angle.
D/R adjust both left and right maximum steering angle at the same time in same ratio.
Please refer p.18 in this manual.



ABOUT THE MENU STRUCTURE

- The user can set up features and do model memory call easily by using each key.
- The Menu consists of Setting, AUX, Model, Timer, Telemetry and System Menu, and related features are included in each menu.



DUAL RATE [D/R] SETTING

- You can adjust steering angle when operating the steering wheel and throttle trigger to their peak. Please adjust the steering angle to fit RC car and surface condition when driving.
  *You can adjust steering for both right and left at the same time and throttle separately for high and brake sides. You can also adjust the brake side more precisely than adjusting with EPA.
- Don't increase the setting rate of dual rates (D/R) from the condition in which the linkage locks by operating the steering wheel and throttle trigger.
- You can also adjust more precisely by adjusting dual rates of the throttle side.
  *A1 and A2 cannot be set even moving to D/R on A1 and A2 page.

1) Select features [ST/TH/BR] to adjust with the up and down key.

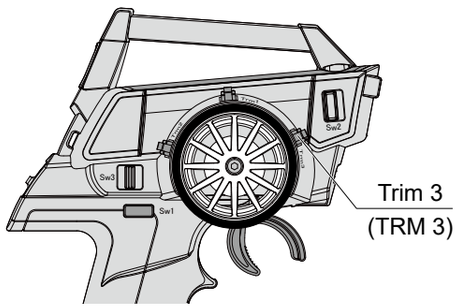
2) Determine the feature to adjust with the Enter key. Adjust the valus of DUAL RATE by up and down key.

3) During operation, the steering dual rates can be adjusted with Trim 3. It's possible to assign other features to Trim 3 with the key assign trim feature (P. 46).

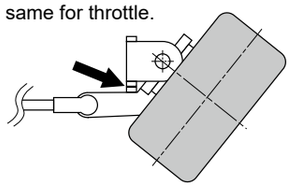
*When cancelling a selected feature, operate the Back key.
*Depending on car types, dual rate is not assigned to TRIM3.

○Setting Range:
ST/TH: 0%～100%
BR: 0%～120%

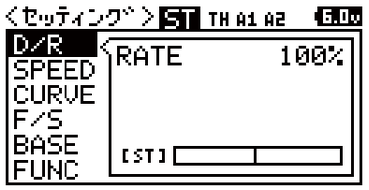
○Default:
ST/TH/BR: 100%



*Make sure that the servos do not lock to make clicking sound!
Note) The same for throttle.

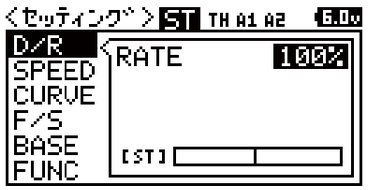


STEERING DUAL RATE SETTING DISPLAY



⇓ ENTER

STEERING DUAL RATE SETTING DISPLAY



NOTE ●If the linkage is locked for a long period, it can cause the servo motor breakage.

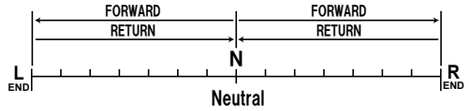
SUPPLEMENT ●Adjust the end point of the steering / throttle linkage before adjusting dual rate (P.23, 24)

SPEED — SETTING

● Features to control the speed of the servos used for steering and throttle. By setting, the RC car is not affected even when doing a sudden operation. On the steering side, smooth corner work becomes possible and on the throttle side, stable rising from a corner by throttle work with saved power.
*When setting AUX TYPE to [CODE], adjusting the speed feature of the AUX channel does not affect the performance.
*When setting the speed of the AUX channel, do so using steering/throttle as a reference.

[ST] STEERING SPEED

● A feature to delay the speed of the steering servos against the steering operation. You can set speed for steering forward and returning individually. For steering operation slower than setting, the speed feature does not work.



1) [ST (Steering)] with up and down key.
2) Setting on the forward side [FORWARD]
Select [FORWARD] with the Enter key and adjust the setting value by up and down key.
*When cancelling a selected feature, use the Back key.
◯Setting Range: 0～-100
◯Default: 0



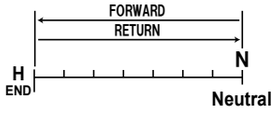
3) Setting on the Return side [RETURN]
Select [RETURN] with the Enter key and adjust the setting value with by up and down key.
◯Setting Range: 0～-100
◯Default: 0

*Adjust during actual operation. When not using the features or when a setting value cannot be determined even after adjustment, set the value to 0% (linear).

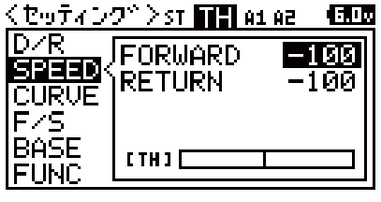
SUPPLEMENT
- For driving an RC car, steering operation that suits the movement of the RC car is important and excessive operation is not recommended. Steering speed can minimize unnecessary operation and enables smooth cornering.
- When steering speed and steering curve are combined, the effect is doubled.

[TH] THROTTLE SPEED

● A feature to slow down the performance speed of the throttle servos and delay the response of the speed controller against throttle operation. You can set speed for entering throttle (Forward) and returning (Return) individually. The speed feature does not work with throttle operation slower than the setting.
*Setting is only for High side and Brake side cannot be set.



1) Select [TH (Throttle)] with up and down key.
2) Setting on the forward side [FORWARD]
Select [FORWARD] with the Enter key and adjust the setting value by up and down key.
*When cancelling a selected feature, use the Back key.
◯Setting Range: 0～-100
◯Default: 0



3) Setting on the Return side (RETURN)
Select [RETURN] with the Enter key and adjust the setting value by up and down key.
◯Setting Range: 0～-100
◯Default: 0

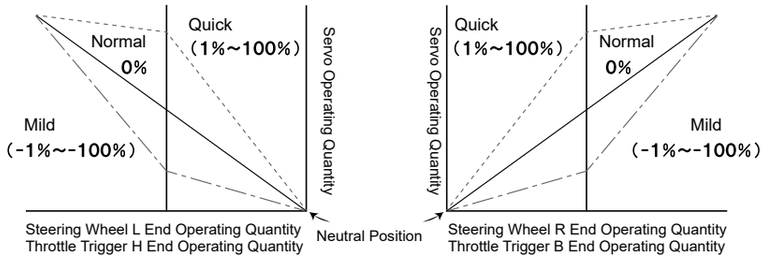
*Adjust during actual operation. When not using the features or when a setting value cannot be determined even after adjustment, set the value to 0% (linear).

SUPPLEMENT
- For driving an RC car, throttle operation that suits the movement of the RC car is important and excessive operation is not recommended. Throttle speed can minimize unnecessary operation and enables smooth performance.
- When throttle speed and throttle curve are combined, the effect is doubled.

CURVE — SETTING

● Curve changes servo work rate by steering and throttle position. It responds quickly when the set value is on plus (+) side whereas it responds mildly when the set value is on minus (-) side.
● MT-R has adjustable rate controller (ARC) of linear position.
*If the AUX type is set to [CODE], curve does not work.
*Please adjust curve setting on AUX cannel to refer steering and throttle.

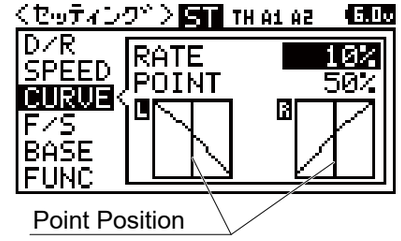
Adjustable rate controller (ARC)
Position at where operation is variable can be changed by adjusting the setting of POINT.



[ST] STEERING CURVE

● You can change the steering feature from Mild to Linear and to Quick.
If you find your RC car oversteering, change the setting to the minus side and if you find understeering, change to the plus side. Steering Adjustable Rate Control is a simultaneous setting for L and R.

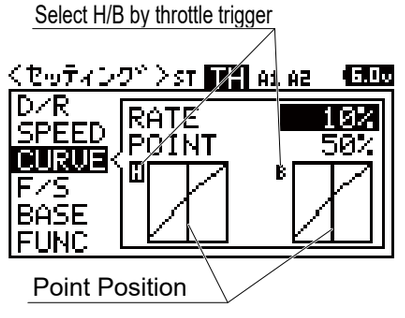
1) Select ST with up and down key.
2) Setting Rate [RATE]
Select [RATE] and adjust the setting value with up and down key.
*When cancelling a selected feature, use the Back button.
◯Setting Range: -100～100% ◯Default: 0%
3) Setting Point [POINT]
Select [POINT] and adjust the setting value with up and down key.
◯Setting Range: 5～95% ◯Default: 50%



[TH] THROTTLE CURVE

● You can change the throttle feature from Mild to Linear and to Quick.
In general, when operating on a slippery road or if you find over powering, change the setting to the minus side. When operating on a high-grip road or if you find lack of power in the power unit, change to the plus side. You can set the High side and the brake side separately.
*Selection of the High side and the brake side is done by trigger operation.

1) Select TH with up and down key.
2) Setting Rate [RATE]
Select [RATE] with with up and down key.
Adjust the setting value.
◯Setting Range: -100～100% ◯Default: 0%
3) Setting Point [POINT]
Select [POINT] with up and down key.
Adjust the setting value.
◯Setting Range: 5～95% ◯Default: 50%
*When cancelling a selected feature, use the Back button.



1.If you feel slippy while driving drift car, please set High side point 20 to 30% and Rate -15 to - 30%. It can be more smooth and getting traction easily. *Please arrange ideal point and rate values while driving.

2. In case of using motor of stock class, please set High side point 20 to 30% and Rate 15 to 30%. It would give quick throttle timing and get more car acceleration.

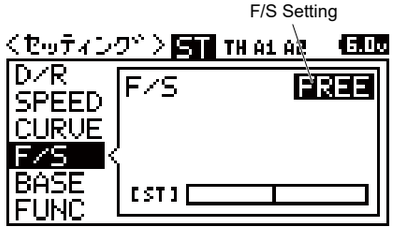
FAIL SAFE [F/S] — SETTING

● Fail Safe Operation is a feature to keep the servos in a predetermined position for each channel in the event that the receiver cannot receive a signal from the transmitter. A feature to keep the servos in a predetermined position for the servo of the throttle channel (2ch) in the event that the battery voltage on the receiver side of an engine RC car goes below the set voltage is Battery Fail Safe Operation.

● Battery Fail Safe Operation cannot be set when the throttle channel (2ch) is set to FREE/HOLD (*Battery Fail Safe Operation works only for the throttle channel).
*Don't use Battery Fail Safe Operation for electric RC cars.

1) Select F/S with up and down key and select a channel to set fail safe operation (ST/TH/A1/A2).

2) Enter the set channel and operate by up and down key.
The fail safe mode setting changes in order of
FREE→FS→HOLD.
○Setting Range: FREE/FS(-100～100%)/HOLD
○Default: FREE



FREE (Free Mode)
When thre receiver cannot receive the signal from the transmitter, the signal output to the servo stops and the servo will be free.

FS (Fail Safe Mode)
When the receiver cannot receive the signal from the transmitter, the servo will be held in the set position.

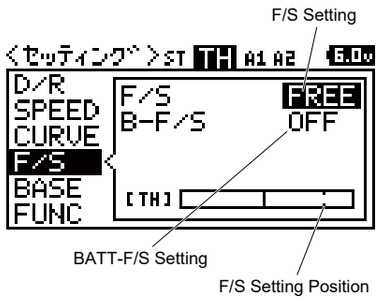
HOLD(Hold Mode)
The last postion before the signal from the transmitter to the receiver is lost will be held.

*When the receiver can receive the signal from the transmitter again, each mode of FREE/HOLD/FS is automatically released.

3) Setting the Fail Safe (FS)
Move to the position where the Fail Safe Operation is used. When the position is determined, holding the Enter key to set the position when the Fail Safe Operation works.
*For safety, we recommend setting the throttle channel on the brake side when setting the Fail Safe.

4) Setting the Battery Fail Safe Operation
After setting the throttle channel position, move the cursor to [B-F/S] to set the voltage.
○Setting Range: OFF, 3.5v ～7.4v
*The Battery Fail Safe Operation is a feature to activate Fail Safe Operation when the receiver battery voltage belows to the set voltage on a Nitro car.
Don't use the Battery Fail Safe feature on electric RC cars.

5) Checking the Fail Safe Operation
Turn off the power of the transmitter while the Fail Safe Operation is set and check if the servo moves to the position where the Fail Safe Operation is set.



IMPORTANT
• About the Fail Safe Operation
When the Fail Safe feature is on, check the setting of the Fail Safe before operating.
Don't change the setting of the Fail Safe during operation.

BASE — SETTING

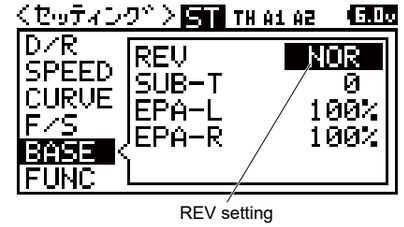
● Base sets multiple functions all at once such as the Reverse that determines the direction of the servo of each channel, the speed controller according to a specific RC car, the Sub Trim that adjusts the neutral position, and the End Point Adjustment [EPA].

REVERSE [REV]

● This is used when operation and the movement of the servo are reversed while operating Steering/throttle/AUX1/AUX2.

1) Select BASE with up and down key
Select a channel to set (ST/TH/A1/A2).

2) Enter with the channel to be set by using up and down key.
The Reverse setting will be changed.
*When cancelling a selected feature, use the back key.
○Setting Range: NOR/REV
○Default: NOR



SUB TRIM [SUB-T]

● Using the Sub Trim feature, correct the neutral (center) of Steering/Throttle/A1/A2 so that Trim can be used from the center position. When installing a servo on to an RC car, center the servo with Sub Trim first before adjusting End Point Adjustment.

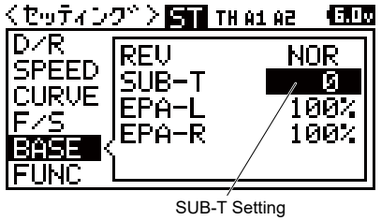
1) Before using, center (0) each main trim.

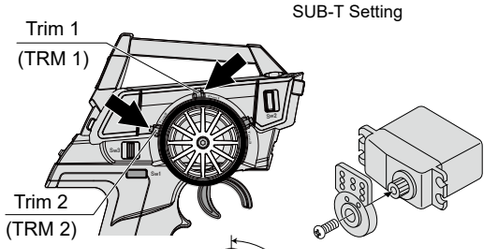
2) Select SUB-T with up and down key
Select a channel (ST/TH/A1/A2) to adjust Sub Trim.

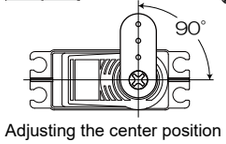
3) Set the channel by Enter key.

4) Install the servo arm (servo saver arm) as close to centered as possible.
*For installation position of the servo horn, follow a car product instruction.

5) Adjust the center by using up and down key.
○Setting Range:L150～R150(ST)
H150～B150(TH)
H150～L150(AUX1, AUX2)
○Default: 0





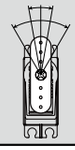


Adjusting the center position

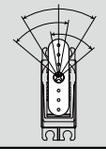
Note
When installing the servo horn onto your servo, fix the servo horn as close to the center as possible and center it with Sub Trim.
If Sub Trim and the transmitter main trim are off to one side, it causes dead band (the range the servo does not move) to the steering wheel and the throttle trigger.

●About Trim and Sub Trim
Trim is a feature for adjusting the neutral (center) position of the servo. When your model does not run straight after installing the steering servo onto the model, Trim adjusts the main trim of the steering. Also, the neutral position of the carburetor on RC cars needs neutral adjustment of the throttle servo along with linkage adjustment after installing the servo. Neutral position adjustment is necessary not only after installing the servo but for changes that happen during running such as tire wears and chassis twist. MT-5 Trim features two types of Trim including Center Trim that adjusts only the neutral position without changing the end of the operating angle and Parallel Trim that moves the end of the operating angle and the neutral position simultaneously. Sub Trim that adjusts the neutral (center) position before fixing the servo horn is Parallel Trim and the main trim is Center Trim.

○Center Trim (Main Trim)
Even if you move the neutral position with Trim, the end of the operation angle does not move.



○Parallel Trim (Sub Trim)
When you move the neutral position with Trim, the end of the operation angle also moves.When Sub Trim is adjusted after linkage is completed, readjustment of End Point Adjustment (EPA) will be necessary.



BASE　SETTING

● Base sets multiple functions all at once such as the Reverse that determines the direction of the servo of each channel, the speed controller according to a specific RC car, the Sub Trim that adjusts the neutral position, and the End Point Adjustment [EPA].

END POINT ADJUSTMENT [EPA]

● EPA setting can adjust left and right steering servo range for steering operation, high and brake throttle working range for throttle trigger operation, and the servo working range for AUX1, AUX2 (3ch, 4ch).

[ST-EPA] STEERING END POINT ADJUSTMENT

● Due to linkage, suspension balance and the difference of the tire diameter, left and right cornering radius can be different. In case of this, this feature adjusts the servo working range of left and right so that left and right cornering radius can be the same.

1) Before adjusting Steering End Point Adjustment (ST-EPA), make a neutral adjustment of the servo (P.22). Neutral adjustment is to align the center position with Sub Trim by turning the power on and installing the servo horn in the approximate center position.

2) Select either of [EPA-L/EPA-R] with up and down key Determine with the Enter.

3) Adjust the working range with up and down key.
*When the cursor is on either of EPA-L/EPA-R, it is also possible to move the cursor by steering operation.

○Setting Range:L/R 0%～150%
○Default: L/R 100%



[TH-EPA] THROTTLE END POINT ADJUSTMENT

● It adjusts the High Point of FET Speed Controller, Brake Point, carburetor of engine and the brake working range.

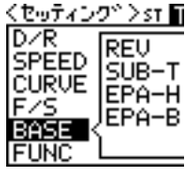
1) For a nitro car, make a neutral adjustment of the servo (P.20) before adjusting the Throttle End Point Adjustment (TH-EPA). Neutral adjustment is to align the center position with Sub Trim by turning the power on and installing the servo horn in the approximate center position.

2) Select [TH/Throttle] with up and down key.

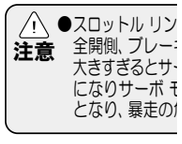
3) Select either of [EPA-H/EPA-B] with up and down key. Determine with the Enter.

4) Adjust the operating quantity with up and down key. When adjusting ESC / FET Speed Controller, normally set both the high side and the brake side to 100% and set neutral, high point and brake point on the ESC / FET Speed Controller side (Setting method is different depending on the ESC / FET Speed Controller).
*When the cursor is on either of EPA-H/EPA-B, it is also possible to move the cursor by trigger operation.

○Setting Range:H/B 0%～150%
○Default: H/B100%







[AUX1-EPA] AUX1・END POINT ADJUSTMENT

● You can use AUX1 for functions of accessories and adjust the maximum steering angle with EPA. Since you can set H/L separately, precise adjustment is possible.
*When setting AUX1 to [CODE5/CODE10] in AUX TYPE, the operation will not be refected even by adjusting EPA.

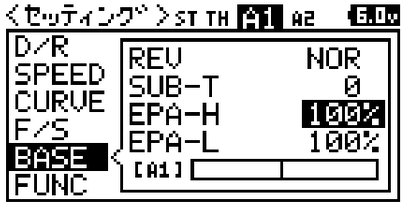
1) Before adjusting AUX1 End Point Adjustment (A1-EPA), make a neutral adjustment of the servo (P. 22). Neutral adjustment is to align the center position with SubTrim by turning the power on and installing the servo horn in the approximate center position.

2) Select [AUX1] with up and down key.

3) Select either of [EPA-H/EPA-L] with up and down key. Determine with the Enter.

4) Adjust the working range with up and down key.

○Setting Range:H/L 0%～150%
○Default: H/L100%



[AUX2-EPA] AUX2・END POINT ADJUSTMENT

● You can use AUX2 for functions of accessories and adjust the maximum steering angle with EPA. Since you can set H/L separately, precise adjustment is possible.
*When setting AUX2 to [CODE5/CODE10] in AUX TYPE, the operation will not be reflected even by adjusting EPA.

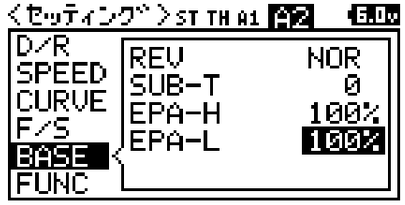
1) Before adjusting AUX2 End Point Adjustment (AUX2-EPA), make a neutral adjustment of the servo (P. 22). Neutral adjustment is to align the center position with Sub Trim by turning the power on and installing the servo horn in the approximate center position.

2) Select [AUX2] with up and down key.

4) Select either of [EPA-H/EPA-L] with up and down key. Determine with the Enter.

3) Adjust the working range with up and down key.

○Setting Range:H/L 0%～150%
○Default: H/L100%



How to Use Each Feature

FUNCTION [FUNC]　SETTING

● Function can set trim, ALB (Anti-Lock Brake), OFFSET, and TH TYPE (Throttle Type) on each channel.

TRIM

● Correct neutral (center) of each channel (ST/TH/A1/A2) with Trim.
● As default, steering is set for Trim 1 (TRM1), and throttle for Trim 2 (TRM2).

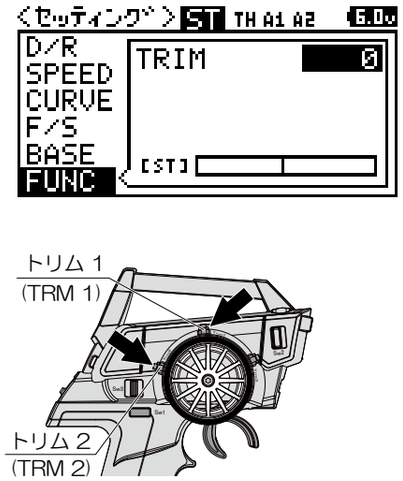
1) Select a channel (ST/TH/AUX1/AUX2) for adjusting Trim with up and down key.

2) Determine with Enter operation and adjust with up and down key.

○ Setting Range:
ST:L100～R100
TH:H100～B100
AUX1:H100～L100
AUX2:H100～L100

○ Default:
ALL : 0

*Make an adjustment with TRM1 (ST) and TRM2 (TH) during operation.You can change the Trim lever position with the Key Assignments Trim feature (P. 46).



重要

●トリムについて
トリムとは、サーボのニュートラル(センター)位置を調整する機能です。
ステアリング サーボを車体に搭載後、走行させて直進しない場合にトリムを調整します。
ニュートラル位置の調整は、サーボ搭載後におこなうだけでなく、タイヤの磨耗やシャシーのねじれなど走行中の変化に対応するためにも必要になります。
●リンケージ調整をするときにセンター位置を調整するのはサブ トリムです。(P.22)

注意

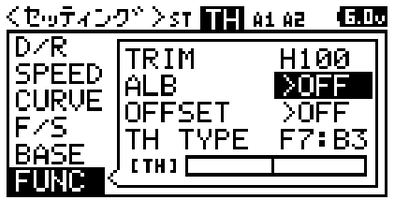
●トリムとサブ トリムが片側にかたよると、ステアリング ホイールやスロットル トリガーにデッドバンド(サーボが動かない領域)が発生します。サーボにサーボホーンを取り付ける際にできるだけセンターに近い位置で固定してサブ トリムでセンター出してください。

ANTI-LOCK BRAKE [ALB]

● Anti-Lock Brake enables stable braking on a low grip road.
● Because of the stable braking, you can drive ideal cornering lines as intended.

1) Select [ALB] with up and down key.

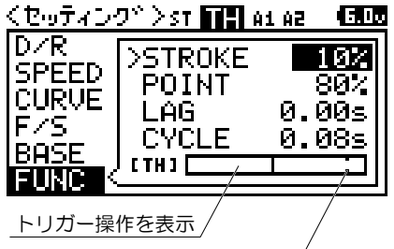
2) The menu changes to ALB setup menu with the enter operation.



ENTER (エンター)　BACK (バック)

3) Setting Stroke (STROKE)
Set Stroke of ALB with up and down key.
Stroke is the width of repeated actions at the time of braking.
○Setting Range:OFF, 0%～100%
○Default:OFF　*ALB does not work when it is off.

4) Setting Point (POINT)
Set Point of ALB with up and down key.
Point is the position where ALB starts acting when operating the brake.
○Setting Range: 5%～100%
○Default: 80%

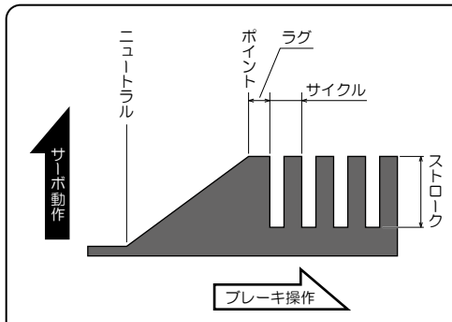


5) Setting Lag (LAG)
Set Lag of ALB with up and down key.
Lag is a setting of time lag from the time when operating to the point to the time when ALB starts acting.
○Setting Range: 0.00s～1.00s
○Default: 0.00s

6) Setting Cycle (CYCLE)
Set a cycle of ALB with up and down key.
Cycle is a frequency setting of repeated actions for braking.
○Setting Range: 0.01s～1.00s
○Default: 0.03s

*While Anti-Lock Brake working, transmitter LED will be high-speed flashing.

*LED flashing time and way of flashing are same in any setting values.



※ポイントの位置からフルブレーキに操作しているときにALBが動作します。

補足

●RCカーのタイヤがグリップ力を失わない(すべらない)程度にブレーキを強めに効かせ、タイヤがロックしてすべる寸前にアンチ ロック ブレーキが働くように調整してください。
●電動RCカーでバック付きスピードコントローラーを使用してALBを設定するとバックの動作が出来なくなる場合があります。バック動作を使用する場合にはALBをOFFにしてください。

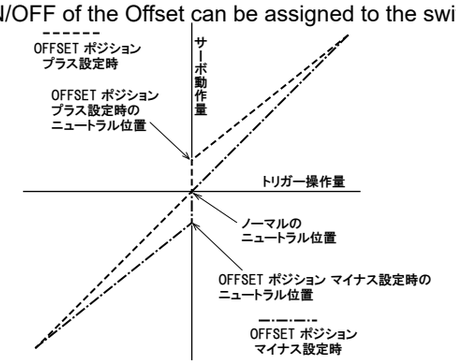
FUNCTION [FUNC]

SETTING

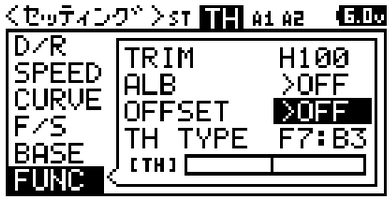
● Function can set trim, ALB (Anti-Lock Brake), OFFSET, and TH TYPE (Throttle Type) on each channel.

OFF SET

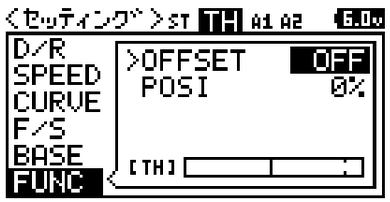
● By moving the position of the throttle neutral at the time of starting a nitro RC car engine, it improves the start-up performance of the engine.
● You can fix at a position where idling speed is increased so that the engine will not stop during refueling your nitro RC car.
● By operating the switch that has been set, you can stop the engine of your RC boat.
● You can use various power sources with Offset feature.
● ON/OFF of the Offset can be assigned to the switch.



1) Select [OFFSET] with up and down key.
2) Determine with enter operation.
   It will change to OFFSET Setting menu.
3) Setting Offset [OFFSET]
   Set ON/OFF of the Offset feature with up and down key.
○ Setting Range: ON/OFF
○ Default: OFF
4) Setting Position [POSI]
   Set Position of the Offset with up and down key.
○ Setting Range: H100%～B100%
○ Default: 0%



ENTER (エンター) ⬇ ⇧ BACK (バック)

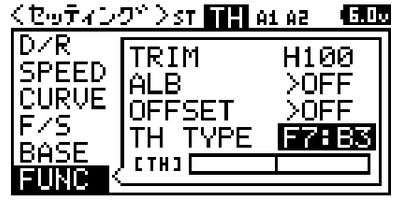


THROTTLE TYPE [TH TYPE]

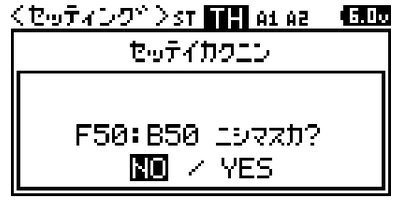
● You can move the neutrals position of the throttle and set the operating ratio of the forward side and the brake (backward) side to either 7:3 or 5:5.
*Set the throttle type according to the speed controller to be used.

1) Select [TH TYPE] with up and down key.
2) Determine with enter operation.
   It will change to TH TYPE Setting menu.
3) Setting the Throttle Type
   Set the Throttle Type with up and down key.
○ Setting Range: F7:B3 / F5:B5
○ Default: F7:B3

*When changing TH TYPE, the screen changes to the confirmation screen and a message is displayed. Operate following the message.



ENTER (エンター) ⬇ ⇧ BACK (バック)



・NO →スロットル タイプ変更キャンセル
・YES →スロットル タイプ変更確定

AUX

AUX

● AUX menu sets the performance of AUX1 and AUX2 (3ch, 4ch). You can choose from STEP AUX (STEP), POINT AUX (POINT), 4WS (4-Wheel Steering: Coordinate Phase, Opposite Phase). MOA (Motor On Axle), AUX-MIX (AUX Mixing: ST → AUX/TH-AUX) and CODE-AUX.

STEP AUX

● Setting Step AUX allows you to set the operating quantity by operating assigned Trim or a switch.
● By factory default, the AUX feature is set to the Step AUX.

1) Select [AUX] with up and down key.

2) Determine with enter operation.
It will change to CH Setting menu.

3) Setting Step AUX (STEP AUX)
Determine [CH] to activate with the enter.
Set the position of the motion with up and down key.

*Operating range also can be set by
EPA (End Point Adjustment, P.24).

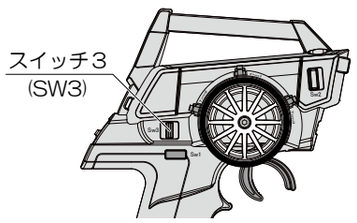
○ Setting Range: H100% ～L100%
○ Default: 0%

4) Mode Setting (MODE)
Determine with enter, and set working step values to the used method.

○ Setting Range: 1/2/5/10/20/25/50/100
○ Default: 5

SET can be AUX TYPE and MODE setting and shortcut of the key assign function.
*Assign the features to Trim and switch with Key Assignments according to the used method.





POINT AUX

● By setting Point AUX and assigning the movement of AUX1/AUX2 (3ch, 4ch) to the switch and Trim, you can move the servo to Point1, Point2, and Point3 position.
The Point that moved can be set with EPA (End Point Adjustment). Adjust the Point position according to the usage.
*Point number is 3 point cannot change.

1) Select [AUX] with up and down key.

2) Change [SET] menu with enter.
*Switch CH to SET with up and down key.

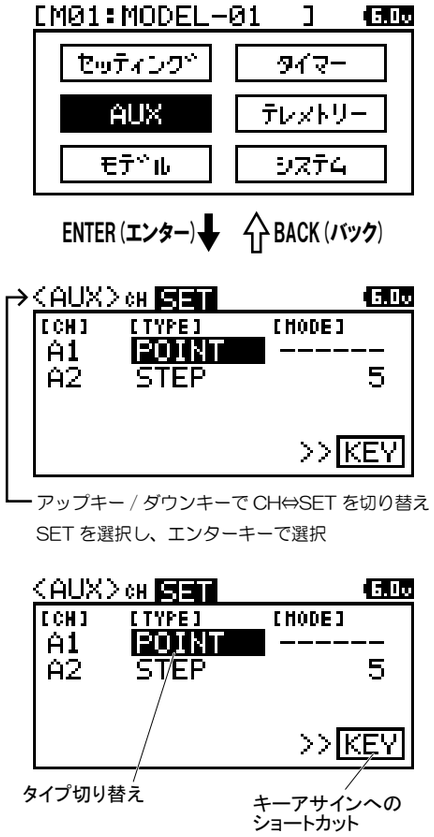
3) Type Setting (POINT)
Select [POINT] on AUX TYPE with up and down key.

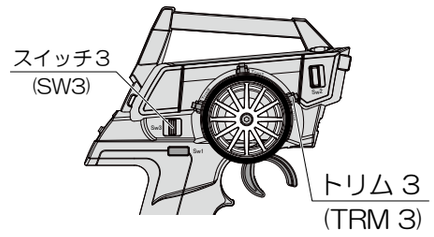
4) Point and setting values
Select A1 or A2 you want to set and enter.
Select 1, 2, or 3 you want to set and enter.
Set values with up and down key.

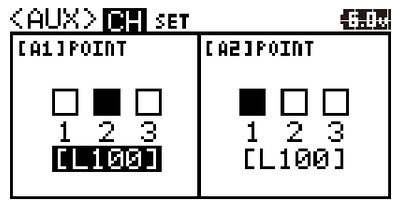
*AUX1 and AUX2 can be set AUX TYPE separately.

*Operating range also can be set by
EPA (End Point Adjustment, P.24).

*Assign on SW3 or trim according to the used method.







AUX

AUX

● AUX menu sets the performance of AUX1 and AUX2 (3ch, 4ch). You can choose from STEP AUX (STEP), POINT AUX (POINT), 4WS (4-Wheel Steering: Coordinate Phase, Opposite Phase). MOA (Motor On Axle), AUX-MIX (AUX Mixing: ST → AUX/TH-AUX) and CODE-AUX.

4-WHEEL STEERING [4WS]

● With the operation of assigned Trim or Switch, control the motion of the 4 Wheel Steering.

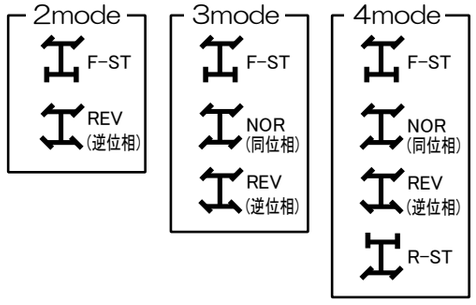
1) Select [AUX] with up and down key.

2) Change [SET] menu with enter.
*Switch CH to SET with up and down key.

2) Type setting (4WS)
Select [4WS] on AUX TYPE setting with up and down key.

4) Mode setting
Set 4WS working mode to used method.

○Setting Range: 2 mode / 3 mode/ 4 mode
○Default: 4 mode

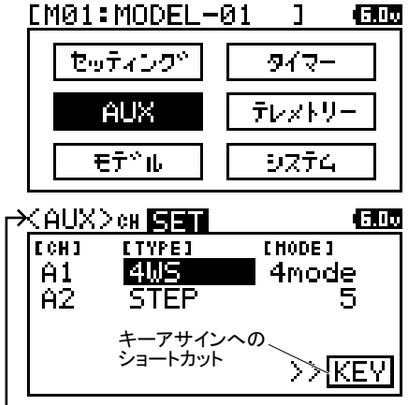


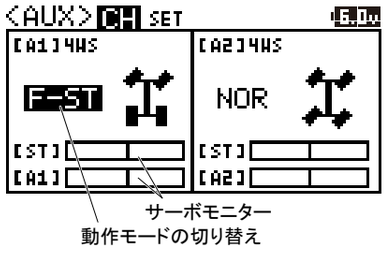
*Please refer the above picture for working mode.

5) Working mode setting
Enter working mode setting and change the mode with up and down key.
*In case of changing mode while driving, please asign workig mode on trim or switch.

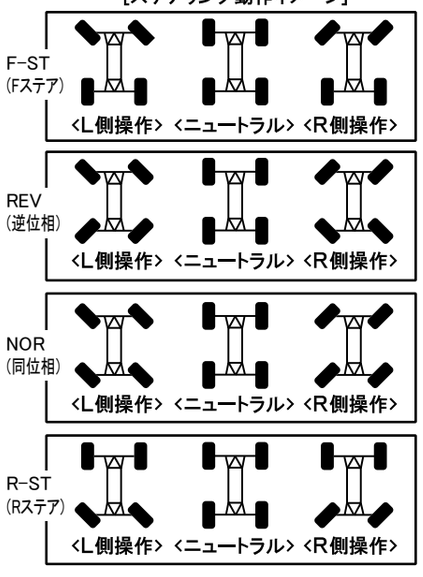
○Setting range: F-ST / REV / NOR / R-ST

* Switch working mode by mode setting on SET.
* Rear steering servo will work on AUX 1 or AUX channel by setting 4WS.
*Operating range can be set by EPA (End Point Adjustment, P.24).





[ステアリング動作イメージ]



FRONT-REAR WHEEL SEPARATE DRIVE [MOA]

● By setting Motor On Axle (MOA), you can adjust the drive ratio of front and rear wheels of a front-rear dual motor car.

1) Select [AUX] with up and down key.

2) Change [SET] menu with enter.

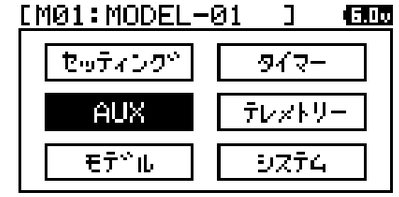
3) TYPE setting (MOA)
Select [MOA] on AUX TYPE setting with up and down key.

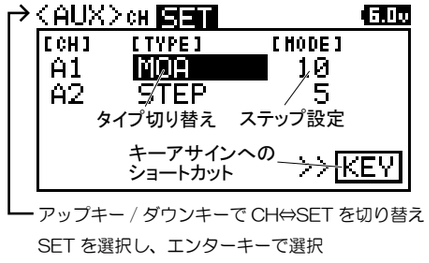
4) MODE setting
Set MOA drive ratio to the used method.

Setting Range: 1/2/5/10/20/25/50/100
Default: 10

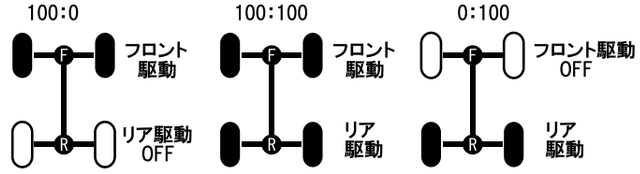
*Connect the speed controller for controlling the rear motor to the channel (AUX1/AUX2) that is set to MOA.

*When using, assign the features to switch or trim or operate with up and down key.

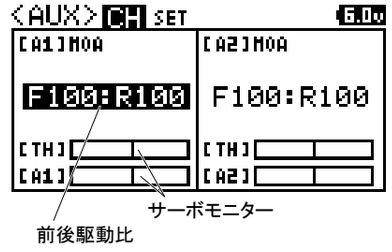




[MOA動作イメージ]



※比率を変更することで前後の駆動比を調整できます。



AUX

AUX

● AUX menu sets the performance of AUX1 and AUX2 (3ch, 4ch). You can choose from STEP AUX (STEP), POINT AUX (POINT), 4WS (4-Wheel Steering: Coordinate Phase, Opposite Phase). MOA (Motor On Axle), AUX-MIX (AUX Mixing: ST → AUX/TH-AUX) and CODE-AUX.

AUX MIXING [AUX MIX]

● Setting AUX Mixing allows you to mix from the steering to AUX and from the throttle to AUX.

1) Select [AUX] with enter.

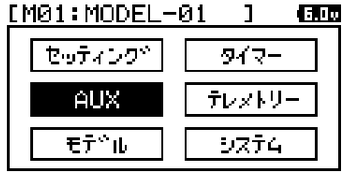
2) Change [SET] menu with enter.
*Switch CH to SET with up and down key.
3) TYPE setting (AUX-MIX)
Select [AUX-MIX] on AUX TYPE setting with up and down key.
4) MODE Setting
Set mixing mode to the used method.

◯Setting Range: ST-mix / TH-mix
◯Default: ST-mix
*ST-mix is mixed from the steering to AUX.
TH-mix is mixed from the throttle to AUX.

5) Mixing rate setting
Set mixing rate with up and down key.

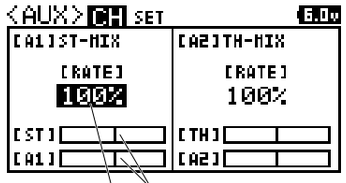
◯Setting Range: 0%～100%
◯Default: 100%

*Assign the features of the Mixing Rate to Trim or the switch with Key Assignments, or operate with up and down key.





アップキー / ダウンキーで CH⇔SET を切り替え
SET を選択し、エンターキーで選択



CODE AUX

● Code AUX (CODE AUX) is a feature to perform code communication by assigning a setting value to each code of CODE1-CODE10.
It is an extension feature to change the setting of speed controller (SUPER VORTEX series/ SV-D2), PGS servo series, and the Gyro System (SGS-01C/SGS01D/SGS-02) that are compatible to CODE AUX.
● You can set 2 types of Code AUX1 and CODE AUX2.
*Please set response mode [SHR] on A1 and A2 when binding with a receiver. (p.43).
*In case of using CODE AUX, please do NOT conect servos on receiver CH3 and CH4 port.

1) Select [AUX] with up and down key.

2) Change [SET] setting menu with enter.
*Switch CH to SET with up and down key.

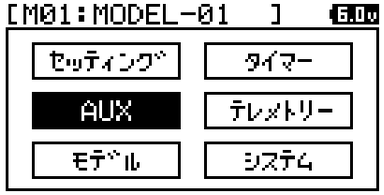
3) Type Setting (CODE AUX)
Select [CODE] on AUX TYPE setting with up and down key.
*CODE is only compatible with CODE10 products.
*MT-R is not compatible with CODE5 products such as SV-ZERO, SV-SPORT, SV-TYPE D, SGS-01, and SGS-01D.

4) Mode setting
Display function name for CODE10 products by setting mode for compatible product.

◯Setting Range: CODE/SV-G/D(only AUX1)
CODE/PGS/SGS-02 (only AUX2)
◯Default: CODE

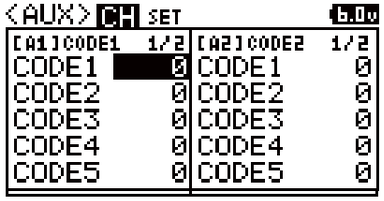
5) CODE AUX setting
Select CODE with enter you want.
Set value with up and down key.

*In case of setting CODE on AUX TYPE, CODE AUX setting condition will display on top screen as below pictures.

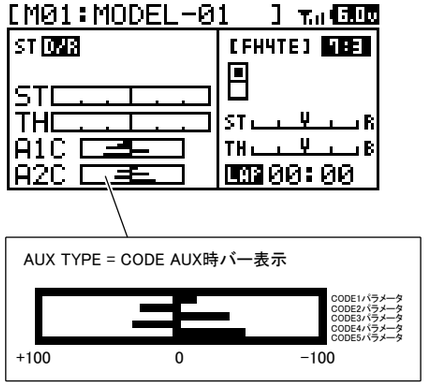




アップキー / ダウンキーで CH⇔SET を切り替え
SET を選択し、エンターキーで選択



MODE設定が[CODE]の場合



※CODE6～10はTOP画面には表示されません。
AUXメニューにある表示を確認してください

MODEL MENU

MODEL

● You can set the features about Model Select, Model Name, Model Copy and Model Clear.
● Installed with high capacity EEPROM and it can memorize data for 20 models of M01 ~ M20.

MODEL SELECT

● You can call model data of memorized M01 ~ M20 easily.

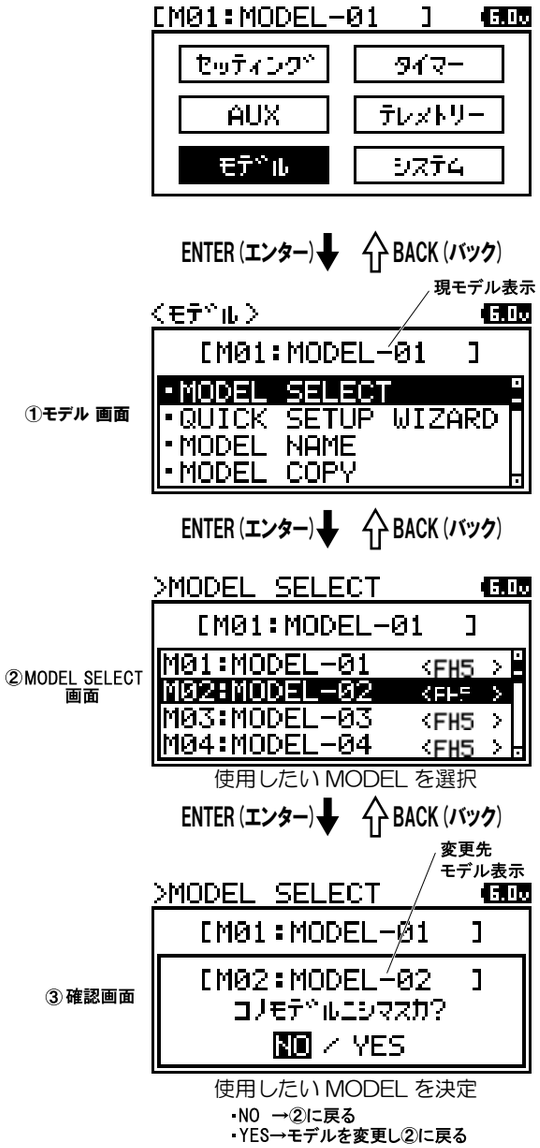
1) Select [MODEL] with up and down key.
Determine with enter.

2) Setting Model Select (MODEL SELECT)
Select [MODEL SELECT] with up and down key.
Determine with enter.

3) Selecting Model
Select Model to call with up and down key.

○ Setting Range: M01 ～M20

4) When moving the cursor to the model to call and Enter is being operated, a message is displayed on the screen.
Follow the display to operate and select a model.



補足

●MT-Rはダイレクト モデル セレクトの機能を装備しています。
バック/キャンセル ボタンを押しながら送信機のパワースイッチをONすると、MODEL SELECT画面からスタートしますので使用するモデルを簡単に呼び出すことができます。

MODEL NAME

● You can register a model name with up to 10 characters of alphabets, numbers, symbols, and Japanese Katakana for each model.

1) Select [MODEL] with up and down key.
Determine with the Enter operation.

2) Setting Model Name [MODEL NAME]
Select [MODEL NAME] with up and down key.
Determine with the Enter operation.

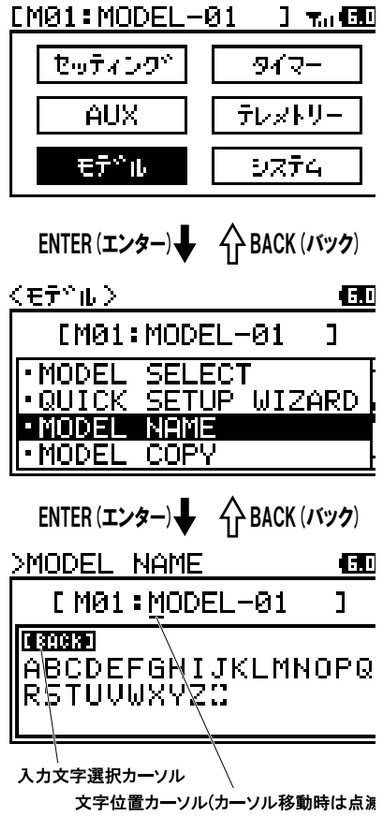
3) Setting Model Name
Move the cursor "_____" with up and down key to the position to input texts. Once the position is determined, press the Enter key to determine the cursor position.
"_____" is flashing when moving, and is turning on when determied.

4) Select texts to enter with up and down key. Once the texts to enter are determined, enter with the Enter key.

*When changing texts are already entered or when moving the cursor of the text input position, press the Back button to cancel the action.

○ Setting Range: A～Z,a～z,0～9,Symbols, Space, Japanese Katakana, Little Katakana.

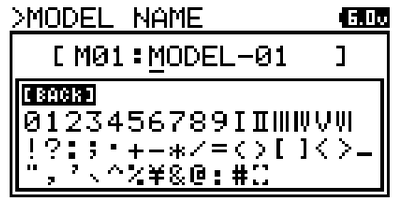
5) Repeat 3) and 4), and enter texts.



アルファベット小文字



数字、記号



カタカナ



カタカナ小文字



MODEL MENU

MODEL

● You can set the features about Model Select, Model Name, Model Copy and Model Clear.
● Installed with high capacity EEPROM and it can memorize data for 20 models of M01 ~ M20.

MODEL COPY

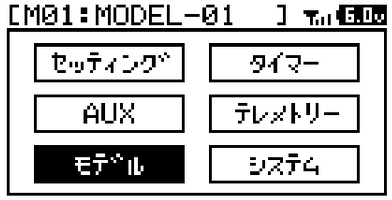
● You can copy a selected model data to another model.

1) Select [MODEL] with up and down key
   Determine with the Enter operation.

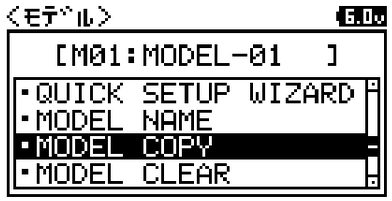
2) Setting Model Copy [MODEL COPY]
   Select [MODEL COPY] with up and down key.
   Determine with the Enter operation.

3) Selection of a Copy Destination Model
   Select a Copy Destination Model with up and down key.
   *Model for copy is model date is current using model.

4) When Enter is being operated a message is displayed
   on the screen. Follow the display to operate
   and complete Model Copy.

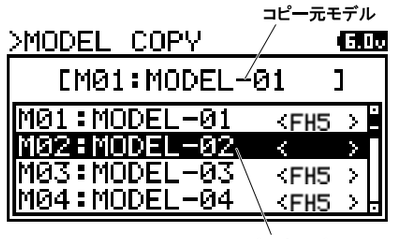


ENTER (エンター) BACK (バック)



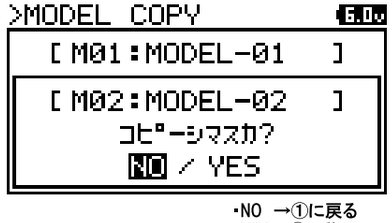
ENTER (エンター) BACK (バック)

①コピー先選択



コピー元モデル
コピー先モデル

②コピー確認画面



・NO →①に戻る
・YES→③に移行
（コピー実行）

③コピー中



・コピー後①に戻る

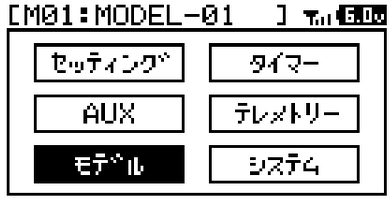
MODEL CLEAR

● A feature to clear (initialize) the setting data of Models.

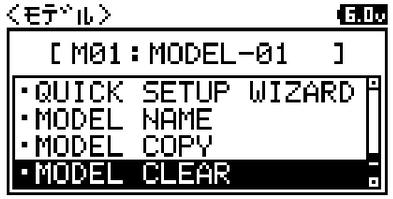
1) Select [MODEL] with up and down key.
   Determine with the Enter operation.

2) Setting Model Clear [MODEL CLEAR]
   Select [MODEL CLEAR] with up and down key.
   Determine with the Enter operation.

3) When Enter is being operated, a message is displayed
   on the screen. Follow the display to operate
   and complete Model Clear.



ENTER (エンター) BACK (バック)



ENTER (エンター) BACK (バック)

①確認画面



・NO →MODEL画面に戻る
・YES→クリアー実行 ②へ

②クリア処理中

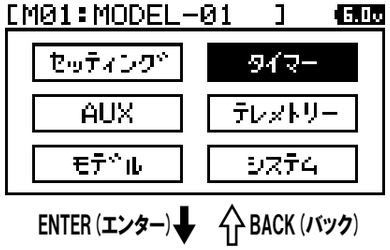


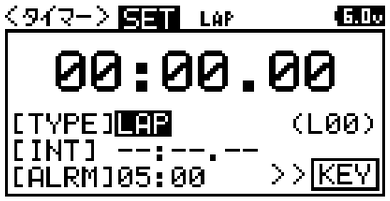
2回点滅表示後
<モデル>画面に戻る

TIMER MENU

TIMER

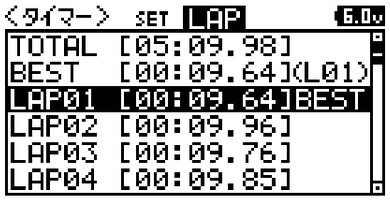
- It has three timer features including Lap Timer, Interval Timer and Down Timer.
- When selecting a timer and operate the up and down key, you can toggle between the timer screen and the setting screen.





<SET画面>

アップキー
ダウンキー



<LAP画面>

●LAP画面で計測したラップ タイムを確認することができます。
●ラップ タイマーが停止している状態でアップキー/ダウンキーを操作してラップを選択します。
※計測したラップ タイムの中でのベスト タイムには[BEST]と表示されます。

LAP TIMER

- You can measure and record each lap up to 99 laps (works for all models).
- Pre Alarm (PRE-ALM) is installed and the alarm goes off before the goal.

1) Select [TIMER] with up and down key. Determine with the Enter operation.

2) Change [SET] menu with enter.
   *Switch SET to LAP with up and down key.

3) TYPE setting
   Change [LAP] on TYPE setting with up and down key.
   Determine with enter.

4) Goal Time setting
   Set goal time [ALRM] with up and down key.
   ○ Setting Range: 00:01 ~ 99:59 (unit: 00:01 each)
   ○ Default: 05:00

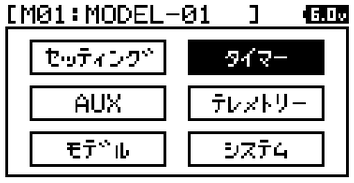
5) As the default, timer swith is set on SW1.
   Holding SW1 will standby timer.
   Then when push SW1 again or operating throttle,
   timer will be started.

6) After starting timer, lap time is recorded when pushing SW1.
   After pushing SW1, the switch will not work while 3 seconds.

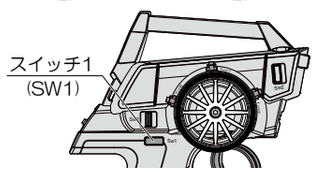
7) Completing measuring
   By holding SW1, measuring will be completed.
   Or pushing SW1 after finished goal time will complete measuring.

   *When turning the power switch off while the timer is activated, the timer will be reset.

   *When the timer is set to SW1, the timer will be in the standby mode by holding the switch even on a screen other than the TIMER setting screen.



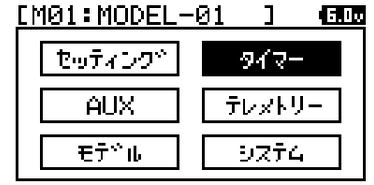




INTERVAL TIME [INT TIMER]

- It activates the alarm at the time set at the beginning of running and uses it as the guideline for the lap time.

1) Select [TIMER] with up and down key.
   Determine with the Enter operation.
2) Change [SET] menu with enter.
   *Switch SET to LAP with up and down key.
3) Setting the Type [TYPE]
   Select [INT] with up and down key. Determine with enter.
4) Setting Interval (INTERVAL)
   Set the Interval Timer.
   ○ Setting Range: 00:00.01 ~ 99:59.99
   ○ Default: 00:00.00
   *Interval timer will not work for 00:00.00.
5) As the default, timer swith is set on SW1.
   Holding SW1 will standby timer.
   Then when push SW1 again or operating throttle,
   timer will be started.
6) After starting timer, lap timer will be reset when pushing SW1.
7) Completing measuring
   By holding SW1, measuring will be completed.
   After finished goal time, pushing SW1 will be lap timer reset.
   *When turning the power switch off while the timer is activated, the timer will be reset.
   *When the timer is set to SW1, the timer will be in the standby mode by holding the switch even on a screen other than the TIMER setting screen.

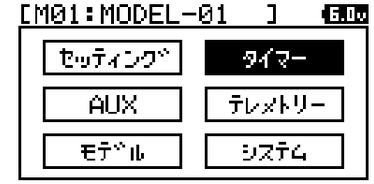




DOWN TIMER

- It can be for calculating running time of an electric RC car and the fuel comsumption of an engine RC car.
- You can set for per second up to 99 : 59.
- When the timer switches to Up Timer after Down Timer ends, you can check lap time after the end.

1) Select [TIMER] with up and down key.
   Determine with the Enter operation.
2) Change [SET] menu with enter.
   *Switch SET to LAP with up and down key.
3) Setting the Type [TYPE]
   Select [DOWN] with up and down key. Determine with enter.
4) Set the Interval Timer.
   ○ Setting Range: 00:01 ~ 99:59
   ○ Default: 05:00
   *Down timer will work as up timer for 00:00.
5) As the default, timer swith is set on SW1.
   Holding SW1 will standby timer.
   Then when push SW1 again or operating throttle,
   timer will be started.
6) After starting timer, down timer will be reset when pushing SW1.
7) Completing measuring
   By holding SW1, measuring will be completed.
   *When turning the power switch off while the timer is activated, the timer will be reset.
   *When the timer is set to SW1, the timer will be in the standbymode by holding the switch even on a screen other than the setting screen.





TELEMETRY MENU

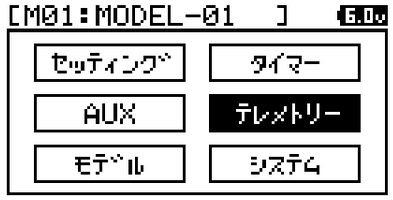
TELEMETRY

- A menu for setting Telemetry-related LOGGER, ALERT SETTING, TELEMETRY SETTING.
- To use the Telemetry, you can check with a compatible device such as SUPER VORTEX series.
- With Telemetry, you can check the data of 2 line of temperature, battery voltage and number of rotations with the transmitter.

・LOGGER:Check 2 line of temperature, battery voltage and number of rotations

・ALERT SETTING:Alert by setting temperature and battery voltage

・TELEMETRY SETTING:Various settings of Telemetry features



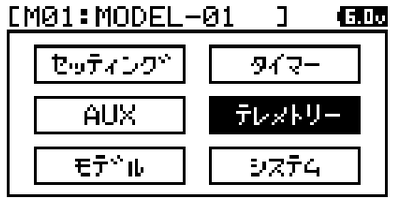
LOGGER

- Transmitter enables to record 2 temperatures (T1/T2) as battery, engine, and motor receiver voltage, engine or motor rotation number (PRM) with compatible receiver and Super Vortex series.
- Record (Log) setting can be set LOG STEP on the TELEMETRY SETTING (p.42). Log data interval is 0.1 ~ 45.9 seconds.
- Record (Log) can be 120 STEP (Min 12 seconds ~ Max 90 minutes).
- Logger working can be started by holding enter on each [LOGGER] display (T1/T2/VOLT/RPM) or assinged switch.

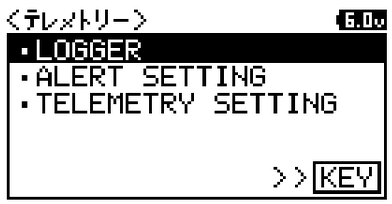
1) Select [TELEMETRY] with up and down key. Determine with enter.

2) Select [LOGGER] with up and down key. Determine with enter.

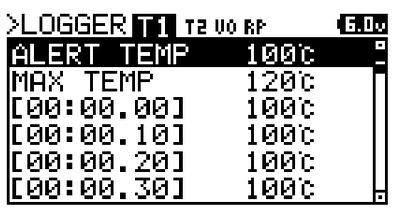
3) Seletct data for display [T1/T2/VOLT/RPM(RP)] with up and down key. Determine with enter.
Check log data with up and down key.



ENTER (エンター) BACK (バック)



ENTER (エンター) BACK (バック)



ALERT SETTING

- Alert setting is alerting by setting temperature and voltage. Also, transmitter blue LED will flash by setting telemetry data.

1) Select [TELEMETRY] with up and down key. Determine with enter.

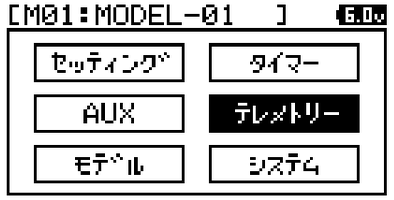
2) Select [ALERT SETTING] with up and down key. Determine with enter.

3) T1 ALERT SETTING
Select [T1 ALERT] with up and down key. Determine with enter.
○ Setting Range: 0～150℃(32～302℉)
○ Default: 100℃(212℉)

4) T2 ALERT SETTING
Select [T2 ALERT] with up and down key. Determine with enter.
○ Setting Range: 0～150℃(32～302℉)
○ Default: 100℃(212℉)

5) VOLT ALERT Setting
Select [VOLT ALERT] with up and down key. Determine with enter.
○ Setting Range: 3.0V ~ 9.0V
○ Default: 3.8V

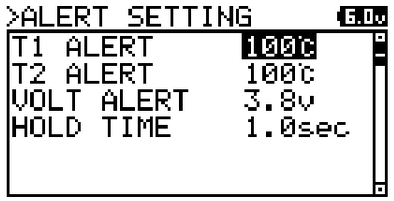
5) HOLD TIME Setting
*Sudden throttle work might be caused to instant voltage drop and it might lead unnessesry alert. In this situation, the HOLD TIME setting can make time to prevent from the unnessesary alert and provide stable alert for the unusual situation.
○ Setting Range: 0.0~5.0 sec
○ Default: 1.0 sec



ENTER (エンター) BACK (バック)



ENTER (エンター) BACK (バック)



TELEMETRY SETTING

- Set each feature of Telemetry.

1) Select [TELEMETRY] with up and down key. Determine with enter.

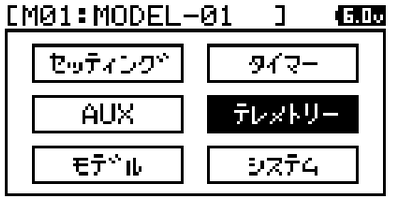
2) Select [ALERT SETTING] with up and down key. Determine with enter.

3) TELEMETRY ON/OFF SETTING
Select [ON/OFF] with up and down key. Determine with enter.
○ Setting Range: ON/OFF
○ Default: ON

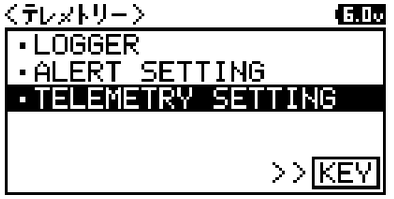
4) LOG STEP SETTING
Select [LOG STEP] with up and down key. Determine with enter.
○ Setting Range: 00.1 ~ 45.9s
○ Default: 00.1s

5) T1/T2 UNIT SETTING (Temperature unit setting)
Select [T1/T2 UNIT] with up and down key. Determine with enter.
○ Setting Range: ℃/℉
○ Default: ℃

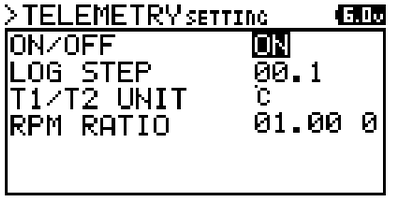
6) RPM RATIO SETTING
*When setting RATIO RPM sensor in the subtracted position, you can display the number of rotations of the motor and engine after back calculation with RATIO setting.
○ Setting Range: 00.001～64.999
○ Default: 01.000



ENTER (エンター) BACK (バック)



ENTER (エンター) BACK (バック)



SYSTEM MENU

SYSTEM

● A feature for setting system of the transmitter, such as Bind, Key Assignments (KEY ASSIGN),Buzzer, Battery, LCD and CALIBRATION.

BIND

● Select the output system that suits the receiver, set a mode for the servo (analog/digital) and the speed controller to be used and bind the transmitter with the receiver.
When using first time, please bind with receiver.

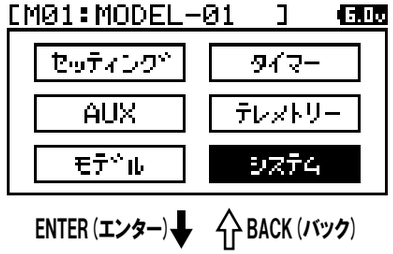
*MT-R does not bind with RX-493i from the factory.

1) Select [SYSTEM] with the up and down key.
Determine with the Enter operation.

2) Select [BIND] with up and down.
Determine with the Enter operation.

3) Setting RF MODE (Signal output system)
○ Output System
・FH5
RX-491,RX-492, RX-492i RX-493, RX-493i
*FH4, FH3, FH-E, DS mode receivers are not compatible.

4)Setting Channel Mode
Set the response mode for each channel with up and down key.
・You can the set the response mode for each channel.
○ Setting Range: NOR(Normal)
SHR(High Response)
SSR(Super Response)
SUR (Ultra Response)
○ Default: NOR



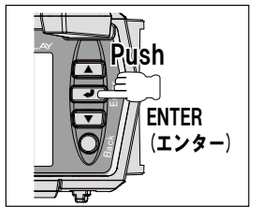
重要

●SHR/SSR/SURモードではアナログサーボは動作しませんのでご注意ください。誤ってSHR/SSR/SURモードでアナログサーボを使用すると正常に動作せずサーボが壊れますので、絶対にSHR/SSR/SURモードでアナログサーボを使用しないでください。
デジタルサーボ(SRG、ERB、ERSシリーズ、Digital ERGシリーズ)の場合はNOR/SHRモードのどちらでも動作します。
●SSRモードはPGS、SRGサーボ、SUPER VORTEXシリーズ、HV-12 STOCK SPECIAL、HV-01のみ動作します。
●SURモードはPGSサーボ、SUPER VORTEX GeN2/PRO/D2のみ動作します。
●SHR/SSR/SURモードではBL-RACER、BL-FORCE、F2000、F2200、F3000、F3300、SBL-01、02、03CLは動作しません。
必ずNORモードでご使用ください。
●BL-SIGMA、SV-08、HV-10、HV-12、F2500はNOR/SHRモードで動作します。

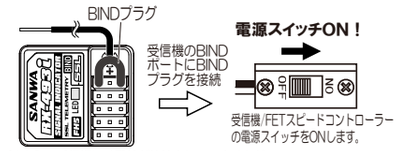
7) Setting BIND

● What is BIND: Each of MT-R transmitters has its own unique ID (solid identification) number. BIND is to let the receiver memorize the ID number. Operation will be possible only between the transmitter and the receiver that completed Binding.

1] When setting in the BIND menu is done, set BIND with up, down, and enter key.
2] Move the cursor to [ENTER] in the BIND menu and operate Enter.
The transmitter now is ready for BIND operation.



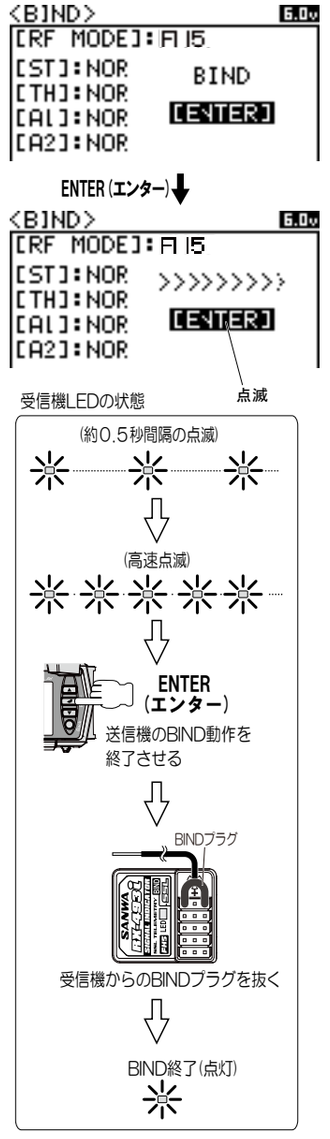
3] Turn on the receiver with inserting Bind Plug in BIND/SSL port.



注)上記の受信機には配線が接続されていませんが、BINDする際には、サーボやFETスピードコントローラー(モーターは除く)、バッテリーを接続した状態でおこなってください。

4] When BINDING is done properly, the LED of the receiver starts flashing slowly at first then it flashes in high speed.
When the LED of the receiver flashes in high speed, operate the Enter key of the transmitter to complete BINDING.
Then, please take off the Bind Plug from the receiver.
When BINDING is done properly, the LED of the receiver is lit.
When the LED of the receiver is lit, please check the bind completion by using servo operation.

*When BINDING cannot be done properly, restart from step 2).



⚠注意

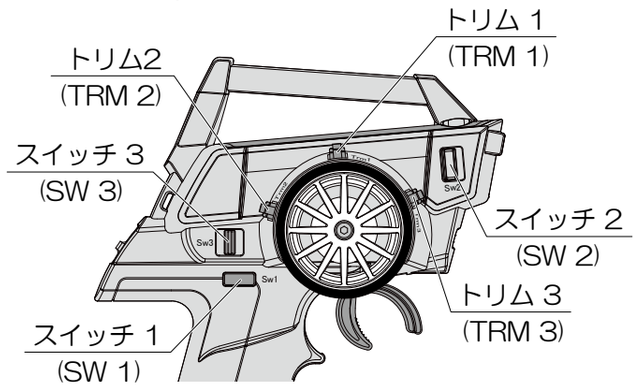
●出荷時にはBINDされていません。ご使用になる前に必ずBINDをおこなってください。
●新たに受信機を購入された場合は、必ず送信機と新しい受信機でBINDをおこなってください。
●必ずBINDした送信機と受信機のセットでお使いください。
●BINDしたあとにBINDメニュー内の設定を変更した場合は再度BINDをおこなってください。
●BIND(バインド)してからチャンネルのモード設定(NOR/SHR/SSR/SUR)の設定を変更した場合には再度BIND(バインド)をおこなってください。再バインドしないと設定変更が反映されません。

SYSTEM MENU

SYSTEM

● A feature for setting system of the transmitter, such as Bind, Key Assignments (KEY ASSIGN),Buzzer, Battery, LCD and CALIBRATION.

Switch and Trim position



Features assigned to the Switch and Trim at the factory
TR1: Steering Trim(TRM-ST)
TR2: Throttle Trim(TRM-TH)
TR3: Dual Rate ST(D/R-ST)
SW1: TIMER
SW2: OFF
SW3: OFF

KEY ASSIGN SWITCH

● You can assign features to the switches (SW1, SW2, SW3) of the transmitter and toggle ON/OFF of the features during operation.

1) Select [SYSTEM] with up and down key.
   Determine with the Enter operation.
2) Select [KEY ASSIGN] with up and down key.
   Determine with the Enter operation.
3) Setting the Switch (SW1/SW2/SW3)
   Operate the Enter with [SW] and set the feature to assign to the switch with up and down key.

○ Setting Range:

スイッチ	割り当て可能な機能
SW1	OFF、ASIST-ST、D/R-ST、D/R-TH、D/R-BR、CUR-ST、CUR-TH、SPD-ST、SPD-TH、ALB、OFFSET、AUX1、AUX2、TIMER、TE-CLR、LOGGER

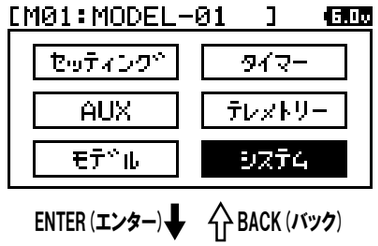
スイッチ	割り当て可能な機能
SW2	OFF、ASIST-ST、D/R-ST、D/R-TH、D/R-BR、CUR-ST、CUR-TH、SPD-ST、SPD-TH、ALB、OFFSET、AUX1、AUX2

スイッチ	割り当て可能な機能
SW3	OFF、D/R-ST、D/R-TH、D/R-BR、CU-R-ST、CU-R-TH、CU-R-BR、SP-ST-F、SP-ST-R、SP-TH-F、SP-TH-R、ALB-ST、ALB-LG、ALB-CY、OFFSET、AUX1(CD1~10)、AUX2(CD1~10)、

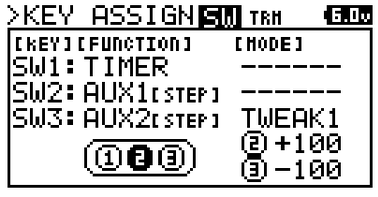
○ Default : SW1: TIMER　SW2: OFF　SW3: OFF

*BY Setting [ASSIST-ST] onto SW1 and SW2,
you can turn ON/OFF the feature of D/R, SPEED and CURVE that can be set onto the steering.

4) Setting Mode
   It sets the switch performance but there are casesthat you cannot set depending on the feature to assign.
   ○ Setting Range
   TOGGLE (Switching between ON/OFF when pressed every time)
   PUSH (ON is worked when switch is only pressed)







SW3のMODE設定について

	①	②	③
TWEAK1	ニュートラル	P1	P2
TWEAK2	P1	ニュートラル	P2

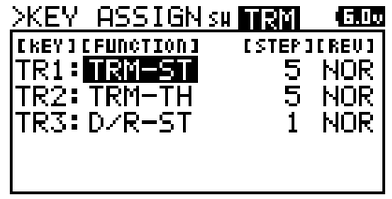
P1/P2のポジションも自由に変更可能です。

KEY ASSIGN TRIM

● You can change the setting value of each feature with Trim1 - Trim3.
● You can also change the setting of the variation change in one time of Trim operation with the STEP setting and the direction of the action with the REV setting.

1) Select [SYSTEM] with up and down key.
   Determine with the Enter operation.

2) Select [KEY ASSIGN] with up and down key.
   Determine with the Enter operation.



3) Setting Trim (TRM1/TRM2/TRM3)
   Select [TRIM] with enter. Change the setting and set a feature to assign with up and down key.

○ Setting Range:

トリム	割り当て可能な機能
TRIM1 TRIM2 TRIM3	OFF、TRIM-ST、TRM-TH、TRIM-A1、TRIM-A2、D/R-ST、D/R-TH、D/R-BR、CU-R-ST、CU-R-TH、CU-R-BR、SP-ST-F、SP-ST-R、SP-TH-F、SP-TH-R、ALB-PO、ALB-ST、ALB-LG、ALB-CY、OFFSET、AUX1(CD1~10)、AUX2(CD1~10)

○ Default:　TR1:TRM-ST
　　TR2:TRM-TH
　　TR3:D/R-ST

4) Setting Step
   Set the variation of the movement by one-time Trim operation.
   Select [STEP] with up and down key. Determine with the Enter operation and set the variation.

○ Setting Range: 1～100
○ Default:　5

5) Setting the Direction of Action
   Set the direction of action when operating Trim. Select [REV] with up and down key.
   Determine with the Enter operation and set the direction of action.

○ Setting Range: NOR/REV
○ Default:　NOR

SYSTEM MENU

SYSTEM

BUZZER

● You can set operating sounds of key operation, Trim and Switch and the buzzer tones.
● You can set 5 steps of the volume and 7 types of tones.

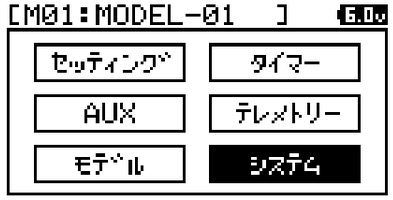
1) Select [SYSTEM] with up and down key.
   Determine with the Enter operation.

2) Select [BUZZER] with up and down key.
   Determine with the Enter operation.

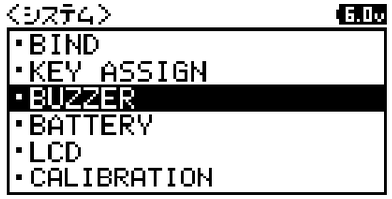
3) Setting Tone and Volume
   You can switch between Tone (scales) and Volume (Sound Volume) with up and down key. Select an item to change setting to adjust.

○ Setting Range: VOLUME OFF~5
TONE 1~7

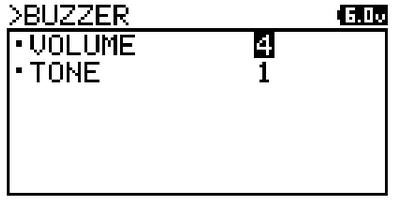
○ Default: VOLUME 4
TONE 1



ENTER (エンター) BACK (バック)



ENTER (エンター) BACK (バック)



BATTERY

● You can change the voltage setting of the battery alarm of the transmitter.
● By selecting Type [DRYx4 (Batteries)/Ni-MH x4 (Nickel Metal Hydride)/Li-Fe x2 (Lithium Ferrite) /Li-Po x2 (Lithium Polymer),CUSTOM], you can set the alarm easily.
*When selecting CUSTOM with the Type, you can set ALERT VOLT that sets voltage to make Alarm go off and LIMIT VOLT of the lower limite voltage.

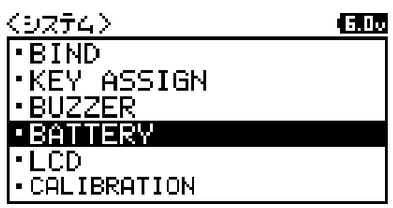
1) Select [SYSTEM] with up and down key.
   Determine with the Enter operation.

2) Select [BATTERY] with up and down key.
   Determine with the Enter operation.

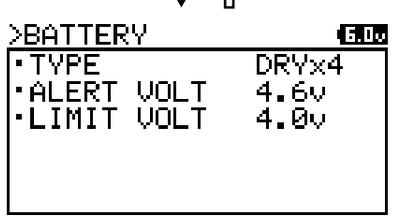
3) Setting TYPE
   Set TYPE for the battery to be used with up and down key.

○ Setting Range: DRY x4 (AA x4)
Ni-MH x2 (Nickel Metal Hydride)
Li-Po x2 (Lithium Polymer)
Li-Fe x2 (Lithium Ferrite)
CUSTOM: ALERT VOLT:4.1 ~ 9.0v
: LIMIT VOLT:4.0 ~ 9.0v

○ Default: DRYx4 (AA x4)



ENTER (エンター) BACK (バック)



LCD

● You can set LCD contrast (intensity) and lighting mode of Back Light.

1) Select [SYSTEM] with up and down key. Determine with the Enter operation.

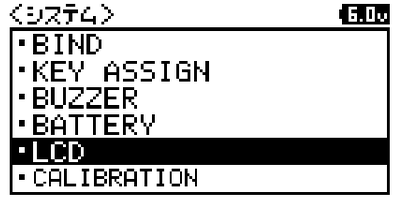
2) Select [LCD] with up and down key. Determine with the Enter operation.

3) Set LCD contrast (intensity), lighting mode of Back Light, and language.

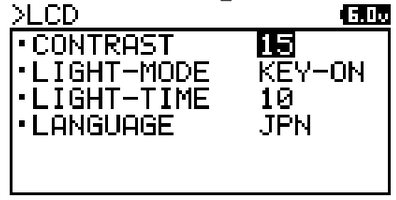
○ Setting Items: CONTRAST (Intensity of Display)
LIGHTS-MODE (Backlight Lighting Mode)
LIGHT-TIME (Backlight Lighting Time)

○Setting Range: CONTRAST:0～30
LIGHT-MODE:OFF /KEY-ON /ALWAYS
LIGHT-TIME:1～30sec

○ Default: CONTRAST:15
LIGHT-MODE:KEY-ON
LIGHT-TIME:10sec



ENTER (エンター) BACK (バック)



CALIBRATION

● Due to wearing and tearing of the internal mechanical elements over the usage time, the neutral position and the operation angle might become off. In such case, you can correct the neutral positions and the operation angle of the steering and the throttle.

1) Select [SYSTEM] with up and down key.
   Determine with the Enter operation.

2) Select [CALIBRATION] with up and down key.
   Determine with the Enter operation.

3) Select a channel to calibrate with up and down key.
   Determine with the Enter operation.

4) When selecting [STEERING], operate the Enter with the steering wheel in neutral, then operate the steering wheel fully to left and right.

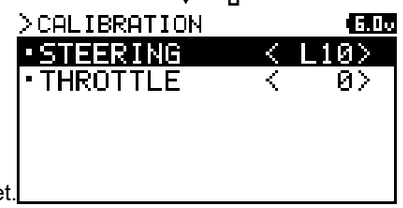
5) When entering the range, [OK] is displayed.
   Operate following the display.

6) When calibration is done, [Executed] is displayed.

*If the throttle side also needs calibration, refer to the steering to set.

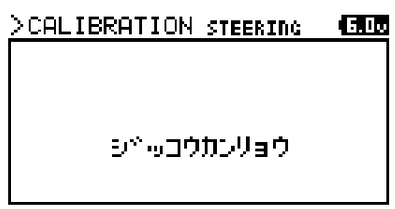


ENTER (エンター) BACK (バック)



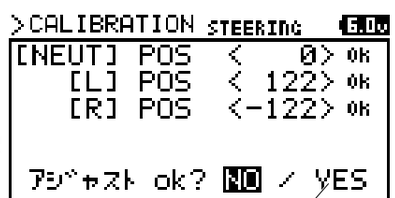


⚠補足
●キャリブレーションをおこなっても正常な動作に戻らないときは、三和サービスへお問い合わせください。



キャリブレーション完了

⇐ YES選択

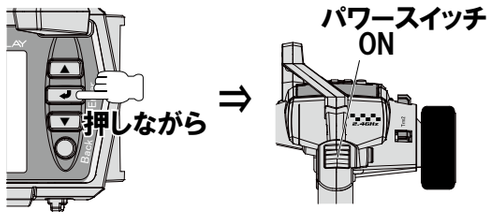


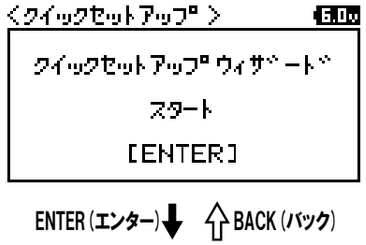
OKならYESを選択

QUICK SETUP WIZARD

●Quick Setup Wizard function is easily to set up when you set up new RC car.
●Setup Wizard is fllowing start menu→model select→type select→model initialize→RF mode select→response mode select→bind→base setting.

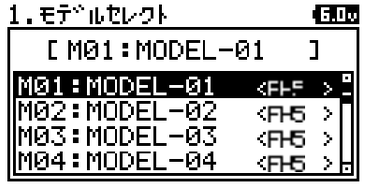
1)Turn the power switch on with holding enter key.



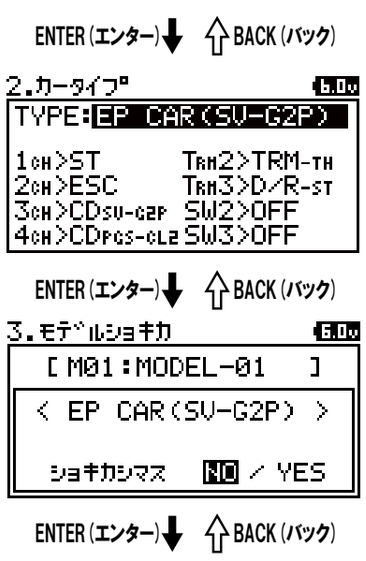


2) Quick Setup screen is displayed.
Setup Wizard will be started with Enter.

3) Switch model select, and select model with up and down key.
Determined car type with enter.



4) When the screen is changed to Car Type selection screen, select a Car Type using Multi-Selector.
When a Car Type is selected, set with Enter.



Setting up Type

○Setting Range:
EP CAR STANDARD
EP CAR DRIFT
EP CAR (PGS)
EP CAR (SV-G2P)
EP CAR (SV-D2)
GP CAR STANDARD
1/5 GP CAR DUAL BR1
1/5 GP CAR DUAL BR2
CRAWLER 4WS/MOA

○Default:
EP CAR STANDARD

TYPE別チャンネル動作仕様

*Channel operation of each type will be as follows.

CH \ TYPE	EP CAR STANDARD	EP CAR DRIFT	EP CAR (PGS) (SV-G2P)	EP CAR (SV-D2)	GP CAR STANDARD	1/5 GP DUAL-BR1	1/5 GP DUAL-BR2	CRAWLER 4WS/MOA
CH1	ステアリング	ステアリング	ステアリング	ステアリング	ステアリング	ステアリング 1	ステアリング	ステアリング F
CH2	ESC	ESC	ESC	ESC	スロットル /ブレーキ	スロットル /ブレーキR	スロットル	ESC F
CH3	AUX1	AUX1	CODE1	CODE1	AUX1	ステアリング 2	ブレーキ R	ステアリング R
CH4	AUX2	AUX2	CODE2	CODE2	CODE2	ブレーキF	ブレーキ F	ESC R

*Select a type to be used according to a R/C.

5) When deciding the car type using Enter, the screen changes to Initialization (Model Initialization) screen.
Do initialization following the message.

6) When initializing (Initializing Model) is completed, the screen changes to RF Mode Selection Screen.
MT-R is only compatible with FH5 RF mode.

○Default: FH5

・Compatible Receivers: FH5
RX-491,RX-492,RX-492i RX-493,RX-493i

7) Once RF Mode for the receiver is determined, the screen changes to the Response Mode screen.
Set Response Mode according to the servos and the equipment to be used.
Set with up and down key and finalize with the Enter key.

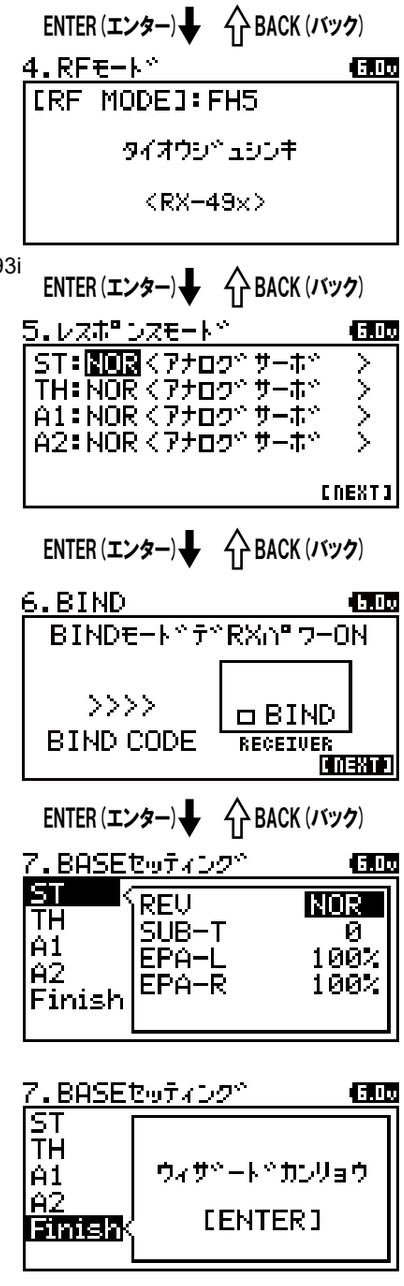
○ Setting Range: NOR(Normal / Analog Servo)
SHR(High Response / Digital Servo)
SSR(Super Response / SRG Servo)
SUR (Ultra Response / PGS Servo)

○ Default: NOR(Normal / Analog Servo)

8) When Response Mode setting is completed, the screen changes to BIND Set up Screen.
Follow the screen message and start Binding.

9) When Binding (BIND) is done, the screen changes to the Base Set Up screen.
Complete setting for each channel (refer to p.43).

10)When Base setting is done, Set Up Wizard will end.
If you press the Enter button, the screen changes to the Top screen.



重要

●SHR/SSR/SURモードではアナログサーボは動作しませんのでご注意ください。
誤ってSHR/SSR/SURモードでアナログサーボを使用すると正常に動作せずサーボが壊れますので、絶対にSHR/SSR/SURモードでアナログサーボを使用しないでください。
デジタルサーボ(SRG、ERB、ERSシリーズ、Digital ERGシリーズ)の場合はNOR/SHRモードのどちらでも動作します。
●SSRモードはPGSサーボ、SRGサーボ、SUPER VORTEXシリーズ、HV-12 STOCK SPECIAL、HV-01のみ動作します。
●SURモードはPGSサーボSUPER VORTEX Gen2/PRO/D2のみ動作します。
●SHR/SSR/SURモードではBL-RACER、BL-FORCE、F2000、F2200、F3000、F3300、SBL-01、02、03CLは動作しません。
必ずNORモードでご使用ください。
●BL-SIGMA、SV-08、HV-10、HV-12、F2500はNOR/SHRモードで動作します。
●お使いになるスピードコントローラーの取扱説明書を必ずお読みください。

ABOUT QUICK SETUP WIZARD

●Quick Setup Wizard function is easily to set up when you set up new RC car.
●Setup Wizard is fllowing start menu→model select→type select→model initialize→RF mode select→response mode select→bind→base setting.

① EP CAR STANDARD
一般的な電動カー用の設定

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC (スピードコントローラー)	SW2 : OFF	TR2 : TRM-TH
3CH : AUX1	SW3 : OFF	TR3 : D/R-ST
4CH : AUX2		

② EP CAR DRIFT
ドリフトカー用の設定
TRM3キーを操作することで、AUX(3CH)の設定を変更することができます。
※3CHに接続されたジャイロなどの設定が可能です。

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC (スピードコントローラー)	SW2 : OFF	TR2 : TRM-TH
3CH : AUX1	SW3 : OFF	TR3 : AUX1
4CH : AUX2		

③ EP CAR (PGS)
ステアリングサーボに「PGS」シリーズを使用する場合の設定
受信機のSSLポートに対象となるサーボを接続することで
「メインメニュー」→「AUX」→「CH」から対象のサーボの設定が可能です。

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC (スピードコントローラー)	SW2 : OFF	TR2 : TRM-TH
3CH : AUX1	SW3 : OFF	TR3 : D/R-ST
4CH : CODE (PGS)		

④ EP CAR (SV-G2P)
ステアリングサーボに「PGS」シリーズ、スピードコントローラーに
「SUPER VOLTEX GEN2/GEN2 PRO/D2」を使用する場合の設定
受信機のSSLポートに対象となるサーボ/スピードコントローラーを接続することで
「メインメニュー」→「AUX」→「CH」から
対象のサーボ/スピードコントローラーの設定が可能です。

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC (スピードコントローラー)	SW2 : OFF	TR2 : TRM-TH
3CH : CODE (SV-G/D)	SW3 : OFF	TR3 : D/R-ST
4CH : CODE (PGS)		

⑤ EP CAR (SV-D2)
スピードコントローラーに「SUPER VOLTEX GEN2/GEN2 PRO/D2」、
ジャイロに「SGS-02」を使用する場合の設定
受信機のSSLポートに対象となるスピードコントローラー/ジャイロを接続することで
「メインメニュー」→「AUX」→「CH」から
対象のスピードコントローラー/ジャイロの設定が可能です。

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC (スピードコントローラー)	SW2 : OFF	TR2 : TRM-TH
3CH : CODE (SV-G2/D)	SW3 : OFF	TR3 : D/R-ST
4CH : CODE (SGS-02)		

⑥ GP CAR STANDARD
GP(エンジン)カー用の設定
SW2にOFFSET機能のON/OFFが設定
ステアリングサーボ/スロットルサーボに「PGS」シリーズを使用する場合の設定
受信機のSSLポートに対象となるサーボを接続することで
「メインメニュー」→「AUX」→「CH」から対象のサーボの設定が可能です。

1CH : ST (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : TH/BR (スロットル／ブレーキ)	SW2 : OFFSET	TR2 : TRM-TH
3CH : AUX1	SW3 : OFF	TR3 : D/R-ST
4CH : CODE (PGS)		

⑦ 1/5GP DUAL -BR1
1CH&3CHにステアリングサーボ、
2CH&4CHにスロットル/ブレーキサーボを使用する場合の設定
TRM2キーの操作で2CH側のブレーキサーボの動作量
TRM3キーの操作で4CH側のブレーキサーボの動作量の設定が可能です。

1CH : ST1 (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : TH/BR (スロットル／ブレーキ)	SW2 : OFFSET	TR2 : D/R-BR
3CH : ST2 (ステアリング)	SW3 : OFF	TR3 : AUX2
4CH : BR (ブレーキ)		

⑧ 1/5GP DUAL-BR2
1CHにステアリングサーボ、2CHにスロットルサーボ、
3CH&4CHにブレーキサーボを使用する場合の設定
TRM2キーの操作で3CH側のブレーキサーボの動作量
TRM3キーの操作で4CH側のブレーキサーボの動作量の設定が可能です。
「メインメニュー」→「AUX」→「CH」から
2CH/3CHのブレーキサーボのミキシング
2CH/4CHのスロットル/ブレーキのミキシングの設定が変更できます

1CH : ST1 (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : TH (スロットル)	SW2 : OFFSET	TR2 : AUX1
3CH : BR1 (ブレーキ)	SW3 : OFF	TR3 : AUX2
4CH : BR2 (ブレーキ)		

⑨ CRAWLER 4WS/MOA
1CH&3CHにステアリングサーボ、
2CH&4CHにスピードコントローラーを使用する場合の設定
TRM3キーの操作で、4WS機能の切り替えが可能です。
[F-ST]⇔[REV]⇔[NOR]⇔[R-ST]
TRM2キーの操作で、MOA-RATEの変更が可能です。
[F100:R0]⇔[F100:R100]⇔[F0:R100]
「メインメニュー」→「AUX」→「CH」から
MOA機能と4WS機能の詳細な設定が変更できます。

1CH : ST1 (ステアリング)	SW1 : TIMER	TR1 : TRM-ST
2CH : ESC1 (スピードコントローラー)	SW2 : OFF	TR2 : AUX2
3CH : ST2 (ステアリング)	SW3 : OFF	TR3 : AUX1
4CH : ESC2 (スピードコントローラー)		

Assign Function List

画面表示	機 能 名 称	トリム	SW1	SW2	SW3
OFF	ーーー(機能割付け無し)	○	○	○	○
TRIM-ST	ステアリング トリム	○	ー	ー	ー
TRIM-TH	スロットル トリム	○	ー	ー	ー
TRIM-A1	AUX1 トリム	○	ー	ー	ー
TRIM-A2	AUX2 トリム	○	ー	ー	ー
D/R-ST	ステアリング デュアルレート	○	○	○	○
D/R-TH	スロットル デュアルレート	○	○	○	○
D/R-BR	ブレーキ デュアルレート	○	○	○	○
CUR-ST	ステアリング カーブ	ー	○	○	ー
CUR-TH	スロットル カーブ	ー	○	○	ー
CU-R-ST	ステアリング カーブ レート	○	ー	ー	○
CU-R-TH	スロットル カーブ レート	○	ー	ー	○
CU-R-BR	ブレーキ カーブ レート	○	ー	ー	○
SPD-ST	ステアリング スピード	ー	○	○	ー
SPD-TH	スロットル スピード	ー	○	○	ー
SP-ST-F	ステアリング スピード フォワード	○	ー	ー	○
SP-ST-R	ステアリング スピード リターン	○	ー	ー	○
SP-TH-F	スロットル スピード フォワード	○	ー	ー	○
SP-TH-R	スロットル スピード リターン	○	ー	ー	○
ALB	アンチ ロック ブレーキ	ー	○	○	ー
ALB-PO	アンチ ロック ブレーキ ポイント	○	ー	ー	ー
ALB-ST	アンチ ロック ブレーキ ストローク	○	ー	ー	○
ALB-LG	アンチ ロック ブレーキ ラグ	○	ー	ー	○
ALB-CY	アンチ ロック ブレーキ サイクル	○	ー	ー	○
OFFSET	オフセット	○	○	○	○
AUX1	AUX1	○	○	○	○
AUX1(CODE1) 〜 AUX1(CODE10)	AUX1(コード1) 〜 AUX1(コード10)	○	ー	ー	○
AUX2	AUX2	○	○	○	○
AUX2(CODE1) 〜 AUX2(CODE10)	AUX2(コード1) 〜 AUX2(コード10)	○	ー	ー	○
ASIST-ST	ステアリング ドライブ アシスト	ー	○	○	ー
TIMER	タイマー	ー	○	ー	ー
TE-CLR	テレメトリー MAX クリア	ー	○	ー	ー
LOGGER	ログ クリア＆スタート	ー	○	ー	ー

設定可能・・・「○」 設定不可・・・「ー」

Transmitter LED Indication List

LED Condition	Working Condition
Light on	Normal Operation (While Transmitter Output)
High-speed Flashing	ALB Working
Medium-speed Flashing	Battery Alarm Working
Flashing	Logger Working
Twice Flashing	OFFSET Working Telemetry Working POWER ON Alarm Working
High-speed Flashing	Battery (LIMIT) Alarm Working Over Voltage Alarm Working
Low-speed Flashing	BIND Command Sending

INDEX

A
ALERT SETTING ···· P.42
Anti-Lock Brake [ALB] ···· P.26
AUX ···· P.29-34
AUX Mixing [AUX-MIX] ···· P.33
B
BASE ···· P.22-24
BATTERY ···· P.47
BIND ···· P.43-44
BUZZER ···· P.47
C
CALIBRATION ···· P.48
CODE AUX ···· P.34
Curve [CURVE] ···· P.20
D
DOWN TIMER ···· P.40
Dual Rates [D/R] ···· P.18
E
End Point Adjustment [EPA] ···· P.23-24
F
Fail Safe [F/S] ···· P.21
4-Wheel Steering [4WS] ···· P.31
Function [FUNC] ···· P.25-28
I
Interval Timer [INT TIMER] ···· P.40
K
Key Assignments Switch [KEY ASSIGN SW] ···· P.45
Key Assignments Trim [KEY ASSIGN TRIM] ···· P.46
L
LAP TIMER ···· P.39
LCD ···· P48
M
MODEL ···· P.35-38
MODEL CLEAR ···· P.38
MODEL COPY ···· P.37
MODEL NAME ···· P.36
MODEL SELECT ···· P.35
Motor On Axel [MOA] ···· P.32
O
Offset ···· P.27
P
POINT AUX ···· P.30
Q
QUICK SETUP Wizard ···· P.49-50
R
Reverse [REV] ···· P.22
S
SETTING ···· P.18-34
SPEED ···· P.19
STEP AUX ···· P.29
SUB TRIM ···· P.22
SYSTEM ···· P.43-48
T
TELEMETRY SETTING ···· P.42
TIMER ···· P.39-40
TRIM ···· P.25

When this happens

現　象	原　因	処　理
電源が入らない。	乾電池またはバッテリーが消耗している。	新しい乾電池または充電されたバッテリーと交換してください。
	乾電池の入れ間違い。	極性表示とおりに入れなおす。
ときどき電源が切れる。	コネクター等の接触不良	サンワサービスへ
距離が届かない。	乾電池またはバッテリーが消耗している。	新しい乾電池または充電されたバッテリーと交換してください。 直らない場合はサンワサービスへ
アラームが鳴り止まない。	送信機のバッテリー電圧が低下している。	新しい乾電池または充電されたバッテリーと交換してください。
キーを押してもクリック音が鳴らない。	BUZZER機能のVOLUMEがOFF（０）になっている。	BUZZER機能を確認してください。(P.47)
サーボのスピードが遅い。	SPEED(スピード)の機能で設定がマイナスになっている。	SPEED(スピード)の機能を確認してください。(P.19)
	受信機バッテリーの電圧が低下している。	新しい乾電池または充電されたバッテリーと交換してください。
	車体側のリンケージが重い。	車体側のリンケージが軽く動くか確認してください。
左右の舵角を合わせても、左右の舵角が違う。	トリムニュートラルがズレている。	トリムを合わせ、EPAを再設定してください。(P.25)
操作したとき両端でサーボが動かない。	D/R、EPAの舵角設定が大きすぎる。	どちらかの値を100%以下に設定します。(P.18、23、24)
トリムを操作してもサーボが動かない。	トリム動作範囲の片側いっぱいになっている。	サーボホーン、トリムセンターを再設定します。(P.22)

Service and Support

This is warranted against manufacturer defects in materials and workmanship, at the original data of purchase. This warranty does not cover components worn by use or damage caused by improper voltage, tempering, modification, misuse, abuse, improper writing, reverse polarity, moisture or using outside its intended scope of use.

Terms of this warranty can vary by region. Please read the warranty card included with your radio control system for specific warranty information.

If you have any questions or concerns, we're here to help. If you encounter a problem with your radio control system, first chek the Troubleshooting Guide on Page 56.

If you require further help that cannot be solved using The Troubleshooting Guide, or if you have technical questions, please contact SANWA service center in your region.

For a complete list of distributors in your rgion, please visit
www.sanwa-denshi.com/rc/distributors.html.

For Service In North America:
Serpent America
5121 NW 79 Ave. Unit 03,
Doral, Florida 33166 USA
Telephone: (305)-677-3253
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Sanwa Electronic Instrument CO., LTD.
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Higashiosaka, Osaka, 578-0982 Japan
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Fax: 81-729-64-2831
Email: rcintl@sanwa-denshi.co.jp

Product features and specifications can vary by region. Not all products are legal for use in all regions.

Please note that products purchased outside of North America cannot be serviced under warranty by Serpent America. In some cases, we can make repairs for products purchased outside of North America, however, applicable repair costs and shipping charges will be applicable. For warranty claims outside North America, please contact the service center in your region.

FCC COMPLIANCE STATEMENT

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the operating instructions, may cause harmful
interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment OFF and ON, the user is encouraged to try to correct
the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced technician for help.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:
1) This device may not cause harmful interference, and....
2) This device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications made to this equipment not expressly approved by SANWA may void the FCC authorization to operate this equipment.

RF Exposure Statement:
This transmitter has been tested and meets the FCC RF exposure guidelines when used with the SANWA accessories supplied or designated for this product, and provided at least 20cm separation between the antenna the user's body is maintained. Use of other accessories may not ensure compliance with FCC RF
exposure guidelines.

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●予告なく外観または仕様の一部を変更することがあります。
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